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**Castors and wheels — Requirements for
applications over 1,1 m/s (4 km/h) and up
to 4,4 m/s (16 km/h)**

*Roues et roulettes — Exigences pour des applications à plus de 1,1 m/s
(4 km/h) et jusqu'à 4,4 m/s (16 km/h)*



Reference number
ISO 22884:2004(E)

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 2.

The main task of technical committees is to prepare International Standards. Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights.

ISO 22884 was prepared by Technical Committee ISO/TC 110, *Industrial trucks*, Subcommittee SC 3, *Castors and wheels*.

This first edition of ISO 22884 cancels and replaces ISO 2175:1981, ISO 2184-1:1972, ISO 3101:1981 and ISO 3102:1981.

Castors and wheels — Requirements for applications over 1,1 m/s (4 km/h) and up to 4,4 m/s (16 km/h)

1 Scope

This International Standard specifies the technical requirements, the appropriate dimensions and the requirements for testing of castors and wheels (which may include accessories), specifically for manually propelled or power-towed industrial applications at speeds over 1,1 m/s (4 km/h) and up to 4,4 m/s (16 km/h).

Pneumatic wheels and drive wheels are not covered by this International Standard.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 22877, *Castors and wheels — Vocabulary, symbols and multilingual terminology*

ISO 22878:2004, *Castors and wheels — Test methods and apparatus*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 22877 apply. Symbols are given in ISO 22878:2004, Annex A.

4 Classification, characteristics and dimensions

4.1 Classification

The castors and wheels are divided into three categories: A, B and C. These categories define three increasing speed ratings and are listed in Table 1.

Table 1

| Category | A | B | C |
|-------------------|---------|----------|----------|
| Speed, m/s (km/h) | 1,7 (6) | 2,8 (10) | 4,4 (16) |

4.2 Characteristics

The characteristics of a castor are

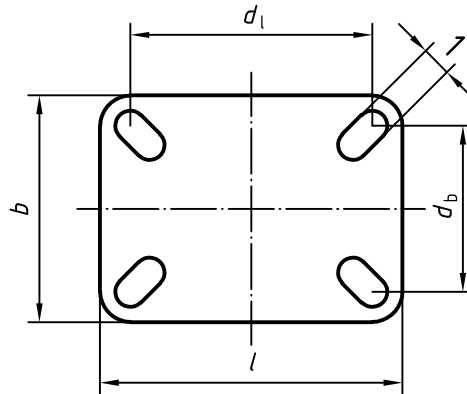
- top plate,
- offset,
- wheel, and
- load capacity.

4.3 Top plate

Rectangular top plates are used with four fixing holes. The design of the outer profile is left to the manufacturer, provided that it is inscribed in a rectangle of maximum size $l \times b$ as indicated in Table 2 and shown in Figure 1.

The fixing holes are located at the corners of a rectangle inscribed in the outer profile. The holes may be oblong and form slots, provided the width of the slot is suitable for bolts of diameter (D_{G1}) as in Table 2.

Table 2 lists the standardized dimensions of the different classes of top plates.



Key

1 adapted to D_{G1}

NOTE The symbols $A \times B$ (top plate outer dimensions) and $a \times b$ (bolt hole spacing) may be used in place of the recommended symbols stated above as these are of common use within the trade.

Figure 1 — Rectangular top plate

Table 2

Dimensions in millimetres

| Class | Top plate outer dimensions $l \times b$ | Bolt hole spacing $d_l \times d_b$ | Fixing bolt diameter D_{G1} |
|-------|--|---------------------------------------|----------------------------------|
| R51 | 160 × 120 | 105 × 80 | 10 |
| | | | 12 |
| R52 | 180 × 160 | 140 × 105 | 10 |
| | | | 12 |
| | | | 14 |
| | | | 16 |
| R53 | 230 × 180 | 160 × 120 | 12 |
| | | | 14 |
| | | | 16 |
| | | | 20 |
| R54 | 270 × 230 | 210 × 160 | 14 |
| | | | 16 |
| | | | 20 |

4.4 Offset

Table 3 specifies the minimum and maximum offset values (d_F) for swivel castors, corresponding to the wheel diameter (D), as in Figure 2.

