

# Earth-moving machinery — Dumpers — Terminology and commercial specifications

ICS 01.040.53; 53.100

## National foreword

This British Standard reproduces verbatim ISO 7132:2003 and implements it as the UK national standard. It supersedes BS 6914-4:1990 which is withdrawn.

The UK participation in its preparation was entrusted by Technical Committee B/513, Construction equipment and plant, and site safety, to Subcommittee B/513/1, Earth-moving machinery (International), which has the responsibility to:

- aid enquirers to understand the text;
- present to the responsible international/European committee any enquiries on the interpretation, or proposals for change, and keep the UK interests informed;
- monitor related international and European developments and promulgate them in the UK.

A list of organizations represented on this subcommittee can be obtained on request to its secretary.

### Cross-references

The British Standards which implement international publications referred to in this document may be found in the *BSI Catalogue* under the section entitled “International Standards Correspondence Index”, or by using the “Search” facility of the *BSI Electronic Catalogue* or of British Standards Online.

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### Summary of pages

This document comprises a front cover, an inside front cover, the ISO title page, pages ii to iv, pages 1 to 28, an inside back cover and a back cover.

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**ISO**  
**7132**

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**Earth-moving machinery — Dumpers —  
Terminology and commercial  
specifications**

*Engins de terrassement — Tombereaux — Terminologie et  
spécifications commerciales*



Reference number  
ISO 7132:2003(E)



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## Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 2.

The main task of technical committees is to prepare International Standards. Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights.

ISO 7132 was prepared by Technical Committee ISO/TC 127, *Earth-moving machinery*, Subcommittee SC 4, *Commercial nomenclature, classification and rating*.

This third edition cancels and replaces the second edition (ISO 7132:1990), which has been technically revised.

# Earth-moving machinery — Dumpers — Terminology and commercial specifications

## 1 Scope

This International Standard establishes a terminology for, and the content of, commercial literature specifications for self-propelled dumpers (including compact dumpers), as defined in ISO 6165, used in earth moving.

## 2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 3450, *Earth-moving machinery — Braking systems of rubber-tyred machines — Systems and performance requirements and test procedures*

ISO 5010, *Earth-moving machinery — Rubber-tyred machines — Steering requirements*

ISO 6014:1986, *Earth-moving machinery — Determination of ground speed*

ISO 6016:1998, *Earth-moving machinery — Methods of measuring the masses of whole machines, their equipment and components*

ISO 6165, *Earth-moving machinery — Basic types — Vocabulary*

ISO 6483:1980, *Earth-moving machinery — Dumper bodies — Volumetric rating*

ISO 6746-1, *Earth-moving machinery — Definitions of dimensions and codes — Part 1: Base machine*

ISO 7457:1997, *Earth-moving machinery — Determination of turning dimensions of wheeled machines*

ISO 9249:1997, *Earth-moving machinery — Engine test code — Net power*

## 3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 6165 and the following apply.

### 3.1 General

#### 3.1.1

##### **dumper**

self-propelled crawler or wheeled machine, with an open body, which transports and dumps or spreads material, loading being performed either by means external to the dumper or by self-loading equipment

#### 3.1.2

##### **base machine**

machine with a cab or canopy and operator-protective structures (if required), without equipment or attachments but possessing the necessary mountings for such equipment and attachments

**3.1.3**

**equipment**

set of components mounted onto the base machine which allows an attachment to perform its design function

**3.1.4**

**self-loading equipment**

an integral mounted, bucket-supporting structure and linkage permanently fitted to a compact dumper enabling it to fill its own open body with material

NOTE See 4.1.5.

**3.1.5**

**attachment**

assembly of components that can be mounted onto the base machine or equipment for a specific use

**3.1.6**

**component**

part of an assembly or of a base machine, equipment or an attachment

**3.2 Performance**

**3.2.1**

**tractive force rimpull**

force available between the tyre and the ground to propel the dumper

**3.2.1.1**

**tractive force with direct drive transmission**

tractive force calculated or measured at the maximum engine torque in each forward gear

NOTE The maximum pull could be limited by mass and traction conditions.

**3.2.1.2**

**tractive force rimpull with powershift transmission [electric drive] [hydrostatic drive]**

tractive force rimpull given by the calculated or measured pull versus machine speed curves in each forward gear range

NOTE The maximum pull could be limited by mass and traction conditions.

**3.2.2**

**empty body dump and return time**

full movement cycle time of a body, door or ejector without load, at the rated engine speed

**3.2.3**

**payload**

manufacturer's rated mass that can be carried by the machine

**4 Base machine**

NOTE The information on the base machine parameters is provided in the referenced figures.

**4.1 Types of dumper**

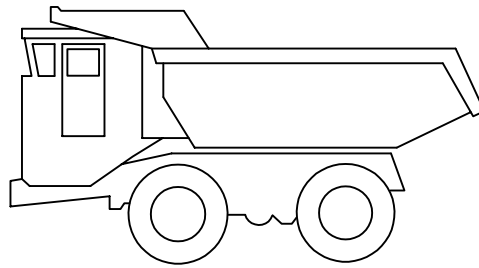
**4.1.1 Method of dumping**

— Rear dump: see Figure 1.

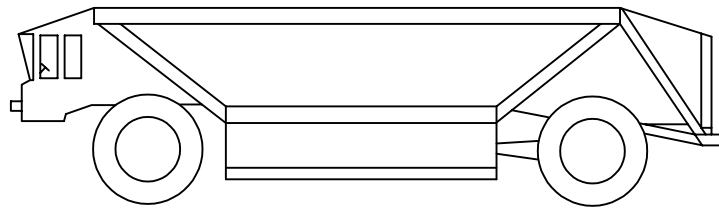
— Bottom dump: see Figure 2.



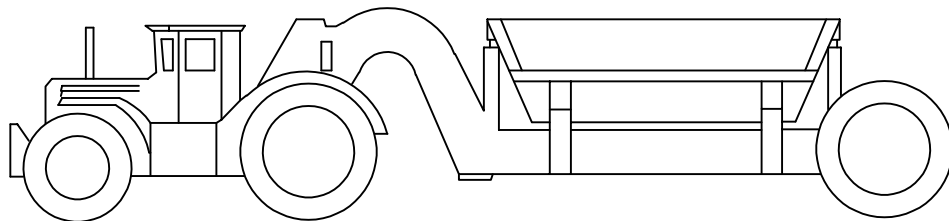
- Side dump: see Figure 3.
- Front dump: see Figure 4.
- Rotating dump: see Figure 5.
- High dump: see Figure 6.
- Slewing dump: see Figure 7.



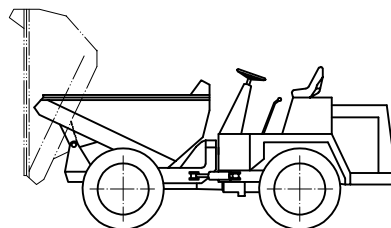
**Figure 1 — Rear dump**



**Figure 2 — Bottom dump**



**Figure 3 — Side dump**



**Figure 4 — Front dump**

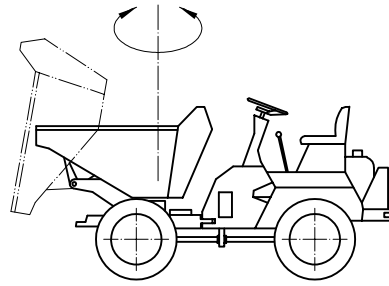


Figure 5 — Rotating dump

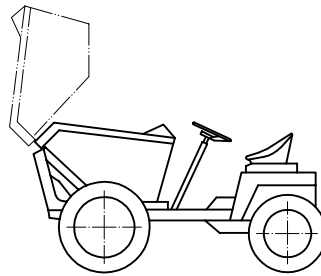


Figure 6 — High dump

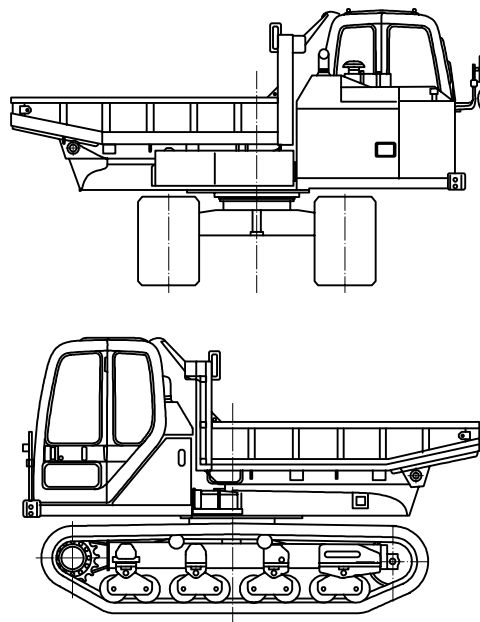
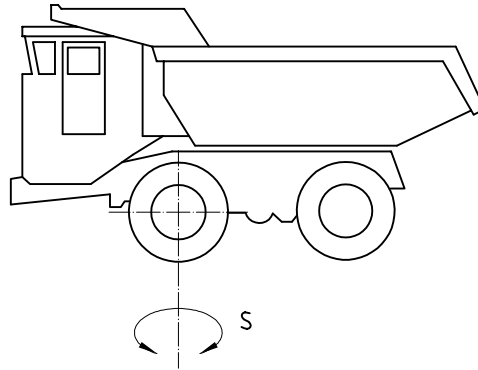


Figure 7 — Slewing dump

#### 4.1.2 Steering system

- Front-wheel steer: see Figure 8.
- Articulated steer: see Figure 9.
- Rear-wheel steer: see Figure 10.

