INTERNATIONAL STANDARD

First edition 2014-06-01

Cranes — General design — Limit states and proof of competence of forged steel hooks

Appareils de levage à charge suspendue — Conception générale — États limites et vérification d'aptitude des crochets forgés

Reference number ISO 17440:2014(E)

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Foreword

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The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2. www.iso.org/directives

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The committee responsible for this document is ISO/TC 96, *Cranes*, Subcommittee SC 8, *Jib cranes*.

Cranes — General design — Limit states and proof of competence of forged steel hooks

1 Scope

This International Standard is intended to be used together with the other relevant International Standards in its series. As such, they specify general conditions, requirements and methods to prevent hazards in hooks as part of all types of cranes.

This International Standard covers the following parts of hooks and types of hooks:

- bodies of any type of point hooks made of steel forgings;
- machined shanks of hooks with a thread/nut suspension.

NOTE 1 The principles of this International Standard can be applied to other types of shank hooks and also where stress concentration factors relevant to that shank construction are determined and used. Plate hooks, which are those assembled from one or several parallel parts of rolled steel plates are not covered in this International Standard.

This International Standard is applicable to hooks from materials with ultimate strength of not more than 800 N/mm2 and yield stress of not more than 600 N/mm2.

The following is a list of significant hazardous situations and hazardous events that could result in risks to persons during normal use and foreseeable misuse. [Clauses](#page-10-1) 4 to 8 of this document are necessary to reduce or eliminate the risks associated with the following hazards:

- a) exceeding the limits of strength (yield, ultimate, fatigue);
- b) exceeding temperature limits of material;
- c) unintentional disengagement of the load from the hook.

The requirements of this International Standard are stated in the main body of the document and are applicable to hook designs in general. The hook body and shank designs listed in [Annexes](#page-44-1) A, \overline{B} and \overline{G} are only examples and should not be referred to as requirements of this International Standard.

This International Standard is applicable to cranes manufactured after the date of its publication, and serves as a reference base for product standards of particular crane types.

NOTE 2 This International Standard deals only with the limit state method in accordance with ISO 8686-1.

2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies. No reproduce the init state method in accordance with ISO 8686-1.

2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and air

indispensable for its applicatio

ISO 148-1, *Metallic materials — Charpy pendulum impact test — Part 1: Test method*

ISO 148-2, *Metallic materials — Charpy pendulum impact test — Part 2: Verification of testing machines*

ISO 643, *Steels — Micrographic determination of the apparent grain size*

ISO 965-1, *ISO general purpose metric screw threads — Tolerances — Part 1: Principles and basic data*

ISO 17440:2014(E)

ISO 4287, *Geometrical Product Specifications (GPS) — Surface texture: Profile method — Terms, definitions and surface texture parameters*

ISO 4306-1, *Cranes — Vocabulary — Part 1: General*

ISO 4301-1, *Cranes and lifting appliances — Classification — Part 1: General*

ISO 6892-1, *Metallic materials — Tensile testing — Part 1: Method of test at room temperature*

ISO 8686-1, *Cranes — Design principles for loads and load combinations — Part 1: General*

ISO 9327-1, *Steel forgings and rolled or forged bars for pressure purposes — Technical delivery conditions — Part 1: General requirements*

ISO7500-1, *Metallic materials— Verification of static uniaxial testing machines— Part1: Tension/compression testing machines — Verification and calibration of the force-measuring system*

ISO 12100, *Safety of machinery — General principles for design — Risk assessment and risk reduction*

ISO 15579, *Metallic materials — Tensile testing at low temperature*

EN 10228-3, *Non-destructive testing of steel forgings ― Part 3: Ultrasonic testing of ferritic or martensitic steel forgings*

EN 10243-1, *Steel die forgings ― Tolerances on dimensions ― Part 1: Drop and vertical press forgings*

3 Terms, definitions and symbols

For the purposes of this document, the terms and definitions given in ISO 12100 and ISO 4306-1 and the following terms, definitions and symbols (see [Table](#page-8-0) 1) apply.

3.1

hook shank

upper part of the hook, from which the hook is suspended to the hoist media of the crane

3.2

hook body

lower, curved part of the hook below the shank

3.3

hook seat

bottom part of the hook body, where the load lifting attachment is resting

3.4

hook suspension articulation

feature of the hook suspension, allowing the hook to tilt along the inclined load line

Table 1 — Symbols

Table 1 *(continued)*

Symbol	Description
$\sigma_{\rm A}$	Stress amplitude in a stress cycle
$\sigma_{\rm Sd}$	Design stress
$\sigma_{\rm M}$	Basic fatigue strength amplitude, un-notched piece
$\sigma_{\rm p}$	Total stress range in a pulsating stress cycle
$\sigma_{\rm W}$	Fatigue strength amplitude, notched piece
σ_{Tmax} , σ_{T1} , σ_{T2}	Transformed stress amplitudes
$\Delta \sigma_c$	Characteristic fatigue strength
$\Delta \sigma_{\rm Rd}$	Limit fatigue design stress
$\Delta \sigma_{\text{Sd},i}$	Stress range in a lifting cycle i
$\Delta \sigma_{\text{Sd,max}}$	Maximum stress range

Table 1 *(continued)*

4 General requirements

4.1 Materials

The hook material in the finished product shall have sufficient ductility to avoid brittle fracture at the temperature range specified for the use of the hook. Hook material, after forging and heat treatment, shall have minimum elongation and Charpy-V impact toughness in accordance with [Table](#page-10-2) 2.

Operation temperature	Impact test temperature	Minimum elongation,	Minimum impact toughness, A_V
$T \ge -10$ °C	0° C		
$T \ge -20$ °C	-10 °C		
-30 °C > T ≥ -40 °C	-30 °C	15 % 35 I	
-40 °C > T ≥ -50 °C	$-40 °C$		

Table 2 — Impact test and elongation requirements for hook material

To satisfy the requirements of the operating temperature, the manufacturer shall select an alloyed or non-alloyed steel, as appropriate, which after suitable heat treatment, shall be consistent with achieving the chosen mechanical property grade for the selected hook form, taking into account its individual ruling thickness.

The steel shall be produced by an electric process or by one of the oxygen processes.

The steel shall be fully killed, stabilized against strain age embrittlement and have an austenitic grain size of 6 or finer when tested in accordance with ISO 643. This shall accomplished, by ensuring that the steel contains sufficient aluminium (minimum 0,025 %) to permit the manufacture of hooks stabilized against strain-age-embrittlement during service. The steel shall be produced by an electric process or by one of the or

The steel shall be fully killed, stabilized against strain age embritt

size of 6 or finer when tested in accordance with ISO 643. This shall

steel c

The steel shall contain no more sulfur and phosphorus than the limits given in [Table](#page-11-1) 3.

Table 3 — Sulfur and phosphorus content

The mechanical properties (*yield stress, ultimate strength*) are dependent upon the thickness of the forged hook body. As a ruling thickness, either the largest width of the hook seat or the diameter of the shank shall be used, whichever is greater

For standardization purposes, a classification of material grades for forged hooks is specified in [Table](#page-11-2) 4. The values of mechanical properties given in [Table](#page-11-2) 4 shall be used as design values and shall be guaranteed as minimum values by the hook manufacturer.

	Mechanical properties			
Material class refer- ence	Upper yield stress or 0,2 % proof stress Jу N/mm^2	Ultimate strength Ĵи N/mm ²		
M	215	340		
P	315	490		
S	380	540		
Т	500	700		
V	600	800		
All materials selected shall fulfil the following requirement: $f_u/f_v \ge 1.2$				

Table 4 — Material properties for classified material grades

4.2 Workmanship

The manufacturing process, factory tests and delivery conditions shall meet the requirements of ISO 9327-1.

Each hook body shall be forged hot in one piece. The macroscopic flow lines of the forging shall follow the body outline of the hook. Excess metal from the forging operation shall be removed cleanly leaving the surface free from sharp edges.

Profile cutting from a rolled plate is not permissible for forged hooks.

The surface roughness of the hook seat in the finished product shall be equal to or better than R_z 500 µm. Grinding may be used to reach the required surface quality. Any grinding marks shall be in a circumferential direction in respect to the seat circle.

After heat treatment, furnace scale shall be removed and the hook body shall be free from harmful defects, including cracks. Hook forging shall be inspected for defects using appropriate NDT-methods according to EN 10228-3. Requirements of quality class 1 of EN 10228-3: shall be met.

No welding shall be carried out at any stage of manufacture.

4.3 Manufacturing tolerances

The dimensional tolerances according to EN 10243-1 for forging grade F shall be fulfilled, except as modified herein.

The seat circle diameter and the throat opening shall be within [0; +7 %] of the nominal dimension. The point height dimension a_3 shall be within $[-7\%; +7\%]$ of the nominal dimension.

The centre line of the machined shank shall not deviate from the seat centre more than ± 0,02 *a*1.

The shape of the hook in its own plane shall be such that the centres of the material sections specified by the two flanks of a section shall fall between two parallel planes with a spacing of 0,05 *d*1.

4.4 Heat treatment

Each forged hook shall either be hardened from a temperature above the AC_3 point and tempered, or normalized from a temperature above the AC₃ point. The tempering temperature shall be at least 475 °C.

The normalizing or tempering conditions shall be at least as effective as a temperature of 475 °C maintained for a period of 1 h.

4.5 Proof loading

As part of the manufacturing process, a hook may be proof loaded. This initial proof loading should be conducted at ambient room temperature and can further assist the Quality Assurance Management process as well as improve the fatigue performance of the hook in general. If proof loading is applied, the process of proof loading shall be as follows:

- a) Proof loading shall be applied after the complete manufacturing process. (forging, heat treatment and machining)
- b) The proof load force shall be applied between shank suspension nut and either:
	- i) the base of the hook seat, for a straight line pull, parallel with the vertical axis of the shank, in the case of a single point hook.
	- ii) two opposite contact points on the hook bowl surface consistent with a symmetrical 90 degree sling spread, and with load lines passing thro' the hook bowl centre(s), in the case of ramshorn hooks.
- c) A relative permanent set due to proof loading measured at the gap opening shall not exceed 0,25 %; For batch-produced hooks the proof loading shall be applied to each and every hook in the batch;
- d) The magnitude of the proof load (*F*PL.) should reflect a 1,5*f*y theoretical maximum tensile stress in the body fibres in section B for single point and section A for ramshorn hooks for the chosen material. The value of this proof load shall be determined as follows relative to either section A(ramshorn) or B(single point) as the case may be:

Single point hook

$$
F_{\rm PL,sp} = \frac{1.5 f_{\rm y} M_{\rm hf}}{1\,000}
$$

Ramshorn hook

$$
F_{\text{PL.rh.}} = \frac{1.5 f_y M_{\text{hf.}}}{1.000 \text{v}}
$$

where F_{PL} is expressed in kilonewtons (kN), f_v is the yield stress of the chosen material, and M_{hf} is a hook factor, i.e. for the hook intradoses of either section A or B, as the case may be, sample data are depicted within **[Annex](#page-53-1) C** for individual hooks of their particular family.

 $v = 0.5x \tan \alpha$

for section A of ramshorn hooks, α = 45° (see [5.5.3](#page-22-0))

*M*_{hf.} is derived from the formula

$$
I\frac{\left(1-\eta_1/R\right)}{\left(R\eta_1\right)}
$$

All definitions are as per [Annex](#page-73-1) H .

- e) After proof loading, the hook shall be inspected for defects using appropriate NDT-methods and found free from harmful flaws, defects and cracks;
- f) Proof loaded hook shall be stamped with symbol "PL" adjacent to the hook type marking.
- g) The application of proof loading will affect (beneficially) subsequent fatigue performance of the hook. Calculation methodology of an example in [Annex](#page-61-1) F can be used to quantify this effect.

Steels and in particular high strength steels for hooks due to be subjected to proof loading should be selected with due attention to the need of their adequate ductility.

NOTE 1 Additional benefits derived from the application of proof loading to the QA Management process is not addressed within this standard.

NOTE 2 The maximum stressed tensile fibres under F_{PL} will of course yield and a redistribution of stress will occur, resulting in a permanent compressive stress in this tensile area when the proof load is removed

4.6 Hook body geometry

Proportions of hook sections shall be such that stresses do not exceed stresses in the critical sections specified in [5.5.1](#page-21-1).

The seat of a hook shall be of circular shape. In a single hook, the centre of curvature shall coincide with the centreline of the machined shank. In a ramshorn hook, the seat circle shall be tangential in respect to the outer edge of the forged shank.

A ramshorn hook shall be symmetrical with respect to the centre line of the shank.

The diameter of the forged shank (d_1) shall be proportioned to circle diameter (a_1) as follows:

*d*₁ ≥ 0,55 *a*₁

The bifurcation point between the inner edge and the seat circle (a_1) shall be from the horizontal in minimum as follows: for a single hook *α* ≥ 60°, for a ramshorn hook *α* ≥ 90°

The full throat opening (a_2) , without consideration to a latch shall be proportioned to the seat circle diameter as follows: $a_2 \le 0.85 a_1$. The effective throat opening with a latch shall be in minimum $a_0 \ge 0.7$ *a*1.

The point height of a hook (a_3) shall be in minimum as follows: $a_3 \ge a_1$.

[Annexes](#page-44-1) \vec{A} and \vec{B} present example sets of hook body dimensions, which fulfil the requirements of this clause.

Other hook bodies differing from those shown within $Annexes A$ $Annexes A$ and B can be technically assessed, either individually or as national groups to the requirements of this standard, provided dimensional characteristics shown within this clause and material requirements are fulfilled.

Furthermore, it is expected that other hook body sets in addition to those currently shown can and will be put forward for inclusion as national groups, within Δ nnexes Δ and \overline{B} . in the future.

4.7 Hook shank machining

Figure 2 — Machined dimensions of shank

The length of the threaded portion of the shank shall be not less than 0,8*d*3.

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The pitch of the thread (*p*) shall be proportioned to the principal diameter of the thread (*d*3) as follows:

 $0,055d_3$ ≤ p ≤ $0,15d_3$

The depth of the thread (*t*) shall be proportioned to the pitch of the thread (*p*) as follows:

0,45*p* ≤ *t* ≤ 0,61*p*

The bottom radius of the thread profile (r_{th}) shall be no less than 0,14*p*. A thread type, where the bottom radius is not specified, shall not be used.

The shank shall be undercut (with a diameter d_4) below the last threads for a length (s) proportioned to the undercut depth as follows: $s \ge 2$ ($d_3 - d_4$). The undercut shall reach deeper than the core diameter of the thread profile (d_5), in minimum as follows: d_4 ≤ (d_5 − 0,3 mm). The undercut shall be machined with a form ground tool to a surface finish of $R_a \leq 3.2 \mu m$ and shall be free from machining marks and defects.

There shall be a relief radius in a transition from the threaded part to the undercut part. The relief radius (*r*₉) shall be proportioned to the diameter of the undercut (d_4) as follows: *r*₉ ≥ 0,06 d₄. The shape of the relief transition need not be a complete quadrant of a circle.

The thinnest section of the machined shank (consequently d_4) shall fulfil the condition $d_4 \ge 0.65d_1$, where d_1 is the diameter of the forged part of the shank, see [Figure](#page-13-1) 1.

The whole machined section of the shank shall have a radius at each change in diameter. The machined section shall not reach the curved part of the forged body.

Screwed threads shall conform to the tolerance requirements of ISO 965-1 (coarse series) and be of medium fit class 6g.

NOTE [Annex](#page-67-1) G presents example sets of machined shank and thread dimensions, which fulfil the geometric requirements. Other hook shank and thread designs differing from those shown within [Annex](#page-67-1) G can be utilized and technically assessed to the requirements of this standard, provided dimensional parameters fulfil the requirements of this clause. Furthermore, it is expected that other hook shank and thread designs in addition to those currently shown can and will be put forward for inclusion as national groups within Δn nex ϵ in the future.

