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ISO 22917

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Precision superabrasives — Limit deviations and run-out tolerances for grinding wheels with diamond or cubic boron nitride

Superabrasifs de précision — Écarts limites et tolérances de battement pour les meules à base de diamant et de nitrure de bore



ISO 22917:2016(E)



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Foreword

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The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

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For an explanation on the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the WTO principles in the Technical Barriers to Trade (TBT) see the following URL: Foreword - Supplementary information

The committee responsible for this document is ISO/TC 29, *Small tools*, Subcommittee SC 5, *Grinding wheels and abrasives*.

This second edition cancels and replaces the first edition (ISO 22917:2004), which has been technically revised with the following changes:

- a) form E added;
- b) dimensions for d_{\min} revised;
- c) dimensions for l_1 partly revised.

Precision superabrasives — Limit deviations and run-out tolerances for grinding wheels with diamond or cubic boron nitride

1 Scope

This International Standard applies to all rotating grinding precision tools with diamond or cubic boron nitride with metal, vitrified or resinoid bonded cores, and circular bores for mounting the grinding tool on a clamping flange as well as to grinding points with cylindrical spindle for mounting in collets. It contains the significant limit deviations and run-out tolerances of these grinding tools.

2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 286-1, Geometrical product specifications (GPS) — ISO code system for tolerances on linear sizes — Part 1: Basis of tolerances, deviations and fits

ISO 286-2:2010, Geometrical product specifications (GPS) — ISO code system for tolerances on linear sizes — Part 2: Tables of standard tolerance classes and limit deviations for holes and shafts

3 Terms and definitions

For the purposes of this document, the terms and definitions in ISO 286-1 and the following apply.

NOTE Some of the terms are defined in a more restricted sense than in common usage.

3.1

size

number expressing, in a particular unit, the numerical value of a linear dimension

3.1.1

basic size

nominal size

size from which the *limits of size* (3.1.3) are derived by the application of the upper and lower deviations (3.2)

3.1.2

actual size

size of a feature, obtained by measurements

3.1.3

limits of size

two extreme permissible sizes of a feature, between which the *actual size* (3.1.2) should lie, the limits of size being included

3.1.3.1

maximum limit of size

greatest permissible size of a feature

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3.1.3.2

minimum limit of size

smallest permissible size of a feature

3.2

deviation

algebraic difference between a size (3.1) (actual size, limit of size, etc.) and the corresponding basic size (3.1.1)

3.2.1

limit deviations

upper deviation and lower deviation

3.2.1.1

upper deviation

algebraic difference between the *maximum limit of size* (3.1.3.1) and the corresponding basic size

3.2.1.2

lower deviation

algebraic difference between the *minimum limit of size* (3.1.3.2) and the corresponding basic size

3.3

size tolerance

difference between the *maximum limit of size* (3.1.3.1) and the *minimum limit of size* (3.1.3.2), i.e. the difference between the *upper deviation* (3.2.1.1) and the *lower deviation* (3.2.1.2)

Note 1 to entry: The tolerance is an absolute value without sign.

4 Limit deviations and run-out tolerance abbreviations

See Table 1.

Table 1 — Limit deviations and run-out tolerance abbreviations

Cl 1	Designation		
Symbol	Abrasive product	Mounted points	
T_{D}	Limit deviations of outside diameter	Limit deviations of outside diameter	
$T_{ m E}$	Limit deviations of thickness at bore		
$T_{ m H}$	Limit deviations of bore diameter		
T_{J}	Limit deviations of contact surface diameter		
$T_{ m K}$	Limit deviations of recess diameter		
$T_{ m L}$		Limit deviations of overall length	
$T_{ m L4}$		Limit deviations of reduced length of spindle	
$T_{ m PL}$	Limit deviations of circular run-out tolerance, axial		
T_{R}	Limit deviations of the radii		
$T_{ m RL}$	Limit deviations of circular run-out tolerance, radial	Limit deviations of circular run-out tolerance, radial	
T_{Sd}		Limit deviations of spindle diameter	
$T_{\rm S1}$		Limit deviations of reduced diameter of spindl	
T_{T}	Limit deviations of overall thickness	Limit deviations of thickness	
$T_{ m U}$	Limit deviations of thickness of superabrasive section		

 Table 1 (continued)

Symbol	Designation		
	Abrasive product	Mounted points	
T_{W}	Limit deviations of rim width		
$T_{\rm X}$	Limit deviations of depth of superabrasive section	Limit deviations of depth of superabrasive section	
T_{α}	Limit deviations of angles		

5 Straight, recessed, tapered and hubbed grinding wheels

5.1 Grinding wheels for peripheral grinding

5.1.1 Designations

See <u>Table 2</u>.

