INTERNATIONAL STANDARD

ISO 11892

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Space systems — Subsystems/units to spacecraft interface control document

Systèmes spatiaux — Document de contrôle des interfaces entre les sous-systèmes/unités et le véhicule spatial



ISO 11892:2012(E)



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6.2

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 2.

The main task of technical committees is to prepare International Standards. Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights.

ISO 11892 was prepared by Technical Committee ISO/TC 20, Aircraft and space vehicles, Subcommittee SC 14, Space systems and operations.

Space systems — Subsystems/units to spacecraft interface control document

1 Scope

This International Standard provides space system manufacturing organizations with the minimum interface related items and generic format for creating the interface control document (ICD) which subsystems or units suppliers prepare for spacecraft systems (SC) integrators.

In this International Standard, ICD is not defined to contain descriptions regarding various properties of subsystems or units or tasks to be done by suppliers, i.e. performance, functions, endurance to launch mechanical environment, or quality assurance provisions. Such descriptions are presumed to be defined in other contractual documents such as technical specifications.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendment) applies.

ISO 15864:2004, Space systems — General test methods for space craft, subsystems and units

3 Terms, definitions and abbreviated terms

3.1 Terms and definitions

3.1.1

subsystem

assembly or group of electrical, thermal and/or mechanical units which is dedicated to specific functions of a spacecraft system (SC)

3.1.2

unit

independently handled device at the lowest level of hardware assembly that works with specified complex electrical, thermal and/or mechanical functions

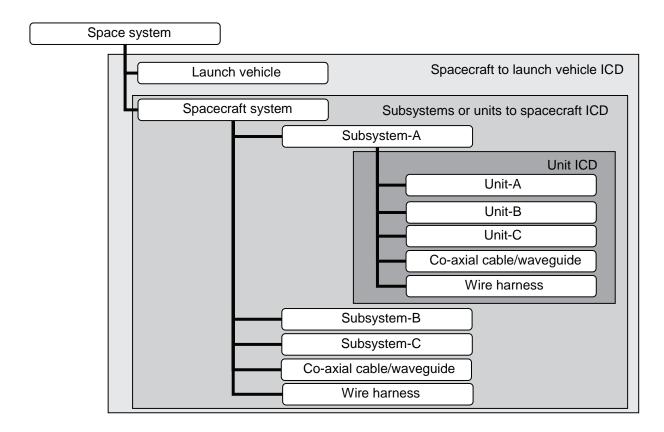
NOTE Several units build up a subsystem. A single unit may occasionally comprise a subsystem by itself.

3.1.3

subsystems/units to spacecraft interface control document

set of documents that defines and controls the electrical, thermal, and mechanical interface requirements between a subsystem and the spacecraft system (SC)

NOTE Figure 1 illustrates the hierarchy of a space system and the ranges where various interface control documents are applicable.



Hierarchy of a space system and related interface control document (ICD)

Abbreviated terms

CAD computer aided design

interface control document ICD

IDS interface data sheet

moment of inertia MOI

RF radio frequency

Subsystem to spacecraft ICD

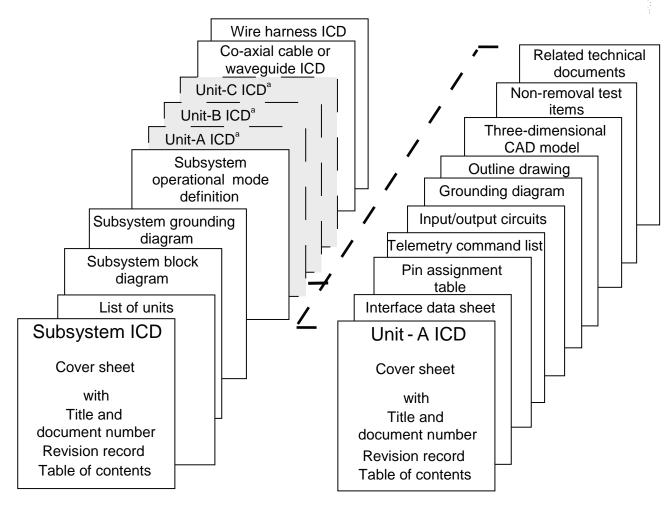
4.1 General

A subsystem ICD is a package constructed of sub-documents as shown in Table 1. It shall contain configuration control information, subsystem definition diagrams, and if applicable, co-axial cable or waveguide or wire harness in the subsystem. An individual ICD of each unit in the subsystem is normally a separate document. However, it may be contained as part of the subsystem ICD.