4.8 Nut

The material grade of the nut shall be equal to that of the hook

The height of the nut shall be such that the threaded length of the hook shank is fully engaged with the nut thread.

The nut shall be positively locked to the shank against rotation to prevent the nut from unscrewing. The locking shall not interfere with the lower two thirds of the nut/shank thread connection. The locking shall allow relative axial movement between the shank and the nut due to play in the threaded connection. Alternatively, if the nut is locked by a dowel or other similar fixing media, it is essential during the locking process that the nut/shank load bearing thread flanks are in direct contact to ensure resultant unimpaired load transmission.

The nut shall rest on an anti-friction bearing, enabling the hook body to rotate about the vertical axis. The contact surface of the nut resting on the bearing shall meet the requirements as stipulated by the related bearing. The height position of the contact surface shall fall within the lower half of the thread connection.

Screwed threads of the nut shall comply with the tolerance requirements of ISO 965-1 (coarse series) and be of medium fit class 6H. The bottom radius of the thread profile for the nut shall be not less than 0,07 p, where p is the pitch of the thread. A thread type, where the bottom radius is not specified, shall not be used.

4.9 Hook suspension

In general, and always for serially produced hook blocks, the hook suspension together with hoist rope reeving system shall be such that the system allows free tilting of the hook in any inclined direction of the load line. In cases where this articulation of the hook suspension is not provided, this shall be specially taken into consideration in the design calculations of the hook. In cases, where by changing the crane/hook block configuration or position the hook suspension can be brought to a rigid position, this shall be taken into account in the design calculation of the hook.

The same load actions as specified for the hook shall be taken into account in the design of the hook suspension.

5 Static strength

5.1 General

The proof of static strength for hooks shall be carried out in accordance with principles of ISO 8686-1. The general design limit for static strength is yielding of the material.

The proof shall be delivered for the specified critical sections of the hook, taking into account the most unfavourable load effects from the load combinations A, B or C in accordance with ISO 8686-1. The relevant partial safety factors γ_p shall be applied. The risk coefficients γ_n shall be applied when required in the specific application or as specified in the relevant European crane type standard.

5.2 Vertical design load

The vertical design force for a hook $F_{Sd,s}$ when hoisting the rated hook load, shall be calculated as follows:

$$
F_{\text{Sd,s}} = \varphi \times m_{\text{RC}} \times g \times \gamma_{\text{p}} \times \gamma_{\text{n}} \tag{1}
$$

with
$$
\varphi = \max \left\{ \varphi_2; \left(1 + \varphi_5 \times \frac{a}{g} \right) \right\}
$$

where

- *ϕ*² is the dynamic factor, when hoisting an unrestrained grounded load, see ISO 8686-1
- *ϕ*⁵ is the dynamic factor for loads caused by hoist acceleration, see ISO 8686-1
- *a* is the vertical acceleration or deceleration;

*m*_{RC} is the mass of the rated hook load;

- *g* is the acceleration due to gravity, $g = 9.81$ m/s²;
- γ_{p} is the partial safety factor, see ISO 8686-1:

 γ_p = 1,34 for regular loads (load combinations A);

- γ_p = 1,22 for occasional loads (load combinations B);
- γ_p = 1,10 for exceptional loads (load combinations C);
- *γ*ⁿ is the risk coefficient.

Other load actions and combinations of ISO 8686-1 may produce vertical forces on the hook, whose load actions shall also be analysed. The vertical design force in such cases is expressed in a general format as follows:

$$
F_{\text{Sd,s}} = F_{\text{H}} \times \gamma_{\text{p}} \times \gamma_{\text{n}} \tag{2}
$$

where

- *F*^H is a vertical force on hook due to other load action than hoisting a rated load; e.g. a test load or a peak load in an overload condition;
- *γ*^p is the partial safety factor as above, see ISO 8686-1;
- *γ*ⁿ is the risk coefficient.

5.3 Horizontal design force

The Horizontal forces that are most significant for the strength of hooks are those caused by horizontal accelerations of the crane motions and these shall be taken into account. Other horizontal forces e.g. due to wind or sideways pull actions shall be taken into account, if significant. The horizontal force shall be assumed to act at the bottom of the hook seat. accelerations of the crane motions and these shall be taken into account. Ot

to wind or sideways pull actions shall be taken into account, if significant.

The horizontal design force of hook H_{Sd₄s} due to horizontal

The horizontal design force of hook *H*_{Sd,s} due to horizontal accelerations shall be calculated as follows:

$$
H_{\text{Sd},\text{s}} = \min \left\{ \frac{m_{\text{RC}} \times a \times \varphi_{\text{S}} \times \gamma_{\text{p}} \times \gamma_{\text{n}}}{C_{\text{t}} \times F_{\text{Sd},\text{s}} / h} \right\} \tag{3}
$$

where

*m*_{RC} is the mass of the rated hook load;

- *a* is the acceleration or deceleration of a horizontal motion;
- *ϕ*⁵ is the dynamic factor for loads caused by horizontal acceleration, see ISO 8686-1. For hook suspensions, which are not rigidly connected in horizontal direction to the moving part of the crane, it shall be set $\phi_5 = 1$;
- $\gamma_{\rm p}$ is the partial safety factor as for Formula (1);
- *γ*ⁿ is the risk coefficient;
- C_t is the relative tilting resistance of the hook suspension in accordance with [Annex](#page-76-1) I;

 $F_{\rm Sd,S}$ is the vertical design force in accordance with 5.2 , related to the loading condition where $H_{\rm Sd,S}$ is specified;

h is the vertical distance from the seat bottom of the hook body to the centre of the articulation.

5.4 Bending moment of the shank

5.4.1 General

The following load action shall be taken into consideration, when determining the total bending moment of the hook shank:

- a) horizontal forces, see [5.4.2](#page-18-0);
- b) inclination of the hook suspension, see [5.4.3](#page-20-0);

c) eccentric action of vertical force in the hook seat, see $5.4.4$;

a) ramshorn hook, half of the rated load on one prong, see $\frac{5.4.5}{5.4.5}$.

The bending moments caused through these load actions shall be addressed to the same load combinations, which the primary loads or operational conditions causing the bending belong to.

5.4.2 Bending moment due to horizontal force

This clause covers the shank bending moment due to external horizontal forces. The moment *M*1 shall be calculated at the critical hook shank section (see [5.6](#page-23-1)) due to the horizontal design force $H_{Sd,s}$.

$$
M_1 = H_{\text{Sd},\text{s}} \times h_{\text{s}} \tag{4}
$$

where

 $H_{Sd,S}$ is the horizontal design force in accordance with 5.3 ;

h^s is the vertical distance from the seat bottom of the hook body to the upper end of the thinnest part of the hook shank. Bending moment due to inclination of hook suspension.

Where the arrangement of the hoist mechanism or hook/hook block is such that the hook suspension may be brought to an inclined position in a loaded condition, the bending moment at the shank caused by this inclination shall be considered in the design calculations. Such an inclination may be caused e.g. by:

- a) Differences in hoist travel distances between two separate hoist drives carrying a load beam with a hook, see [Figure](#page-18-1) 3;
- b) Tilting of a single rope reeving during hoisting/lowering motion, see [Figure](#page-19-0) 4;
- c) Tilting of a crane part, to which a hook is rigidly attached; or
- d) Two-blocking of a bottom block in the uppermost hoist position with a crane part, after which this crane part is tilted.

Figure 3 — Tilting of a hook in case of different hoist travel distances

Due to an inclination, the vertical force has a force component perpendicular to the axis of the hook shank. This force shall be taken into account in the same way as the horizontal forces. The bending moment *M*2 caused at the critical hook shank section is proportional to the vertical design force as follows:

$$
M_2 = F_{\text{Sd},\text{s}} \times h_{\text{s}} \times \sin(\beta) \tag{5}
$$

where

- *F*_{Sd,s} is the vertical design force in accordance with [5.2](#page-16-1), related to the condition with a hook inclination *β*;
- *β* is the maximum, total inclination in each relevant load combination;
- *h_s* is the vertical distance from the seat bottom of the hook body to the upper end of the thinnest part of the hook shank.

In a rope balanced hook suspension with multiple rope falls and a single running rope coming from the drum, the hoisting/lowering movement causes the hook suspension to tilt, see [Figure](#page-19-0) 4. The inclination is calculated as follows:

$$
\beta = \arctan(C_t/h) \tag{6}
$$

where

- C_t is the relative tilting resistance of the hook suspension in accordance with [Annex](#page-76-1) I;
- *h* is the vertical distance from the seat bottom of the hook body to the centre of the articulation.

The maximum inclination, the related vertical force and the consequent moment *M*2 shall be calculated separately for all relevant loading conditions of the crane.

5.4.3 Bending moment due to eccentricity of vertical force

A hoist load attachment may not always settle in the middle of the hook seat. The deviation of the vertical load action line from the centre line of the shank causes a bending moment, which shall be calculated as follows:

$$
M_3 = c_e \times F_{\text{Sd},s} \times a_1 \tag{7}
$$

where

*F*_{Sd,s} is the vertical design force in accordance with [5.2;](#page-16-1)

- a_1 is the seat circle diameter of the hook body;
- c_e is a coefficient for the eccentricity (c_e = 0,05).

NOTE A smaller eccentricity may be used in the design calculations, if a positive, mechanical means is provided ensuring that the hoist load attachment settles closer to the hook seat centre.

5.4.4 Special case for a ramshorn hook

As a special loading case for ramshorn hooks it shall be assumed, that half of the vertical force acts on one prong while the other prong is unloaded. This loading case is addressed in the calculations to the load combination C.

For a ramshorn hook with one-sided loading, the bending moment *M*4 caused at the critical hook shank section shall be calculated as follows:

$$
M_4 = F_{\text{Sd},s} / 2 \times \left[e_R \times (1 - h_s / h) + h_s / h \times \min \begin{Bmatrix} e_R \\ C_t \end{Bmatrix} \right]
$$
(8)

with

 $e_R = (a_1 + d_1)/2$

where

 $F_{Sd,s}$ is the vertical design force in accordance with 5.2 and γ_p for load combination C;

- *d*¹ is the diameter of the forged shank;
- *a*¹ is the seat circle diameter of the hook;
- *e*^R is the distance of the vertical load line from the centre line of the shank;
- *h* is the vertical distance from the seat bottom of the hook body to the centre of the articulation;
- *h_s* is the vertical distance from the seat bottom of the hook body to the upper end of the thinnest part of the hook shank;
- C_t is the relative tilting resistance of the hook suspension, see [Annex](#page-76-1) I.

5.4.5 Design bending moment of the shank

In general, the design bending moment at the critical shank section $M_{Sd,s}$ for the loading conditions in accordance with $\frac{5.4.2}{5.4.4}$ $\frac{5.4.2}{5.4.4}$ $\frac{5.4.2}{5.4.4}$ shall be calculated separately for each relevant load combination as follows:

$$
M_{\text{Sd},\text{s}} = \min \left\{ \begin{pmatrix} (M_1 + M_2 + M_3) \\ C_\text{t} \times F_{\text{Sd},\text{s}} \end{pmatrix} \right\} \tag{9}
$$

where

*M*₁ *to M*₃ are the bending moments in accordance with [5.4.2](#page-18-0) to [5.4.4;](#page-20-1)

 C_t is the relative tilting resistance of the hook suspension, see [Annex](#page-76-1) I;

 $F_{\text{Sd,s}}$ is the vertical design force in accordance with 5.2 .

Additional to the above, the design bending moment in accordance with the special case of [5.4.5](#page-21-2) shall be taken into account in a load combination *C* as follows:

$$
M_{\text{Sd},\text{s}} = M_4 \tag{10}
$$

where M_4 is the bending moment in accordance with $\frac{5.4.5}{5.4.5}$ $\frac{5.4.5}{5.4.5}$ $\frac{5.4.5}{5.4.5}$.

5.5 Hook body, design stresses

5.5.1 Loadings

The vertical design force *F*_{Sd,s} shall be divided into two force components, acting in the centre of the seat circle symmetrically on the opposite sides of the vertical centre line and in an angle *α* in respect to vertical, see [Figure](#page-22-1) 5.

As a minimum value of α , it shall be assumed that $\alpha = 45^{\circ}$.

For ramshorn hooks, an equal load distribution shall be assumed between the two prongs in load combinations A and B.

As a special loading case, for ramshorn hooks it shall be assumed that half of the vertical force acts on one prong while the other prong is unloaded. This loading case is addressed in the calculations to the load combination C. No reproduction or networking is unito added. I his loading case is addressed in the calculations to the

load combination of Crees shall be neglected in the hook body calculations.

The horizontal forces shall be neglecte

The horizontal forces shall be neglected in the hook body calculations.

Figure 5 — Load actions on hook body and critical sections for calculation

5.5.2 Stress calculation methods

Stresses in the designated sections of a hook body shall be analysed either by the theory of curved beam bending in accordance with [Annex](#page-73-1) H, by finite element methods or by full scale experiments. Stresses in section B of a ramshorn hook may, however be analysed by the conventional beam bending theory. 5.5.2 Stress calculation methods
Stresses in the designated sections of a hook body shall be analysed been
bending in accordance with Annex H, by finite element methods or
m section by a representation of the form of Carr

The following subclause is based upon the theory of curved beam bending.

5.5.3 Design stresses

The design stresses *σ*_{Sd} in sections A and B of single hooks and in the section A of ramshorn hooks shall be calculated as follows:

$$
\sigma_{\text{Sd,s}} = \frac{v \times F_{\text{Sd,s}} \times R \times \eta_1}{I} \times \frac{1}{1 - \eta_1/R}
$$
\n(11)

with

$$
R = a_1 / 2 + \eta_1
$$

and

 $v = 1$ for section B of single hooks;

 $v = 0.5 \times \tan \alpha$ for section A of single and ramshorn hooks, $\alpha = 45^{\circ}$;

where

R is the hook curvature radius determined by the centroid of the section;

*F*_{Sd,s} is the vertical design force in accordance with [5.2;](#page-16-1)

- *I* is the reference moment of inertia for curved beam;
- *a*¹ is the seat circle diameter of the hook;
- *η*¹ is the absolute value of the coordinate *y* at inner edge of the particular section;
- α is the angle of the load action lines in respect to vertical, see [Figure](#page-22-1) 5.

The quantities *η*1 and *I* are section specific values and shall be calculated in accordance with [Annex](#page-73-1) H. The design stress in section B of ramshorn hook for the special case of $\overline{5.4.5}$ shall be calculated as follows:

$$
\sigma_{\text{Sd,s}} = \frac{F}{A_{\text{d1}}} + \frac{F \times (a_1 + d_1) \times d_1 / 4}{I_{\text{d1}}}
$$
\n(12)

with

$$
F = F_{\text{Sd},\text{s}} / 2
$$

where

 $F_{Sd,s}$ is the vertical design force in accordance with 5.2 and γ_p for load combination C;

A_{d1} is the cross section area of the forged shank;

 I_{d1} is the moment of inertia of the forged shank;

- *d*¹ is the diameter of the forged shank;
- *a*¹ is the seat circle diameter of the hook.

