

Low-voltage switchgear and controlgear —

Part 1: General rules

ICS 29.130.20

National foreword

This British Standard is the UK implementation of EN 60947-1:2007+A2:2014. It is identical to IEC 60947-1:2007, incorporating amendment 1:2010 and amendment 2:2014. It supersedes BS EN 60947-1:2007+A1:2011, which is withdrawn.

The start and finish of text introduced or altered by amendment is indicated in the text by tags. Tags indicating changes to IEC text carry the number of the IEC amendment. For example, text altered by IEC amendment 1 is indicated by **A1** **A1**.

The UK participation in its preparation was entrusted by Technical Committee PEL/17, Switchgear, controlgear, and HV-LV co-ordination, to Subcommittee PEL/17/2, Low voltage switchgear and controlgear.

A list of organizations represented on this subcommittee can be obtained on request to its secretary.

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English version

**Low-voltage switchgear and controlgear -
Part 1: General rules
(IEC 60947-1:2007)**

Appareillage à basse tension -
Partie 1: Règles générales
(CEI 60947-1:2007)

Niederspannungsschaltgeräte -
Teil 1: Allgemeine Festlegungen
(IEC 60947-1:2007)

This amendment A1 modifies the European Standard EN 60947-1:2007; it was approved by CENELEC on 2011-01-01. CENELEC members are bound to comply with the CEN/CENELEC Internal Regulations which stipulate the conditions for giving this amendment the status of a national standard without any alteration.

Up-to-date lists and bibliographical references concerning such national standards may be obtained on application to the Central Secretariat or to any CENELEC member.

This European Standard exists in three official versions (English, French, German). A version in any other language made by translation under the responsibility of a CENELEC member into its own language and notified to the Central Secretariat has the same status as the official versions.

CENELEC members are the national electrotechnical committees of Austria, Belgium, Bulgaria, Cyprus, the Czech Republic, Denmark, Estonia, Finland, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, the Netherlands, Norway, Poland, Portugal, Romania, Slovakia, Slovenia, Spain, Sweden, Switzerland and the United Kingdom.

CENELEC

European Committee for Electrotechnical Standardization
Comité Européen de Normalisation Electrotechnique
Europäisches Komitee für Elektrotechnische Normung

Central Secretariat: rue de Stassart 35, B - 1050 Brussels

Foreword

The text of document 17B/1550/FDIS, future edition 5 of IEC 60947-1, prepared by SC 17B, Low-voltage switchgear and controlgear, of IEC TC 17, Switchgear and controlgear, was submitted to the IEC-CENELEC parallel vote and was approved by CENELEC as EN 60947-1 on 2007-07-01.

This European Standard supersedes EN 60947-1:2004.

The main changes with respect to EN 60947-1:2004 are as follows:

- modification and restructuration of 7.1;
- introduction of new figures concerning EMC tests;
- introduction of new Annexes Q, R and S.

The following dates were fixed:

- latest date by which the EN has to be implemented at national level by publication of an identical national standard or by endorsement (dop) 2008-04-01
- latest date by which the national standards conflicting with the EN have to be withdrawn (dow) 2010-07-01

This European Standard has been prepared under a mandate given to CENELEC by the European Commission and the European Free Trade Association and covers essential requirements of EC Directives EMC (98/336/EEC) and EMC2 (2004/108/EC). See Annex ZZ.

Annexes ZA and ZZ have been added by CENELEC.

Endorsement notice

The text of the International Standard IEC 60947-1:2007 was approved by CENELEC as a European Standard without any modification.

Foreword to amendment A1

The text of document 17B/1710/FDIS, future amendment 1 to IEC 60947-1:2007, prepared by SC 17B, Low-voltage switchgear and controlgear, of IEC TC 17, Switchgear and controlgear, was submitted to the IEC-CENELEC parallel vote and was approved by CENELEC as amendment A1 to EN 60947-1:2007 on 2011-01-01.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CEN and CENELEC shall not be held responsible for identifying any or all such patent rights.

The following dates were fixed:

- latest date by which the amendment has to be implemented at national level by publication of an identical national standard or by endorsement (dop) 2011-10-01
- latest date by which the national standards conflicting with the amendment have to be withdrawn (dow) 2014-01-01

Annex ZA has been added by CENELEC.

Endorsement notice

The text of amendment 1:2010 to the International Standard IEC 60947-1:2007 was approved by CENELEC as an amendment to the European Standard without any modification.

In the official version, for Bibliography, the following notes have to be added for the standards indicated:

- | | | |
|------------------------|------|---|
| [5] IEC 60947-7-1 | NOTE | Harmonized as EN 60947-7-1. |
| [6] IEC 60998-2-2:2002 | NOTE | Harmonized as EN 60998-2-2:2004 (modified). |
-

Foreword to amendment A2

The text of document 121A/15/FDIS, future IEC 60947-1:2007/A2, prepared by SC 121A "Low-voltage switchgear and controlgear" of IEC/TC 121 "Switchgear and controlgear and their assemblies for low voltage" was submitted to the IEC-CENELEC parallel vote and approved by CENELEC as EN 60947-1:2007/A2:2014.

The following dates are fixed:

- latest date by which the document has to be implemented at national level by publication of an identical national standard or by endorsement (dop) 2015-07-14
- latest date by which the national standards conflicting with the document have to be withdrawn (dow) 2017-10-14

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CENELEC [and/or CEN] shall not be held responsible for identifying any or all such patent rights.

This document has been prepared under a mandate given to CENELEC by the European Commission and the European Free Trade Association, and supports essential requirements of EU Directive.

For the relationship with EU Directive see informative Annex ZZ, which is an integral part of this document.

This standard covers the Principle Elements of the Safety Objectives for Electrical Equipment Designed for Use within Certain Voltage Limits (LVD - 2006/95/EC).

Endorsement notice

The text of the International Standard IEC 60947-1:2007/A2:2014 was approved by CENELEC as a European Standard without any modification.

In the Bibliography of EN 60947-1:2007, the following notes have to be **added** for the standards indicated:

IEC 60695-11-5	NOTE	Harmonized as EN 60695-11-5.
IEC 60947-3:2008	NOTE	Harmonized as EN 60947-3:2009 (not modified).
IEC 60947-3:2008/A1:2012	NOTE	Harmonized as EN 60947-3:2009/A1:2012 (not modified).
IEC 60947-4-1:2009	NOTE	Harmonized as EN 60947-4-1:2010 (not modified).
IEC 60947-4-1:2009/A1:2012	NOTE	Harmonized as EN 60947-4-1:2010/A1:2012 (not modified).
IEC 60947-4-2:2011	NOTE	Harmonized as EN 60947-4-2:2012 (not modified).
IEC 60947-4-3:1999	NOTE	Harmonized as EN 60947-4-3:2000 ¹⁾ (not modified).
IEC 60947-4-3:1999/A1:2006	NOTE	Harmonized as EN 60947-4-3:2000/A1:2006 ¹⁾ (not modified).
IEC 60947-4-3:1999/A2:2011	NOTE	Harmonized as EN 60947-4-3:2000/A2:2011 ¹⁾ (not modified).
IEC 60947-5-2:2007	NOTE	Harmonized as EN 60947-5-2:2007 (not modified).
IEC 60947-5-2:2007/A1:2012	NOTE	Harmonized as EN 60947-5-2:2007/A1:2012 (not modified).
IEC 60947-6-1:2005	NOTE	Harmonized as EN 60947-6-1:2005 (not modified).
IEC 60947-6-1:2005/A1:2013	NOTE	Harmonized as EN 60947-6-1:2005/A1:2014 (not modified).