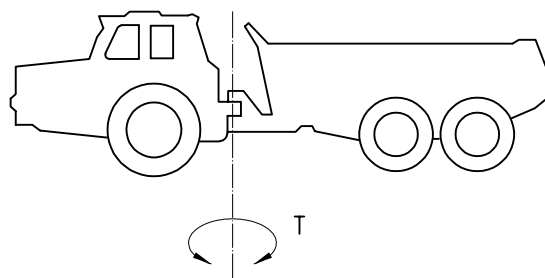
- All-wheel steer: see Figure 11.
- Crawler skid steer: see Figure 12.
- Wheel skid steer: see Figure 13.



**Key**

S steerable wheels

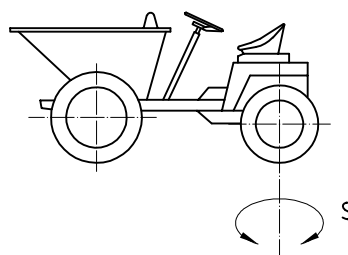
**Figure 8 — Front-wheel steer**



**Key**

T turning centre

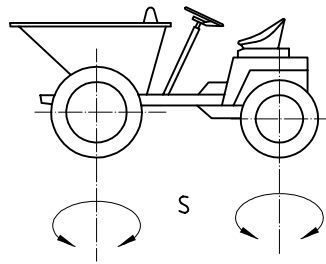
**Figure 9 — Articulated steer**



**Key**

S steerable wheels

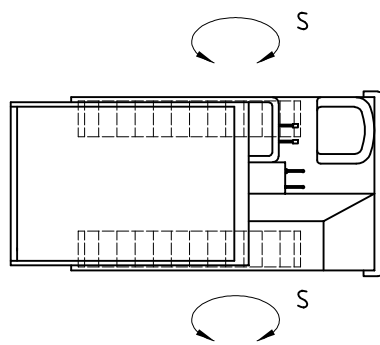
**Figure 10 — Rear-wheel steer**



**Key**

S steerable wheels

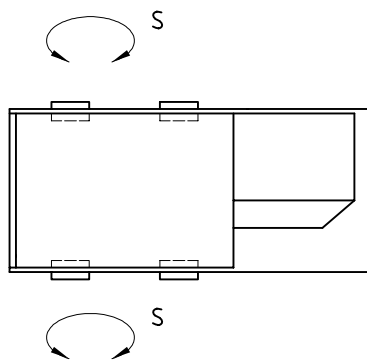
**Figure 11 — All-wheel steer**



**Key**

S steerable track

**Figure 12 — Crawler skid steer**



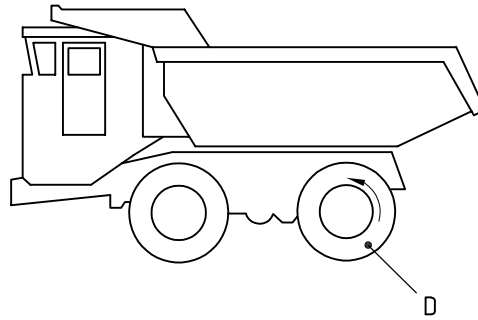
**Key**

S steerable wheels

**Figure 13 — Wheel skid steer**

**4.1.3 Drive system**

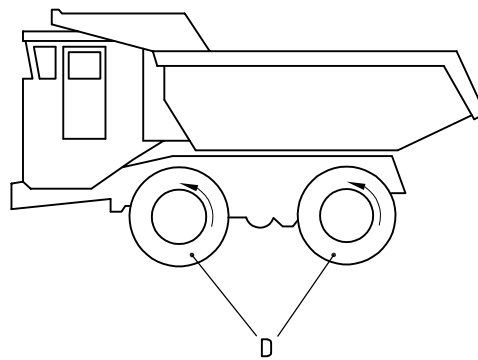
- Rear-wheel drive: see Figure 14.
- All-wheel drive: see Figure 15.
- Centre-axle drive: see Figure 16.
- Crawler drive: see Figure 17.



**Key**

D drive wheels

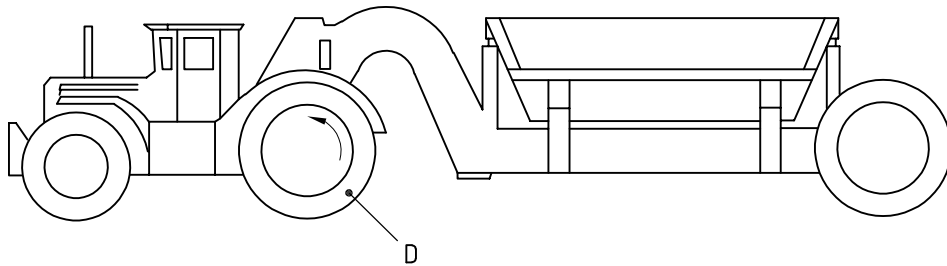
**Figure 14 — Rear-wheel drive**



**Key**

D drive wheels

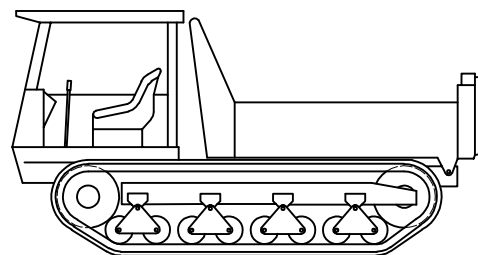
**Figure 15 — All-wheel drive**



**Key**

D drive wheels

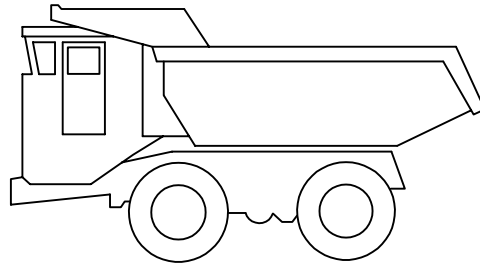
**Figure 16 — Centre-axle drive**



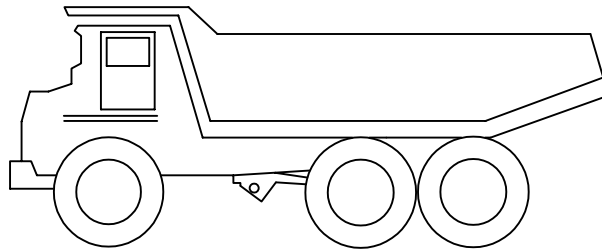
**Figure 17 — Crawler drive**

**4.1.4 Number of axles**

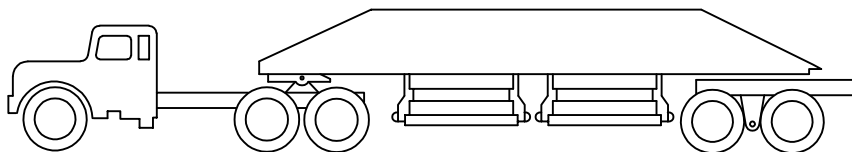
- Two axles: see Figure 18.
- Three axles: see Figure 19.
- More than three axles: see Figure 20.



**Figure 18 — Two axles**



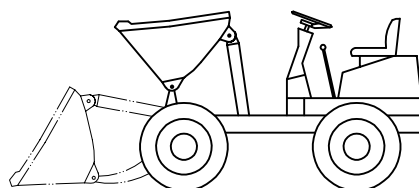
**Figure 19 — Three axles**



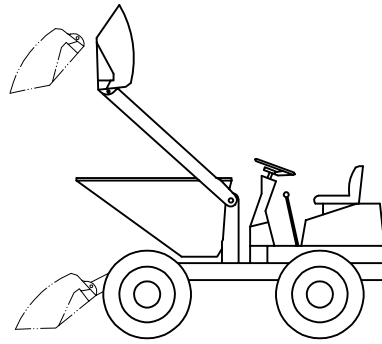
**Figure 20 — More than three axles**

**4.1.5 Method of self-loading**

- Body loading: see Figure 21.
- Shovel loading: see Figure 22.



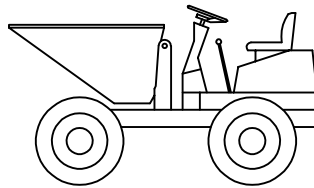
**Figure 21 — Body loading**



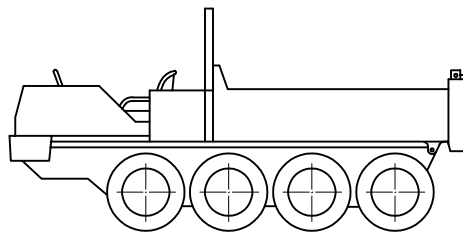
**Figure 22 — Shovel loading**

#### 4.1.6 Operator position

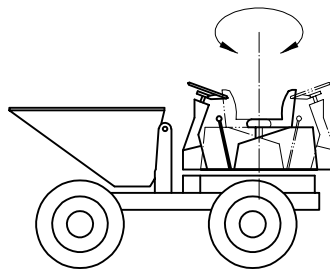
- Rear operator position: see Figure 23.
- Front operator position: see Figure 24.
- Reversible operator position: see Figure 25.