For shock-absorbing castors, the offset may vary from the dimensions stated.

Table 3

Dimensions in millimetres

| Wheel diameter D | Offset d_F | |
|-----------------------|-----------------|---------|
| | Minimum | Maximum |
| 125 | 25 | 75 |
| 150/160 | 30 | 95 |
| 200 | 40 | 120 |
| 250 | 50 | 150 |
| 280/300 | 55 | 180 |
| 350/360 | 70 | 215 |
| 400 | 80 | 240 |
| 450 | 90 | 270 |
| 500 | 100 | 300 |

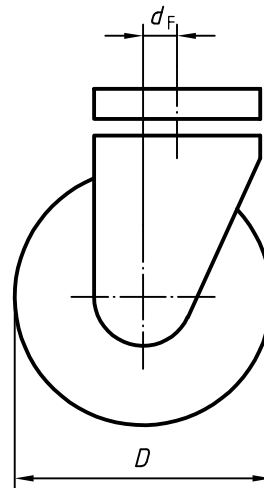


Figure 2 — Offset

4.5 Wheel

4.5.1 Characteristics

The characteristics of a wheel are

- diameter,
- hub width,
- bore diameter, and
- load capacity.

The characteristics of the wheel are illustrated in Figure 3 and the hub width (b_{T1}) and bore diameter (D_d) corresponding to each wheel diameter (D) are listed in Table 4. Wheels are not restricted to these hub widths and bores when used in castors.

The user shall verify the mechanical strength of axle components (bolts, nuts, bushes, spacers, etc.).

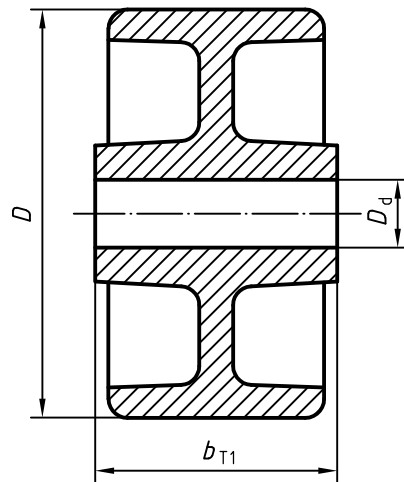


Figure 3 — Wheel dimensions

Table 4

Dimensions in millimetres

| Wheel diameter D | Hub width b_{T1} | Bore diameters ^a D_d |
|-----------------------|-----------------------|--------------------------------------|
| 125 | 50 | 20 |
| | | 25 |
| 150/160 | 60 | 20 |
| | | 25 |
| 200 | 60 | 20 |
| | | 25 |
| | 75 | 25 |
| | | 30 |
| 250 | 60 | 25 |
| | | 30 |
| | 75 | 25 |
| | | 30 |
| | 90 | 25 |
| | | 30 |
| 140 | 30 | |
| | 40 | |

Table 4 (continued)

Dimensions in millimetres

| Wheel diameter D | Hub width b_{T1} | Bore diameters ^a D_d | |
|-----------------------|-----------------------|--------------------------------------|----|
| 280 | 60 | 25 | |
| | | 30 | |
| | 75 | 25 | |
| | | 30 | |
| | 90 | 25 | |
| | | 30 | |
| 300 | 90 | 25 | |
| | | 30 | |
| | | 35 | |
| | 120 | 35 | |
| | | 40 | |
| | | | |
| 350/360 | 75 | 30 | |
| | | 40 | |
| | 90 | 35 | |
| | | 40 | |
| | 400 | 75 | 30 |
| | | | 35 |
| 40 | | | |
| | | | |
| 90 | | 35 | |
| | | 40 | |
| 120 | | 40 | |
| | | 50 | |
| 140 | 40 | | |
| | 50 | | |
| 450 | 90 | 40 | |
| | | 50 | |
| | 120 | 60 | |
| 500 | 90 | 40 | |
| | | 50 | |
| | 120 | 60 | |
| | | 160 | 60 |

^a The above bores refer to the nominal diameter of the axle.