¹⁾ Superseded by EN 60947-4-3:2014 (IEC 60947-4-3:2014).

IEC 60947-6-2:2002	NOTE	Harmonized as EN 60947-6-2:2003 (not modified).
IEC 60947-6-2:2002/A1:2007	NOTE	Harmonized as EN 60947-6-2:2003/A1:2007 (not modified).
IEC 61095:2009	NOTE	Harmonized as EN 61095:2009 (not modified).
IEC 61439 Series	NOTE	Harmonized as EN 61439 Series (not modified).
IEC 61508-6	NOTE	Harmonized as EN 61508-6.
CISPR 22	NOTE	Harmonized as EN 55022.
ISO 50001	NOTE	Harmonized as EN ISO 50001.

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LOW-VOLTAGE SWITCHGEAR AND CONTROLGEAR –

Part 1: General rules

1 General

The purpose of this standard is to harmonize as far as practicable all rules and requirements of a general nature applicable to low-voltage switchgear and controlgear in order to obtain uniformity of requirements and tests throughout the corresponding range of equipment and to avoid the need for testing to different standards.

All those parts of the various equipment standards which can be considered as general have therefore been gathered in this standard together with specific subjects of wide interest and application, e.g. temperature-rise, dielectric properties, etc.

For each type of low-voltage switchgear and controlgear, only two main documents are necessary to determine all requirements and tests:

- 1) this basic standard, referred to as "Part 1" in the specific standards covering the various types of low-voltage switchgear and controlgear;
- 2) the relevant equipment standard hereinafter referred to as the "relevant product standard" or "product standard".

For a general rule to apply to a specific product standard, it shall be explicitly referred to by the latter, by quoting the relevant clause or subclause number of this standard followed by "IEC 60947-1" e.g. "7.2.3 of IEC 60947-1".

A specific product standard may not require, and hence may omit, a general rule (as being not applicable), or it may add to it (if deemed inadequate in the particular case), but it may not deviate from it, unless there is a substantial technical justification.

A1 NOTE The product standards forming the series of IEC standards covering low-voltage switchgear and controlgear are:

IEC 60947-2:	Part 2: Circuit-breakers
IEC 60947-3:	Part 3: Switches, disconnectors, switch-disconnectors and fuse combination units
IEC 60947-4:	Part 4: Contactors and motor-starters
IEC 60947-5:	Part 5: Control-circuit devices and switching elements
IEC 60947-6:	Part 6: Multiple function equipment
IEC 60947-7:	Part 7: Ancillary equipment
IEC 60947-8:	Part 8: Control units for built-in thermal protection (PTC) for rotating electrical machines. A1

1.1 Scope and object

A2 This standard applies, when required by the relevant product standard, to low-voltage switchgear and controlgear hereinafter referred to as "equipment" or "device" and intended to be connected to circuits the rated voltage of which does not exceed 1 000 V a.c. or 1 500 V d.c.

This standard states the general rules and common safety requirements for low-voltage switchgear and controlgear, including:

- definitions;
- characteristics; **A2**

- A₂** – information supplied with the equipment;
- normal service, mounting and transport conditions;
 - constructional and performance requirements;
 - verification of characteristics and performance;
 - environmental aspects.

This standard does not apply to low-voltage switchgear and controlgear assemblies which are dealt with in IEC 61439 series, as applicable. **A₂**

1.2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60050(151):2001, *International Electrotechnical Vocabulary (IEV) – Chapter 151: Electrical and magnetic devices*

IEC 60050(441):1984, *International Electrotechnical Vocabulary (IEV) – Chapter 441: Switchgear, controlgear and fuses*
Amendment 1 (2000)

IEC 60050(604):1987, *International Electrotechnical Vocabulary (IEV) – Chapter 604: Generation, transmission and distribution of electricity – Operation*
Amendment 1 (1998)

IEC 60050(826):2004, *International Electrotechnical Vocabulary (IEV) – Chapter 826: Electrical installations*

IEC 60060, *High-voltage test techniques*

IEC 60068-1:1988, *Environmental testing – Part 1: General and guidance*
Amendment 1 (1992)

IEC 60068-2-1:1990, *Environmental testing – Part 2-1: Tests – Tests A: Cold*
Amendment 1 (1993)
Amendment 2 (1994)

IEC 60068-2-2:1974, *Environmental testing – Part 2-2: Tests – Tests B: Dry heat*
Amendment 1 (1993)
Amendment 2 (1994)

IEC 60068-2-6:1995, *Environmental testing – Part 2-6: Tests – Test Fc: Vibration (sinusoidal)*

IEC 60068-2-27:1987, *Environmental testing – Part 2-27: Tests – Test Ea and guidance: Shock*

IEC 60068-2-30:2005, *Environmental testing – Part 2-30: Tests – Test Db: Damp heat, cyclic (12 h + 12 h cycle)*

IEC 60068-2-52:1996, *Environmental testing – Part 2-52: Tests – Test Kb: Salt mist, cyclic (sodium chloride solution)*

IEC 60068-2-78:2001, *Environmental testing – Part 2-78: Tests – Test Cab: Damp heat, steady state*

IEC 60071-1:1993, *Insulation co-ordination – Part 1: Definitions, principles and rules*

IEC 60073:2002, *Basic and safety principles for man-machine interface, marking and identification – Coding principles for indicators and actuators*

IEC 60085:2004, *Electrical insulation – Thermal classification*

A₂ IEC 60092-504:2001, *Electrical installations in ships – Part 504: Special features – Control and instrumentation* **A₂**

IEC 60112:2003, *Method for the determination of the proof and the comparative tracking indices of solid insulating materials*

IEC 60216, *Guide for the determination of thermal endurance properties of electrical insulating materials*

IEC 60228:2004, *Conductors of insulated cables*

IEC 60269-1:1998, *Low-voltage fuses – Part 1: General requirements*
Amendment 1 (2005)

IEC 60269-2:1986, *Low-voltage fuses – Part 2: Supplementary requirements for fuses for use by authorized persons (fuses mainly for industrial application)*
Amendment 1 (1995)
Amendment 2 (2001)

A₂ IEC 60300-3-5:2001, *Dependability management – Part 3-5: Application guide – Reliability test conditions and statistical test principles* **A₂**

IEC 60344:1980, *Guide to the calculation of resistance of plain and coated copper conductors of low-frequency cables and wires*
Amendment 1 (1985)

IEC 60364-4-44:2001, *Electrical installations of buildings – Part 4-44: Protection for safety – Protection against voltage disturbances and electromagnetic disturbances*
Amendment 1 (2003)

IEC 60417-DB:2002¹, *Graphical symbols for use on equipment*

A₂ *Text deleted* **A₂**

IEC 60445:1999, *Basic and safety principles for man-machine interface, marking and identification – Identification of equipment terminals and of terminations of certain designated conductors, including general rules of an alphanumeric system*

IEC 60447:2004, *Basic and safety principles for man-machine interface, marking and identification – Actuating principles*

IEC 60529:1989, *Degrees of protection provided by enclosures (IP code)*
Amendment 1 (1999)

IEC 60617-DB:2001¹, *Graphical symbols for diagrams*

A₂ IEC 60664-1:2007, *Insulation coordination for equipment within low-voltage systems – Part 1: Principles, requirements and tests* **A₂**

A₁ IEC 60664-3:2003, *Insulation coordination for equipment within low-voltage systems – Part 3: Use of coating, potting or moulding for protection against pollution*

IEC 60664-5:2007, *Insulation coordination for equipment within low-voltage systems – Part 5: Comprehensive method for determining clearances and creepage distances equal to or less than 2 mm* **A₁**

IEC 60695-2-2:1991, *Fire hazard testing – Part 2: Test methods – Section 2: Needle-flame test*
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¹ “DB” refers to the IEC on-line database.