5.6 Hook shank, design stresses

The vertical design forces in accordance with 5.2 and the design bending moments in accordance with [5.4](#page-17-2) shall be taken into account in the proof calculations of a hook shank. In general, the critical section of the shank is the undercut part immediately below the threaded section with a diameter d_4 , see [Figure](#page-13-1) 1. Maximum design stress $\sigma_{Sd,s}$ is calculated as a nominal stress without stress concentration factors and using conventional beam bending theory as follows: $F = F_{Sd,s}/2$

where
 $F_{Sd,s}$ 1s the vertical design force in accordance with 5.2 and γ_p for load c
 A_{d1} is the cross section area of the forged shank;
 I_d is the diameter of the forged shank;
 a_1 is the seat ci

$$
\sigma_{\text{Sd,s}} = \frac{F_{\text{Sd,s}}}{A_{\text{d4}}} + \frac{M_{\text{Sd,s}} \times d_4/2}{I_{\text{d4}}}
$$
(13)

where

*F*_{Sd,s} is the vertical design hook force;

*M*_{Sd,s} is the design bending moment in the critical section, see [5.4.5](#page-21-2);

 A_{d4} is the cross section area of the critical section of the hook shank;

 I_{d4} is the moment of inertia of the critical section of the hook shank.

5.7 Hook, proof of static strength

5.7.1 General for hook body and shank

Both for the hook body and the hook shank, it shall be proven for relevant load actions specified in [5.2](#page-16-1) to [5.4](#page-17-2) that

$$
\sigma_{\text{Sd,s}} \le f_{\text{Rd}} = f_1 \times \frac{f_y}{\gamma_m \times \gamma_{\text{sm}}} \tag{14}
$$

where

 $\sigma_{\text{Sd,s}}$ is the maximum design stress in accordance with 5.5 and 5.6 in the critical section;

 $f_{\rm Rd}$ is the limit design stress;

f^y is the yield stress of the material in the finished product;

 f_1 is the influence factor for the operation temperature;

 $\gamma_{\rm m}$ is the general resistance coefficient in accordance with ISO 8686-1 ($\gamma_{\rm m}$ = 1,1);

*γ*sm is the specific resistance coefficient for the section, as follows:

*γ*sm = 0,75 for the hook body section B of single hooks, or

alternatively, if addressing a national standard particular hook form, *γ*sm can be evaluated by superimposing Formula (14) characteristics within Formula (11) and applying that national standard's noted maximum rated capacity together with its nominated yield stress. Sample indications are contained within [Annex](#page-53-1) C. $\sigma_{\text{Sd},0} \le f_{\text{Rd},1} = f_1 \times \frac{f_f}{f_{\text{Rd}}}$

where
 $\sigma_{\text{Sd},0}$ is the rimit design stress;
 f_{d} is the limit design stress in accordance with 5.5 and 5.6 in the critical section, g_{G}
 f_{d} is the final design stress in the
rejection between the two temperature, g_{G}
 f_{d} is the final design stress in the
transverse, g_{d} is the final average. The

*γ*sm = 0,90 for hook body section A of single point and ramshorn type hooks

*γ*sm *=* 1,0 for all shank sections

In the absence of other data, the factor *f*1 taking into consideration the reduction of the yield stress in high temperatures shall be calculated as follows:

For
$$
-50
$$
 °C $\leq T \leq 100$ °C:

 $f_1 = 1$

For $100 °C < T \leq 250 °C$:

$$
f_1 = 1 - 0.25 \times (T - 100) / 150 \tag{15}
$$

where *T* is the operation temperature in degrees Celsius (°C).

5.7.2 The use of static limit design force for verification of the hook body

The static limit design force $F_{Rd,s}$ covers the proof of static strength for sections A and B of single hooks and for section A of ramshorn hooks. It shall be calculated as follows:

$$
F_{\rm Rd,s} = \frac{f_{\rm y}}{\gamma_{\rm m} \times \gamma_{\rm sm}} \times \frac{I \times (1 - \eta_1 / R)}{\nu \times R \times \eta_1}
$$
(16)

For a single hook the static limit design force is calculated separately for the two sections A and B and the smaller value of the two is used.

It shall also be proven for all relevant load actions and combinations specified in [5.2](#page-16-1) that

$$
F_{\text{Sd},\text{s}} \le f_1 \times F_{\text{Rd},\text{s}} \tag{17}
$$

where

*F*_{Sd,s} is the vertical design force in accordance with [5.2;](#page-16-1)

*F*Rd,sis the static limit design force

*f*¹ is the influence factor for the operation temperature in accordance with Formula (15).

NOTE 1 Additionally, the proof of static strength for the shank is carried out in accordance with [5.7.1](#page-24-1).

NOTE 2 In cases where the selected hook body is in accordance with [Annexes](#page-44-1) A or B and the yield and ultimate strength values are those specifically noted within [Table](#page-11-2) 4, the proof of static strength can be based on the static limit design force shown in [Annex](#page-53-1) C.

NOTE 3 The dimensions of the ramshorn hooks in Δn nex ΔB are proportioned such that section B of the hook body does not become governing in respect to static strength of the body, i.e. the proof of a special case in [5.4.5](#page-21-2) is not required.

6 Fatigue strength

6.1 General

The proof of fatigue strength for hooks shall be carried out in accordance with principles of ISO 8686-1. A hook shall have the design life in minimum equal to that of the related crane or hoist.

The proof shall be delivered for the specified critical sections of the hook, taking into account the most unfavourable load effects from the load combinations A in accordance with ISO 8686-1, setting all partial safety factors $\gamma_p = 1$ and the risk coefficients $\gamma_n = 1$.

The number of stress cycles for the proof shall be based on the total number of working cycles during the design life of the crane, as specified in ISO 4301-1. In general, for the hook body, one lifting cycle induces one stress cycle. If a working cycle consists of several lifting cycles, this shall be taken into account, when counting the stress cycles. For the hook shank, additionally the number of positioning movements shall be taken into account, when counting the number of bending stress cycles.

6.2 Vertical fatigue design force

The vertical design force $F_{Sd, f, i}$ for a lifting cycle *i* shall be calculated as follows:

$$
F_{\text{Sd},f,i} = \varphi_2 \times m_i \times g \tag{18}
$$

where

 ϕ_2 is the dynamic factor, when hoisting an unrestrained grounded load, see ISO 8686-1;

- *mi* is the mass of the hook load in a lifting cycle *i*;
- *g* is the acceleration due to gravity, $g = 9.81$ m/s².

6.3 Horizontal fatigue design force

The horizontal design force *H*Sd,f,*i* for a lifting cycle *i* due to horizontal accelerations shall be calculated as follows:

$$
H_{\text{Sd},f,i} = \min \left\{ \frac{m_i \times a \times \varphi_5}{C_\text{t} \times m_i \times g/h} \right\} \tag{19}
$$

where

- *mi* is the mass of the hook load in a lifting cycle *i*;
- *a* is the acceleration or deceleration of a horizontal motion;
- *ϕ*⁵ is the dynamic factor for loads caused by horizontal acceleration, see ISO 8686-1. For hook suspensions, which are not rigidly connected in horizontal direction to the moving part of the crane, it shall be set $\phi_5 = 1$;
- C_t is the relative tilting resistance of the hook suspension, see **Annex I**;
- *g* is the acceleration due to gravity, $g = 9.81$ m/s²;
- *h* is the vertical distance from the seat bottom of the hook body to the centre of the articulation.

6.4 Fatigue design bending moment of shank

6.4.1 Bending moment due to horizontal force

The moment *M*_{1,f,*i*} shall be calculated at the critical hook shank section, due to the horizontal design force $H_{Sd,f,i}$ in accordance with 6.3 :

$$
M_{1,\text{f},i} = H_{\text{Sd},\text{f},i} \times h_{\text{s}}
$$
 (20)

where

 $H_{Sdf,i}$ is the horizontal design force in a lifting cycle *i* in accordance with 6.3 ;

h^s is the vertical distance from the seat bottom of the hook body to the upper end of the thinnest part of the hook shank.

6.4.2 Bending moment due to inclination of hook suspension

The basis causing inclination and the method of calculation shall be taken into consideration in analogy to [5.4.3.](#page-20-0) For the proof of fatigue strength the consideration, which of the loading events of load combination A are regular loadings, shall be based upon the crane configuration and application.

As a minimum, the following shall be considered to occur regularly in each lifting cycle: In a rope balanced hook suspension with multiple numbers of falls and a single running rope coming from the

drum, the hoisting/lowering movement causes the hook suspension to tilt, see [Figure](#page-19-0) 4. The bending moment *M*_{2,f,*i*} caused at the critical hook shank section is calculated as follows:

$$
M_{2,\text{f},i} = F_{\text{Sd},\text{f},i} \times h_{\text{s}} \times \sin(\beta) \tag{21}
$$

where

 $F_{Sdf,i}$ is the vertical design force in a lifting cycle *i*, in accordance with 6.2 ;

- *h*^s is the vertical distance from the seat bottom of the hook body to the upper end of the thinnest part of the hook shank;
- *β* is the inclination of the hook suspension in accordance with Formula (6).

6.4.3 Bending moment due to eccentricity of vertical force

A hoist load attachment may not always settle in the middle of the hook seat. The deviation of the vertical load action line from the centre line of the shank causes a bending moment, which shall be calculated as follows:

$$
M_{3, f, i} = c_e \times F_{\text{Sd}, f, i} \times a_1 \tag{22}
$$

where

 $F_{Sd, f}$ *is* the vertical design force in a lifting cycle *i*, in accordance with 6.2 ;

- a_1 is the seat circle diameter of the hook body;
- c_e is a coefficient for the eccentricity, $c_e = 0.05$.

NOTE A smaller eccentricity can be used in the design calculations if a positive, mechanical means is provided that ensures the hoist load attachment settles closer to the hook seat centre.

6.5 Proof of fatigue strength, hook body

6.5.1 Design stress calculation

The proof of fatigue strength shall be based upon cumulative effect of stress ranges in the critical sections. It shall be assumed that the load is grounded in each lifting cycle, i.e. the hook load range is from zero to full load, with dynamic factor inclusion.

Calculation of the stress ranges is comparable to that of the static design stress in $5.5.3$, when applying the vertical fatigue design load from [6.2:](#page-25-1)

 $\Delta \sigma_{\text{Sd},i} = \sigma_{\text{Sd},s}$

in accordance with Formula (11) in $\overline{5.5.3}$ $\overline{5.5.3}$ $\overline{5.5.3}$, when setting $F_{\rm Sd,s} = F_{\rm Sd,fi}$

where

 $iⁱ$ is the index of a lifting cycle;

 $\Delta \sigma_{Sd,i}$ is the stress range in a cycle *i*;

 $F_{Sdf,i}$ is the vertical fatigue design force in accordance with 6.2 . No reproduction or networking permitted without license for IHS

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$$
\sigma_{\rm Sd, pb, min} = \sigma_{\rm Sd, pr}
$$

to a maximum value of the design stress in the body of "proofed" hook σ_{Sd,max} calculated by adding the stress range $\Delta \sigma_{Sd,i}$ for the hook load applied $F_{Sd,s} = F_{Sd,f,i}$ (calculated as shown above) to the initial residual stress σ_{Sd.pr}.

 $\sigma_{\text{Sd},\text{nbmax}} = \sigma_{\text{Sd},\text{pr}} + \Delta \sigma_{\text{Sd},i}$

In the proof of fatigue strength of "non-proofed" hooks, the design stress will cycle/range from the minimum value of zero at the intrados of the hook bowl at zero hook load. This will also be the case for the "proofed" hooks if the beneficial effects of this process are neglected, in which case the results will be conservative.

The calculation procedure outlined in [6.5](#page-27-1) is based on a pulsating stress cycle (stress cycling from zero to a maximum value) and the stress cycle in "proofed" hook body has to be transformed to an equivalent pulsating cycle first, for instance using a procedure outlined in [Annex](#page-61-1) F before the procedures of [6.5](#page-27-1) can be applied.

6.5.2 Stress history in general

The cumulative fatigue effect of the stress history from all of the stress cycles is condensed to a single stress history parameter *s*h . This is calculated as follows:

$$
s_h = k_h \times v_h \tag{23}
$$

with

$$
k_{\rm h} = \frac{1}{N} \sum_{i=1}^{N} \left(\frac{\Delta \sigma_{\rm Sd,i}}{\Delta \sigma_{\rm Sd,max}} \right)^{m} \tag{24}
$$

and

$$
v_h = \frac{N}{N_D} \tag{25}
$$

where

- k_h is the stress spectrum factor;
- *ν*^h is the relative number of stress cycles;
- *i* is the index of a lifting cycle;
- *N* is the total number of lifting cycles;
- N_D is the reference number of cycles $(N_D = 2 \times 10^6)$;
- *Δσ*Sd,*ⁱ* is the stress range in a cycle *i*;
- *Δσ*Sd,maxis the maximum stress range;
- *m* is the slope parameter of the characteristic fatigue design curve $(m = 6)$.

The total number of lifting cycles (*N)* shall conform to the total number of working cycles (*C)* during the design life of the crane as specified in ISO 4301-1 .

6.5.3 Stress history based upon classified duty

The hook body represents a special case, where the stress variations depend upon the hoist load variations, only. Because of this, the stress history parameter can be derived directly from the classes Q and U of ISO 4301-1, instead of using a case specific stress history and detailed calculation of *s*h in accordance with [6.5.2](#page-28-0). In cases where the intended duty is specified through the classes Q and U only, the calculation of *s*h shall be carried out as presented in Formula (27).

A load history parameter *s*Q is defined by the equation

$$
s_{\rm Q} = kQ \times N / N_{\rm D} \tag{26}
$$

where

- *kQ* is the load spectrum factor in accordance with [Table](#page-30-0) 5, see also ISO 4301-1; extended to include *Q*0−*Q*5 category status;
- *N* is the total number of lifting cycles. Typically, for a hook this shall be taken as the number work cycles (C) specified for the crane through the class U of ISO 4301-1. Each intermediate grounding of the load within a work cycle shall, however, be counted as an additional lifting cycle and added to the value of *N*;
- N_D is the reference number of cycles $(N_D = 2 \times 10^6)$.

The load spectrum factor (*kQ*) is calculated by a Wöhler curve slope with an exponent of 3, whereas the hook body fatigue is related to a slope *m* = 6. For a load distribution with a given shape, a conversion factor can be calculated to create a connection between the load spectrum of ISO 4301-1 and the stress history parameter of hooks. For a classified duty shapes of load distributions given in [Annex](#page-57-1) E shall be applied

In cases where the load spectrum is specified through the classification of ISO 4301-1, the stress history parameter *s*h for a hook body shall be calculated as follows:

$$
s_{\rm h} = \frac{s_{\rm Q}}{\left(k_6\right)^m} \tag{27}
$$

with

$$
k_6^* = 6\frac{kQ}{k_h} \tag{28}
$$

where k_6 ^{*} is the specific spectrum ratio factor.

Standardized, conventional values in accordance with [Table](#page-30-0) 5 shall be used for design of hook body. See also [Annex](#page-57-1) E. $k_6 \hat{\ } = \oint_{\text{O}} \frac{\text{Nc}}{\text{k}}$

where k_6 ^{*} is the specific spectrum ratio factor.

Standardzed contains to Equality conventional values in accordance with Table 5 shall be used for design of hook body. See

also Annex

6.5.4 Limit fatigue design stress

The basic assumption is that the fatigue strength curves in the $log(\sigma)/log(N)$ -scale are straight lines, with the same slope (m) for all material grades. This is a reasonable approximation in the range of high number of stress cycles, where fatigue is the governing design criteria.

The limit fatigue design stress at the reference point N_D is calculated as follows:

$$
\Delta \sigma_{\text{Rd}} = f_1 \times f_2 \times \Delta \sigma_{\text{c}} \tag{29}
$$

where

*Δσ*Rdis the limit fatigue design stress;

- $\Delta \sigma_c$ is the characteristic fatigue strength at $N_D = 2 \times 10^6$ cycles, dependent on the material;
- *f*¹ is the influence factor for the operation temperature, in accordance with Formula (31);
- *f*² is the influence factor for the material thickness, in accordance with Formula (32).

The characteristic fatigue strength $\Delta \sigma_c$ is dependent upon the ultimate strength of the material. For the classified material grades in accordance with [Table](#page-11-2) 4, the fatigue strength shall be taken from [Table](#page-30-1) 6.