Table 2 — Designations for grinding wheels for peripheral grinding

Designation	Sketch	Basic core shape
Straight peripheral wheel	$ \begin{array}{c c} \hline & T_{PL} & A \\ \hline & T_{RL} & A \end{array} $	1
Single hubbed wheel	A SOUTH AND A SOUT	3
Wheel tapered one side	D X X	4

Basic Designation Sketch core shape D Grinding wheel recessed on one K side 6 Н D Grinding wheel recessed on both K sides 9 HD Double hubbed wheel Χ 14 Н

Table 2 (continued)

5.1.2 Limit deviations and run-out tolerances for grinding wheels for peripheral grinding

5.1.2.1 Limit deviations of the outside diameter, T_D , circular run-out tolerance, axial, T_{PL} , and circular run-out tolerance, radial, T_{RL}

The limit deviations of the outside diameter, T_D , the circular run-out tolerance, axial, T_{PL} , and circular run-out tolerance, radial, T_{RL} , as specified in <u>Table 3</u>, apply to the respective range of diameters, D.

Table 3 — Limit deviations and run-out tolerances of the outside diameter for grinding wheels for peripheral grinding

Dimensions in millimetres

	1	1	
Outside diameter D	T_{D}	$T_{ m PL}$	$T_{ m RL}$
<i>D</i> ≤ 3	±0,3		
3 < D ≤ 6	±0,3		0.02
6 < D ≤ 30	±0,3	0.05	0,03
$30 < D \le 120$	±0,3	0,05	
$120 < D \le 400$	±0,5		0.05
D > 400	±0,8		0,05

5.1.2.2 Limit deviations of the bore diameter, $T_{\rm H}$

The limit deviations of the bore diameters, $T_{\rm H}$, as specified in <u>Table 4</u>, correspond to the tolerance zone H7 in accordance with ISO 286-2:2010, Table 6, and apply to the respective range of bore diameters, H.

Table 4 — Limit deviations and run-out tolerances of the bore diameter for grinding wheels for peripheral grinding

Dimensions in millimetres

Bore diameter H	$T_{ m H}$
<i>H</i> ≤ 3	+0,010
3 < H ≤ 6	+0,012
6 < <i>H</i> ≤ 10	+0,015 0
10 < <i>H</i> ≤ 18	+0,018
18 < <i>H</i> ≤ 30	+0,021 0
30 < <i>H</i> ≤ 50	+0,025 0
50 < <i>H</i> ≤ 80	+0,030
80 < <i>H</i> ≤ 120	+0,035 0
120 < <i>H</i> ≤ 180	+0,040
180 < <i>H</i> ≤ 250	+0,046
250 < <i>H</i> ≤ 315	+0,052
315 < <i>H</i> ≤ 400	+0,057
400 < <i>H</i> ≤ 500	+0,063

5.1.2.3 Limit deviations of overall thickness, $T_{\rm T}$, and of thickness of superabrasive section, $T_{\rm U}$

The limit deviations of the overall thickness, $T_{\rm T}$, and of the thickness of the superabrasive section, $T_{\rm U}$, as specified in Table 5, apply to the respective ranges of thickness, T and U.

Table 5 — Limit deviations of the overall thickness and the thickness of the superabrasive section for grinding wheels for peripheral grinding

Thicknesses T and U	$T_{ m T}$	T_{U}
<i>T</i> or <i>U</i> < 30	±0,2	±0,2
$30 < T \text{ or } U \le 120$	±0,5	±0,3
$120 < T \text{ or } U \le 400$	±0,8	±0,5
$400 < T \text{ or } U \le 500$	±1,0	±0,8

5.1.2.4 Limit deviations of depth of superabrasive section, T_X

The limit deviations of the depth of superabrasive section, T_X , as specified in <u>Table 6</u>, apply to the respective range of depths of the superabrasive section, X.