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A2 Amendment 1 (2009) **A2**

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Amendment 1 (2006)

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- A1** IEC 60999-1:1999, *Connecting devices – Electrical copper conductors – Safety requirements for screw-type and screwless-type clamping units – Part 1: General requirements and particular requirements for clamping units for conductors from 0,2 mm² up to 35 mm² (included)*

IEC 60999-2:2003, *Connecting devices – Electrical copper conductors – Safety requirements for screw-type and screwless-type clamping units – Part 2: Particular requirements for clamping units for conductors above 35 mm² up to 300 mm² (included)* **A1**

IEC 61000-3-2:2005, *Electromagnetic compatibility (EMC) – Part 3-2: Limits – Limits for harmonic current emissions (equipment input current ≤ 16 A per phase)*

A2 Amendment 1 (2008)
Amendment 2 (2009) **A2**

- A2** IEC 61000-3-3:2013, *Electromagnetic compatibility (EMC) – Part 3-3: Limits – Limitation of voltage changes, voltage fluctuations and flicker in public low-voltage supply systems, for equipment with rated current ≤ 16 A per phase and not subject to conditional connection*

IEC 61000-4-2:2008, *Electromagnetic compatibility (EMC) – Part 4-2: Testing and measurement techniques – Electrostatic discharge immunity test* **A2**

IEC 61000-4-3:2006, *Electromagnetic compatibility (EMC) – Part 4-3: Testing and measurement techniques – Radiated, radio-frequency, electromagnetic field immunity test*

A2 Amendment 1 (2007)
Amendment 2 (2010) **A2**

- A2** IEC 61000-4-4:2012, *Electromagnetic compatibility (EMC) – Part 4-4: Testing and measurement techniques – Electrical fast transient/burst immunity test* **A2**

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- A2** IEC 61000-4-6:2013, *Electromagnetic compatibility (EMC) – Part 4-6: Testing and measurement techniques – Immunity to conducted disturbances, induced by radio-frequency fields*

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^{A2} Amendment 1 (2009) ^{A2}

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IEC 61131-2:2003, *Programmable controllers – Part 2: Equipment requirements and tests*

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Amendment 1 (2004)

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^{A2} CISPR 11:2009, *Industrial, scientific and medical equipment – Radio-frequency disturbance characteristics – Limits and methods of measurement*

Amendment 1 (2010)

IEC 61508 (all parts), *Functional safety of electrical/electronic/programmable electronic safety-related systems* ^{A2}

^{A1} IEC 61557-2, *Electrical safety in low voltage distribution systems up to 1 000 V a.c. and 1 500 V d.c. – Equipment for testing, measuring or monitoring of protective measures – Part 2: Insulation resistance* ^{A1}

^{A2} IEC 61649:2008, *Weibull analysis*

IEC 62061:2005, *Safety of machinery – Functional safety of safety-related electrical, electronic and programmable electronic control systems*

IEC 62430:2009, *Environmentally conscious design for electrical and electronic products*

IEC 62474:2012, *Material declaration for products of and for the electrotechnical industry*

ISO 13849-1:2006, *Safety of machinery – Safety-related parts of control systems – Part 1: General principles for design* ^{A2}

2 Definitions

NOTE 1 Most of the definitions listed in this clause are taken unchanged from the IEV (IEC 60050). When this is the case, the IEV reference is given in brackets with the title (the first group of 3 figures indicates the IEV chapter reference).

When an IEV definition is amended, the IEV reference is not indicated with the title, but in an explanatory note.

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2.1 General terms

2.1.1

switchgear and controlgear

general term covering switching devices and their combination with associated control, measuring, protective and regulating equipment, also assemblies of such devices and equipment with associated interconnections, accessories, enclosures and supporting structures

[441-11-01]

2.1.2

switchgear

general term covering switching devices and their combination with associated control, measuring, protective and regulating equipment, also assemblies of such devices and equipment with associated interconnections, accessories, enclosures and supporting structures, intended in principle for use in connection with generation, transmission, distribution and conversion of electric energy

[441-11-02]

2.1.3

controlgear

general term covering switching devices and their combination with associated control, measuring, protective and regulating equipment, also assemblies of such devices and equipment with associated interconnections, accessories, enclosures and supporting structures, intended in principle for the control of electric energy consuming equipment

[441-11-03]

2.1.4

over-current

current exceeding the rated current

[441-11-06]

2.1.5

short circuit

accidental or intentional conductive path between two or more conductive parts forcing the electric potential differences between these conductive parts to be equal to or close to zero

[151-12-04]

2.1.6

short-circuit current

over-current resulting from a short circuit due to a fault or an incorrect connection in an electric circuit

[441-11-07]

2.1.7

overload

operating conditions in an electrically undamaged circuit which cause an over-current

[441-11-08]

2.1.8

overload current

over-current occurring in an electrically undamaged circuit

2.1.9

ambient air temperature

temperature, determined under prescribed conditions, of the air surrounding the complete switching device or fuse

[441-11-13]

NOTE For switching devices or fuses installed inside an enclosure, it is the temperature of the air outside the enclosure.

2.1.10

conductive part

part which is capable of conducting current although it may not necessarily be used for carrying service current

[441-11-09]

2.1.11

exposed conductive part

conductive part which can readily be touched and which is not normally alive, but which may become alive under fault conditions

[441-11-10]

NOTE Typical exposed conductive parts are walls of enclosures, operating handles, etc.

2.1.12

extraneous conductive part

conductive part not forming part of the electrical installation and liable to introduce a potential, generally the earth potential

[826-03-03]

2.1.13

live part

conductor or conductive part intended to be energized in normal use, including a neutral conductor but, by convention, not a PEN conductor

[826-03-01]

NOTE This term does not necessarily imply a risk of electric shock.

2.1.14

protective conductor (symbol PE)

conductor required by some measures for protection against electric shock for electrically connecting any of the following parts:

- exposed conductive parts,
- extraneous conductive parts,
- main earthing terminal,
- earth electrode,
- earthed point of the source or artificial neutral

[826-04-05]

2.1.15

neutral conductor (symbol N)

conductor connected to the neutral point of a system and capable of contributing to the transmission of electrical energy

[826-01-03]

NOTE In some cases, the functions of the neutral conductor and the protective conductor may be combined under specified conditions in one and the same conductor referred to as the PEN conductor (Symbol PEN).