**Figure 23 — Rear operator position**



**Figure 24 — Front operator position**



**Figure 25 — Reversible operator position**

4.2 Dimensions (see ISO 6746-1)

4.2.1 Dumpers

See Figure 26. For additional definitions of dimensions and their terms and codes related to dumpers, see Annex A.

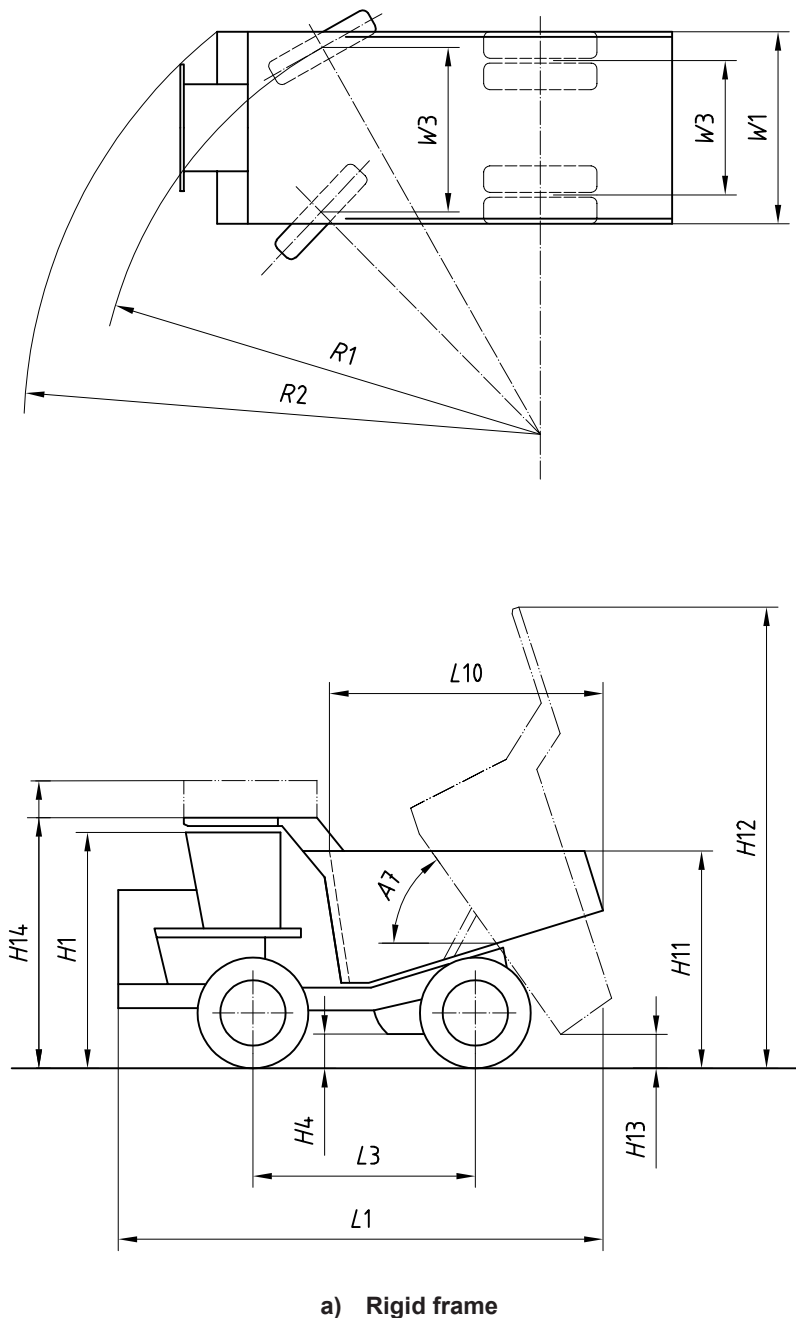


Figure 26 — Dimensions of base machine — Dumper



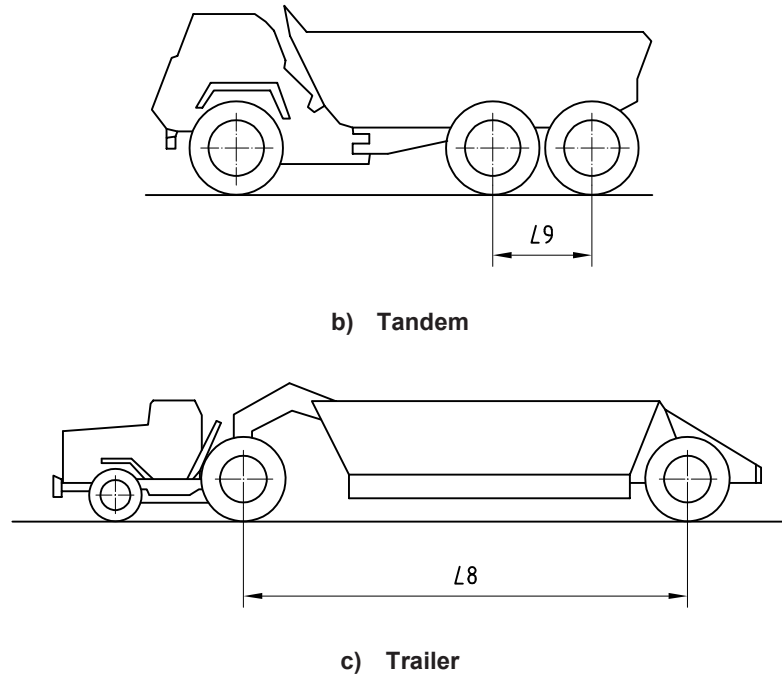


Figure 26 — Dimensions of base machine — Dumper

#### 4.2.2 Compact dumpers

See Figures 27, 28, 29, 30 and 31. For definitions of dimensions and their terms and codes, see Annex A. For additional dimensions and codes strictly related to compact dumpers, see Annex B.