Table 6 — Characteristic fatigue strength of forged hook materials

Material class	$\frac{\Delta \sigma_{\rm c}}{\rm N/mm^2}$
M	170
	220
	235
	280
	305

For other materials and in cases where the classified material grades are not applied, the characteristic fatigue strength $\Delta\sigma_c$ shall be calculated as follows:

$$
\Delta \sigma_{\rm c} = 0.315 \times f_{\rm u} \times \lg \frac{13001}{f_{\rm u}}
$$
\n(30)

where $f_{\rm u}$ is the ultimate strength of the material in newtons per square millimetre (N/mm²). $\Delta \sigma_c = 0.315 \times f_u \times \lg \frac{13001}{f_u}$

where f_u is the ultimate strength of the material in newtons per square millimetre (N/mm²).

The influence factor f_1 for the operation temperature is calculated as follows:

for

The influence factor f_1 for the operation temperature is calculated as follows:

for $100 °C \le T \le 250 °C$:

$$
f_1 = 1 - 0.1 \times (T - 100) / 150 \tag{31}
$$

for
$$
-50
$$
 °C $\leq T \leq 100$ °C:

$$
f_1 = 1
$$

where *T* is the operation temperature in degrees Celsius (°C).

The influence factor f_2 for the material thickness is calculated as follows:

for 25 mm $\leq b_{\text{max}} \leq 150$ mm:

$$
f_2 = \left(\frac{b_{\text{ref}}}{b_{\text{max}}}\right)^{0,167} \tag{32}
$$

for b_{max} < 25 mm

$$
f_2 = 1
$$

for b_{max} > 150 mm:

$$
f_2=0.74
$$

where

 b_{ref} is the reference width (b_{ref} = 25 mm);

 b_{max} is the maximum width in the critical hook body section, see [Figure](#page-22-1) 5.

6.5.5 Execution of the proof

The proof shall be carried out separately for all relevant sections of the hook body.

For the proof of fatigue strength, it shall be proven that

[∆] ∆ ∆ σ σ γ σ ^γ Sd,max Rd Hf h Rd Hf Q ≤ [×] ⁼ [×] *s* × *k m m s* 6 * (33) No reproduction or networking permitted without license from IHS Not for Resale, 05/21/2014 09:13:19 MDT --`,,,`,````,,,,`,````,,``````,`-`-`,,`,,`,`,,`---

where

 $\Delta\sigma_{\text{Sd,max}}$ is the maximum stress range within the total stress history;

 $\Delta \sigma_{\text{Rd}}$ is the limit fatigue design stress in accordance with Formula (29);

*γ*_{Hf} is the fatigue strength specific resistance factor in accordance with [Table](#page-32-1) 7;

- *m* is the slope parameter of the characteristic fatigue design curve $(m = 6)$;
- *s*^h is the stress history parameter;
- $k₆$ ^{*} is the specific spectrum ratio factor;
- *s*^O is the load history parameter.

For the calculation utilizing the classification in accordance with ISO 4301-1, the values for the following conversion factor are given in [Annex](#page-57-1) E:

$$
k_{\rm C} = k_{\rm G}^* / m/s_{\rm Q} \tag{34}
$$

6.5.6 The use of fatigue limit design force for verification of the hook body

The fatigue limit design force $F_{\rm Rd,f}$ shall be calculated as follows:

$$
F_{\rm Rd,f} = \frac{f_2 \times \Delta \sigma_{\rm c}}{\gamma_{\rm Hf}} \times \frac{I \times (1 - \eta_1/R)}{\nu \times R \times \eta_1}
$$
(35)

For a single hook, the fatigue limit design force shall be calculated separately for the two sections A and B and the smaller value of the two is used.

It shall also be proven for all relevant load actions and combinations specified in [6.2](#page-25-1) that

$$
F_{\text{Sd,f}} \le \frac{f_1 \times F_{\text{Rd,f}}}{\sqrt[m]{s_{\text{h}}}} = \frac{f_1 \times k_6^* \times F_{\text{Rd,f}}}{\sqrt[m]{s_{\text{Q}}}}\tag{36}
$$

where

 $F_{Sd,f}$ is the maximum vertical fatigue design load in accordance with 6.2 ;

*F*_{Rd,f}is the fatigue limit design force;

*f*¹ is the influence factor for the operation temperature in accordance with Formula (31).

In cases where the selected hook body is in accordance with Δ nnexes Δ or B, the proof of fatigue strength may be based on the fatigue limit design force shown in [Annex](#page-55-1) D.

6.6 Proof of fatigue strength, hook shank

6.6.1 General

The number of stress cycles is derived from the total number of lifting cycles (*N*), which shall conform to the total number of working cycles (*C)* during the design life of the crane as specified in accordance with ISO 4301-1.

6.6.2 Design stress calculation

The design stresses shall be calculated in the undercut section of the shank immediately below the threads with a diameter *d*4, see [Figure](#page-13-1) 1. Basic stresses are calculated without stress concentration factors and using conventional beam bending theory. The following equations are general and apply in [6.6](#page-32-2) for any vertical design force and design bending moment: The number of stress cycles is derived from the total number of lifting cycles (*N*), which shall conform
to the total number of working cycles (*C*) during the design life of the crane as specified in accordance
with ISO

$$
\sigma_{\rm a}(F) = \frac{F}{A_{\rm d4}}\tag{37}
$$

$$
\sigma_{\rm b}(M) = \frac{M \times d_4/2}{I_{\rm d4}}\tag{38}
$$

where

- *σ*^a is the shank stress (axial) due to vertical design force;
- $\sigma_{\rm b}$ is the shank stress (bending) due to design bending moment;
- *F* is the vertical design force in a fatigue load cycle;
- *M* is the design bending moment in a fatigue load cycle;
- *A*d4 is the cross section area of the critical section of the hook shank;
- I_{d4} is the moment of inertia of the critical section of the hook shank.

6.6.3 Applied stress cycles

Within each lifting cycle, the two types of stress cycles shown below shall be considered, as relevant.

In the Proof of fatigue strength of "non-proofed" hooks residual compressive stress σ_{Sd,sh,pr} in the equations below is set to zero. For "proofed" hooks residual compressive stress $\sigma_{Sd,sh,pr}$ set up in the undercut region where maximum stress during proof loading has exceeded the yield stress (e.g. the run out of shank thread) can be neglected (by setting in the equations below the value of the residual stress *σ*Sd,sh,pr to zero — a conservative approach) or the beneficial effects taken into account as shown in both types of stress cycles below. Nota,

Within each lifting cycle, the two types of stress cycles shown below shall

In the Proof of fatigue strength of "non-proofed" hooks residual compressive

equations below siste to zero. For "proofed" hooks residua

Cycle Type 1: A stress cycle due to lifting a load and lowering it down on the ground, with due consideration to the bending stress due to inclination of hook suspension and eccentricity of the vertical load. The specifics of each stress cycle (i) are as follows:

a) Axial stress is $\sigma_{a1} = \sigma_a (F_{Sd,f,i})$ (Formula (37)), where $F_{Sd,f,i}$ is in accordance with [6.2](#page-25-1).

Residual compressive stress $\sigma_{Sd,sh,pr}$ set up in the region of shank undercut where maximum stress during proof loading has exceeded the yield stress has to be taken into account. The design axial stress will cycle/range from the minimum value of the axial design stress in the shank of "proofed" hook *σ*Sd,ps,m*i*n equal to residual stress *σ*Sd,sh,pr at zero hook load.

 $\sigma_{Sd,a,psmin} = \sigma_{Sd,sh,pr}$ to a maximum value of the axial design stress in the shank of "proofed" hook *σ*Sd,ps,max calculated by adding the stress *σ*a1 for the hook load *F*Sd,f,*i* (calculated as shown above) to the value of the initial residual stress $\sigma_{Sd,sh,pr}$:

 $\sigma_{\text{Sd,a,psmax}} = \sigma_{\text{Sd.sh.nr}} + \sigma_{\text{a1}}$

b) Bending stress is $\sigma_{b1} = \sigma_b(M)$ [Formula (38)], where $M = \max\left[M_{2,\text{f},i}, M_{3,\text{f},i}\right]$ is in accordance with [6.4.2](#page-26-2) and [6.4.3.](#page-27-2)

Residual compressive stress $\sigma_{Sd,sh,pr}$ set up in the region of shank undercut where maximum stress during proof loading has exceeded the yield stress has to be taken into account and the design bending stress type 1, σ_{b1} has to be added to the axial stress including residual stress as calculated above.

c) Pulsating stress cycle from 0 to $\sigma_{a1} + \sigma_{b1}$, mean stress $\sigma_{m1,i} = (\sigma_{a1} + \sigma_{b1})/2$, stress amplitude $\sigma_{A1,i} = \sigma_{m1,i}$.

With residual compressive stress σ_{Sd,sh,pr} present in the region of "proofed" hook shank undercut the design stress Type 1 will cycle/range from the minimum value of the design stress σ Sd,ps1,min equal to residual stress $\sigma_{Sd,sh,pr}$ at zero hook load:

 $\sigma_{\text{Sd},\text{ps1,min}} = \sigma_{\text{Sd},\text{sh,pr}}$

to a maximum value of the design stress in the shank of "proofed" hook σ_{Sd,ps1,max} calculated by adding the stress σ_{a1} for the hook load $F_{Sd,f,i}$ (calculated as shown above) and bending stress σ_{b1} to the value of initial residual stress $\sigma_{\text{Sd,sh,pr}}$.

 $\sigma_{\text{Sd,ps1,max}} = \sigma_{\text{Sd,sh,pr}} + \sigma_{\text{a1}} + \sigma_{\text{b1}}$

With the procedures of [6.6.8](#page-38-0) being based on the cycle in [6.6.3](#page-33-0) being a pulsating stress cycle (stress cycling from zero to a maximum value) the stress cycle in "proofed" hook shank has to be first transformed to an equivalent pulsating cycle, e.g. using the transformation equation shown in [Annex](#page-76-1) I before the procedures of [6.6.8](#page-38-0) can be applied.

d) The total number of stress cycles is $N_1 = N$

Cycle Type 2: A stress cycle due to horizontal acceleration and resulting load sway shall be taken into consideration as follows.

e) Axial stress as in Cycle Type 1

Residual compressive stress $\sigma_{Sd,sh,pr}$ set up in the region of shank undercut during proof loading has to be taken into account. The extreme values of the design axial stress Type 2, will be calculated in the manner analogous described in Paragraph a) for Type 1, viz. design stress cycling/ranging from the minimum value of the axial design stress in the shank of "proofed" hook *σ*_{Sd,a2,ps,m/n} equal to residual stress $\sigma_{Sd,sh,pr}$ at zero hook load

 $\sigma_{\text{Sd,a2,ps,min}} = \sigma_{\text{Sd,sh,pr}}$

to a maximum value of the axial design stress in the shank of "proofed" hook $\sigma_{Sd,a2,ps,max}$ calculated by adding the stress σ_{a2} to the value of the initial residual stress $\sigma_{Sd,sh,pr}$

 $\sigma_{\text{Sd,a,psmax}} = \sigma_{\text{Sd,sh,pr}} + \sigma_{\text{a1}}$

f) Bending stress is $\sigma_{b2,i} = \sigma_b (M_{1,fi})$ [Formula (38)], where $M_{1,fi}$ is in accordance with [6.4.1](#page-26-3)

Residual compressive stress $\sigma_{Sd,sh,pr}$ set up in the region of shank undercut during proof loading has to be taken into account and the design bending stress type 2, σ_{b2} has to be added to the axial stress including residual stress as calculated above.

g) Each stress cycle with a mean stress $\sigma_{m2,i} = \sigma_{a1,i}$ and stress amplitude $\sigma_{A2,i} = \sigma_{b2,i}$

With residual compressive stress σ_{Sd,sh,pr} present in the region of "proofed" hook shank undercut the design stress Type 2 will cycle/range from the minimum value of the design stress σ_{Sd,ps2},_{min} equal to $(\sigma_{\text{Sd},sh,pr} - \sigma_{\text{b2}})$ at zero hook load F) Bending stress is $\sigma_{\text{L2},i} = \sigma_{\text{b}}(M_{1,li})$ [Formula (38)], where $M_{1,li}$ is in accordance with 6.4.1

Residual compressive stress $\sigma_{\text{3d,sh,pr}}$ set up in the region of shank undercut during proof loading has

t

 $\sigma_{\text{Sd,ps2,min}} = \sigma_{\text{Sd,sh,pr}} - \sigma_{\text{b2}}$

to a maximum value of the design stress in the shank of "proofed" hook σ_{Sd,ps1,max} calculated by adding the stress σ_{a2} for the hook load $F_{Sd,f,i}$ (calculated as shown above) and bending stress σ_{b2} to the value of initial residual stress $σ_{Sd,sh,pr}$

 $\sigma_{\text{Sd,DS2,max}} = \sigma_{\text{Sd,sh,pr}} + \sigma_{\text{a2}} + \sigma_{\text{b2}}$

With the procedures of $6.6.8$ being based on the assumption of the Type 2 stress cycle in $6.6.3$ being a pulsating stress cycle (stress cycling from zero to a maximum value) the stress cycle in "proofed" hook shank has to be first transformed to an equivalent pulsating cycle, e.g. using the transformation equation shown in Δ nnex I before the procedures of [6.6.8](#page-38-0) can be applied.

h) The total number of stress cycles is $N_2 = p_a \times N$

Within each lifting cycle, the hook load specific for that cycle shall be used.

NOTE The axial stresses within the Cycle Type 2 may be calculated without the effect of the factor ϕ_2 in [6.2](#page-25-1).

The parameter p_a shall be selected in accordance with [Table](#page-35-0) 8.

Table 8 — **Average number** of **horizontal accelerations** p_a

6.6.4 Basic fatigue strength of material

The basic, alternating fatigue strength of the material, for zero mean stress (σ_m = 0) and for the reference number of stress cycles N_D = 2 000 000 is calculated based upon the ultimate strength of the material as follows:

$$
\sigma_{\rm M} = 0.45 \times f_{\rm u} \tag{39}
$$

6.6.5 Stress concentration effects from geometry

The factors calculated within this clause are the stress concentration factor *α* and, as a final outcome, the notch effect factor *β*n. Both of them shall be calculated separately for the shoulder and for the thread bottom in accordance with the equations in [Table](#page-36-0) 9. The maximum value of the two *β*n shall be used in the proof of fatigue strength of the shank.

NOTE The thread is assumed to be of a single lead type.
	Shoulder	Thread
Mean thread diameter d_e	$d_e = 0.6 \times d_3 + 0.4 \times d_5$	
Depth of notch	$u_{\rm S} = \frac{(d_{\rm e} - d_4)}{2}$	$u_T = \frac{(d_e - d_5)}{2}$
Factor φ	$\phi = \frac{1}{2 + 4 \times \sqrt{\frac{u_S}{r_o}}}$	$\phi = \frac{1}{2 + 4 \times \sqrt{\frac{u_{\text{T}}}{r_{\text{th}}}}}$
Factor χ	$\chi = \frac{2 \times (1 + \phi)}{r_{\text{g}}}$	$\chi = \frac{2 \times (1 + \phi)}{r_{\text{th}}}$
Support factor n	$n=1+\sqrt{\chi}\times10^{-(0,33+f_{y}/712)}$	
Geometric stress concen- tration factor	$\alpha_{\rm S}$ [Formula (40)]	α _T [Formula (41)]
Notch effect factor	$\beta_{\rm n} = \frac{\alpha_{\rm s}}{n}$	$\beta_n = \alpha_T$

Table 9 — Parameters for calculation of stress concentration factors

The shoulder stress concentration factor α_S shall be calculated as follows:

$$
\alpha_{\rm S} = 1 + \frac{1,1}{\sqrt{0,22 \times \frac{r_9}{u_{\rm S}} + 2,74 \times \frac{r_9}{d_4} \times \left(1 + 2\frac{r_9}{d_4}\right)^2}}
$$
(40)

The thread stress concentration factor α_T shall be calculated as follows:

^α T T th S = × × × × 1 8 5 0 3 0 2 0 1 4 5 , , , , *^p d u r p u d d* 3 5 5 2 ¹ ¹ 0 22 2 74 1 2 × + × + × × ⁺ , , *^r u r d r d* th T th th (41) No reproduction or networking permitted without license from IHS Not for Resale, 05/21/2014 09:13:19 MDT --`,,,`,````,,,,`,````,,``````,`-`-`,,`,,`,`,,`---

The geometric symbols in <u>[Table](#page-36-0) 9</u> and in Formulae (40) and (41) are according to those in <u>[Figure](#page-14-0) 2</u>. The yield stress f_y in the equation for n shall be in newtons per square millimetre (N/mm²).