2.1.16

enclosure

part providing a specified degree of protection of equipment against certain external influences and a specified degree of protection against approach to or contact with live parts and moving parts

NOTE This definition is similar to IECV 441-13-01, which applies to assemblies.

2.1.17

integral enclosure

enclosure which forms an integral part of the equipment

2.1.18

utilization category (for a switching device or a fuse)

combination of specified requirements related to the conditions in which the switching device or the fuse fulfils its purpose, selected to represent a characteristic group of practical applications

[441-17-19]

NOTE The specified requirements may concern e.g. the values of making capacities (if applicable), breaking capacities and other characteristics, the associated circuits and the relevant conditions of use and behaviour.

2.1.19

isolation (isolating function)

function intended to cut off the supply from all or a discrete section of the installation by separating the installation or section from every source of electrical energy for reasons of safety

2.1.20

electric shock

pathophysiological effect resulting from an electric current passing through a human or animal body

[826-03-04]

2.1.21

manufacturer

for the purposes of this standard, any person, company or organisation with ultimate responsibility as follows:

- to verify compliance with the appropriate standard or standards
- to provide the product information according to Clause 5

NOTE For instance, in the case of “protected starters” assembled according to the instructions of the component providers, the manufacturer will be the entity that undertook the assembly.

A₂ 2.1.22

solid insulation

solid insulating material interposed between two conductive parts **A₂**

A₂ 2.1.23

insulation coordination barrier

solid insulating material that is not an integral part, provided for the purpose of increasing either creepage distances or clearance distances or both **A₂**

2.2 Switching devices

2.2.1

switching device

device designed to make or break the current in one or more electric circuits

[441-14-01]

NOTE A switching device may perform one or both of these operations.

2.2.2

mechanical switching device

switching device designed to close and open one or more electric circuits by means of separable contacts

[441-14-02]

NOTE Any mechanical switching device may be designated according to the medium in which its contacts open and close, e.g.: air, SF₆, oil.

2.2.3

semiconductor switching device

switching device designed to make and/or break the current in an electric circuit by means of the controlled conductivity of a semiconductor

NOTE This definition differs from IEC 441-14-03 since a semiconductor switching device is also designed for breaking the current.

2.2.4

fuse

device that, by the fusing of one or more of its specifically designed and proportioned components, opens the circuit in which it is inserted by breaking the current when this exceeds a given value for a sufficient time. The fuse comprises all the parts that form the complete device

[441-18-01]

2.2.5

fuse-link

part of a fuse (including the fuse-element(s)) intended to be replaced after the fuse has operated

[441-18-09]

2.2.6

fuse-element

part of the fuse-link designed to melt under the action of current exceeding some definite value for a definite period of time

[441-18-08]

2.2.7

fuse-combination unit

combination of a mechanical switching device and one or more fuses in a composite unit, assembled by the manufacturer or in accordance with his instructions

[441-14-04]

2.2.8

disconnector

mechanical switching device which, in the open position, complies with the requirements specified for the isolating function

NOTE This definition differs from IEC 441-14-05 because the requirements for the isolating function are not based only on an isolating distance.

2.2.9

switch (mechanical)

mechanical switching device capable of making, carrying and breaking currents under normal circuit conditions which may include specified operating overload conditions and also carrying for a specified time currents under specified abnormal circuit conditions such as those of short circuit

[441-14-10]

NOTE A switch may be capable of making but not breaking short-circuit currents.

2.2.10

switch-disconnector

switch which, in the open position, satisfies the isolating requirements specified for a disconnector

[441-14-12]

2.2.11

circuit-breaker

mechanical switching device, capable of making, carrying and breaking currents under normal circuit conditions and also making, carrying for a specified time and breaking currents under specified abnormal circuit conditions such as those of short circuit

[441-14-20]

2.2.12

contactor (mechanical)

mechanical switching device having only one position of rest, operated otherwise than by hand, capable of making, carrying and breaking currents under normal circuit conditions including operating overload conditions

[441-14-33]

NOTE Contactors may be designated according to the method by which the force for closing the main contacts is provided.

2.2.13

semiconductor contactor (solid-state contactor)

device which performs the function of a contactor by utilizing a semiconductor switching device

NOTE A semiconductor contactor may also contain mechanical switching devices.

2.2.14

contactor relay

contactor used as a control switch

[441-14-35]

2.2.15
starter

combination of all the switching means necessary to start and stop a motor, in combination with suitable overload protection

[441-14-38]

NOTE Starters may be designated according to the method by which the force for closing the main contacts is provided.

2.2.16
control circuit device

electrical device, intended for the controlling, signalling, interlocking, etc. of switchgear and controlgear

NOTE Control circuit devices may include associated devices dealt with in other standards, such as instruments, potentiometers, relays, in so far as such associated devices are used for the purposes specified.

2.2.17
control switch (for control and auxiliary circuits)

mechanical switching device which serves the purpose of controlling the operation of switchgear or controlgear, including signalling, electrical interlocking, etc.

[441-14-46]

NOTE A control switch consists of one or more contact elements with a common actuating system.

2.2.18
pilot switch

non-manual control switch actuated in response to specified conditions of an actuating quantity

[441-14-48]

NOTE The actuating quantity may be pressure, temperature, velocity, liquid level, elapsed time, etc.

2.2.19
push-button

control switch having an actuator intended to be operated by force exerted by a part of the human body, usually the finger or palm of the hand, and having stored energy (spring) return

[441-14-53]

2.2.20
terminal block

insulating part carrying one or more mutually insulated terminal assemblies and intended to be fixed to a support

2.2.21
short-circuit protective device (SCPD)

device intended to protect a circuit or parts of a circuit against short-circuit currents by interrupting them

2.2.22
surge arrester

device designed to protect the electrical apparatus from high transient overvoltages and to limit the duration and frequently the amplitude of the follow-on current

[604-03-51]

A₂ 2.2.23

individual enclosure

enclosure designed and dimensioned to contain one equipment only **A₂**

2.3 Parts of switching devices

2.3.1

pole of a switching device

portion of a switching device associated exclusively with one electrically separated conducting path of its main circuit and excluding those portions which provide a means for mounting and operating all poles together

[441-15-01]

NOTE A switching device is called single-pole if it has only one pole. If it has more than one pole, it may be called multipole (two-pole, three-pole, etc.) provided the poles are or can be coupled in such a manner as to operate together.

2.3.2

main circuit (of a switching device)

all the conductive parts of a switching device included in the circuit which it is designed to close or open

[441-15-02]

2.3.3

control circuit (of a switching device)

all the conductive parts (other than the main circuit) of a switching device which are included in a circuit used for the closing operation or opening operation, or both, of the device

[441-15-03]

2.3.4

auxiliary circuit (of a switching device)

all the conductive parts of a switching device which are intended to be included in a circuit other than the main circuit and the control circuits of the device

[441-15-04]

NOTE Some auxiliary circuits fulfil supplementary functions such as signalling, interlocking, etc., and, as such, they may be part of the control circuit of another switching device.