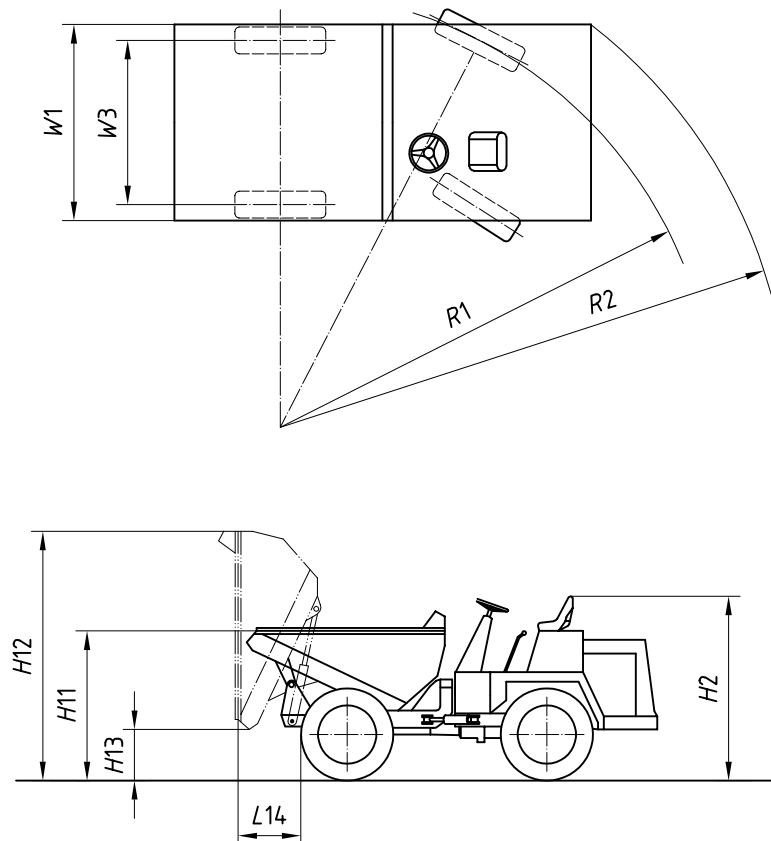


Figure 27 — Dimensions of wheeled compact dumper — Four-wheel

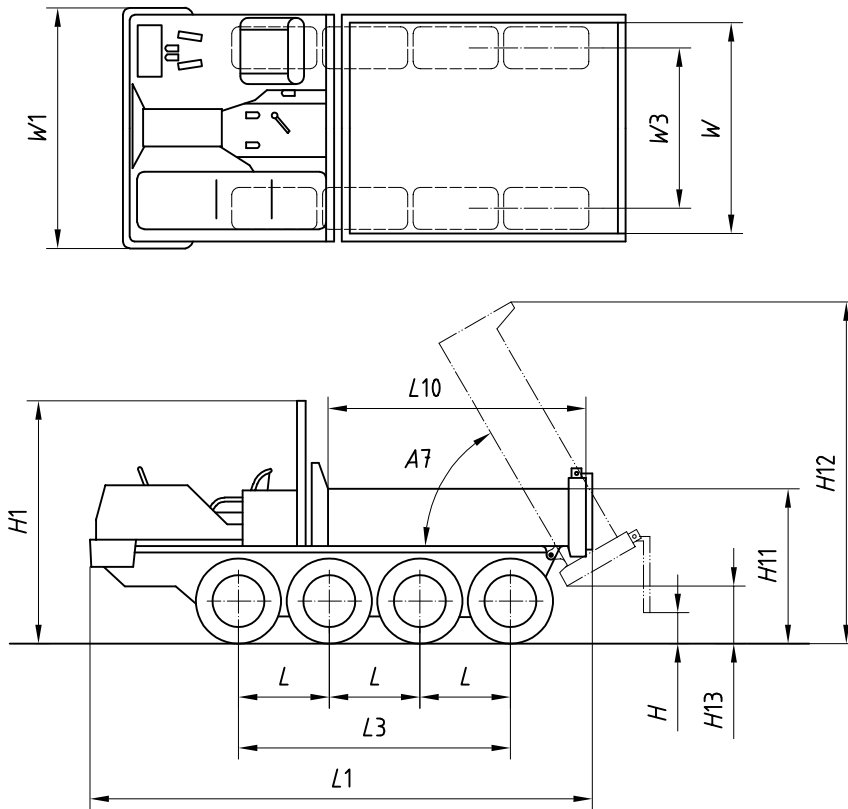


Figure 28 — Dimensions of wheeled compact dumper — Eight-wheel

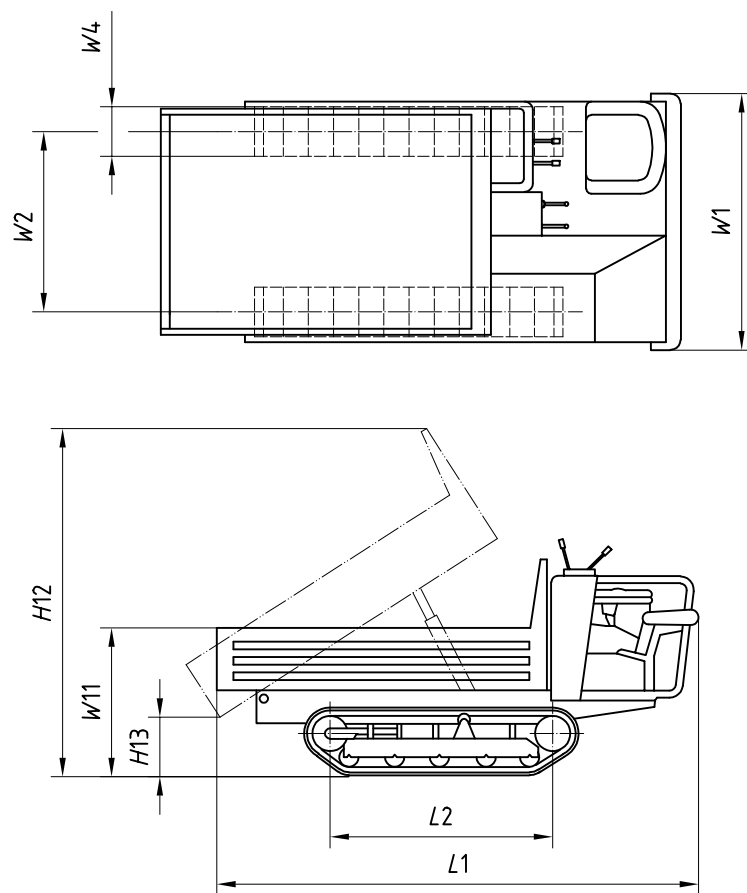


Figure 29 — Dimensions of crawler compact dumper — Rear operator position

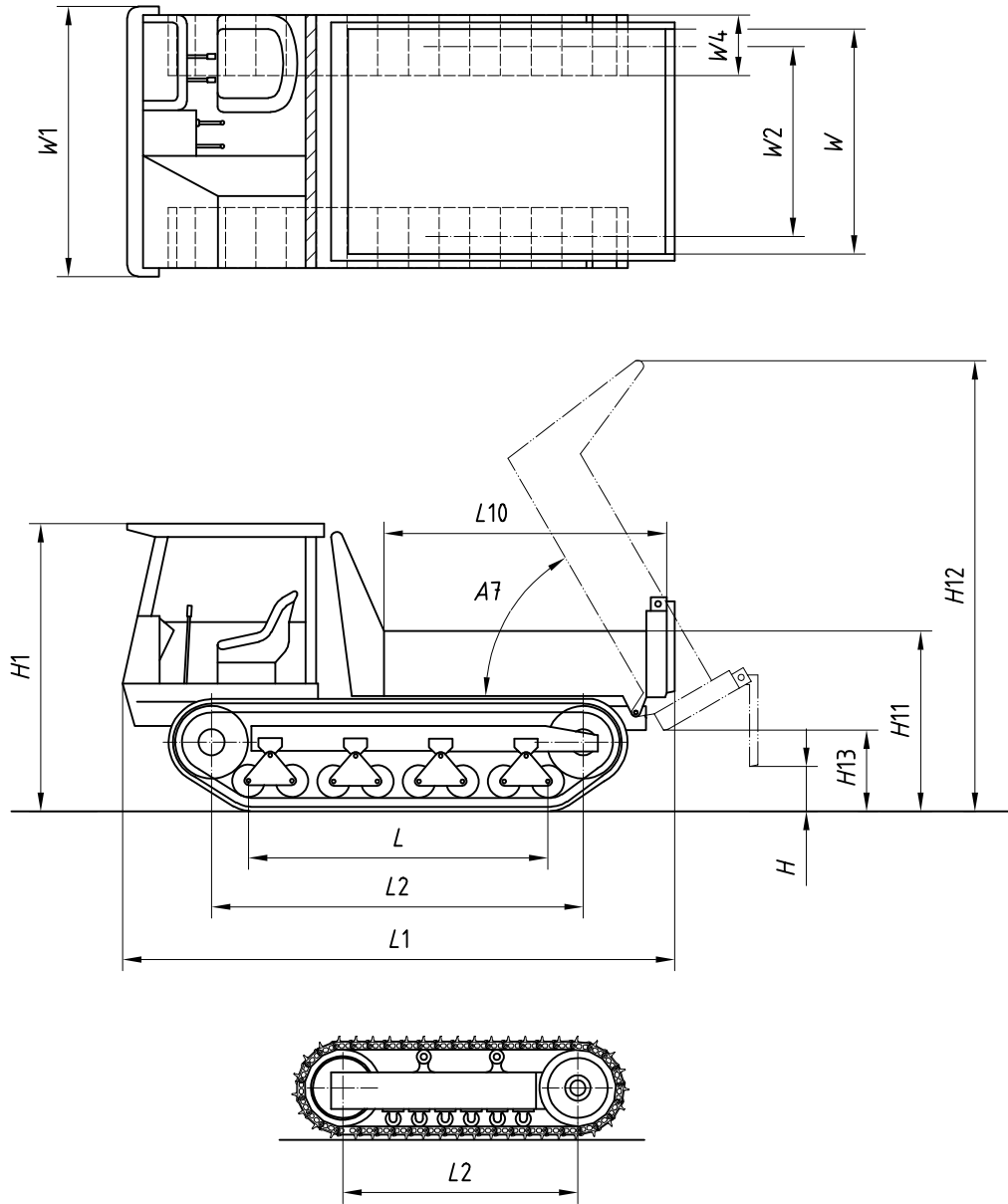


Figure 30 — Dimensions of crawler compact dumper — Front operator position

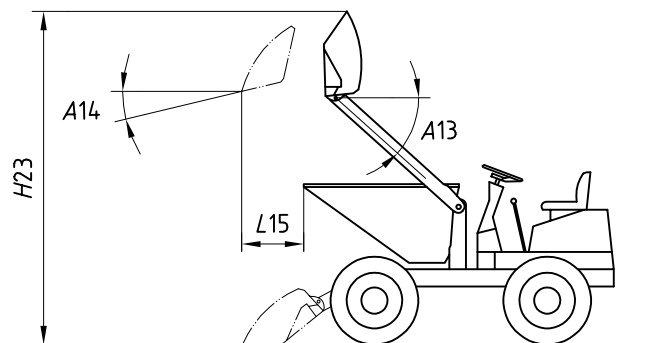


Figure 31 — Dimensions of self-loading compact dumper

### 4.3 Masses

See ISO 6016.

### 4.4 Component nomenclature

- Two-axle rear dump: see Figure 32.
- Two- and four-wheel tractor: see Figure 33.
- Trailing units: see Figure 34.
- Wheeled compact dumpers: see Figures 35 and 36.
- Crawler compact dumpers: see Figures 37 and 38.