Layered construction of a subsystem ICD package is illustrated in Figure 2.

Construction of subsystem to spacecraft ICD package

No	Title	Description (Subclause)
1	Cover sheet (with title and document number, revision record and table of contents)	4.2
2	Applicability	4.3
3	List of units	4.4
4	Subsystem block diagram	4.5
5	Subsystem grounding diagram	4.6
6	Subsystem operational mode definition (if applicable)	4.7
7	Unit ICD (if applicable)	4.8
8	Co-axial cable or waveguide ICD (if applicable)	4.9
9	Wire harness ICD (if applicable)	4.10



a The individual ICD of each unit may be contained as a part of the subsystem ICD.

Layered construction of subsystem ICD package

4.2 Cover sheet

4.2.1 Title and document number

The cover sheet	of the subsystem	ICD shall contain	the following items:

- title of the subsystem ICD package;
- document number of the ICD package;
- issue date;
- issuing organization.

4.2.2 Revision record

The revision record shall contain the following items:

- revision number;
- revision date;
- summary of revision contents;
- authorization.

4.2.3 Table of contents

The table of contents shall indicate the name, document number and revision number of the following subdocuments which build up the subsystem ICD:

- list of units;
- subsystem block diagram;
- subsystem grounding diagram;
- subsystem operational mode definition (if applicable);
- unit ICD (if applicable);
- co-axial cable or waveguide ICD (if applicable);
- wire harness ICD (if applicable);
- non-removal test items (if applicable).

Applicability 4.3

The following information shall be addressed in the ICD:

- applicable documents;
- definitions;
- physical units.

List of units

The list of units shall contain all units included in the subsystem, including the co-axial cable or waveguide and/or wire harness provided to the spacecraft system by the subsystem organization. The list of units shall include the document number and revision record of each unit ICD if it is a separate document.

4.5 Subsystem block diagram

The subsystem block diagram shall graphically indicate the connection and relationship of all of the units included in the subsystem. The subsystem block diagram shall also show the connection and relationship between the subsystem and other relevant subsystems.

4.6 Subsystem grounding diagram

The subsystem grounding diagram shall graphically indicate the grounding and bonding configuration of all the units included in the subsystem.

4.7 Subsystem operational mode definition (if applicable)

The subsystem operational mode definition shall indicate all of the operational modes of the subsystem if applicable.

For this International Standard, "operational mode" is defined as any operational status which has different power consumption or heat dissipation from another status. Operational modes can also be differentiated by mechanical configurations, e.g. before and after deployment.

The definition shall also describe whether transition to the designated mode is caused by the subsystem itself or by a trigger from another subsystem.

4.8 Unit ICD (if applicable)

The unit ICD shall show the interface information of each unit contained in the subsystem. Details are defined in Clause 5.

4.9 Co-axial cable or waveguide ICD (if applicable)

The co-axial cable or waveguide ICD shall show the interface information of the co-axial cable or waveguide connecting the units in the subsystem or connecting the units to other subsystems.

4.10 Wire harness ICD (if applicable)

The wire harness ICD shall show the interface information of the wire harness connecting the units in the subsystem or connecting the units to other subsystems.

5 Unit ICD in detail

5.1 General

A unit ICD is a document package constructed from a sub-document as shown in Table 2.

Construction of unit ICD package

No	Title	Description (Subclause)
1	Cover sheet (with title and document number, revision record and table of contents)	5.2
2	Interface data sheet (IDS)	5.3
3	Pin assignment table	5.4
4	Telemetry command list	5.5
5	Input/output circuits	5.6
6	Grounding diagram	5.7
7	Outline drawing	5.8
8	Three-dimensional CAD model (if applicable)	5.9
9	Non-removal test items (if applicable)	5.10
10	Related technical documents (if applicable)	5.11

5.2 Cover sheet

5.2.1 Title and document number

The cover sheet of a unit ICD shall contain the following items:

- title of the unit ICD package;
- document number and revision of the ICD package;
- issue date;
- issuing organization.