2.3.5

contact (of a mechanical switching device)

conductive parts designed to establish circuit continuity when they touch and which, due to their relative motion during an operation, open or close a circuit or, in the case of hinged or sliding contacts, maintain circuit continuity

[441-15-05]

2.3.6

contact piece

one of the conductive parts forming a contact

[441-15-06]

2.3.7

main contact

contact included in the main circuit of a mechanical switching device, intended to carry, in the closed position, the current of the main circuit

[441-15-07]

2.3.8

arcing contact

arc contact on which the arc is intended to be established

[441-15-08]

NOTE An arcing contact may serve as a main contact; it may be a separate contact so designed that it opens after and closes before another contact which it is intended to protect from deterioration.

2.3.9

control contact

contact included in a control circuit of a mechanical switching device and mechanically operated by this device

[441-15-09]

2.3.10

auxiliary contact

contact included in an auxiliary circuit and mechanically operated by the switching device

[441-15-10]

2.3.11

auxiliary switch (of a mechanical switching device)

switch containing one or more control and/or auxiliary contacts mechanically operated by a switching device

[441-15-11]

2.3.12

"a" contact – make contact

control or auxiliary contact which is closed when the main contacts of the mechanical switching device are closed and open when they are open

[441-15-12]

2.3.13

"b" contact – break contact

control or auxiliary contact which is open when the main contacts of the mechanical switching device are closed and closed when they are open

[441-15-13]

2.3.14

relay (electrical)

device designed to produce sudden, predetermined changes in one or more electrical output circuits when certain conditions are fulfilled in the electrical input circuits controlling the device

[446-11-01]

2.3.15

release (of a mechanical switching device)

device, mechanically connected to a mechanical switching device, which releases the holding means and permits the opening or the closing of the switching device

[441-15-17]

NOTE A release can have instantaneous, time-delay, etc., operation. The various types of releases are defined in 2.4.24 to 2.4.35.

2.3.16

actuating system (of a mechanical switching device)

whole of the operating means of a mechanical switching device which transmit the actuating force to the contact pieces

NOTE The operating means of an actuating system may be mechanical, electromagnetic, hydraulic, pneumatic, thermal, etc.

2.3.17

actuator

part of the actuating system to which an external actuating force is applied

[441-15-22]

NOTE The actuator may take the form of a handle, knob, push-button, roller, plunger, etc.

2.3.18

position indicating device

part of a mechanical switching device which indicates whether it is in the open, closed, or, where appropriate, earthed position

[441-15-25]

2.3.19

indicator light

light signal giving information either by lighting or extinguishing

2.3.20

anti-pumping device

device which prevents reclosing after a close-open operation as long as the device initiating closing is maintained in the position for closing

[441-16-48]

2.3.21

interlocking device

device which makes the operation of a switching device dependent upon the position of operation of one or more other pieces of equipment

[441-16-49]

A1) 2.3.22

connecting device

a device for the electrical connection of one (or more) conductor(s), comprising one (or more) terminal(s), either fixed to a base or forming an integral part of the equipment

[IEC 60999-1:1999, 3.3]

2.3.23

terminal

conductive part of one pole of a device for electrical connection to external circuit, composed of one or more clamping unit(s) and insulation if necessary

[IEC 60999-1:1999, 3.2, modified] **A1**

A1 2.3.24

screw-type terminal

terminal intended for the connection and disconnection of conductors or for the interconnection of two or more conductors, the connection being made, directly or indirectly, by means of screws or nuts of any kind

NOTE Examples are given in Annex D.

2.3.25

screwless-type terminal

terminal intended for the connection and disconnection of conductors or for the interconnection on two or more conductors, the connection being made, directly or indirectly, by means of springs, wedges, eccentrics or cones, etc.

NOTE Examples are given in Annex D.

2.3.25.1

universal terminal

terminal for the connection and disconnection of all types of conductors (rigid and flexible)

[IEC 60998-2-2:2002, 3.101.1]

2.3.25.2

non-universal terminal

terminal for the connection and disconnection of a certain kind of conductor only (for example, solid conductors only or rigid [solid and stranded] conductors only)

[IEC 60998-2-2:2002, 3.101.2]

2.3.25.3

push-wire terminal

non-universal terminal in which the connection is made by pushing in rigid (solid or stranded) conductors

[IEC 60998-2-2:2002, 3.101.3]

2.3.26

clamping unit

the part(s) of the terminal necessary for the mechanical clamping and the electrical connection of the conductor(s), including the parts which are necessary to ensure the correct contact pressure

[IEC 60999-1:1999, 3.1]

2.3.26.1

universal clamping unit

clamping unit intended for all types of conductors

2.3.26.2

non-universal clamping unit

clamping unit intended for certain types of conductors only, for example:

- push-wire clamping unit for solid conductors only
- push-wire clamping unit for rigid (solid and stranded) conductors only

NOTE On push-wire clamping unit the connection is made by simple insertion of rigid conductors. (see 7.1.8.1) **A1**

A1 2.3.27

unprepared conductor

conductor which has been cut and the insulation of which has been removed for insertion into a terminal

NOTE A conductor the shape of which is arranged for introduction into a terminal or the strands of which are twisted to consolidate the end is considered to be an unprepared conductor.

2.3.28

prepared conductor

conductor, the strands of which are soldered or the end of which is fitted with a cable lug, eyelet, etc.

A2 2.3.29

solid conductor

conductor consisting of a single wire

NOTE 1 The solid conductor may be circular or shaped.

NOTE 2 Solid conductor is defined as class 1 conductor in IEC 60228, or by IEC 60344, or equivalent AWG/kcmil.

[461-01-06, modified]

2.3.30

stranded conductor

conductor consisting of a number of wires, all or some of which are wound in a helix

NOTE Stranded conductor is defined as class 2 conductor in IEC 60228, or by IEC 60344, or equivalent AWG/kcmil.

[151-12-36, modified]

2.3.31

rigid conductor

solid or stranded conductor having wires of such diameters, or so assembled, that the conductor is not suitable for use in a flexible cable

2.3.32

flexible conductor

stranded conductor having wires of diameters small enough and so assembled that the conductor is suitable for use in a flexible cable

NOTE Flexible conductor is defined as class 5 or class 6 conductor in IEC 60228, or by IEC 60344, or equivalent AWG/kcmil.

[461-01-11, modified] **A2**

A2 2.3.33 **A2**

multiple tip contact system

contact system comprising more than one contact gap per pole, which can be switched, in series and/or in parallel

A2 2.3.34 **A2**

minimum cross-section

value of the smallest connectable conductor cross-section stated by the manufacturer as suitable for the terminal

NOTE The manufacturer may declare several minimum cross-sections depending on the type of conductor, for example rigid, stranded, flexible, with or without ferrule.

A2 2.3.35 **A2**

maximum cross-section

value of the largest connectable conductor cross-section stated by the manufacturer as suitable for the terminal

NOTE 1 The manufacturer may declare several maximum cross-sections depending on the type of conductor, for example rigid, stranded, flexible, with or without ferrule.

NOTE 2 The term “rated cross-section” used in IEC 60947-7-1 and IEC 60999-2 and the term “rated connecting capacity” of a clamping unit used in IEC 60999-1 are considered equivalent when referring to certain thermal, mechanical and electrical requirements, as stated by the manufacturer and as specified in their relevant product standard.