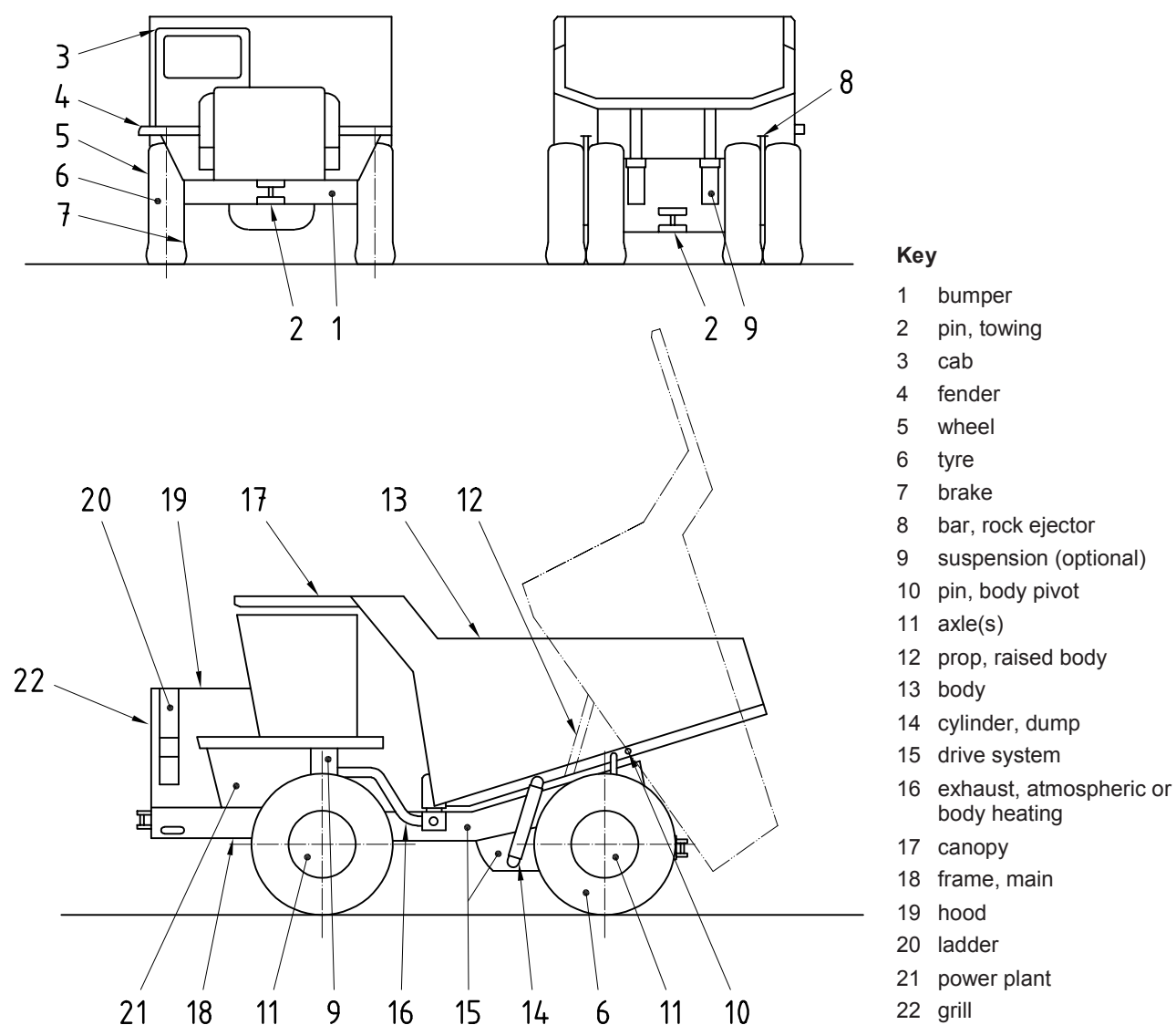
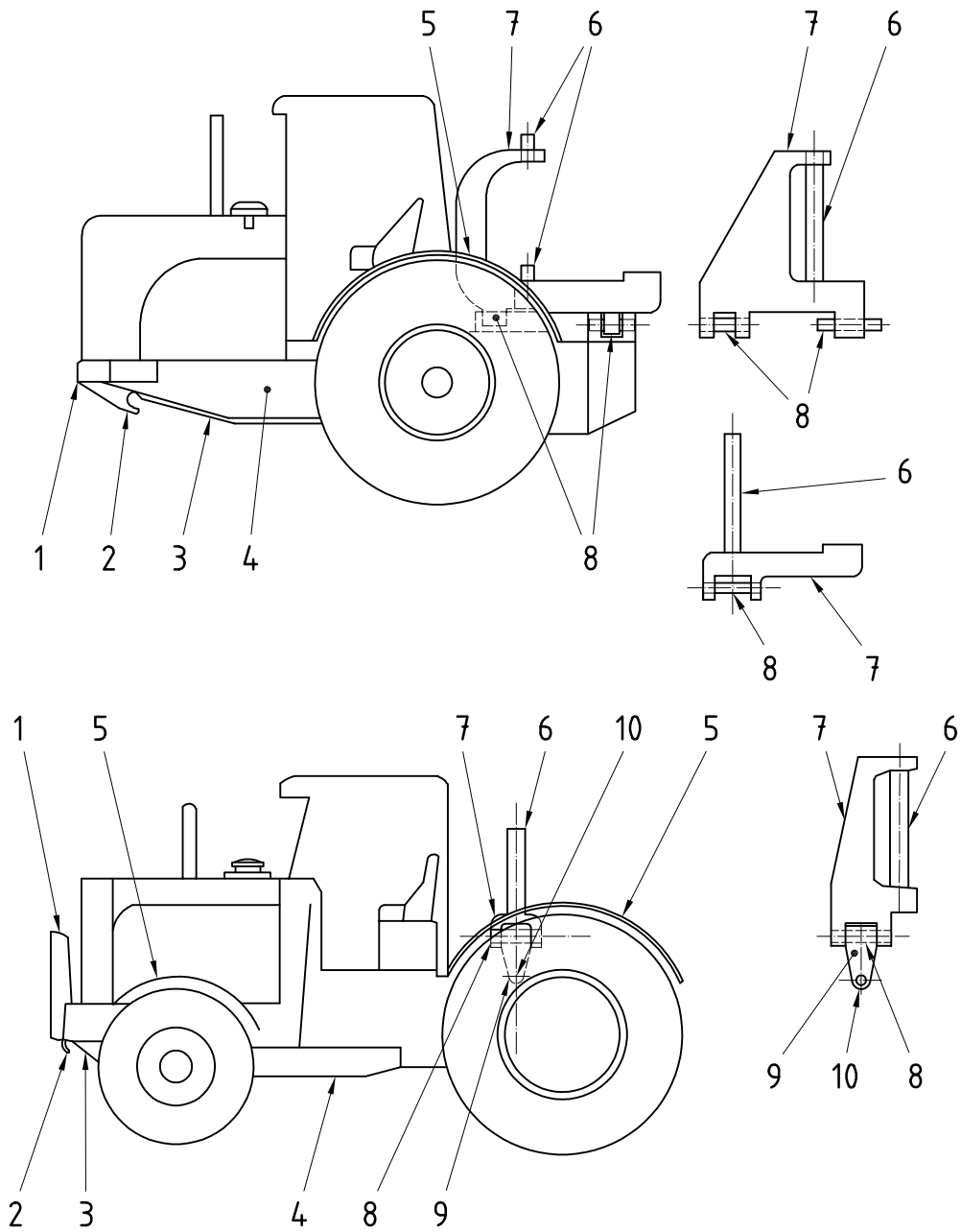


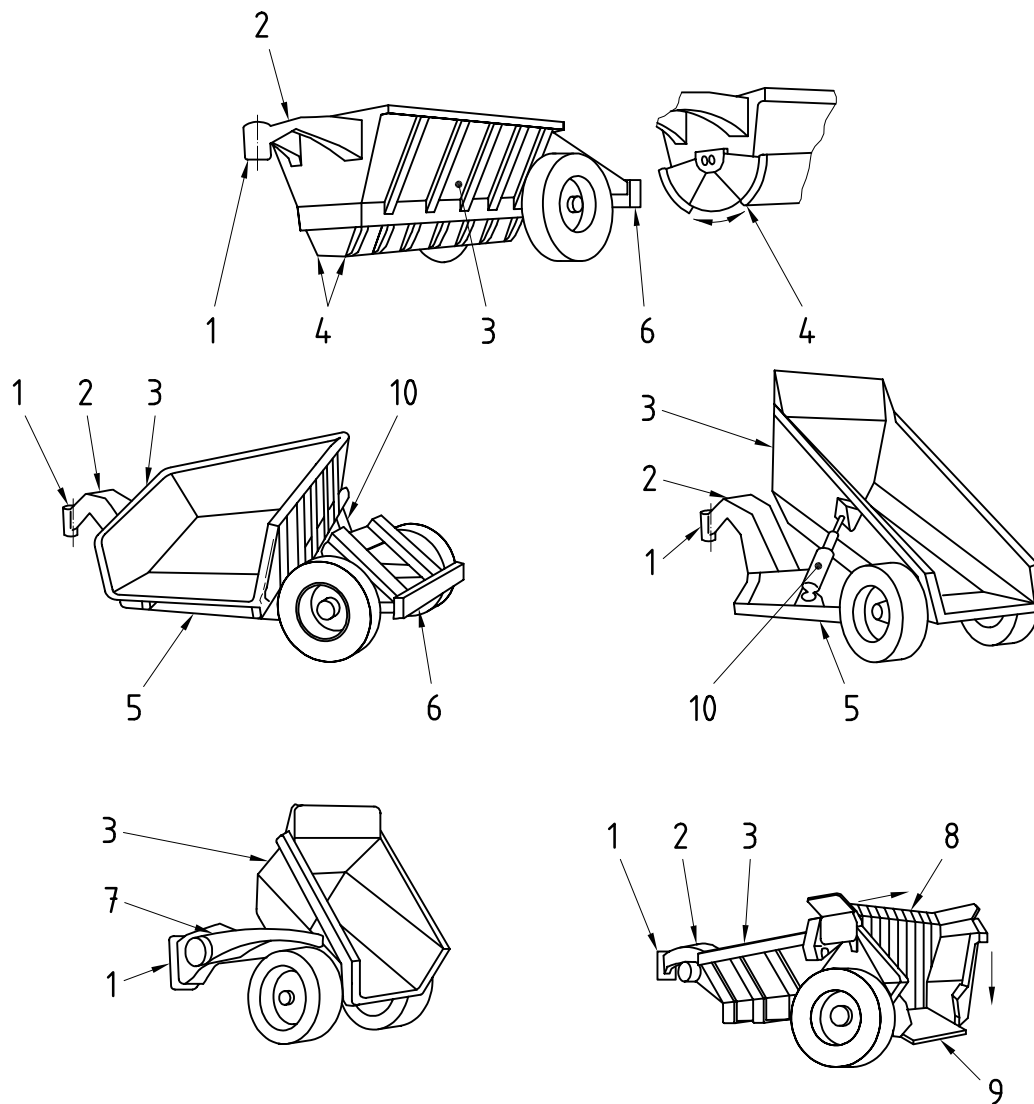
Figure 32 — Component nomenclature — Two-axle rear dump