Table 6 — Limit deviations of the depth of the superabrasive section for grinding wheels for peripheral grinding

Dimensions in millimetres

Depth of superabrasive section X	$T_{ m x}$ a
$0,5 \le X \le 1$	+0,2 0
1 < <i>X</i> ≤ 6	+0,2 -0,1
6 < <i>X</i> ≤ 30	+0,3 -0,2
^a Excluding electroplated single layer.	

5.1.2.5 Limit deviations of thickness at bore, $T_{\rm E}$

For grinding wheels with one recess (see type 6), or grinding wheels with two recesses (see type 9), the limit deviations of thickness at bore, $T_{\rm E}$, as specified in <u>Table 7</u>, apply to the respective range of thickness at bore, E.

Table 7 — Limit deviations of thickness at bore for grinding wheels for peripheral grinding

Dimensions in millimetres

Thickness at bore E	$T_{ m E}$
<i>E</i> ≤ 6	±0,3
6 < E ≤ 30	±0,3
30 < E ≤ 120	±0,3

5.1.2.6 Limit deviations of contact surface diameter, $T_{\rm I}$, and of recessed diameter, $T_{\rm K}$

The limit deviations of contact surface diameter, $T_{\rm J}$, (see types 3, 4, 14) and of the recessed diameter, $T_{\rm K}$, (see types 6, 9), as specified in Table 8, apply to the respective range of outside diameters, D.

Table 8 — Limit deviations of contact surface diameter and recessed diameter for grinding wheels for peripheral grinding

Outside diameter D	$T_{ m J}$, $T_{ m K}$
6 ≤ <i>D</i> ≤ 120	±1
D > 120	±2

5.1.2.7 Limit deviations of the radii, T_R

The limit deviations of the radii, T_R , as specified in Table 9 (see, e.g. shapes of abrasive sections F, FF and Q, shown in Figures 1 to 3), apply to the respective range of radii, R.

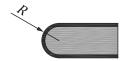


Figure 1 — Shape F



Figure 2 — Shape FF

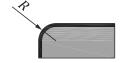


Figure 3 — Shape Q

Table 9 — Limit deviations of radii for grinding wheels for peripheral grinding

Dimensions in millimetres

Radius <i>R</i>	$T_{ m R}$
<i>R</i> ≤ 3	±0,2
3 < R ≤ 6	±0,2
6 < R ≤ 30	±0,2

5.1.2.8 Limit deviations of angles, T_{α}

The limit deviations of angles, T_{α} , as specified in <u>Table 10</u> (see, e.g. the shape of abrasive sections B and E — <u>Figures 4</u> and <u>5</u>), apply to the respective range of angles, α .



Figure 4 — Shape B



Figure 5 — Shape E

Table 10 — Limit deviations of angles for grinding wheels for peripheral grinding

Values in degrees

Angle α	T_{α}
$\alpha \le 50$	±0,5
50 < α ≤ 120	±1

5.2 Grinding wheels for face grinding

5.2.1 Designations

See Table 11.

Table 11 — Designations for grinding wheels for face grinding

Designation	Sketch	Basic core shape
Straight grinding wheel	D W T PL A T T PL A	1
Cylinder wheel		2

 Table 11 (continued)

Designation	Sketch	Basic core shape
Single hubbed wheel	D W 45°	3
Wheel tapered one side		4
Straight cup wheel		6
Double cup wheel		9
Concave double- angle cup wheel		10

Basic core Designation Sketch shape D Taper cup wheel 11 Н K D Taper cup wheel WK 12 Н D Taper cup wheel WK 13 Н

Table 11 (continued)

5.2.2 Limit deviations and run-out tolerances for grinding wheels for face grinding

5.2.2.1 Limit deviations of the outside diameter, $T_{\rm D}$, circular run-out tolerance, axial, $T_{\rm PL}$, and circular run-out tolerances, radial, $T_{\rm RL}$

The limit deviations of the outside diameter, $T_{\rm D}$, the circular run-out tolerances, axial, $T_{\rm PL}$, and the circular run-out tolerances, radial, $T_{\rm RL}$, as specified in Table 12, apply to the respective range of outside diameters, D.