4.5.2 Wheel diameter tolerance

The tolerance on wheel diameter (D) shall be $\pm 1,5\%$.

4.5.3 Hub width tolerance

The tolerance on hub width (b_{T1}) shall be $\begin{matrix} 0 \\ -2\% \end{matrix}$.

4.6 Load capacity

This is the maximum load, in newtons, which can be carried by a wheel or a castor so as to fully comply with the required acceptance criteria.

5 Requirements for testing

5.1 General

Test apparatus and procedures shall be as specified in ?ISO 22878:-?. A static test is not required for this type of castor.

5.2 Standard conditions

5.2.1 Environmental conditions

Tests shall be carried out at a temperature between 15 °C and 28 °C. During the 24 h prior to the test, the samples shall remain at the specified temperature, in an environment with a relative humidity between 40 % and 70 %.

Samples shall not be artificially cooled during testing.

5.2.2 Test sequence

Tests, where applicable, shall be carried out in the sequence as listed in Table 5.

Table 5

| Reference in this International Standard | Test sequence | Castors and wheel types | Test procedures given in ISO 22878:2004, subclause |
|--|--|--|--|
| 5.3 | Initial wheel play | All castors | 4.2 |
| 5.4 | Initial swivel play | Swivel castors with or without accessories | 4.3 |
| 5.5 | Electrical resistance | Castors and wheels electrically conductive or antistatic | 4.4 |
| 5.6 | Fatigue test for braking and/or locking device | Castors with <ul style="list-style-type: none"> — wheel locking/braking device — directional locking device — total locking/braking device — central locking/braking device If device is operated by means of threaded mechanism this test will not be applicable. | 4.5 |
| 5.7 | Efficiency check of wheel braking and/or locking device | Castors with <ul style="list-style-type: none"> — wheel locking/braking device — total locking/braking device — central locking/braking device | 4.6 |
| 5.8 | Efficiency check of swivel braking and/or locking device | Castors with <ul style="list-style-type: none"> — directional locking/braking device — total locking/braking device — central locking/braking device | 4.7 |

Table 5 (continued)

| Reference in this International Standard | Test sequence | Castors and wheel types | Test procedures given in ISO 22878:2004, subclause |
|--|--|--|--|
| 5.9 | Static test | This test is not required | 4.9 |
| 5.10 | Dynamic test | All castors | 4.8 |
| 5.11 | Efficiency check of wheel braking and/or locking device | Castors with — wheel locking/braking device — total locking/braking device — central locking/braking device | 4.6 |
| 5.12 | Efficiency check of swivel braking and/or locking device | Castors with — directional locking/braking device — total locking/braking device — central locking/braking device | 4.7 |
| 5.13 | Final wheel play | All castors | 4.2 |
| 5.14 | Final swivel play | Swivel castors with or without accessories | 4.3 |

5.3 Initial wheel play

5.3.1 Test objectives, apparatus and procedures

These shall be as specified in ISO 22878:2004, 4.2.

5.3.2 Acceptance criteria

The measured initial wheel play shall not exceed the value d_{W1} given in Table 6.

Table 6

| Symbol | Value | Description |
|----------|--------------|----------------------------|
| D | variable | wheel diameter |
| d_{W1} | 0,5 % of D | maximum initial wheel play |

5.4 Initial swivel play

5.4.1 Test objectives, apparatus and procedures

These shall be as specified in ISO 22878:2004, 4.3.

5.4.2 Acceptance criteria

The measured initial swivel play shall not exceed the value d_{S1} given in Table 7.

Table 7

| Symbol | Value | Description |
|----------|-------|-----------------------------|
| d_{S1} | 3 mm | maximum initial swivel play |

5.5 Electrical resistance test

5.5.1 Test objectives, apparatus and procedures

These shall be as specified in ISO 22878:2004, 4.4.

5.5.2 Test values

The test values shall be as listed in Table 8.