A2 2.3.36 **A2**

electronically controlled electromagnet

electromagnet in which the coil is controlled by a circuit with active electronic elements **A1**

2.4 Operation of switching devices

2.4.1

operation (of a mechanical switching device)

transfer of the moving contact(s) from one position to an adjacent position

[441-16-01]

NOTE 1 For example, for a circuit-breaker, this may be a closing operation or an opening operation.

NOTE 2 If distinction is necessary, an operation in the electrical sense, e.g., make or break, is referred to as a switching operation, and an operation in the mechanical sense, e.g., close or open, is referred to as a mechanical operation.

2.4.2

operating cycle (of a mechanical switching device)

succession of operations from one position to another and back to the first position through all other positions, if any

[441-16-02]

2.4.3

operating sequence (of a mechanical switching device)

succession of specified operations with specified time intervals

[441-16-03]

2.4.4

manual control

control of an operation by human intervention

[441-16-04]

2.4.5

automatic control

control of an operation without human intervention, in response to the occurrence of predetermined conditions

[441-16-05]

2.4.6

local control

control of an operation at a point on or adjacent to the controlled switching device

[441-16-06]

2.4.7

remote control

control of an operation at a point distant from the controlled switching device

[441-16-07]

2.4.8

closing operation (of a mechanical switching device)

operation by which the device is brought from the open position to the closed position

[441-16-08]

2.4.9

opening operation (of a mechanical switching device)

operation by which the device is brought from the closed position to the open position

[441-16-09]

2.4.10

positive opening operation (of a mechanical switching device)

opening operation which, in accordance with specified requirements, ensures that all the main contacts are in the open position when the actuator is in the position corresponding to the open position of the device

[441-16-11]

2.4.11

positively driven operation

operation which, in accordance with specified requirements, is designed to ensure that auxiliary contacts of a mechanical switching device are in the respective positions corresponding to the open or closed position of the main contacts

[441-16-12]

2.4.12

dependent manual operation (of a mechanical switching device)

operation solely by means of directly applied manual energy such that the speed and force of the operation are dependent upon the action of the operator

[441-16-13]

2.4.13

dependent power operation (of a mechanical switching device)

operation by means of energy other than manual, where the completion of the operation is dependent upon the continuity of the power supply (to solenoids, electric or pneumatic motors, etc.)

[441-16-14]

2.4.14

stored energy operation (of a mechanical switching device)

operation by means of energy stored in the mechanism itself prior to the completion of the operation and sufficient to complete it under predetermined conditions

[441-16-15]

NOTE This kind of operation may be subdivided according to:

- 1 the manner of storing the energy (spring, weight, etc.);
- 2 the origin of the energy (manual, electric, etc.);
- 3 the manner of releasing the energy (manual, electric, etc.).

2.4.15

independent manual operation (of a mechanical switching device)

stored energy operation where the energy originates from manual power, stored and released in one continuous operation, such that the speed and force of the operation are independent of the action of the operator

[441-16-16]

2.4.16

independent power operation (of a mechanical switching device)

stored energy operation where the stored energy originates from an external power source and is released in one continuous operation, such that the speed and force of the operation are independent of the action of the operator

2.4.17

actuating force (moment)

force (moment) applied to an actuator necessary to complete the intended operation

[441-16-17]

2.4.18

restoring force (moment)

force (moment) provided to restore an actuator or a contact element to its initial position

[441-16-19]

2.4.19

travel (of a mechanical switching device or a part thereof)

displacement (translation or rotation) of a point on a moving element

[441-16-21]

NOTE Distinction may be made between pre-travel, over-travel, etc.

2.4.20

closed position (of a mechanical switching device)

position in which the predetermined continuity of the main circuit of the device is secured

[441-16-22]

2.4.21

open position (of a mechanical switching device)

position in which the predetermined dielectric withstand voltage requirements are satisfied between open contacts in the main circuit of the device

NOTE This definition differs from IEC 441-16-23 to meet the requirements of dielectric properties.

2.4.22

tripping (operation)

opening operation of a mechanical switching device initiated by a relay or release

2.4.23

trip-free mechanical switching device

mechanical switching device, the moving contacts of which return to and remain in the open position when the opening (i.e. tripping) operation is initiated after the initiation of the closing operation, even if the closing command is maintained

NOTE 1 To ensure proper breaking of the current which may have been established, it may be necessary that the contacts momentarily reach the closed position.

NOTE 2 The wording of IEC 441-16-31 has been completed by adding "(i.e. tripping)" since the opening operation of a trip-free mechanical switching device is automatically controlled.

2.4.24

instantaneous relay or release

relay or release which operates without any intentional time-delay

2.4.25

over-current relay or release

relay or release which causes a mechanical switching device to open with or without time-delay when the current in the relay or release exceeds a predetermined value

NOTE This value can in some cases depend upon the rate-of-rise of current.

2.4.26

definite time-delay over-current relay or release

over-current relay or release which operates with a definite time-delay which may be adjustable, but is independent of the value of the over-current

2.4.27

inverse time-delay over-current relay or release

over-current relay or release which operates after a time-delay inversely dependent upon the value of the over-current

NOTE Such a relay or release may be designed so that the time-delay approaches a definite minimum value for high values of over-current.

2.4.28

direct over-current relay or release

over-current relay or release directly energized by the current in the main circuit of a switching device

2.4.29

indirect over-current relay or release

over-current relay or release energized by the current in the main circuit of a switching device through a current transformer or a shunt

2.4.30

overload relay or release

over-current relay or release intended for protection against overloads

2.4.31

thermal overload relay or release

inverse time-delay overload relay or release depending for its operation (including its time-delay) on the thermal action of the current flowing in the relay or release

2.4.32

magnetic overload relay or release

overload relay or release depending for its operation on the force exerted by the current in the main circuit exciting the coil of an electromagnet

NOTE Such a relay or release usually has an inverse time-delay/current characteristic.

2.4.33

shunt release

release energized by a source of voltage

[441-16-41]

NOTE The source of voltage may be independent of the voltage of the main circuit.

2.4.34

under-voltage relay or release

relay or release which permits a mechanical switching device to open or close, with or without time-delay, when the voltage across the terminals of the relay or release falls below a predetermined value

2.4.35

reverse current relay or release (d.c. only)

relay or release which permits a mechanical switching device to open, with or without time-delay, when the current flows in the reverse direction and exceeds a predetermined value

2.4.36

operating current (of an over-current relay or release)

value of current at and above which the relay or release will operate

2.4.37

current-setting (of an over-current or overload relay or release)

value of current of the main circuit to which the operating characteristics of the relay or release are referred and for which the relay or release is set

NOTE A relay or release may have more than one current setting, provided by an adjustment dial, interchangeable heaters, etc.

2.4.38

current setting range (of an over-current or overload relay or release)

range between the minimum and maximum values over which the current setting of the relay or release can be adjusted

2.5 Characteristic quantities

2.5.1

nominal value

value of a quantity used to designate and identify a component, device, equipment, or system

[151-16-09]

NOTE The nominal value is generally a rounded value.

2.5.2

limiting value

in a specification of a component, device, equipment, or system, the greatest or smallest admissible value of a quantity

[151-16-10]

2.5.3

rated value

value of a quantity used for specification purposes, established for a specified set of operating conditions of a component, device, equipment, or system

[151-16-08]

2.5.4

rating

set of rated values and operating conditions

[151-16-11]

2.5.5

prospective current (of a circuit and with respect to a switching device or a fuse)
current that would flow in the circuit if each pole of the switching device or the fuse were replaced by a conductor of negligible impedance

[441-17-01]

NOTE The method to be used to evaluate and to express the prospective current is to be specified in the relevant product standard.