Table 12 — Limit deviations and run-out tolerances of the outside diameter for grinding wheels for face grinding

Outside diameter D	T_{D}	$T_{ m PL}$, $T_{ m RL}$
<i>D</i> ≤ 30	±0,3	
30 < D ≤ 120	±0,4	0,05
120 < D ≤ 300	±0,5	
D > 300	±0,8	0,05

5.2.2.2 Limit deviations of the bore diameter, $T_{\rm H}$

The limit deviations of the bore diameter, $T_{\rm H}$, as specified in Table 13, correspond to the tolerance zone H7 in accordance with ISO 286-2:2010, Table 6, and apply to the respective range of bore diameters, H.

Table 13 — Limit deviations and run-out tolerances of the bore diameter for grinding wheels for face grinding

Dimensions in millimetres

Bore diameters H	$T_{ m H}$
<i>H</i> ≤ 3	+0,010
3 < H ≤ 6	+0,012
6 < <i>H</i> ≤ 10	+0,015 0
10 < H ≤ 18	+0,018
18 < H ≤ 30	+0,021
30 < H ≤ 50	+0,025 0
50 < <i>H</i> ≤ 80	+0,030 0
80 < <i>H</i> ≤ 120	+0,035 0
120 < <i>H</i> ≤ 180	+0,040
180 < H ≤ 250	+0,046 0
250 < <i>H</i> ≤ 315	+0,052 0
315 < <i>H</i> ≤ 400	+0,057 0
400 < H ≤ 500	+0,063

5.2.2.3 Limit deviations of the overall thickness, $T_{\rm T}$, of the thickness of superabrasive section, $T_{\rm U}$, and rim width, $T_{\rm W}$

The limit deviations of the overall thickness, $T_{\rm T}$, of the thickness of superabrasive section, $T_{\rm U}$, and rim width, $T_{\rm W}$, as specified in Table 14, apply to the respective range of nominal size of the overall thickness, $T_{\rm C}$, the thickness of superabrasive section, $U_{\rm C}$, and rim width, $W_{\rm C}$.

For T < 0.03 D of basic core shape 1 to 4, the limit deviation, T_T , shall only apply in the positive range.

Table 14 — Limit deviations of the overall thickness, the thickness of the superabrasive section and the rim width for grinding wheels for face grinding

Di	Dimensions in millimetres	
Range of nominal size <i>T, U, W</i>	T_{T} , T_{U} , T_{W}	
$T \text{ or } U \text{ or } W \le 30$	±0,3	
$30 < T \text{ or } U \text{ or } W \le 120$	±0,3	
$120 < T \text{ or } U \text{ or } W \le 400$	±0,3	
T or U or W > 400	±0,3	

5.2.2.4 Limit deviations of the thickness at bore, $T_{\rm E}$

The limit deviations of the thickness at bores, $T_{\rm E}$, for grinding wheels with one side recessed (see basic core shapes 6, 11, 12, 13, 15) or grinding wheels with two sides recessed, as specified in <u>Table 15</u>, apply to the respective range of thickness at bore, E.

For E < 0.2 T of basic core shape 6 to 15, the limit deviations, T_E , shall only apply in the positive range.

Table 15 — Limit deviations of thickness at bore for grinding wheels for face grinding

	Dimensions in millimetres
Thickness at bore E	$T_{ m E}$
<i>E</i> ≤ 6	±0,1
6 < E ≤ 30	±0,2
30 < E ≤ 120	±0,3
$120 < E \le 230$	±0,5

5.2.2.5 Limit deviations of the depth of superabrasive section, $T_{\rm X}$

The limit deviations of the depth of superabrasive section, T_x , as specified in <u>Table 16</u>, apply to the respective depth of superabrasive section, X.