**Key**

- |                 |                            |
|-----------------|----------------------------|
| 1 bumper        | 6 kingpin, hitch           |
| 2 hook, pull    | 7 hitch                    |
| 3 guard, bottom | 8 pin, oscillating pivot   |
| 4 frame, main   | 9 yoke, hitch              |
| 5 fender        | 10 pin, fore and aft pivot |

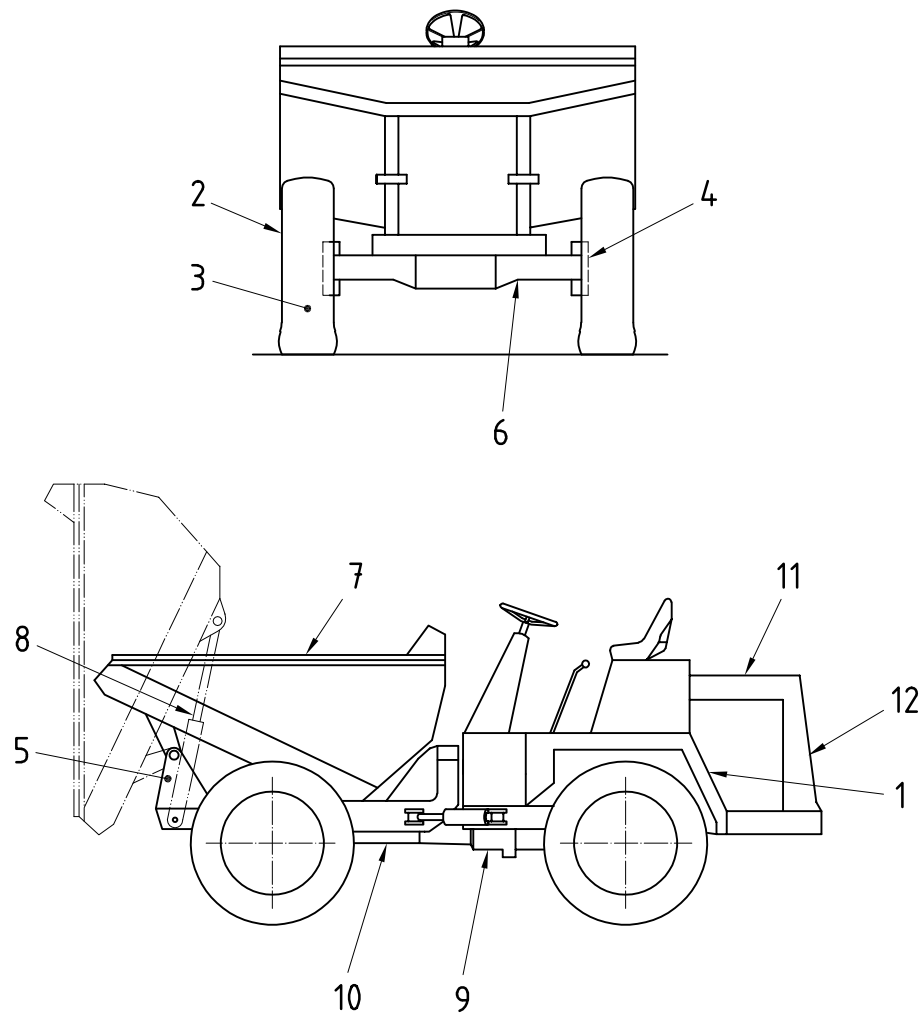
**Figure 33 — Component nomenclature — Two- and four-wheel tractors**



**Key**

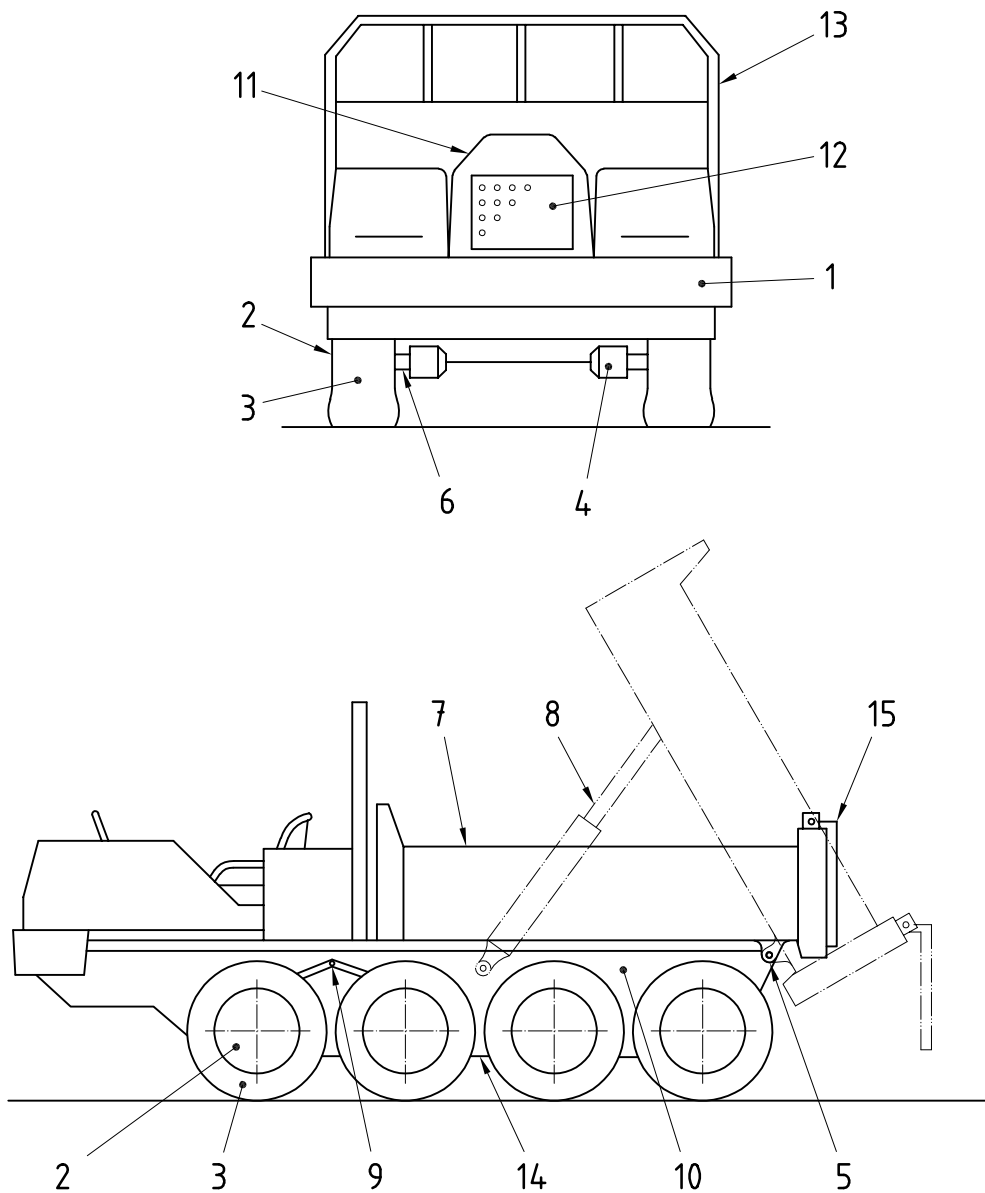
- |                    |                   |
|--------------------|-------------------|
| 1 housing, kingpin | 6 bumper          |
| 2 gooseneck        | 7 frame, draft    |
| 3 body             | 8 ejector         |
| 4 doors            | 9 tailgate        |
| 5 frame, main      | 10 cylinder, dump |