Table 8

| Symbol | Value | Description |
|------------|--------------------|-----------------------|
| F_{\max} | variable | load capacity |
| F_{17} | 10 % of F_{\max} | test load |
| R | variable | electrical resistance |

5.5.3 Tolerances

The tolerances shall be as shown in Table 9.

Table 9

| Symbol | Unit | Tolerance | |
|----------|------|---|------|
| | | Acceptable | Unit |
| F_{17} | N | $\begin{matrix} +2\% \\ 0 \end{matrix}$ | N |

5.5.4 Acceptance criteria

The resistance R of the sample tested shall be

- $R \leq 10^5 \Omega$ for conductive castors or wheels, and
- $10^5 \Omega < R \leq 10^7 \Omega$ for antistatic castors or wheels.

5.6 Fatigue test for braking and/or locking device

5.6.1 Test objectives, apparatus and procedures

These shall be as specified in ISO 22878:2004, 4.5.

5.6.2 Test values

The test values shall be as listed in Table 10.

Table 10

| Symbol | Value | Description |
|------------|--------------------|------------------------------|
| n_E | 5 000 | number of locking actions |
| f_E | 10 cycles per min | frequency of locking actions |
| F_{\max} | variable | load capacity |
| F_3 | 10 % of F_{\max} | test load |

5.6.3 Tolerances

The tolerances shall be as shown in Table 11.

Table 11

| Symbol | Unit | Tolerance | |
|--------|------------|---|------------|
| | | Acceptable | Unit |
| n_E | — | $\begin{matrix} 0 \\ -1\% \end{matrix}$ | — |
| f_E | cycles/min | $\begin{matrix} 0 \\ -2 \end{matrix}$ | cycles/min |
| F_3 | N | $\begin{matrix} +2\% \\ 0 \end{matrix}$ | N |

5.6.4 Acceptance criteria

There shall be no wear and/or permanent deformation that adversely affects the performance of the sample.

5.7 Efficiency check of wheel braking and/or locking device

5.7.1 Test objectives, apparatus and procedures

These shall be as specified in ISO 22878:2004, 4.6.

5.7.2 Test values

The test values shall be as listed in Table 12.

Table 12

| Symbol | Value | Description |
|------------|---|---------------------------|
| F_{\max} | variable | load capacity |
| F_{11} | equal to F_{\max} | test load |
| F_{K1} | tread hardness ≥ 90 Shore A: 10 % of F_{\max} tread hardness < 90 Shore A: 15 % of F_{\max} | horizontal tractive force |

5.7.3 Tolerances

The tolerances shall be as shown in Table 13.

Table 13

| Symbol | Unit | Tolerance | |
|----------|------|---|------|
| | | Acceptable | Unit |
| F_{11} | N | $\begin{matrix} +2\% \\ 0 \end{matrix}$ | N |
| F_{K1} | N | $\begin{matrix} +4\% \\ 0 \end{matrix}$ | N |

5.7.4 Acceptance criteria

There shall be no revolving movement around the wheel axis during the second application of the force F_{K1} .

5.8 Efficiency check of swivel braking and/or locking device

5.8.1 Test objectives, apparatus and procedures

These shall be as specified in ISO 22878:2004, 4.7.

5.8.2 Test values

The test values shall be as listed in Table 14.

Table 14

| Symbol | Value | Description |
|------------|---|---------------------------|
| F_{\max} | variable | load capacity |
| F_{11} | equal to F_{\max} | test load |
| F_{k2} | tread hardness \geq 90 Shore A: 10 % of F_{\max} tread hardness $<$ 90 Shore A: 15 % of F_{\max} | horizontal tractive force |

5.8.3 Tolerances

The tolerances shall be as shown in Table 15.

Table 15

| Symbol | Unit | Tolerance | |
|----------|------|---|------|
| | | Acceptable | Unit |
| F_{11} | N | $\begin{matrix} +2\% \\ 0 \end{matrix}$ | N |
| F_{k2} | N | $\begin{matrix} +4\% \\ 0 \end{matrix}$ | N |

5.8.4 Acceptance criteria

There shall be no swivelling movement during the second application of the force F_{k2} .