Table 16 — Limit deviations of the depth of the superabrasive section for grinding wheels for face grinding

Depth of superabrasive section X	T_{X}
0,5 ≤ <i>X</i> ≤ 1	+0,2 0
1 < <i>X</i> ≤ 6	+0,2 -0,1
6 < <i>X</i> ≤ 30	+0,3 -0,2

5.2.2.6 Limit deviations of the contact surface diameter, $T_{\rm J}$, and of the recess diameter, $T_{\rm K}$

The limit deviations of the contact surface diameter, $T_{\rm J}$, and of the recess diameter, $T_{\rm K}$, as specified in Table 17, apply to the respective range of outside diameter, D.

Table 17 — Limit deviations of contact surface diameter and recessed diameter for grinding wheels for face grinding

Dimensions in millimetres

Outside diameter D	$T_{ m J},T_{ m K}$
<i>D</i> ≤ 400	±1
D > 400	±2

6 Mounted points

6.1 Designation

See Table 18.

Table 18 — Designation of mounted points

Designation	Sketch	Basic core shape
Mounted points		1

6.2 Limit deviations and circular run-out tolerances

6.2.1 Limit deviations of the outside diameter, T_D , of the thickness, T_T , of the depth of superabrasive section, T_X , and circular run-out tolerance, axial, T_{RL}

The limit deviations of the outside diameter, $T_{\rm D}$, of the thickness, $T_{\rm T}$, of the depth of superabrasive section, $T_{\rm X}$, and the circular run-out tolerance, axial, $T_{\rm RL}$, as specified in Table 19, apply to the respective ranges of nominal sizes of outside diameter, D, thickness, T, and depth of superabrasive section, X.

Table 19 — Limit deviations of the outside diameter, the thickness and the depth of the superabrasive section and run-out tolerances

Dimensions in millimetres

Nominal sizes <i>T, D, X</i>	T_{D}	$T_{ m T}$	$T_{ m X}^{ m a}$	$T_{ m RL}$
$0.5 \le T \text{ or } D \text{ or } X \le 3$	±0,15	.0.1	+0,2 0	
$3 < T \text{ or } D \text{ or } X \le 6$	±0,2	±0,1	+0,2 -0,1	0,03
6 < <i>T</i> or <i>D</i> or <i>X</i> ≤ 30	±0,5	±0,2	+0,3 -0,2	
$T_{ m x}$ excluding electroplated single layer.				

6.2.2 Limit deviations of the spindle diameter, $T_{\rm Sd}$, and of the reduced diameter of spindle, $T_{\rm S1}$

The limit deviations of the spindle diameter, $T_{\rm Sd}$, as specified in <u>Table 20</u>, correspond to the tolerance zone g6 in accordance with ISO 286-2:2010, Table 21, and apply to the respective ranges of diameters, $S_{\rm d}$. The limit deviations of the reduced spindle, $T_{\rm S1}$, apply to the respective range of diameter of the reduced spindle, $S_{\rm 1}$.

Table 20 — Limit deviations of the spindle diameter and of the reduced diameter

Dimensions in millimetres

$\begin{array}{c} \textbf{Diameter} \\ S_{d}, S_{1} \end{array}$	$T_{ m Sd}$	T_{S1}
$1 \le S_{\mathrm{d}} \text{ or } S_1 \le 3$	-0,002 -0,008	.01
$3 < S_{\rm d} \text{ or } S_1 \le 6$	-0,004 -0,008	±0,1
$6 < S_{\rm d} \text{ or } S_1 \le 10$	-0,005 -0,014	.0.2
$10 < S_{\rm d} \text{ or } S_1 \le 18$	-0,006 -0,017	±0,2
$18 < S_{\rm d} \text{ or } S_1 \le 30$	-0,007 -0,020	±0,5

6.2.3 Limit deviations of the overall length, $T_{\rm L}$, and of the reduced length of spindle, $T_{\rm L4}$

The limit deviations of the overall length, T_L , and of the reduced length of the spindle, T_{L4} , as specified in Table 21, apply to the respective ranges of the overall lengths, L, and the reduced lengths of the spindle, L_4 .

Table 21 — Limit deviations of the overall length and the reduced length of spindle

Lengths L, L4	$T_{ m L}$, $T_{ m L4}$
$L \text{ or } L_4 \le 120$	±1

7 Superabrasives with metal core for hand-held grinding

7.1 Designation

See Table 22.