6.6.6 Fatigue strength of notched shank

The further following calculation shall be performed for the more critical of the two shank sections. The basic material fatigue strength shall be reduced to a comparable value in respect to nominal stresses in the shank.

The fatigue strength amplitude, notch piece factor σ_W shall be calculated as follows:

$$
\sigma_{\rm W} = f_1 \times \frac{\sigma_{\rm M}}{\left(\beta_{\rm n} + \frac{1}{f_3} - 1\right)}
$$
\n(42)

with

$$
f_3 = 1 - 0.29 \times \lg \frac{R_a}{0.4} \times \lg \frac{f_u}{200}
$$
 (43)

where

- *σ*^M is the basic fatigue strength of the material;
- β_n is the maximum of β_{nS} and β_{nT} ;
- f_1 is the influence factor for the operation temperature, in accordance with Formula (31);
- f_3 is the factor for the surface roughness influence;
- *R*_a is the surface finish grade in micrometres (µm) within the limits 0,4 µm $\leq R_a \leq 3.2$ µm;
- $f_{\rm u}$ is the ultimate strength of the material in newtons per square millimetre (N/mm²), $f_u ≥ 300 N/mm².$

NOTE The factor for reducing the material strength by increasing diameter is not applicable in this document. The true material properties for the actual diameter are used in the design calculations.

6.6.7 Mean stress influence

The above *σw* values apply for a pure alternating stress with zero mean stress. Hook shank represents a type of component, where the reduction of fatigue strength by increasing mean stress shall be considered. The mean stress influence is illustrated through a principal Smith diagram in [Figure](#page-38-0) 6. Characteristics of the diagram are as follows:

- a) The fatigue strength σ_W is fixed at mean stress $\sigma_m = 0$;
- b) Upper limit line of the diagram is specified through a mean stress influence factor μ ;
- c) Stress amplitudes at a related mean stress shall be within the lower and upper limits of the diagram.

Figure 6 — Smith diagram and transformation of stress amplitude

The upper limit line of the diagram is specified through the assumption that with pulsating stress, the total stress variation is limited to $\sigma_p = 1.7 \sigma_W$. From this rule, the mean stress influence factor is calculated as follows:

$$
\mu = \tan(\alpha) = \frac{\sigma_W}{1.7 \times \sigma_W / 2} - 1 = 0.1765
$$
\n(44)

NOTE The mean stress influence parameters μ and α correspond to the parameters μ_1 and α_1 , so that in this document α is counted always positive.

6.6.8 Transformation of stresses to a constant mean stress

The stress amplitudes with related mean stresses as specified in $6.6.3$ are transformed to a stress amplitude with an equal fatigue influence. Transformation to a stress cycle with a mean stress zero is made as follows:

Cycle Type 1

$$
\sigma_{T1,i} = \sigma_{A1,i} + \mu \times \sigma_{m1,i} \tag{45}
$$

Cycle Type 2

$$
\sigma_{\text{T2},i} = \sigma_{\text{A2},i} + \mu \times \sigma_{\text{m2},i} \tag{46}
$$

where $\sigma_{T1,i}$ and $\sigma_{T2,i}$ are the transformed stress amplitudes at zero mean stress, and μ is the mean stress influence factor. where $σ_{T1,i}$ and $σ_{T2,i}$ are the transformed stress amplitudes at zero mean stress, and $μ$ is the mean
stress influence factor.
The transformation of $σ_{A,i}$ to $σ_{T,i}$ is illustrated in Figure 6.
 $F_{Covright}$

The transformation of $\sigma_{A,i}$ to $\sigma_{T,i}$ is illustrated in [Figure](#page-38-0) 6.

6.6.9 Stress history parameter in general

The cumulative fatigue effect of the stress history from all of the stress cycles is condensed into a single stress history parameter *s*s. This is calculated as follows:

$$
s_{\rm s} = k_{\rm s} \times v_{\rm s} \tag{47}
$$

with

$$
k_{\rm s} = \frac{1}{N + p_{\rm a} \times N} \times \left[\sum_{i=1}^{N} \left(\frac{\sigma_{\rm T1,i}}{\sigma_{\rm Tmax}} \right)^{m} + p_{a} \times \sum_{i=1}^{N} \left(\frac{\sigma_{\rm T2,i}}{\sigma_{\rm Tmax}} \right)^{m} \right]
$$
(48)

and

$$
v_s = \frac{N + p_a \times N}{N_D} \tag{49}
$$

where

 σ_{Tmax} is the maximum of the transformed stress amplitudes $\sigma_{\text{T1},i}$ and $\sigma_{\text{T2},i}$,

- *k*^s is the stress spectrum factor for the hook shank;
- *ν*^s is the relative number of stress cycles;
- *i* is the index of a lifting cycle
- *N* is the total number of lifting cycles
- *m* is the slope parameter of the characteristic fatigue design curve $(m = 5)$.

6.6.10 Stress history parameter based upon classified duty

The hook shank represents a special case, where the magnitudes of stress variations are directly proportional to the hoist load variations. Because of this, the stress history parameter can be derived directly from the classes Q and U of ISO 4301-1, instead of using a case specific stress history and detailed calculation in accordance with [6.6.9.](#page-39-0)

The load spectrum factor (*kQ*) is calculated by a Wöhler curve slope with an exponent of 3, whereas the hook shank fatigue is related to a slope *m* = 5. For a load distribution with a given shape, a conversion factor can be calculated to create a connection between the load spectrum of ISO 4301-1 and the stress history parameter of hook shank. For a classified duty shapes of load distributions given in [Annex](#page-57-0) E shall be applied

In cases where the intended duty is specified through the classes Q and U of ISO 4301-1, the stress history parameter shall be calculated as follows:

$$
s_s = k_s \times v_s \tag{50}
$$

with

$$
k_{s} = \frac{1}{1 + p_{a}} \times \frac{kQ}{\left(k_{5}^{*}\right)^{m}} \left[\left(\frac{\sigma_{\text{T1,max}}}{\sigma_{\text{Tmax}}}\right)^{m} + p_{a} \times \left(\frac{\sigma_{\text{T2,max}}}{\sigma_{\text{Tmax}}}\right)^{m} \right]
$$
(51)

$$
v_s = \frac{N}{N_D} \times (1 + p_a) \tag{52}
$$

and

$$
k_5^* = \sqrt[5]{\frac{kQ}{k_5}}
$$
\n
$$
\tag{53}
$$

where

kQ is the load spectrum factor in accordance with [Table](#page-40-0) 10;

*σ*T1,max, are the maximums of the transformed stress amplitudes in Cycle Types 1 and 2; *σ*T2,max

- *N* is the total number of lifting cycles, which, typically for a hook, shall be taken as equal to the number of work cycles (C) specified for the crane through the class U of ISO 4301-1; each intermediate grounding of the load within a work cycle shall, however, be counted as an additional lifting cycle and added to the value of N;
- k_5 ^{*} is the specific spectrum ratio factor.

Standardized, conventional values in accordance with [Table](#page-40-0) 10 shall be used for design of hook shank. See also [Annex](#page-57-0) E.

Class Q of ISO 4301-1 extended.to Q_0-Q_5	Load spectrum factor kQ	Factor k_5 [*] for $m = 5$
Q_0	0,0313	1,292
Q_1	0,0625	1,286
Q_2	0,125	1,22
Q3	0,250	1,14
Q4	0,500	1,07
Q5	1,000	1,00

Table $10 -$ **Specific spectrum** ratio factors $k5^*$

6.6.11 Execution of the proof

For the proof of fatigue strength it shall be proven that

$$
\sigma_{\text{Tmax}} \leq \frac{\sigma_W}{\gamma_{\text{SF}} \times \sqrt[m]{s_s}}
$$

where

*σ*Tmax is the maximum, transformed stress amplitude within the total stress history; For the proof of fatigue strength it shall be proven that
 $\sigma_{\text{Tmax}} \leq \frac{\sigma_W}{\gamma_{\text{SF}} \times \sqrt{\gamma_S_s}}$ (5)

where
 σ_{Tmax} is the maximum, transformed stress amplitude within the total stress history;
 σ_W is the limit fati

- *σ*^W is the limit fatigue design stress in accordance with Formula (42);
- *γ*_{Sf} is the fatigue strength specific resistance factor for hook shank (*γ*_{Sf} = 1,35);
- *m* is the slope parameter of the characteristic fatigue design curve (*m* = 5);
- *s*_s is the stress history parameter.

(54)

6.7 Fatigue design of hook shanks for serially produced hooks

The following design assumptions shall be used as a minimum for the design of hook shanks in serially produced hooks with a finished shank:

- a) Fatigue limit design force of the hook body shall be used as a fatigue design force for the shank;
- b) Number of shank bending cycles due to horizontal load sway is $p_a = 4$;
- c) For calculation of horizontal fatigue design force in 6.3 the horizontal acceleration is set $a = 0.2$ m/s² and $\phi_5 = 1$;
- d) Hook suspension tilting resistance is assumed to correspond to a horizontal force in the hook seat equal to 2 % of the vertical force.

7 Verification of conformity with the requirements

7.1 General

Conformity with the requirements given in [Clauses](#page-16-0) 5 and 6 shall be verified by design calculations.

The design assumptions, e.g. intended duty and the intended hook capacity, shall conform to the corresponding design parameters of the related crane. This conformity shall be verified by engineering assessment.

All verifications in accordance with [Clause](#page-41-0) 7 shall be documented as a part of the technical file. See also [Annex](#page-82-0) K for required documentation.

7.2 Verification of manufacture

Manufacturing conformity shall be verified through adherence to a written description of the hook manufacturing process, documented and certified by the manufacturer.

Conformity with the dimensional and material requirements shall be verified by measurements and tests. The results shall be recorded and retained by the hook manufacturer.

The test pieces for tensile, elongation and impact testing shall be taken longitudinally at the upper part of the hooks shank, preferably at a distance of 1/3 radius from the shanks surface. As an alternative, e.g. where the shank is too small, tests may be carried out on sample material selected from the same material melt and subjected to identical heat treatment. The required tensile/elongation qualities shall be specified by the manufacturer on the basis of ISO 7500-1 and either ISO 6892-1 or ISO 15579 as the case dictates.

The required Charpy impact qualities shall be specified by the manufacturer on the basis of ISO 148-1 and ISO 148-2.

7.3 Proof loading

A hook shall be able to withstand the proof load without excessive permanent deflection. The throatopening dimension shall be measured before and after the test loading, using the specific measure points (1), see [Figure](#page-43-0) 7. A permanent set shall not exceed 0,25 %.

7.4 None destructive testing (NDT)

Hooks shall be examined, both for surface and internal defects using NDT methods that permit reliable detection.

Hook forging shall be inspected for defects using appropriate NDT-methods according to EN 10228-3, quality class 1 of this standard shall be met.

7.5 Test sampling

Material tests are to be carried out on either each individual hook or on the production batch principle.

Hooks having a ruling thickness 150 mm or greater, shall have all tests carried out on each and every hook.

Hooks having a ruling thickness less than 150 mm may be batch tested. The maximum batch size shall comprise the number of hooks, which can be manufactured from the same raw material cast or billet and undergoes identical heat treatment.

8 Information for use

8.1 Maintenance and inspection

The hook shall be handled as an issue of its own in the maintenance and inspection manuals of the related crane.

Maintenance of the following items shall be addressed as a minimum in the maintenance manual:

- a) thrust bearing under the nut;
- b) crosshead hinge.

The following items shall be addressed as a minimum in the inspection instruction, with their related frequency of inspection and rejection criteria:

- c) deformation (gap opening) of the hook body;
- d) wear of the hook body;
- e) inspection for surface defects, cracks and corrosion, with the hook suspension disassembled for the inspection of shank;
- f) safety locking of the nut;
- g) safety latch, if provided.

The acceptable wear depth of the hook body at the bottom of the seat is 5 % of the nominal height of the body section, dimension h_2 in Δn nnex Δ . The worn areas shall have smooth transition to adjacent areas. They shall be free of any sharp marks or edges, or defects opening onto the surface.

8.2 Marking

The hook body shall have a permanent marking positioned as item 2 in [Figure](#page-43-0) 7 specifying the following:

- a) size and shape of hook using a unique identification, e.g. hook number in accordance with [Annex](#page-44-0) A or B;
- b) material designation, either the class symbol in accordance with 4.1 or other documented designation;
- c) number of the reference standard or specification;
- d) if relevant, marking of the proof loading, see [4.5](#page-12-0).

EXAMPLE A hook fulfilling the requirements of this International Standard, size and shape being according to number 12 of [Annex](#page-44-0) A and being made from material P has the marking:

RS12 – P – ISO 17440

Additionally the hook may be marked with a designation or symbol identifying the manufacturer. The hook body itself shall have no marking indicating either the load or the duty classification.

Figure 7 — Markings on a hook

The hook shall have permanent centre punch markings placed as item 1 in [Figure](#page-43-0) 7. As appropriate dimensions *y* or *y*1 and *y*2 shall be recorded and placed within hook documentation.

The fixed hoist media, from which the hook is suspended, should be marked as a part of the crane, indicating the mass of the rated capacity and the related "A" series duty classification (as per ISO 4301-1), as required by the relevant crane type standard.

8.3 Safe use

The following issues of safe use shall be, as a minimum, addressed in the user's manual of either the related crane or the stand alone hook/hook block as a component:

- free functioning of the hook suspension articulation (hinge), allowing the hook to align without obstacles in the direction of the load, either vertically or inclined during load sway;
- instructions for lashing a load on the hook, maximum 90° angle between the slings;
- shape requirement of the load attachment set on the hook, to avoid damage of the surface of the hook seat;
- the two prongs of a ramshorn hook shall be loaded symmetrically and equally;
- in cases, where a safety latch is provided, it shall be allowed to close freely after the load is attached;
- temperature limits of the hook.

Annex A (informative)

Sample sets of single point hooks

A.1 A series of single point hooks of type RSN, dimensions of forgings

See [Figure](#page-44-1) A.1 and [Table](#page-45-0) A.1.

Key

Designation:

RF without forged nose for latch

Figure A.1 — Symbols of dimensions for single point hooks with concave flanks

For hooks type RSN, see also $C.1$, $D.1$ and either $C.1$ or $C.2$ dependent upon size.

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A.2 A series of single point hooks of type RF/RFN, dimensions of forgings

See [Figure](#page-47-0) A.2 and [Table](#page-48-0) A.2.

For hooks type RF and RFN, see also $C.1$, $D.1$ and either $C.1$ or $C.2$ dependent upon size.

Table A.2 — Dimensions of forgings for single point hooks in millimetres (mm)

A.3 A series of single point hooks of type B, dimensions of forgings

See [Figure](#page-49-0) A.3 and [Table](#page-50-0) A.3.

Figure A.3 — Symbols of dimensions for single point hooks

For hook type B, see also $C.2$, $D.2$ and $G.4$.