5.2.2 Revision record

The revision record shall contain the following items:

- revision number;
- revision date;
- summary of revision contents;
- authorization.

5.2.3 Table of contents

The table of contents shall indicate the name, document number and revision number of each sub-document which builds up the unit ICD:

- interface data sheet;
- pin assignment table;
- telemetry command list;
- input/output circuits;
- grounding diagram;
- outline drawing;

- photographs (if applicable);
- three-dimensional CAD model (if applicable);
- structure mathematical model (if applicable);
- thermal mathematical model (if applicable);
- appendix.

5.3 Interface data sheet (IDS)

Each interface item shall be given in the standard tabular format. A sample is shown in Table 3.

If the description is expressed with a drawing, figure or separate document, the ID number shall be listed.

Values shall be given with appropriate tolerances reflecting design maturity.

Interface data sheet (IDS) - Example

Name	Full name of the unit			Part number	Part num	art number of the unit	
Acronym	Abbreviation of unit name			Revision	the table		
Category	No	Item	Description			Notes	
Mechanical	1	Identification		scribe identification marking the unit. Indicate location of el.		Refer to drawing	
	2	Physical configuration		licate the physical configura	In drawing		
	3	Dynamic envelope (volume)		licate the envelope affected rations, acoustic influence,		In drawing	
	4	External surface finish	1	scribe surface finish of exterface except for mounting su		Refer to drawing	
	5	Mounting surface finish		scribe surface finish of mou face.	nting		
	6	Mounting surface roughness		scribe roughness of mounting	ng		
	7	Mounting surface flatness	De	scribe flatness of mounting	surface.		
			Describe material of chassis, and connectors if they use non-standard materials.		May refer to declared material list if available		
	9	Thickness of mounting foot	De foo	scribe the thickness of mou	nting	Refer to drawing	
	10	Key hole location	Indicate the key (datum) hole location.			In drawing	
	11	Mounting hole location		licate the mounting hole loca	ation and	In drawing	
	12	Fastener	De	scribe the type of fastener.			
	13	Fastener torque	De	scribe fastener torque with t	olerance.	Unit: Nm	
	14	Coordination system	De uni	scribe the coordination syst t.	em of the		
	15	Mounting requirement		scribe specific requirements unting, e.g. alignment.	s for		
	16	Stiffness	nat	scribe the lowest fundamen tural frequency in mounted ofiguration, for each axis if r		Unit: Hz	
	17	Mass	De	scribe mass with tolerance.		Unit: kg	
	18	Center of mass location	Ind	licate the location of centre	of mass.	In drawing	
	19	Mass properties	of i	scribe product of inertia and nertia (MOI) for each axis the ntre of mass with tolerance.		Unit: kg/m ²	

Name	Full name of the unit			Part number	Part num	ber of the unit
Acronym	Abbreviation of unit name Revision Issue of				Issue of t	he table
Category	No	Item	De	scription		Notes
Electrical	20	Radio frequency (RF) input/output connector	Indicate location and ID of RF connectors. Show pin assignment list as defined in Table 4.		In drawing	
	21 Grounding/bonding point Indicate location of the grounding or bonding point where continuity check will be made. 22 Non-RF input/output connector Indicate location and ID of non-RF connectors. Show pin assignment list as defined in Table 4. 23 Operational modes Describe operational modes defining power consumption and heat dissipation.		bor	bonding point where continuity check		In drawing
				In drawing		
			efining			
24 Power consumption Describe power consumption in each operational mode with tolerance. Provide maximum and minimum value considering input voltage variation and temperature. Indicate time variation, if applicable.		ce. m values ition and	Unit: W Refer to 2D plot for time variation			
	25	RF power	mo and var	scribe RF power in each op de with tolerance. Provide r d minimum values consideri iation. Indicate time variatio blicable.	maximum ng power	Unit: W or W/m ²