2.5.6

prospective peak current
peak value of a prospective current during the transient period following initiation

[441-17-02]

NOTE The definition assumes that the current is made by an ideal switching device, i.e. with instantaneous transition from infinite to zero impedance. For circuits where the current can follow several different paths, e.g. polyphase circuits, it further assumes that the current is made simultaneously in all poles, even if only the current in one pole is considered.

2.5.7

prospective symmetrical current (of an a.c. circuit)
prospective current when it is initiated at such an instant that no transient phenomenon follows the initiation

[441-17-03]

NOTE 1 For polyphase circuits the condition of non-transient period can only be satisfied for the current in one pole at a time.

NOTE 2 The prospective symmetrical current is expressed by its r.m.s. value.

2.5.8

maximum prospective peak current (of an a.c. circuit)
prospective peak current when initiation of the current takes place at the instant which leads to the highest possible value

[441-17-04]

NOTE For a multipole device in a polyphase circuit, the maximum prospective peak current refers to one pole only.

2.5.9

prospective making current (for a pole of a switching device)
prospective current when initiated under specified conditions

[441-17-05]

NOTE The specified conditions may relate to the method of initiation, e.g. by an ideal switching device, or to the instant of initiation, e.g., leading to the maximum prospective peak current in an a.c. circuit, or to the highest rate of rise. The specification of these conditions is given in the relevant product standard.

2.5.10

prospective breaking current (for a pole of a switching device or a fuse)
prospective current evaluated at a time corresponding to the instant of the initiation of the breaking process

[441-17-06]

NOTE Specifications concerning the instant of the initiation of the breaking process are given in the relevant product standard. For mechanical switching devices or fuses, it is usually defined as the moment of initiation of the arc during the breaking process.

2.5.11

breaking current (of a switching device or a fuse)

current in a pole of a switching device or in a fuse at the instant of initiation of the arc during a breaking process

[441-17-07]

NOTE For a.c., the current is expressed as the symmetrical r.m.s. value of the a.c. component.

2.5.12

breaking capacity (of a switching device or a fuse)

value of prospective breaking current that a switching device or a fuse is capable of breaking at a stated voltage under prescribed conditions of use and behaviour

[441-17-08]

NOTE 1 The voltage to be stated and the conditions to be prescribed are dealt with in the relevant product standard.

NOTE 2 For a.c., the current is expressed as the symmetrical r.m.s. value of the a.c. component.

NOTE 3 For short-circuit breaking capacity, see 2.5.14.

2.5.13

making capacity (of a switching device)

value of prospective making current that a switching device is capable of making at a stated voltage under prescribed conditions of use and behaviour

[441-17-09]

NOTE 1 The voltage to be stated and the conditions to be prescribed are dealt with in the relevant product standard.

NOTE 2 For short-circuit making capacity, see 2.5.15.

2.5.14

short-circuit breaking capacity

breaking capacity for which prescribed conditions include a short circuit at the terminals of the switching device

[441-17-11]

2.5.15

short-circuit making capacity

making capacity for which prescribed conditions include a short circuit at the terminals of the switching device

[441-17-10]

2.5.16

critical load current

value of breaking current, within the range of service conditions, at which the arcing time is significantly extended

2.5.17

critical short-circuit current

value of breaking current, less than the rated short-circuit breaking capacity, at which the arc energy is significantly higher than at the rated short-circuit breaking capacity

2.5.18

Joule integral (I^2t)

integral of the square of the current over a given time interval

[441-18-23]

$$I^2t = \int_{t_0}^{t_1} i^2 dt$$

2.5.19

cut-off current – let-through current

maximum instantaneous value of current attained during the breaking operation of a switching device or a fuse

[441-17-12]

NOTE This concept is of particular importance when the switching device or the fuse operates in such a manner that the prospective peak current of the circuit is not reached.

2.5.20

time-current characteristic

curve giving the time, e.g. pre-arcing time or operating time, as a function of the prospective current, under stated conditions of operation

[441-17-13]

2.5.21

cut-off (current) characteristic – let-through (current) characteristic

curve giving the cut-off current as a function of the prospective current, under stated conditions of operation

[441-17-14]

NOTE In the case of a.c., the values of the cut-off currents are the maximum values which can be reached whatever the degree of asymmetry. In the case of d.c., the values of the cut-off currents are the maximum values reached related to the time constant as specified.

2.5.22

over-current protective co-ordination of over-current protective devices

co-ordination of two or more over-current protective devices in series to ensure overcurrent discrimination (selectivity) and/or back-up protection

2.5.23

A_2 over-current selectivity A_2

co-ordination of the operating characteristics of two or more over-current protective devices such that, on the incidence of over-currents within stated limits, the device intended to operate within these limits does so, while the other(s) does (do) not

A_2 text deleted A_2

NOTE Distinction is made between series A_2 selectivity A_2 involving different over-current protective devices passing substantially the same over-current and network A_2 selectivity A_2 involving identical protective devices passing different proportions of the over-current.

2.5.24

back-up protection

over-current co-ordination of two over-current protective devices in series where the protective device, generally but not necessarily on the supply side, effects the over-current protection with or without the assistance of the other protective device and prevents any excessive stress on the latter

2.5.25

take-over current

current co-ordinate of the intersection between the time-current characteristics of two over-current protective devices

[441-17-16]

2.5.26

short-time delay

any intentional delay in operation within the limits of the rated short-time withstand current

2.5.27

short-time withstand current

current that a circuit or a switching device in the closed position can carry during a specified short time under prescribed conditions of use and behaviour

[441-17-17]

2.5.28

peak withstand current

value of peak current that a circuit or a switching device in the closed position can withstand under prescribed conditions of use and behaviour

[441-17-18]

2.5.29

conditional short-circuit current (of a circuit or a switching device)

prospective current that a circuit or a switching device, protected by a specified short-circuit protective device, can satisfactorily withstand for the total operating time of that device under specified conditions of use and behaviour

NOTE 1 For the purpose of this standard, the short-circuit protective device is generally a circuit-breaker or a fuse.

NOTE 2 This definition differs from IEC 441-17-20 by broadening the concept of current limiting device into a short-circuit protective device, the function of which is not only to limit the current.

2.5.30

conventional non-tripping current (of an over-current relay or release)

specified value of current which the relay or release can carry for a specified time (conventional time) without operating

2.5.31

conventional tripping current (of an over-current relay or release)

specified value of current which causes the relay or release to operate within a specified time (conventional time)

2.5.32

applied voltage (for a switching device)

voltage which exists across the terminals of a pole of a switching device just before the making of the current

[441-17-24]

NOTE This definition applies to a single-pole device. For a multipole device it is the phase-to-phase voltage across the supply terminals of the device.

2.5.33

recovery voltage

voltage which appears across the terminals of a pole of a switching device or a fuse after the breaking of the current

[441-17-25]

NOTE 1 This voltage may be considered in two successive intervals of time, one during which a transient voltage exists, followed by a second one during which the power-frequency voltage or the steady-state recovery voltage alone exists.