Table 22 — Designation of superabrasives with metal core for hand-held grinding

Designation	Sketch	Basic core shape
Taper cup wheel	D W K	13

7.2 Limit deviations and run-out tolerances

7.2.1 Limit deviations of the outside diameter, T_D , of the overall thickness, T_T , circular run-out tolerance, axial, T_{PL} , and circular run-out tolerance, radial, T_{RL}

The limit deviations of the outside diameter, $T_{\rm D}$, of the overall thickness, $T_{\rm T}$, the circular run-out tolerance, axial, $T_{\rm PL}$, and the circular run-out tolerance, radial, $T_{\rm RL}$, as specified in Table 23, apply to the respective ranges of nominal outside diameters, D.

Table 23 — Limit deviations of the outside diameter and the overall thickness, and circular runout tolerances, axial and radial

Dimensions in millimetres

Outside diameters D	T_{D}	$T_{ m T}$	$T_{ m PL}$	$T_{ m RL}$
$30 \le D \le 120$ ±0,8		.0.5	0.02	0.02
120 < D ≤ 230	±1,2	±0,5	0,02	0,03

7.2.2 Limit deviations of the bore diameter, $T_{\rm H}$

The limit deviations of the bore diameter, $T_{\rm H}$, as specified in <u>Table 24</u>, correspond to the tolerance zone H7 in accordance with ISO 286-2:2010, Table 6, and apply to the respective ranges of bore diameters, H.

Table 24 — Limit deviations of the bore diameter

Bore diameters H	$T_{ m H}$
6 ≤ <i>H</i> ≤ 10	+0,015 0
10 < <i>H</i> ≤ 18	+0,018 0
18 < H ≤ 30	+0,021 0
30 < H ≤ 50	+0,025 0
50 < <i>H</i> ≤ 80	+0,030 0

7.2.3 Limit deviations of the depth of superabrasive section, T_X

The limit deviations of the depth of the superabrasive section, T_X , as specified in <u>Table 25</u>, apply to the respective depths of superabrasive section, X.

Table 25 — Limit deviations of the depth of superabrasive section

Dimensions in millimetres

Depth of superabrasive section X	$T_{ m X}$
$0,5 \le X \le 1$	+0,2 0
1 < <i>X</i> ≤ 6	+0,2 -0,1
6 < <i>X</i> ≤ 30	+0,3 -0,2

7.2.4 Limit deviations of the rim width, $T_{\rm W}$

The limit deviations of the rim width, T_W , as specified in <u>Table 26</u>, apply to the respective ranges of nominal size of rim width, W.

Table 26 — Limit deviations of the rim width

Dimensions in millimetres

Rim width W	T_{W}
<i>W</i> ≤ 30	±0,2
30 < W ≤ 120	±0,3
120 < <i>W</i> ≤ 400	±0,5
W > 400	±0,8

7.2.5 Limit deviations of the thickness at bore, $T_{\rm E}$

The limit deviations of the thickness at bore, $T_{\rm E}$, as specified in Table 27, apply to the respective ranges of nominal size of thickness at bore, E.

Table 27 — Limit deviations of the thickness at bore

Thickness at bore E	$T_{ m E}$
<i>E</i> ≤ 6	±0,1
6 < E ≤ 30	±0,2
30 < E ≤ 120	±0,3
120 < E ≤ 230	±0,5

7.2.6 Limit deviations of the contact surface diameter, $T_{\rm I}$, and of the recess diameter, $T_{\rm K}$

The limit deviations of the contact surface diameter, $T_{\rm J}$, and of the recess diameter, $T_{\rm K}$, as specified in Table 28, apply to the respective range, of nominal size, J and K.

Table 28 — Limit deviations of the contact surface and of the recess diameter

Dimensions in millimetres

Diameters J, K	$T_{ m J},T_{ m K}$
<i>J</i> or <i>K</i> ≤ 3	
3 < <i>J</i> or <i>K</i> ≤ 6	
6 < <i>J</i> or <i>K</i> ≤ 30	±1
$30 < J \text{ or } K \le 120$	
$120 < J \text{ or } K \le 400$	