A ∂_1 $B - B$

 $h₂$

ň

Table A.3 — Dimensions of forgings for single point hooks in millimetres (mm)

Annex B

(informative)

Sample set of ramshorn hooks

A series of ramshorn hooks of type RS/RSN and RF/RFN, dimensions of forgings

See [Figure](#page-51-0) B.1 and [Table](#page-51-1) B.1.

Key

Designation:

RS/RSN concave flanks (a), without or with nose RF/RFNstraight flanks (b), without or with nose

Figure B.1 — Symbols of dimensions for ramshorn hooks

Ramshorn														Dimensions for guidance						
hook no.	a ₁	a ₂	a_3	b ₁	d ₁	f ₁	H	r_1	r ₂	r_3	ϵ	f ₂	f_3	\mathfrak{g}	r ₄	r ₅	L			
05	34	27	44	22	24	130	27	3	3	36	80	20	12	10	6	1,6	165			
08	38	30	49	26	30	150	33	4	3	41	83	22	12	10,5	6	1,6	183			
1	40	32	52	28	30	158	36	4	3,5	44	96	22	14	12	$\overline{7}$	1,6	195			
1.6	45	36	59	34	36	183	43	5	4	51	100	28	14	12,5	7	1,6	222			
2.5	50	40	65	40	42	208	50	6	4,5	58	112	30	14	14	$\overline{7}$	1,6	250			
$\overline{\mathbf{4}}$	56	45	73	48	48	238	60	7	5,5	67	124	33	23	16	10	2,5	280			
5	63	50	82	53	53	266	67	8	6,5	75	143	40	23	16	10	2,5	312			
6	71	56	92	60	60	301	75	9	7	85	160	44	23	18	10	2,5	375			
Hook sizes 50–250 preferably with straight flanks.																				
NOTE								Dimensions based upon DIN 15400 series of hooks.												

Table B.1 — Dimensions of forgings for ramshorn hooks in millimetres (mm)

Ramshorn							H								Dimensions for guidance		
hook no.	a_1	a ₂	a_3	b ₁	d_1	f_1		r_1	r ₂	r_3	\boldsymbol{e}	f ₂	f_3	$\mathfrak g$	r_4	r ₅	L
8	80	63	103	67	67	337	85	10	8	95	182	48	23	18	10	2,5	415
10	90	71	116	75	75	377	95	11	9	106	192	54	27	23	12	3	450
12	100	80	130	85	85	421	106	125	10	118	210	60	27	23	12	3	510
16	112	90	146	95	95	471	118	14	11	132	237	69	36	28	16	4	580
20	125	100	163	106	106	531	132	16	12,5	150	265	75	36	33	16	4	650
25	140	112	182	118	118	598	150	18	14	170	315	86	45	33	20	5	715
32	160	125	205	132	132	672	170	20	16	190	335	94	45	38	20	5	790
40	180	140	230	150	150	754	190	22	18	212	375	104	45	38	20	5	885
50	200	160	260	170	170	842	212	25	20	236	420	120	56	42	25	6	965
63	224	180	292	190	190	944	236	28	22	265	460	131	56	42	25	6	1090
80	250	200	325	212	212	1062	265	32	25	300	515	144	56	45	25	6	1 2 3 5
100	280	224	364	236	236	1 1 8 6	300	36	28	335	575	157	56	45	25	6	1375
125	315	250	408	265	265	1330	335	40	32	375	645	178	68	50	30	8	1550
160	355	280	458	300	300	1505	375	45	36	425	725	198	68	50	30	8	1745
200	400	315	515	335	335	1685	425	50	40	475	800	218	68	55	30	8	1998
250	450	355	580	375	375	1885	475	56	45	530	875	240	68	55	30	8	2 2 5 0
Hook sizes 50-250 preferably with straight flanks.																	
NOTE						Dimensions based upon DIN 15400 series of hooks.											

Table B.1 *(continued)*

For hooks type RS/RF and RSN/RFN, see also [C.1](#page-53-0), [D.1](#page-55-0) and either [G.1](#page-67-0) or [G.2](#page-68-0) dependent upon size.

Annex C

(informative)

[Annexes](#page-44-0) A and [B](#page-51-2) static limit design forces for hook bodies

C.1 Static limit design forces of hook bodies for hook types RS/RSN and RF/RFN (see [Table](#page-53-1) C.1.)

C.2 Static limit design forces of hook bodies for a series of hooks of type B, with additional materials (see [Table](#page-54-1) C.2)

					Single hooks, type B				
	All materials				Classified material grades $F_{\rm Rd,s}$			Additional materials	
Hook no.	Hook family factor $\gamma_{\rm sm}$	Section B Hook factor M _{hf.} mm ²	M	\mathbf{P}	S	T	\mathbf{V}	f_{y} N/mm ²	$F_{\rm Rd.s}$
B0.8		25,392	5,75	8,43	10,2	13,4	16,1		11,5
B 1.6		49,722	11,3	16,5	19,9	26,2	31,5		22,5
B2.5		81,543	18,5	27,1	32,6	43	51,6		36,9
B4		127,31	28,8	42,3	51	67,1	80,5		57,7
B.5	0,86	157,79	35,8	52,4	63,2	83,2	99,8	430	71,5
B6.3		201,91	45,8	67	80,9	106	128		91,5
B 10		319,35	72,4	106	128	168	202		144
B 8		258,77	58,6	86	104	136	164		117
B12.5		399,34	90,5	133	160	210	253		181
B 16		514,76	121	179	216	284	340		227
B20	0,83	649,89	154	226	272	358	430		286
B25		807,66	191	280	338	445	534		356
B32	0,75	948,18	245	358	432	569	683	400	455
B 40	0,71	1128,78	310	454	547	720	864		576
B50	0,68	1379,07	399	585	706	929	1114		742
B63	0,64	1587,16	487	713	880	1132	1358		905

Table C.2 — Static limit design forces *F*Rd,s **in kilonewtons** (kN) **— Valid for temperature influence factor** $f_1 = 1$ ($T \le 100$ °C)

All hooks of this family shall be proof loaded as per 4.5 .

When dimensionally sizing all hooks of greater capacity than those listed within [Table](#page-54-1) C.2 it shall be assumed, for this calculation only, that the proof load F_{PL} is equal 1,5 times their required maximum static rated capacity.

For hook sizes greater than B 63, the value of $\gamma_{\rm sm}$ factor shall be taken as 0,64.

Annex D

(informative)

[Annexes](#page-44-0) A and [B](#page-51-2) fatigue limit design forces for hook bodies

D.1 Fatigue limit design forces of hook bodies for hooks of type RS and RF (see [Table](#page-55-1) D.1)

Table D.1 — Fatigue limit design forces *F*Rd,f **in kilonewtons (kN) — Factors** *f*2 **and** *γ*Hf **incorporated, temperature influence factor** $f_1 = 1$ ($T \le 100$ °C)

D.2 Fatigue limit design forces of hook bodies for a series of hooks of type B, with additional materials (see [Table](#page-56-1) D.2)

The section B type modulus is as defined below [Table C.2](#page-54-1). Its values for hook sizes B 0.8 to B 63 are shown in [Table](#page-56-1) D.2. For hook sizes greater than B $\overline{63}$, its value can be calculated from the dimensions of the hook and of its section B.

Annex E

(normative)

Hook body calculation and specific spectrum ratio factors

E.1 Conversion factor for hook body, k_c

When classified duty is utilized, k_c shall be calculated in accordance with [Table](#page-57-1) E.1.

Table E.1 — Conversion factor $k_c = k_6^* \sqrt{6/\varepsilon_0}$

E.2 Specific spectrum ratio factors

The presentation of distributions with discrete values can be shown as spectrum or as accumulated spectrum. [Figure](#page-57-2) E.1 illustrates both presentations for discrete distributions.

a) Spectrum, where *n* **is the relative number of cycles** with amplitude **q:** $\sum n = 1$ **b)** Accumulated spectrum

The presentation of distributions given by continuous functions can be shown as density function or as accumulated density function. [Figure](#page-58-0) E.2 illustrates both presentations for distributions given by continuous functions.

Figure E.2 — Continuous distributions

NOTE Whereas *n*(*q*) gives the relative number of cycles with amplitude *q*, the accumulated value of *N*(*q*) gives the number of cycles with amplitudes greater than q.

The stress spectrum factor k_m shall be calculated from the density function or from the accumulated density by

$$
k_m = \int_{q_0}^{1} q^m \times n \times dq = \int_{0}^{1} q^m \times dN
$$

The specific spectrum ratio factors (see [6.5.3\)](#page-29-0) then follows as

$$
k_m^* = m \sqrt{\frac{kQ}{k_m}} = m \sqrt{\frac{k_3}{k_m}}
$$

E.3 Underlying spectra for the specific spectrum ratio factors

In cases where the load spectrum of the crane is specified through the class Q only, the shape of load distribution in accordance with [Table](#page-59-0) E.3 shall be assumed. Consequently, the specific spectrum ratio factors as given in [Table](#page-58-1) E.2 can be derived and shall be used for calculation of the stress history parameter sh for the hook.

Class Q of ISO 4301-1	Load spectrum factor k0	Factor k^* ₅ for <i>m</i> = 5	Factor k [*] ₆ for <i>m</i> = 6
Q0	0,0313	1,292	1,348
Q1	0,0625	1,286	1,343
Q2	0,125	1,217	1,259
Q3	0,25	1,144	1,172
Q ₄	0,5	1,070	1,084

Table E.2 — Specific spectrum ratio factors

[Table](#page-59-0) E.3 gives the underlying density functions and accumulated density functions for [Table](#page-58-1) E.2.

ISO 17440:2014(E)

Annex F

(informative)

Sample fatigue strength calculations of proofed hooks (with proof load applied)

F.1 Data

NOTE Calculations for single point hooks with dimensions in accordance with [A.3](#page-49-1), [Table A.3](#page-50-0).

Hook size: Size B10, [Table A.3](#page-50-0)

Nominal hook load:

 $F_H = 10$ Te = 98,07 kN

NOTE Te denotes metric tonnes, 1 000 kgf.

Hook dimensions and section properties:

 $a_1 = 92$ mm seat circle diameter

Section B-B:

f^u = 620 N mm−2 min. ultimate strength of hook material

Fatigue and service duty parameters:

Utilization class U7 (to ISO 4301-1:1986, Table 1) hence *N* = 2 × 106, total number of load cycles

Load spectrum class $Q4$ (to ISO 4301-1:1986, Table 2) hence $kQ = 1$, load spectrum factor, max.

All load cycles are assumed to be the same and at full load.

F.2 Proof of competence in fatigue for hooks which have had proof load applied

F.2.1 Stresses in the bowl of "Non-proofed" hook (no residual stress present):

ϕ = 1,3 dynamic factor

 $F_{\text{Sd.f}} = \phi_2 F_H = 127,49 \text{ kN}$ vertical design force for fatigue, Formula (18)

Moment on hook section due to vert. design force $F_{\text{Sd,f}}$:

$$
M_{\text{Sd,f}} = F_{\text{Sd,f}}R = 10,48 \text{ kN m}
$$

Maximum design stress at the intrados of the hook due to vertical design force, Formula (11):

$$
\sigma_{\text{Sd,f}} = \frac{v \times M_{\text{Sd,f}}}{I} \times \frac{R \times \eta_1}{R - \eta_1} = 399,28 \text{ N mm}^{-2}
$$

Stress range at the intrados of the hook for fatigue (due to load $F_{Sd,f}$, cycling from 0 to maximum):

 $\Delta \sigma_{\rm Sd,f} = \sigma_{\rm Sd,f} = 399,28$ N mm⁻²

With loads of one magnitude only assumed, viz. *F*_{Sd,f}, max. stress range at the intrados of the hook for fatigue:

 $\Delta \sigma_{\rm Sd, max} = \Delta \sigma_{\rm Sd,f} = 399,28$ N mm²

F.2.2 Stresses in the bowl of "proofed" hook (residual stress present)

F.2.2.1 Proof load for the hook

Proof load *F*PL for the hook is calculated from

$$
F_{\rm PL} = 1.5 \times f_{\rm y} \times M \qquad \qquad \text{[see 4.5 e]}
$$

where

$$
M = I \times \left[\frac{1 - \frac{\eta_1}{R}}{R \times \eta_1}\right] = 319,29 \text{ mm}^2
$$

and proof load $F_{PL} = 1.5 \times f_V \times M = 205.94$ kN

F.2.2.2 Stresses in the section of "proofed" hook (residual stress present)

Moment on hook section due to proof load force F_{PL} : $M_{\text{PL}} = F_{\text{PL}} \times R = 16,92 \text{ kN m}$

Maximum virtual design stress at the intrados of the hook with proof load applied, Formula (11):

$$
\sigma_{\text{p,max,v}} = \frac{v \times M_{\text{PL}}}{I} \times \frac{R \times \eta_1}{R - \eta_1} = 645 \text{ N mm}^{-2}
$$

NOTE Maximum stress at the intrados of the hook with proof load applied and on the assumption of no plastic deformation.

An "ideal elastic-plastic" stress model for the material behaviour is assumed, with the onset of plastic deformation occurring at the yield stress and the maximum stress remaining constant at the yield stress level. Hence max. stress at proof load:

$$
\sigma_{p, max} = f_y = 420 \text{ N mm}^{-2}
$$

Stress change during unloading when the proof load is removed, is assumed to take place along the elastic line. Hence residual stress after full unloading will be

 $\sigma_{\text{r},\text{p,max}} = \sigma_{\text{p,max}} - \sigma_{\text{p,max,v}} = -225 \text{ N mm}^{-2}$

Maximum stress range due to full service load F_{Sdf} = 127,49 kN applied is

$$
\Delta \sigma_{\text{Sd,max}} = 399,28 \text{ N mm}^{-2}
$$

giving a rise to a maximum stress at the intrados due to full service load

 $\sigma_{sd, p, \text{max}} = \sigma_{r, p, \text{max}} + \Delta \sigma_{Sd, \text{max}} = 174,28 \text{ N mm}^{-2}$

and to a stress cycling between the extreme values of

 $\sigma_{r.p,max} = -225$ N mm⁻² and $\sigma_{sd,n,max} = 174,28$ N mm⁻²

The stress cycle must be transformed to an equivalent pulsating cycle (0 to max. stress), done below using the standard equation derived from the Haigh/Smith diagram:

$$
\sigma_{a,p,t} = \frac{\sigma_{a,p} - \mu \times \sigma_{m,p}}{1 - \mu \times \frac{(1 + R_s)}{(1 - R_s)}}
$$
\n
$$
\sigma_{m,p,t} = \sigma_{a,p,t}
$$

where

 $\sigma_{\rm a,p,t}$

are the amplitude and mean stress components of transformed stress cycle;

 $\sigma_{\rm m,p,t}$

*R*_s stress ratio of the transformed cycle, $\sigma_{\min}/\sigma_{\max}$:

 $R_s = 0$, for pulsating cycle 0 to max.;

 $\mu = -0.1765$ from Formula (44), [6.6.7](#page-37-0) (note the negative sign).