**Figure 34 — Component nomenclature — Trailing units**

**Key**

1	fender	7	body
2	wheel	8	cylinder
3	tyre	9	drive system
4	brake	10	frame, main
5	pin, body pivot	11	hood
6	axle(s)	12	power plant

**Figure 35 — Component nomenclature — Two-axle wheeled compact dumpers**

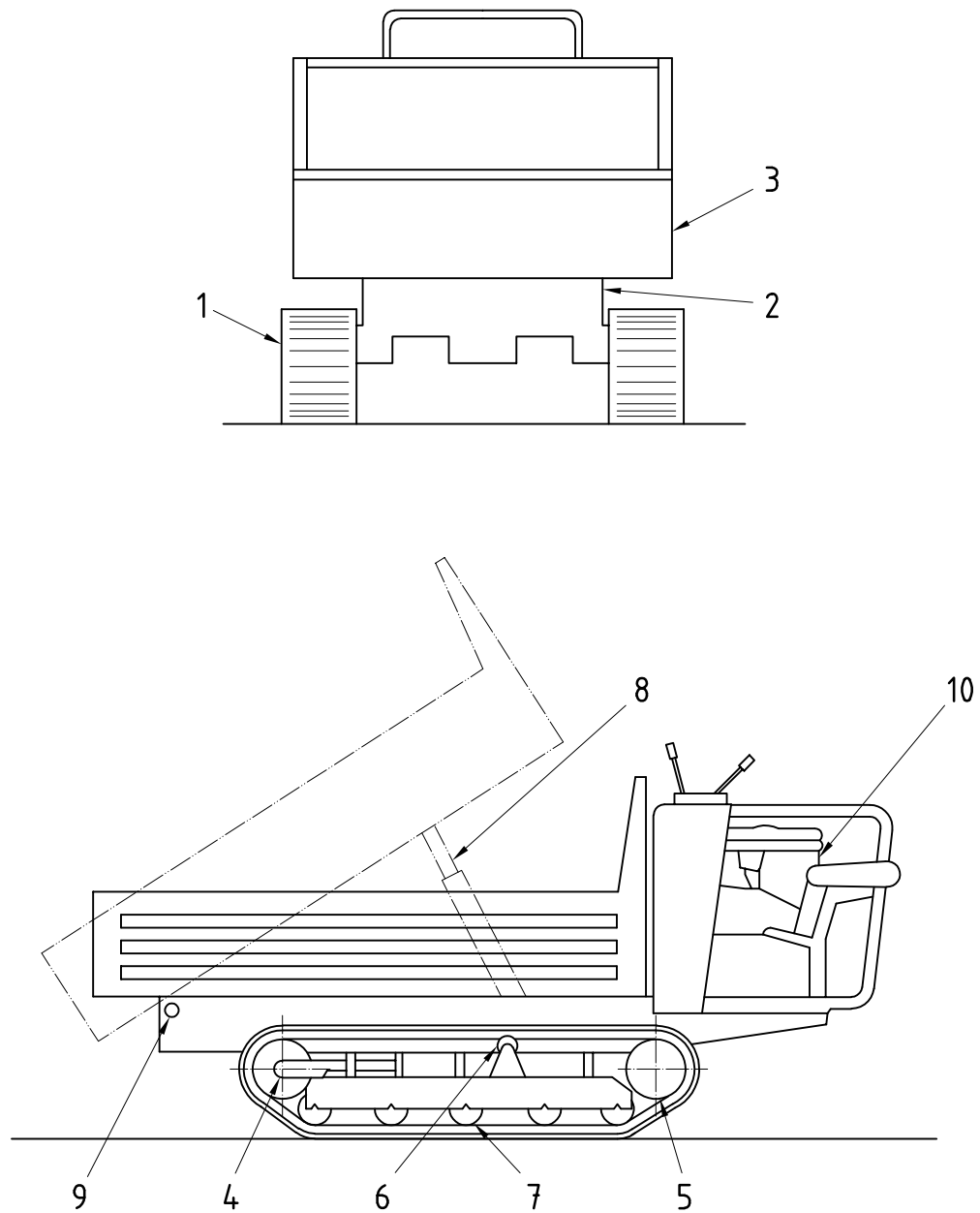


**Key**

- |                   |                      |
|-------------------|----------------------|
| 1 bumper          | 9 drive system       |
| 2 wheel           | 10 frame, main       |
| 3 tyre            | 11 hood              |
| 4 brake           | 12 power plant       |
| 5 pin, body pivot | 13 guard             |
| 6 axle            | 14 case, chain drive |
| 7 body            | 15 tailgate          |
| 8 cylinder, dump  |                      |

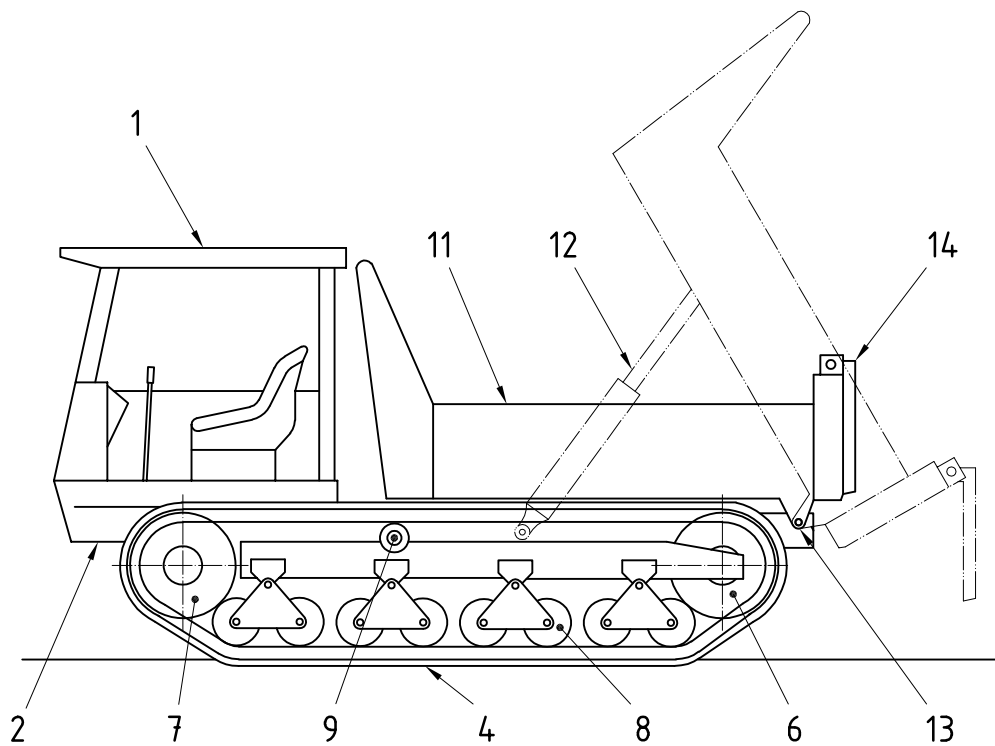
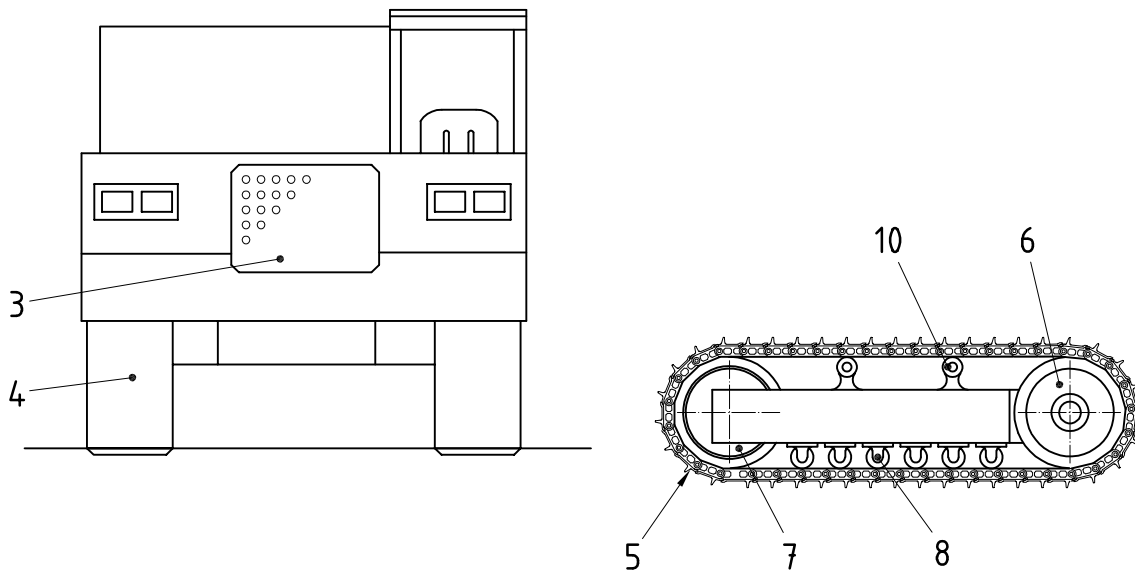
**Figure 36 — Component nomenclature — More-than-three-axle, wheeled compact dumpers**



**Key**

1	track	6	roller, carrier
2	frame, main	7	roller, track
3	body	8	cylinder, dump
4	idler	9	pin, body pivot
5	sprocket	10	power plant

**Figure 37 — Component nomenclature — Crawler compact dumpers without canopy**



**Key**

- |                   |                    |
|-------------------|--------------------|
| 1 canopy          | 8 roller, lower    |
| 2 frame, main     | 9 roller, upper    |
| 3 power plant     | 10 slide plate     |
| 4 crawler, rubber | 11 body            |
| 5 crawler, steel  | 12 cylinder, dump  |
| 6 sprocket        | 13 pin, body pivot |
| 7 idler           | 14 tailgate        |

**Figure 38 — Component nomenclature — Crawler dumpers with canopy**

## 5 Performance characteristics

The following performance characteristics are used in connection with dumpers: the International Standard indicates further characteristics and test methods as appropriate; the term number refers to the term as defined in this International Standard.