5.9 Static test

This is not required.

5.10 Dynamic test

5.10.1 Test objectives, apparatus and procedures

These shall be as specified in ISO 22878:2004, 4.8.

5.10.2 Test values

The test values shall be as listed in Tables 16 and 17.

Table 16

| Symbol | Value | Description |
|------------|---|---|
| F_{\max} | variable | load capacity ^a |
| v_1 | see Table 17 | average speed of running period |
| v_2 | see Table 17 | speed at impact with obstacles |
| h_1 | height of obstacles for wheels with: tread hardness ≥ 90 Shore A: 2,5 % of D tread hardness < 90 Shore A: 5,0 % of D | height of obstacles |
| d_c | see Table 17 | distance between obstacles |
| n | 5 times D , in mm | number of obstacles to be passed by the wheel |
| n_{r1} | not required in this test | number of wheel revolutions |
| t_{z1} | 3 min | running period |
| t_{z2} | 1 min | pause |
| D | variable | wheel diameter |

^a A simulated load applied mechanically, hydraulically or pneumatically is acceptable provided that it has been previously verified.

Table 17 — Test settings for speed categories

| Category | A | B | C |
|--|---------|----------|----------|
| Average speed of running period, m/s (km/h) | 1,7 (6) | 2,8 (10) | 4,4 (16) |
| Speed of impact with the obstacles, m/s (km/h) | 1,7 (6) | 2,8 (10) | 4,4 (16) |
| Minimum distance between obstacles, m | 1 | 1,5 | 3 |

5.10.3 Tolerances

The tolerances shall be as shown in Table 18.

Table 18

| Symbol | Unit | Tolerance | |
|----------|------|---|------|
| | | Acceptable | Unit |
| v_1 | m/s | $\begin{matrix} +5\% \\ 0 \end{matrix}$ | m/s |
| v_2 | m/s | $\begin{matrix} +5\% \\ 0 \end{matrix}$ | m/s |
| h_1 | mm | $\begin{matrix} 0 \\ -5\% \end{matrix}$ | mm |
| n | — | $\begin{matrix} +1\% \\ 0 \end{matrix}$ | — |
| n_{r1} | — | $\begin{matrix} +1\% \\ 0 \end{matrix}$ | — |
| t_{z1} | min | ± 10 | s |
| t_{z2} | min | ± 10 | s |

5.10.4 Acceptance criteria

There shall be no permanent deformation of the sample that adversely affects its performance.

5.11 Efficiency check of wheel braking and/or locking device

Repeat test 5.7.

5.12 Efficiency check of swivel braking and/or locking device

Repeat test 5.8.

5.13 Final wheel play

5.13.1 Test objectives, apparatus and procedures

These shall be as specified in ISO 22878:2004, 4.2.

5.13.2 Acceptance criteria

The wheel wear play shall not exceed the value d_{W2} given in Table 19.

Table 19

| Symbol | Value | Description |
|----------|--------------|-------------------------|
| D | variable | wheel diameter |
| d_{W2} | 0,5 % of D | maximum wheel wear play |

5.14 Final swivel play

5.14.1 Test objectives, apparatus and procedures

These shall be as specified in ISO 22878:2004, 4.3.

5.14.2 Acceptance criteria

The swivel wear play shall not exceed the value d_{S2} as given in Table 20.

Table 20

| Symbol | Value | Description |
|----------|-------|--------------------------|
| d_{S2} | 3 mm | maximum swivel wear play |

6 Conformity

On request, the manufacturer shall declare by a certificate of conformity that the castors or wheels are in accordance with the requirements as stated in this International Standard.

The type of test machine shall be stated in the conformity document.

7 Marking of the product

7.1 Product marking

All the products shall be permanently and visibly marked with a name and/or trademark of the manufacturer.

7.2 Marking of electrically conductive or antistatic castors or wheels

All products shall bear on their outer surface a clearly visible mark as follows:

- antistatic: a white mark and, where appropriate and possible, the word “antistatic”;
- conductive: a yellow mark and, where appropriate and possible, the word “conductive”.

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