Component of the stress cycle:

σ σ $m_{\text{cm,p}} = \frac{\sigma_{\text{sd,p,max}} + \sigma_{\text{r,p,max}}}{2} = -25.36 \text{ N mm}^{-2}$ the mean stress component

σ $\sigma_{\rm cdm}$ may $-\sigma$ $a_{\text{ap}} = \frac{\sigma_{\text{sd},p,\text{max}} - \sigma_{\text{r},p,\text{max}}}{2} = 199,64 \text{ N mm}^{-1}$ $\frac{100 \text{ r}, \text{p,max}}{2}$ = 199,64 N mm⁻² the amplitude stress component $\frac{1}{\sigma_{\rm ap}} = \frac{\sigma_{\rm sd,p,max} - \sigma_{\rm r,p,max}}{2} = 199{,}64\ \rm N\ mm^{-2}$

component

Components of the transformed cycle:
 $\frac{\sigma_{\rm q,p}}{\sigma_{\rm q}} = \frac{\sigma_{\rm sd,p,max} - \sigma_{\rm r,p,max}}{\sigma_{\rm q}} = \frac{\sigma_{\rm sd,p,max} - \sigma_{\rm r,p,max}}{\sigma_{\rm q}}$

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Components of the transformed cycle:

From the equations above, amplitude and mean stress components of the transformed cycle

$$
\sigma_{a,p,t} = \frac{\sigma_{a,p} - \mu \times \sigma_{m,p}}{1 - \mu \times \frac{(1 + R_s)}{(1 - R_s)}} = 165,89 \text{ N mm}^{-2}
$$
 the amplitude stress

component

Maximum stress range at intrados:

$$
\Delta \sigma_{\text{Sd,p,f,max}} = 2 \times \sigma_{\text{a,p,t}} = 331,77 \text{ N mm}^{-2}
$$
 the maximum stress range at the intrados of the "prooted"

 $\sigma_{m,p,t} = \sigma_{a,p,t} = 165.89$ N mm⁻² , the mean stress component for pulsating cycle

Stress cycling between 0 and maximum of 2 × amplitude stress component

Hook for fatigue, due to $F_{Sd,f}$, load cycling from 0 to maximum.

F.2.3 Execution of proof for fatigue strength

F.2.3.1 Limit design stress, load history parameter and stress history parameter

$$
\Delta \sigma_{R,d} = f_1 \times f_2 \times \Delta \sigma_c
$$

the limit fatigue design stress, Formula (29), [6.5.4](#page-30-0).

Take $f_1 = 1$, the temperature factor, Formula (31), [6.5.4,](#page-30-0) and with $b_{\text{max}} = 55$ mm maximum width of hook cross section:

$$
f_2 = \left[\frac{25 \text{ mm}}{b_{\text{max}}}\right]^{0,167} = 0.877
$$

the material thickness influence factor, Formula (32), [6.5.4](#page-30-0).

Characteristic fatigue strength, Formula (30), [6.5.4](#page-30-0):

$$
\Delta \sigma_c = 0.315 \times f_u \times \lg \left[\frac{13\,000}{f_u} \right] = 258.11 \text{ N mm}^{-2}
$$

and the limit fatigue design stress range, Formula (29), [6.5.4](#page-30-0):

$$
\Delta \sigma_{\text{Rd}} = f_1 \times f_2 \times \Delta \sigma_{\text{c}} = 226,27 \text{ N mm}^{-2}
$$

$$
s_{\mathbf{Q}} = kQ \times \frac{N}{N_{\mathbf{D}}}
$$

the load history parameter, Formula (26), 6.5.3, with $N_D = 2 \times 10^6$ reference number of cycles

$$
\Delta \sigma_c = 0,315 \times f_u \times \lg \left[\frac{13000}{f_u} \right] = 258,11 \text{ N mm}^{-2}
$$

and the limit fatigue design stress range, Formula (29), 6.5.4:

$$
\Delta \sigma_{\text{Rd}} = f_1 \times f_2 \times \Delta \sigma_c = 226,27 \text{ N mm}^{-2}
$$

$$
s_Q = kQ \times \frac{N}{N_D}
$$
the load history parameter, Formula (26), 6.5.3, with $N_D = 2 \times 10^6$ reference number of cycles

$$
N_D = 2 \times 10^6 \qquad s_Q = kQ \times \frac{N}{N_D} = 1
$$

$$
k_6^* = 1
$$

the specific spectrum ratio factor, Formula (28), [5.3,](#page-17-0) and [Table](#page-30-1) 5 for standardized classification

$$
S_{\rm h} = \frac{S_{\rm Q}}{\left(k_6^*\right)^m}
$$

the stress history factor, with $m = 6$ for hook bowl/material, Formula (27), [6.5.2,](#page-28-0) [6.5.3](#page-29-0)

$$
s_{\rm h} = \frac{s_{\rm Q}}{\left(k_6^*\right)^m} = 1
$$

F.2.3.2 Proof of competence for the fatigue strength of "non-proofed" hook

Inequality to be satisfied $[6.5.5,$ $[6.5.5,$ Formula (33)]:

$$
\Delta \sigma_{\text{Sd,max}} \le \frac{\Delta \sigma_{\text{Rd}}}{\gamma_{\text{Hf}} \times^m \sqrt{s_{\text{h}}}} \text{ or } \Delta \sigma_{\text{Sd,max}} \le \frac{k_6^* \times \Delta \sigma_{\text{Rd}}}{\gamma_{\text{Hf}} \times^m \sqrt{s_{\text{Q}}}}
$$

$$
\gamma_{\text{Hf}} = 1.25
$$

the fatigue strength resistance specific factor, see [Table 7](#page-32-0).

Hence:

$$
\Delta \sigma_{\text{Sd,max}} = 399,28 \text{ N mm}^{-2} \text{ vs. } \frac{\Delta \sigma_{\text{Rd}}}{\gamma_{\text{Hf}} \times m \sqrt{s_{\text{h}}}} = 181,01 \text{ N mm}^{-2}
$$

i.e. the inequality and hence also proof of fatigue strength for the load stated are not satisfied; either the load applied or life, in number of cycles, has to be reduced (from F_H or *N* of 2×10^6 cycles, resp.). $Y_{\text{HF}} = 1.25$

the fattgue strength resistance specific factor, see Table 7.

Hence:
 $\Delta \sigma_{\text{Sd,pax}} = 399.28 \text{ N mm}^{-2} \text{ vs. } \frac{\Delta \sigma_{\text{tot}}}{\gamma_{\text{H}} \times \frac{m}{\sqrt{3}} \text{ s}} = 181.01 \text{ N mm}^{-2}$

i.e. the inequality and hence also pro

Reduced hook load:

$$
F_{\text{H,red}} = F_{\text{H}} \times \frac{\Delta \sigma_{\text{Rd}}}{\gamma_{\text{Hf}} \times m \sqrt{s_{\text{h}}}} \times \frac{1}{\Delta \sigma_{\text{Sd,max}}} = 44,46 \text{ kN}
$$

Reduced life/number of cycles, can be calculated using Formulae (26) and (27).

F.2.3.3 Proof of competence for the fatigue strength of "proofed" hook

Inequality to be satisfied $[6.5.5,$ $[6.5.5,$ Formula (33)]:

$$
\Delta \sigma_{\text{Sd},\text{p,max}} \le \frac{\Delta \sigma_{\text{Rd}}}{\gamma_{\text{Hf}} \times^m \sqrt{s_{\text{h}}}} \text{ or } \Delta \sigma_{\text{Sd},\text{p,max}} \le \frac{k_{\text{G}}^* \times \Delta \sigma_{\text{Rd}}}{\gamma_{\text{Hf}} \times^m \sqrt{s_{\text{Q}}}}
$$

NOTE That there is no change on the R.H.S. of the inequality expression.

The limit fatigue design stress range:

$$
\Delta \sigma_{\text{Rd}} = 226,27 \text{ N mm}^{-2}
$$

load history parameter, Formula (26), 6.5.3, with $N_D = 2 \times 10^6$ reference number of cycles, $s_Q = 1$;

 $\kappa^*_{6}=$ 1 $\,$ the specific spectrum ratio factor, Formula (28), <u>6.5.3</u>, and <u>Table 5</u> for standardized classification;

 $s_h = 1$ the stress history factor, with $m = 6$ for hook/bowl material, Formula (27), [6.5.2](#page-28-0) and [6.5.3](#page-29-0);

$$
N_{\rm D}=2\ 000\ 000\ m=6;
$$

 $\gamma_{\text{Hf}} = 1.25$ the fatigue strength resistance specific factor, see [Table 7](#page-32-0).

Hence:

$$
\Delta \sigma_{\text{Sd,p,f,max}} = 331,77 \text{ N mm}^{-2} \text{ vs. } \frac{\Delta \sigma_{\text{Rd}}}{\gamma_{\text{Hf}} \times^m \sqrt{s_{\text{h}}}} = 181,01 \text{ N mm}^{-2}
$$

i.e. the inequality and hence also the proof of competence for fatigue for the load stated has not been satisfied; either the load applied or the life required, in number of cycles has to be reduced (from F_H or N of 2×10^6 cycles, resp.).

Reduced hook load:

$$
F_{\rm H,p,red} = F_{\rm H} \times \frac{\Delta \sigma_{\rm Rd}}{\gamma_{\rm Hf}^2 m v_{\rm S}^2} \times \frac{1}{\Delta \sigma_{\rm Sd,p,f,max}} = 53.5 \text{ kN}
$$

(compared to 44,5 kN for un-proofed hook)

Alternatively, reduced life/ number of cycles to satisfy the inequality above can be calculated, using Formulae (26) and (27).

Annex G (informative)

Sample set of hook shank and thread designs

G.1 A series of hook shank and thread designs, a knuckle thread

See [Figure](#page-67-1) G.1 and [Table](#page-67-2) G.1.

Key

1 hook shank

2 nut

Figure G.1 — Symbols of dimensions for hook shank and thread

The nut dimensions (*D* and *D*1) and the forged shank diameter (*d*1) are for guidance only. The shank machining and thread may be applied for any forged sizes and types within the requirements of this standard.

(d_1)	Thread designation	d_3	\boldsymbol{p}	d4	d_5	r ₉	S	$r_{\rm th}$	$r_{\rm p}$	t	\mathfrak{m}	(D)	(D_1)
212	$Rd180 \times 20$	180	20	156	158,0	12	60	4,42	3,07	11,0	160	182	160
236	$Rd200 \times 22$	200	22	173	175,8	12	70	4,86	3,38	12,1	180	202,2	178
265	Rd 225 \times 24	225	24	196	198,6	12	80	5,31	3,69	13,2	200	227.4	201
300	$Rd250 \times 28$	250	28	217	219,2	15	90	6,19	4,30	15,4	225	252,8	222
335	$Rd280 \times 32$	280	32	242	244.8	18	100	7,07	4,92	17,6	250	283,2	248
375	Rd 320 \times 36	320	36	278	280,4	20	110	7,96	5,53	19,8	280	323,6	284
	The nut dimensions (D and De) and the forged shank diameter (d_1) are for guidance only. The shank machining and thread												

Table G.1 *(continued)*

The nut dimensions (D and D_1) and the forged shank diameter (d_1) are for guidance only. The shank machining and thread may be applied for any forged sizes and types within the requirements of this standard.

G.2 A series of hook shank and thread designs, a metric thread

Key

1 hook shank

2 nut

Thread designation	d_3	p	d_4	d_5	r ₉	\mathcal{S}	r_{th}	\mathfrak{r}	m
M 10 \times 1,5	10	1,5	7,5	8,16	1,0	5	0,21	0,92	9
M 12 \times 1,75	12	1,75	9,0	9,85	1,2	6	0,25	1,07	11
M 14 \times 2	14	2	11,2	11,55	1,4	6	0,28	1,23	14
M 16 \times 2	16	2	12,5	13,55	1,2	$\overline{7}$	0,28	1,23	15
M 20 \times 2,5	20	2,5	16,6	16,93	1,6	8	0,35	1,53	18
M 24 \times 3	24	3	20,0	20,32	2,0	9	0,42	1,84	22
M 30 \times 3,5	30	3,5	25,4	25,71	2,0	11	0,49	2,15	27
M 33 \times 3,5	33	3,5	28,4	28,71	3,3	11	0,49	2,15	33
M 36 \times 4	36	$\overline{4}$	30,0	31,09	2,0	12	0,56	2,45	32
M 39 \times 4	39	$\overline{4}$	33,8	34,09	3,9	12	0,56	2,45	39
M 42 \times 4,5	42	4,5	36,2	36,48	3,0	13	0,63	2,76	36
M 45 \times 4,5	45	4,5	38,5	39,48	3,0	13	0,63	2,76	40
M 48 \times 5	48	5	41,6	41,87	4,8	15	0,70	3,07	48
M 52 \times 5	52	5	45,6	45,87	5,2	15	0,70	3,07	52
$M\,60 \times 5,5$	60	5,5	53,0	53,25	6,0	17	0,77	3,37	60
M 68 \times 6	68	6	60,3	60,64	6,8	18	0,84	3,68	68
M 72 \times 6	72	6	64,3	64,64	7,2	18	0,84	3,68	72
$M80 \times 6$	80	6	72,3	72,64	8,0	18	0,84	3,68	80
M 90 \times 6	90	6	82,3	82,64	9,0	18	0,84	3,68	90
M 100 \times 8	100	8	89,9	90,19	10,0	24	1,12	4,91	100
M 110 \times 8	110	$\, 8$	99,9	100,19	11,0	24	1,12	4,91	110

Table G.2 — Dimensions of hook shank and thread in millimetres (mm)

G.3 A series of hook shank and thread designs, a modified metric thread

Figure G.3 — Symbols of dimensions for a hook shank and thread

Key $\mathbf{1}$ 2	hook shank nut												
					Figure G.3 – Symbols of dimensions for a hook shank and thread								
					Table G.3 – Dimensions of hook shank and thread in millimetres (mm)								
(d_1)	Thread desig- nation	d_3	\boldsymbol{p}	d_4	D_5	r _q	S	r_{th}	t	m	(D)	(D_1)	(r_{th2})
60	ATS 52×5	52	5	46	46,587	10	15,41	1,083	2,71	43	52,361	47,670	0,361
67	ATS 56×5.5	56	5,5	50	50,046	11	18,41	1,191	2,98	48	56,396	51,237	0,397
	ATS 64×6	64	6	57	57,505	12	21,48	1,299	3,25	54	64,433	58,804	0,433
75		72	6	65	65,505	14	26,48	1,299	3,25	61	72,430	66,804	0,430
85	ATS 72 \times 6												
95	ATS 80×7	80	7	72	72,422	16	29,55	1,516	3,79	67	80,505	73,938	
106	ATS 90×7	90	7	82	82,422	19	34,55	1,516	3,79	77	90,505	83,938	0,505 0,505
118	ATS 100×8	100	8	91	91,340	20	37,61	1,732	4,33	85	100,577	93,072	0,577

(d_1)	Thread desig- nation	d_3	p	d4	D_5	r ₉	S	$r_{\rm th}$	t	m	(D)	(D_1)	(r_{th2})	(t_2)
132	ATS 110×8	110	8	101	101,340	22	42,61	1,732	4,33	96	110.577	103.072	0.577	3,75
150	ATS 125×10	125	10	113	114,175	25	46,82	2,165	5,41	106	125.722	116.340 0.722		4,69
170	ATS 140×10	140	10	128	129.175	28	56,82	2,165	5,41	120	140.722	131.340 0.722		4,69
190	ATS 160×12	160	12	146	147,010	32	62,95	2,598	6,50	134	160.866	149.608 0.866		5,63
212	ATS 180×12	180	12	166	167,010	36	72,95	2,598	6,50	154	180.866	169.608 0.866		5,63
236	ATS 200×14	200	14	183	184.845	40	77,16	3.031	7,58	170	201,000	187.876	1,01	6,56
265	ATS 225 \times 14	225	14	208	209.845	45	92,16	3.031	7,58	192		226.010 212.876	1.01	6,57
300	ATS 250×16	250	16	230	232,680	50	101.36	3.464	8,66	211	251.155	236.144	1.155	7,51
335	ATS 280×16	280	16	260	262,680	56	121,36	3.464	8,66	240	281,155	266.144	1.155	7,51
375	ATS 320×18	320	18	298	300,515	63	137,50	3,897	9,74	268	321.199	304.412	1.299	8,39

Table G.3 *(continued)*

The nut dimensions and the forged shank diameter (*d*1) are for guidance only. The shank machining and thread may be applied for any forged sizes and types within the requirements of this standard.