- a) ISO net power (engine): see ISO 9249.
- b) Maximum travel speed: see ISO 6014.
- c) Tractive force rimpull (3.2.1):
  - 1) Tractive force with direct drive transmission (3.2.1.1);
  - 2) Tractive force rimpull with powershift transmission, electric drive or hydrostatic drive (3.2.1.2).
- d) Empty body dump and return time (3.2.2).
- e) Steering capability
  - 1) Turning radius: see ISO 7457.
  - 2) Machine clearance diameter: see ISO 7457.
- f) Braking performance: based on requirements given in ISO 3450.
- g) Payload (3.2.3).

## 6 Commercial literature specifications (SI units)

### 6.1 Engine

Specify the characteristics:

- a) manufacturer and model;
- b) compression-ignition (diesel) or spark-ignition;
- c) type of cycle (two- or four-stroke);
- d) naturally aspirated, mechanically supercharged, or turbo-charged, with or without aftercooling;
- e) number of cylinders;
- f) bore;
- g) stroke;
- h) displacement;
- i) cooling system (air or water cooled);
- j) type of fuel;
- k) power, flywheel net: ..... at ..... r/min;
- l) torque, maximum: ..... at ..... r/min;
- m) starter type;
- n) electrical system: ..... V.

## **6.2 Transmission**

Specify the type, for example:

- manual shift with flywheel clutch;
- power shift with torque converter;
- hydrostatic;
- electric;
- number of gear speeds, forward and reverse;
- travel speeds (forward and reverse).

A graph of rimpull versus speed should be shown.

## **6.3 Drive axle(s)**

Specify the type, for example:

- steerable;
- fixed, oscillating and/or suspended;
- hydrostatic;
- electric;
- bevel gear and pinion;
- differential — standard, non-slip, limited slip or lock-up;
- planetary final drive.

## **6.4 Steering**

### **6.4.1 Type**

Specify type in accordance with ISO 5010, for example:

- articulated frame;
- front-wheel steer;
- rear-wheel steer;
- all-wheel steer;
- crawler skid steer;
- boosted, manual, hydrostatic;
- emergency steer method.

#### **6.4.2 Performance**

Specify:

- turning radius: ....., left and right;
- machine clearance diameter: .....

### **6.5 Brakes**

#### **6.5.1 Service brakes**

Specify, for example:

- type (drum, disc, wet or dry);
- actuating system type (mechanical, air, hydraulic, electrical, combination, etc.).

#### **6.5.2 Parking brake**

Specify type.

#### **6.5.3 Secondary brake**

Specify type.

#### **6.5.4 Retarding brake**

Specify:

- type;
- actuating system.

#### **6.5.5 Brake performance**

Specify in accordance with ISO 3450.

### **6.6 Tyres**

Specify:

- size and type;
- ply rating;
- rim size.

### **6.7 Hydraulic system**

#### **6.7.1 Empty body dump and return time**

Specify:

- pump flow: ..... at ..... pressure and engine rated r/min;
- relief valve opening pressure: .....

- pump type;
- body raise cylinders: number, type;
- empty body dump and return time: .....

#### **6.7.2 Steering**

Specify:

- pump flow: ..... at ..... pressure;
- pump type;
- relief valve opening pressure: .....

### **6.8 Suspension**

Specify at the individual wheel, complete axle or track.

#### **6.8.1 Type**

Specify type, for example:

- mechanical spring: coil, leaf;
- shock absorber cylinder: air, oil, air/oil;
- elastomer;
- pneumatic.

#### **6.8.2 Capacity**

Specify stroke.

#### **6.8.3 Load/deflection rate**

Specify whether this is

- empty, or
- loaded.

### **6.9 Body**

#### **6.9.1 Rated body capacity**

Specify this in cubic metres, in accordance with ISO 6483.

#### **6.9.2 Method of self-loading**

Specify whether the method is

- body loading, or
- shovel loading.

### 6.10 Operator station

Specify whether this is at the

- rear,
- front, or
- reversible.

### 6.11 Masses

Provide the following information.

- a) Distribution, empty operating mass:
  - front axle;
  - drive axle;
  - trailer axle.
- b) Total empty operating mass.
- c) Payload, rated.
- d) Distribution, loaded mass:
  - front axle;
  - drive axle;
  - trailer axle.
- e) Total loaded mass.

### 6.12 System fluid capacities

Provide details of the following:

- fuel tank;
- engine crankcase;
- cooling system;
- hydraulic system;
- transmission;
- differential;
- final drive.

### **6.13 Overall dumper dimensions**

Supply an outline drawing.

Examples of significant dimensions to be specified:

- maximum total height without body;
- ground clearance, axles;
- ground clearance, bottom dump body, doors closed;
- ground clearance, under open doors;
- loading height;
- dump height;
- discharge height;
- maximum height with body;
- maximum width;
- tread;
- maximum length;
- wheelbase;
- tandem centre distance;
- turning radius;
- clearance diameter.



## Annex A (normative)

### Dimensions for dumpers

This annex defines dumper dimensions and specifies their codes.

Code	Term and definition	Illustration
<i>H11</i>	<b>loading height</b> distance on Z coordinate between the ground reference plane (GRP) and the highest point of the load-containing sides, body empty	See Figure 26, a)
<i>H12</i>	<b>dump height</b> distance on Z coordinate between the GRP and the highest point on the dumper, body fully raised	See Figure 26, a)
<i>H13</i>	<b>(rear or side dump) discharge height</b> distance on Z coordinate between the GRP and the lowest point on the body, body fully raised	See Figure 26, a)
<i>H14</i>	<b>maximum height of dumper body or hitch</b> distance on Z coordinate between the GRP and the highest point on the dumper body or the hitch connection, dumper body in loading position with spillage guard if fitted, body empty	See Figure 26, a)
<i>L8</i>	<b>(trailer) wheelbase</b> distance on X coordinate between two X planes passing through the centres of the rear wheels of the tractor and the rear wheels of the trailer. In machines equipped with tandem wheels, the centre of the wheels is the line midway between the two axles of the tandem.	See Figure 26, c)
<i>L9</i>	<b>tandem centre distance</b> distance on X coordinate between X planes passing through the centres of front and rear wheels of the tandem	See Figure 26, b)
<i>L10</i>	<b>length of loading body</b> distance on X coordinate between two X planes passing through the farthest internal point on the rear of the body and the farthest internal point on the front of the load-carrying part of the body	See Figure 26, a)
<i>A7</i>	<b>(rear dump) body dump angle</b> angle on Y plane between the body main floor and GRP, body fully raised	See Figure 26, a)
NOTE The X, Y and Z coordinates and the GRP are defined in ISO 6746-1.		

## Annex B (normative)

### Dimensions for compact dumpers

This annex defines compact dumper dimensions and specifies their codes.

Code	Term and definition	Illustration
<i>H11</i>	<b>loading height</b> distance on Z coordinate between the ground reference plane (GRP) and the highest point of the load containing sides, body empty	See Figure 27
<i>H12</i>	<b>dump height</b> distance on Z coordinate between the GRP and the highest point on the dumper, body fully raised	See Figure 27
<i>H13</i>	<b>discharge height</b> distance on Z coordinate between the GRP and the lowest point on the body, body fully raised	See Figure 27
<i>H23</i>	<b>self-loading dump height</b> distance on Z coordinate between the GRP and the highest point on the self-loading apparatus	See Figure 31
<i>L14</i>	<b>discharge distance</b> distance on X coordinate between the forward face of the front wheels and the forward edge of the body, body fully raised	See Figure 27
<i>A13</i>	<b>self-loading rear dump angle</b> maximum angle that the rear discharge face of the bucket will rotate below the horizontal with the bucket in the fully raised position	See Figure 31
<i>A14</i>	<b>self-loading front dump angle</b> maximum angle that the bottom face of the bucket will rotate below the horizontal with the bucket rotated fully forwards $A14 < 30^\circ$	See Figure 31
<i>L15</i>	<b>self-loading dump reach</b> the maximum distance on the X coordinate between the forward edge of the body and the forward edge of the bucket at its maximum forward extension $L15 < 200$ mm	See Figure 31
NOTE The X and Z coordinates and the GRP are defined in ISO 6746-1.		



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