Name Full name of the ur		name of the unit		Part number	Part num	ber of the unit	
Acronym	Abbreviation of unit name			Revision Issue of the		he table	
Category	No	Item	De	scription		Notes	
Thermal	26	Contact area		Describe mounting surface contact		Unit: mm ²	
				area.		Refer to drawing or photograph	
	27	Heat dissipation		scribe heat dissipation		Unit: W	
			Pro	operational mode with tolerance. Provide maximum and minimum values considering input voltage and		Refer to 2D plot for time variation	
	28 Heat flow rate den			temperature. Indicate time variation, if applicable.		Refer to figure or drawing for localization	
			hea	icate the different loca at dissipation (e.g. with units).			
		Heat flow rate density	mo	scribe heat flow rate de unting interface. Indica ation in drawing if requ	ate heat spot	Unit: W/m ²	
	29	Heat capacity	De	Describe heat capacity of the unit.		Unit: J/°C	
	30	0 Allowable temperature		Describe allowable temperature		Unit: °C	
		range	and	ge in non-operational, d start up (with qualifica ceptance limits).		Refer to separate table if complicated	
				scribe allowable limits chanical loads if applic			
	31	Allowable temperature transition rate		scribe allowable tempensition rate.	erature	Unit: °C/min	
	32	Temperature reference point		icate location where al		In drawing	
	33	Temperature sensor location		icate location of tempensor(s).	erature	In drawing	

Name	Full name of the unit			Part number	Part num	ber of the unit
Acronym	Abbreviation of unit name			Revision	Issue of the table	
Category	No	Item	Des	scription	Notes	
Thermal	34	Temperature sensor type	Des	scribe type of temperature s	sensor.	
	35	Interface temperature	Define temperature range of the spacecraft structure where unit is mounted.			
		te		ine requirements for interfa perature stability and interf perature homogeneity if ap	face	
	36	Emissivity		scribe the emissivity of exte		Refer to separate table
				sh. Clarify whether value is nispherical or normal emiss		Refer to 2D plot, drawing and photograph if
		 	area (be	Describe name/reference of the finish, area, temperature variation, ageing (beginning of life/end of life) and specularity.		applicable.
	37	Absorptivity		Describe the solar absorptivity of		Refer to separate table
			1	ernal finish, if unit is expose ce environment.	ed to	Refer to 2D plot, drawing and photograph if
	Describe name/reference of the finish area, temperature variation, ageing (beginning of life/end of life) and specularity.		geing	applicable.		
	38	Active thermal control characteristics	the	scribe the characteristics of rmal control, such as therm trolled heaters, thermo elec- lers or cryogenic coolers.	ostat-	Refer to drawing, figure or photograph if applicable.
				scribe temperature stability nogeneity if applicable.	and	
	39	Passive thermal control characteristics	the	scribe the characteristics of rmal control, e.g. multi-laye ulations, thermal insulating rmal straps etc.	r [']	Refer to drawing, figure or photograph if applicable.
				scribe temperature stability nogeneity if applicable.	and	

Name	Full name of the unit		Full name of the unit Part number Part number		Part num	mber of the unit	
Acronym	Abbr	eviation of unit name	Revision	Issue of the table			
Category	No	Item	Description	Notes			
Misc.	40	Envelope for deployable portion		Indicate the envelope of the deployable elements of the unit in drawings.			
	41	Deployable characteristics	Describe the dynamic disturbance of the deployable elements.				
	42	Field of view	Indicate the field of view of the drawings.				
	43	Rotor characteristics	Describe the dynamic charact of rotating elements, e.g. mass axis, MOI.				
	44	Structure mathematical model	Indicate the document numbe applicable.	r if			
			The model shall be submitted another package or electronic				
	45	Thermal mathematical model	Indicate the document numbe applicable.	r if			
ĺ			The model shall be submitted in another package or electronically.				
	46	Polarity	Describe specific requirement regarding polarity and direction shall be managed by the SC in	on, which			
			Definition of geometrical directions of attitude ser their relationship with signal polarity;	sors, and			
			Definition of geometri and directions of moving or rotating object, a relationship with electric characteristics;	g element and their			
			Definition of geometri and directions of attitude actuators, and their rewith drive signals;	de control			
			 Relationship between positions and drive signa 				
	47	Standard signal interface	Define major frame rate and m frame rate.	ninor			
	48	Electromagnetic compatibility	Indicate electrical and magnet within which units stay at their functional performance.		For particularly sensitive units		
	49	Mechanical stay-out zone or authorised zone	Indicate stay-out zone or auth- zone for integration at higher I flight/test hardware (e.g. therm subsystem components as ter sensors, heaters or multi-layer insulations, etc.).	evels of nal control nperature	In drawing		

5.4 Pin assignment table

The pin assignment table of RF and non-RF connectors shall show the pin assignment and characteristics of the signals of each connector in the unit. A sample is shown in Table 4.