G.4 Hook shank and thread designs for hooks of type B

See [Figure](#page-71-1) G.4 and [Table](#page-72-0) G.4.

Figure G.4 — Symbols of dimensions for a hook shank and thread

NOTE Width of undercut, s, is measured from the shoulder of the shank to the crest of the last full thread.
Hook no.	d_2	Thread desig- nation	d_3	p	d_4	d_5	r ₉	S	r_{th}	t	r_{th} 11	m	
B 0.8	15	$M14 \times 2$	14	2	11,25	11,55	1,5	6	0,28	1,23	$\overline{2}$	14	
B 1.6	20	$M20 \times 2,5$	20	2,5	16,63	16,93	2	7,5	0,35	1,53	$\overline{2}$	20	
B2.5	25	$M24 \times 3$	24	3	20,02	20,32	2,5	9	0,42	1,84	3	24	
B 4	30	$M30 \times 3,5$	30	3,5	25,41	25,71	3	10,5	0,49	2,15	3	30	
B 5	35	$M33 \times 3,5$	33	3,5	28,41	28,71	3,5	10,5	0,49	2,15	$\overline{4}$	33	
B 6.3	40	$M39 \times 4$	39	$\overline{4}$	33,79	34,09	$\overline{4}$	12	0,56	2,45	$\overline{4}$	39	
B 8	45	$M42 \times 4,5$	42	4,5	36,18	36,48	4,5	13,5	0,63	2,76	5	42	
B 10	50	$M48 \times 5$	48	5	41,57	41,87	5	15	0,7	3,07	5	48	
B 12.5	55	$M52 \times 5$	52	5	45,57	45,87	5,5	15	0,7	3,07	6	52	
B 16	60	$M60 \times 5,5$	60	5,5	52,95	53,25	6	16,5	0,77	3,37	6	60	
B20	70	$M68 \times 6$	68	6	60,34	60,64	7	18	0,84	3,68	$\overline{7}$	70	
B25	80	$M72 \times 6$	72	6	64,34	64,64	8	18	0,84	3,68	8	72	
B 32	85	$M80 \times 6$	80	6	72,34	72,64	8,5	18	0.84	3,68	9	80	
B 40	100	M 90 \times 6	90	6	82,34	82,64	10	18	0,84	3,68	10	90	
B 50	110	$M100 \times 8$	100	8	89,89	90,19	11	24	1,12	4,91	11	100	
B63	120	$M110 \times 8$	110	8	99,89	100,19	12	24	1,12	4,91	12	110	
	NOTE 1 For an explanation of dimension e_1 see $\underline{A.3}$.												
	NOTE 2 Width of undercut s is measured from the shoulder of the shank to the crest of the last full thread.												

Table G.4 — Dimensions of hook shank and thread in millimetres (mm)

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Annex H (normative)

Bending of curved beams

H.1 Basic equations for stresses

The stresses calculated below represent true primary tensile stresses in the cross section of a curved beam, derived from the theory of elasticity and with the assumption of no plastic behaviour of material.

The equations below are in a general format of equations for a curved beam and they apply to an analogous problem of stress distribution in a cross section of the curved part of the hook bowl body. The designations refer to [Figure](#page-73-0) H.1.

Figure H.1 — Symbols for curved beam bending calculation

For a curved beam with a solid section, a reference moment of inertia shall be calculated as follows:

$$
I = \int_{-\eta_1}^{+\eta_2} \frac{y^2 \times b(y)}{1 + \frac{y}{R}} dy
$$
 (H.1)

where

- *y* is the distance in radial direction, measured from the centroid of cross section; taken as positive between the centroid and the extrados of the section and negative between the intrados and centroid of the section;
- *b* is the width of the section at a location *y*;
- *R* is the radius of curvature of centroid axis of the curved beam at the cross section under consideration;
- *η*¹ is the absolute value of the coordinate *y* at the inside radius;
- *η*² is the absolute value of the coordinate *y* at the outside radius.

The maximum tensile stress *σ* in the cross section shown is at the intrados and shall be calculated as follows:

$$
\sigma = \frac{F \times R \times \eta_1}{I} \times \frac{1}{1 - \eta_1/R} \tag{H.2}
$$

where

- *F* is the force acting perpendicularly to the plane of the section and through the centre of the curvature;
- *R* is the radius of curvature of centroid axis of the hook bowl at the cross section under consideration;
- *η*¹ is the absolute value of the coordinate *y* at the intrados;
- *I* is the a reference moment of inertia of the section in accordance with Equation (H.1).

NOTE Equation (H.2) contains the combined effect of direct tension and bending moment. The equation is only valid in the case where the force causing the bending acts through the centre of the beam curvature. Under such a loading configuration the neutral axis coincides with the centroid of the section.

H.2 Approximation of the reference moment of inertia

The reference moment of inertia of a curved beam shall be expressed and calculated as follows:

I is the a reference moment of inertia of the section in accordance with Equation (H.1).
\nNOTE Equation (H.2) contains the combined effect of direct tension and bending moment. The equation is
\nonly valid in the case where the force causing the bending acts through the centre of the beam curvature. Under
\nsuch a loading configuration the neutral axis coincides with the centroid of the section.
\nH.2 Approximation of the reference moment of inertia
\nThe reference moment of inertia of a curved beam shall be expressed and calculated as follows:
\n
$$
I = k \times I_2 = k \times \int_{-71}^{+72} y^2 \times b(y) \times dy
$$
 (H.3)
\nwhere
\n I_2 is the conventional moment of inertia of the section about the z-axis;
\n*k* is a conversion factor depending of the shape of the section and the relative curvature, see
\nFigure H.2.
\n**Conviety Mannations** Consider a
\n**Corro** equation shows that the velocity of the velocity of the velocity.

where

- *I*^z is the conventional moment of inertia of the section about the z-axis;
- *k* is a conversion factor depending of the shape of the section and the relative curvature, see [Figure](#page-75-0) H.2.

with 0,45 < *b*min/*b*max < 0,55, where *b*max is the larger, inner edge width of the section and *b*min is the smaller, outer edge width of the section.

Figure H.2 — Factor k for a selection of section types

Key

- 1 rectangular section
- 2 circular and rounded sections
- 3 trapezoidal section

Annex I (normative)

Calculation of hook suspension tilting resistance, articulation by a hinge or rope reeving system

I.1 General

The hook tilting resistance factor C_t represents the friction in the hook suspension resisting the tilting of the hook. It is a characteristic of the suspension only and its value is independent upon external loadings. The factor C_t is defined through Equation (I.1) as follows:

$$
C_{t} = \frac{M}{F}
$$
 (1.1)

where

- C_t is the hook tilting resistance factor;
- *M* is the moment resisting the tilting movement of the hook, see [Figure](#page-76-0) I.1;
- *F* is the vertical force acting on the hook.

Key

β direction of the tilting movement

Figure I.1 — General presentation of hook tilting resistance

I.2 Articulation of hook by a hinge

See [Figure](#page-77-0) I.2.

Figure I.2 — A hook suspension with a hook articulation by a hinge

Rope reeving system is such that the hook suspension stays horizontal, when the hook is tilted along the load line. Tilting resistance factor is calculated as follows:

$$
C_{t} = \frac{M}{F} = \mu \times \frac{d_{h}}{2} \tag{I.2}
$$

where

- *d*^h is the diameter of the sliding surface of the hinge;
- μ is the friction in the hinge, to be taken as follows:

 μ = 0,1 for non-grease able, special coated bearing bushings;

 μ = 0,25 for re-grease able, bronze/steel bearing bushings;

 μ = 0,4 for non-grease able steel/steel hinges;

 μ = 0 (zero) for hinges with anti-friction bearings.

As the tilting resistance is significant for the fatigue of the hook shank, the friction figures represent long term values to be expected in practice. This shall be taken into consideration, if the friction values should be based upon tests. *μ* = 0,1 for non-grease able, special coated bearing bushings;
 μ = 0,25 for re-grease able, bronze/steel bearing bushings;
 μ = 0,4 for non-grease able steel/steel hinges;
 μ = 0 (zero) for hinges with anti-fr

I.3 Articulation of a hook suspension by a balanced rope reeving

Due to a wide variety of possible configurations, an example only is given here, i.e. the calculation of the resistance factor for an eight-fall rope system.

In a balanced rope reeving system, for example that shown in [Figure](#page-78-0) I.3, differential tensions are generated within the individual rope falls due to sheave losses, when the hook suspension is tilted e.g. due to a horizontal force on the hook.

The sample reeving system assumes:

- a) symmetry about the hook centre line;
- b) sheaves are similar except that the middle sheave has a different efficiency than the others.

Key

- *β* direction of tilting
- *h* distance from the hook seat to the centre of the articulation
- H horizontal force causing the tilting

Figure I.3 — An example of a rope reeving system

When the hook suspension is tilted, maximum force is generated in rope fall no. 1, minimum force in fall no. 8, and the rope forces fulfil a relationship as depicted within [Table](#page-78-1) I.1.

Table I.1 — Rope forces in a tilted condition

where

- R_1 is the force in rope fall no. 1, the extreme rope on the descending side of the reeving;
- *η* is the efficiency of a basic sheave;
- *η*^B is the efficiency of the middle sheave.

Equilibrium condition in vertical direction presumes that the sum of the rope forces equals to the vertical force acting on the hook. From this we can derive Equation (I.3) for the rope force R1.

$$
R_1 = \frac{F}{1 + \eta + \eta^2 + \eta^3 + \eta_B \times \eta^3 + \eta_B \times \eta^4 + \eta_B \times \eta^5 + \eta_B \times \eta^6}
$$
(I.3)

where *F* is the vertical force acting on the hook.

The other rope forces *Ri* are derived based upon Equation (I.3) and the equations in [Table](#page-78-1) I.1. Forces *Rⁱ* combine with distances *ei* and generate a turning moment about the central vertical axis; this moment is derived as per Equation (I.4):

$$
M = \sum_{i=1}^{8} R_i \times e_i \tag{I.4}
$$

where e_i is the horizontal coordinate of the rope (i) from the hook suspension centre. Coordinates are taken positive on the descending side of the hook suspension, see [Figure](#page-78-0) I.3.

By placing the contents of [Table](#page-78-1) I.1 and Equation (I.3) to Equation (I.4), we get finally the tilting resistance *C*_t for this specific rope reeving system as follows:

$$
C_{\rm t} = \frac{M}{F} = \frac{e_{\rm B} \times (1 + \eta - \eta_B \times \eta^5 - \eta_B \times \eta^6) + e_{\rm A} \times (\eta^2 + \eta^3 - \eta_B \times \eta^4 - \eta_B \times \eta^4)}{1 + \eta + \eta^2 + \eta^3 + \eta_B \times \eta^5 + \eta_B \times \eta^6 + \eta_B \times \eta^6}
$$
\n(1.5)
\nwhere $\vec{e}_{\rm A}$ and $e_{\rm B}$ are the horizontal distances of the sheaves from the hook suspension centre, see
\nFigure 1.3.
\n
$$
\sum_{\text{Poisson} \text{ is the same at the point of the body}} \frac{\sqrt{2} \times (1 + \eta - \eta_B \times \eta^5 - \eta_B \times \eta^4)}{2}
$$
\n(1.5)

where e_A and e_B are the horizontal distances of the sheaves from the hook suspension centre, see [Figure](#page-78-0) I.3.

Annex J (informative)

Guidance for selection of hook size using [Annexes](#page-53-0) C to [E](#page-57-0)

J.1 General

In cases where a hook body in accordance with [Annex](#page-44-0) A or B is used, the proofs of static and fatigue strength of the hook body can be done using the limit design forces in [Annexes](#page-53-0) C and [D.](#page-55-0)

Additionally, the proof of competence for the machined shank with a chosen design shall be carried out in accordance with appropriate sub-clauses in [Clauses](#page-16-0) 5 and [6.](#page-25-0)

All the assessments, choices of values and conclusions concerning the case specific loads and factors are given as an example only. Those shall not be considered as a general guidance for the same.

J.2 Case description

Search for a minimum size hook for the following case:

- mass of the rated load of the crane/hook: m_{RC} = 50 t;
- governing load factor $φ$: $φ_2$ = 1,21;
- operating temperature for the hook: *T* = 150 °C;
- governing load case is regular loads: *γ*_p = 1,34;
- normal crane application, the risk factor: $γ_n = 1$;
- chosen to use a single hook from Δ nnex A;
- chosen to use the material class T:
- the use of the crane is specified through the classification as follows: number of cycles in accordance with class U_5 and load spectrum class Q_4 .

J.3 Proof of static strength

Starting point is the condition given in Formula (16). The influence factor f_1 for the operation temperature is calculated in accordance with Formula (15):

$$
f_1 = 1 - 0.25 \times (T - 100) / 150 = 0.9167
$$
\n(J.1)

The minimum, required static limit design force of the hook can be written, based upon Formulae (1) and (16) as follows:

$$
F_{\rm Rd,s} \ge \frac{F_{\rm Sd,s}}{f_1} = \frac{\varphi_2 \times m_{\rm RC} \times g \times \gamma_{\rm p} \times \gamma_{\rm n}}{f_1} = \frac{1,21 \times 50 \times 9,81 \times 1,34}{0,9167} = 868 \quad [\text{kN}]
$$
 (J.2)

The hook is then searched from [Table](#page-53-1) C.1 from the material column "T". The hook number 16 has a static limit design force $F_{\text{Rd},s}$ = 963 kN, which fulfils the requirement in Equation (J.2).

J.4 Proof of fatigue strength

Starting point is the condition given in Formula (35). The influence factor f_1 for the operation temperature is calculated in accordance with Formula (31):

$$
f_1 = 1 - 0.1 \times (T - 100) / 150 = 0.967
$$
 (J.3)

The value for the conversion factor k_C is found from [Annex](#page-57-0) E at intersection of row U5 and column $Q₄$.

$$
k_{\rm C} = k_6 \sqrt[4]{\sqrt[6]{s_{\rm Q}}} = 1.53 \tag{J.4}
$$

The minimum, required fatigue limit design force of the hook can be written, based upon Formulae (18) and (35) as follows:

$$
F_{\rm Rd,f} \ge \frac{F_{\rm Sd,f}}{f_1 \times \left(\frac{k_6}{m} \right)^*} = \frac{\varphi_2 \times m_{\rm RC} \times g}{f_1 \times k_{\rm C}} = \frac{1,21 \times 50 \times 9,81}{0,967 \times 1,53} = 401 \quad \text{[kN]}
$$
(J.5)

The hook is then searched from <u>[Table](#page-55-1) D.1</u> from the material column "T". The hook number 25 has a fatigue limit design force $F_{\text{Rd,f}}$ = 420 kN, which fulfils the requirement in Formula (J.5).

J.5 Final selection of hook

The selection of hook body shall meet both design criteria for static and fatigue strength. Consequently, the larger of the resulting hooks in 1.3 and 1.4 shall be chosen. For this case the minimum single hook of those in [Annex](#page-44-0) A is the hook number 25, of material class T.

The final selection of the hook, which depends on the detailed shank design, shall have to take into account also the results of calculations in accordance with [Clauses](#page-16-0) 5 and [6](#page-25-0).

Annex K (normative)

Information to be provided by the hook manufacturer

The hook manufacturer shall provide the following information for the technical file of the crane.

Bibliography

- [1] DIN 15400, *Lifting hooks; materials, mechanical properties, lifting capacity and stresses*
- [2] BS 2903, *Specification for higher tensile steel hooks for chains, slings, blocks and general engineering purposes* 1)

¹⁾ Withdrawn. Replaced by [BS EN 1677-5:2001+A1:2008](http://shop.bsigroup.com/ProductDetail/?pid=000000000030188389).

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