Pin assignment table — Example

No	Item	Description	Notes
1	Connector ID	Define connector ID	
2	Туре	Describe connector type	
3	Product name	Describe commercial product name	
4	Pin number	Describe pin number	
5	Full name of signal	Describe full name of signal	
6	Acronym for signal	Describe abbreviated name of signal	
7	Type of signal	Describe type of signal (e.g. analog, digital, pulse)	
8	Wire gauge	Describe wire gauge (AWG) within unit	
9	Current	Describe current	Unit: mA
10	Voltage	Describe voltage	Unit: V
11	Input or output	Designate input or output	
12	Frequency or bit rate	Describe frequency or bit rate of the signal	
13	Interface circuit	Designate interface circuit defined in 5.6	
14	HOT/Return pairing information	Describe pairing HOT or Return pin number, if applicable	
15	Requirement for harness	Describe requirement for harness (shielding, twisting, etc.)	
16	Redundant connection type	Define redundant connection type (e.g. single, wired or cross strap)	
17	Redundant pairing information	Describe pairing redundant pin number if applicable	
18	Destination	Define connection destination	
19	Notes	Describe special requirements or notifications	
20	Resistance to grounding	Describe insulation resistance of wires against grounding if applicable	Unit: M Ohm

5.5 Telemetry command list

This section shall show a tabular list which describes the following characteristics of the telemetry and commands for the unit:

- ID number;
- abbreviated name;
- signal type;
- packet length;
- description.

5.6 Input/output circuits

This section of the ICD shall show the simplified full schematic diagram of each input/output interface circuit.

Detailed schematics shall show full components reference, internal power supply range and RLC figures.

5.7 **Grounding diagram**

This section shall show a simplified schematic diagram which illustrates the grounding and bonding connections of the unit.

Outline drawing

This section of the ICD shall show configuration drawings of the unit, which show and define the following physical characteristics of the unit with appropriate tolerances reflecting design maturity:

- outline dimensions with maximum envelope;
- mounting hole location, size and quantity;
- mounting footprint;
- mounting foot thickness;
- location of identification marking;
- location of centre of mass:
- location and orientation of connectors with pin#1 location;
- location of temperature reference point;
- location of temperature sensors;
- location of venting holes;
- location of ground path;
- field of view (if applicable);
- coordinate axes definition;
- mechanical stay-out or authorised zones;
- external surface finishes of major exposed parts.

Three-dimensional CAD model (if applicable)

This section shall describe the three-dimensional CAD model of the unit. The model shall be submitted in another package or electronically.

An example of the model data format is the STEP format defined in ISO 10303-203.

5.10 Non-removal test items (if applicable)

This section shall describe non-removal test items as interface information, if applicable. Non-removal test items are the test devices left in flight hardware after use, e.g. thermocouples, strain gauges and accelerometers installed inside the unit. They shall be indentified in the ICD and inhibited or disabled after use if applicable.

5.11 Related technical documents (if applicable)

This section shall describe the related technical documents used to draft the ICD, if applicable, such as the design basis of ICD, analysis documents of products etc.

6 Verification

6.1 General

Each subsystem or unit provider shall provide the SC integrator with the documents necessary to assure compliance of the deliverable hardware with the ICD.

6.2 Verification method

In principle, all the items described in the ICD shall be verified. The verification methods shall be inspection, test or analysis, depending on each item. The basic physical characteristics such as physical dimensions shall be measured. However, complex physical characteristics, such as MOI, may be verified by analysis based on measurements. General requirements for testing and inspection are defined in ISO 15864.

Bibliography

[1] ISO 10303-203, Industrial automation systems and integration — Product data representation and exchange — Part 203: Application protocol: Configuration controlled 3D design of mechanical parts and assemblies

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