NOTE 2 This definition applies to a single-pole device. For a multipole device it is the phase-to-phase voltage across the supply terminals of the device.

2.5.34

transient recovery voltage (abbreviation TRV)

recovery voltage during the time in which it has a significant transient character

[441-17-26]

NOTE The transient voltage may be oscillatory or non-oscillatory or a combination of these depending on the characteristics of the circuit, the switching device or the fuse. It includes the voltage shift of the neutral of a polyphase circuit.

2.5.35

power-frequency recovery voltage

recovery voltage after the transient voltage phenomena have subsided

[441-17-27]

2.5.36

d.c. steady-state recovery voltage

recovery voltage in a d.c. circuit after the transient voltage phenomena have subsided, expressed by the mean value where ripple is present

[441-17-28]

2.5.37

prospective transient recovery voltage (of a circuit)

transient recovery voltage following the breaking of the prospective symmetrical current by an ideal switching device

[441-17-29]

NOTE The definition assumes that the switching device or the fuse, for which the prospective transient recovery voltage is sought, is replaced by an ideal switching device, i.e. having instantaneous transition from zero to infinite impedance at the very instant of zero current, i.e. at the "natural" zero. For circuits where the current can follow several different paths, e.g. a polyphase circuit, the definition further assumes that the breaking of the current by the ideal switching device takes place only in the pole considered.

2.5.38

peak arc voltage (of a mechanical switching device)

maximum instantaneous value of voltage which, under prescribed conditions, appears across the terminals of a pole of a switching device during the arcing time

[441-17-30]

2.5.39

opening time (of a mechanical switching device)

interval of time between the specified instant of initiation of the opening operation and the instant when the arcing contacts have separated in all poles

[441-17-36]

NOTE The instant of initiation of the opening operation, i.e. the application of the opening command (e.g. energizing the release), is given in the relevant product standard.

2.5.40

arcing time (of a pole or a fuse)

interval of time between the instant of the initiation of the arc in a pole or a fuse and the instant of final arc extinction in that pole or that fuse

[441-17-37]

2.5.41

arcing time (of a multipole switching device)

interval of time between the instant of the first initiation of an arc and the instant of final arc extinction in all poles

[441-17-38]

2.5.42

break time

interval of time between the beginning of the opening time of a mechanical switching device (or the pre-arcing time of a fuse) and the end of the arcing time

[441-17-39]

2.5.43

make time

interval of time between the initiation of the closing operation and the instant when the current begins to flow in the main circuit

[441-17-40]

2.5.44

closing time

interval of time between the initiation of the closing operation and the instant when the contacts touch in all poles

[441-17-41]

2.5.45

make-break time

interval of time between the instant when the current begins to flow in a pole and the instant of final arc extinction in all poles, with the opening release energized at the instant when current begins to flow in the main circuit

[441-17-43]

2.5.46

clearance

distance between two conductive parts, along a string stretched the shortest way between these conductive parts

[441-17-31]

2.5.47

clearance between poles

clearance between any conductive parts of adjacent poles

[441-17-32]

2.5.48

clearance to earth

clearance between any conductive parts and any parts which are earthed or intended to be earthed

[441-17-33]

2.5.49

clearance between open contacts (gap)

total clearance between the contacts, or any conductive parts connected thereto, of a pole of a mechanical switching device in the open position

[441-17-34]

2.5.50

isolating distance (of a pole of a mechanical switching device)

clearance between open contacts meeting the safety requirements specified for disconnectors

[441-17-35]

2.5.51

creepage distance

shortest distance along the surface of an insulating material between two conductive parts

NOTE A joint between two pieces of insulating material is considered part of the surface.

2.5.52

working voltage

highest r.m.s. value of the a.c. or d.c. voltage across any particular insulation which can occur when the equipment is supplied at rated voltage

NOTE 1 Transients are disregarded.

NOTE 2 Both open-circuit conditions and normal operating conditions are taken into account.

2.5.53

temporary overvoltage

phase-to-earth, phase-to-neutral or phase-to-phase overvoltage at a given location and of relatively long duration (several seconds)

2.5.54

transient overvoltages

transient overvoltages in the sense of this standard are the following:

2.5.54.1

switching overvoltage

transient overvoltage at a given location on a system due to a specific switching operation or a fault

2.5.54.2

lightning overvoltage

transient overvoltage at a given location on a system due to a specific lightning discharge

[see also IEC 60060 and IEC 60071-1]

2.5.54.3

functional overvoltage

deliberately imposed overvoltage necessary for the functioning of a device

2.5.55

impulse withstand voltage

highest peak value of an impulse voltage, of prescribed form and polarity, which does not cause breakdown under specified conditions of test

2.5.56

power-frequency withstand voltage

r.m.s. value of a power-frequency sinusoidal voltage which does not cause breakdown under specified conditions of test

2.5.57

pollution

any condition of foreign matter, solid, liquid or gaseous (ionized gases), that may affect dielectric strength or surface resistivity

2.5.58

pollution degree (of environmental conditions)

conventional number based on the amount of conductive or hygroscopic dust, ionized gas or salt and on the relative humidity and its frequency of occurrence, resulting in hygroscopic absorption or condensation of moisture leading to reduction in dielectric strength and/or surface resistivity

NOTE 1 The pollution degree to which equipment is exposed may be different from that of the macro-environment where the equipment is located because of protection offered by means such as an enclosure or internal heating to prevent absorption or condensation of moisture.

NOTE 2 For the purpose of this standard, the pollution degree is that of the micro-environment.

2.5.59

micro-environment (of a clearance or creepage distance)

ambient conditions which surround the clearance or creepage distance under consideration

NOTE The micro-environment of the creepage distance or clearance and not the environment of the equipment determines the effect on the insulation. The micro-environment might be better or worse than the environment of the equipment. It includes all factors influencing the insulation, such as climatic and electromagnetic conditions, generation of pollution, etc.

2.5.60

overvoltage category (of a circuit or within an electrical system)

conventional number based on limiting (or controlling) the values of prospective transient overvoltages occurring in a circuit (or within an electrical system having different nominal voltages) and depending upon the means employed to influence the overvoltages

NOTE In an electrical system, the transition from one overvoltage category to another of lower category is obtained through appropriate means complying with interface requirements, such as an overvoltage protective device or a series-shunt impedance arrangement capable of dissipating, absorbing, or diverting the energy in the associated surge current, to lower the transient overvoltage value to that of the desired lower overvoltage category.

2.5.61

co-ordination of insulation

correlation of insulating characteristics of electrical equipment with the expected overvoltages and the characteristics of overvoltage protective devices on the one hand, and with the expected micro-environment and the pollution protective means on the other hand

2.5.62

homogeneous (uniform) field

electric field which has an essentially constant voltage gradient between electrodes, such as that between two spheres where the radius of each sphere is greater than the distance between them

2.5.63

inhomogeneous (non-uniform) field

electric field which has not an essentially constant voltage gradient between electrodes

2.5.64

tracking

progressive formation of conducting paths which are produced on the surface of a solid insulating material, due to the combined effects of electric stress and electrolytic contamination on this surface

2.5.65

comparative tracking index (CTI)

numerical value of the maximum voltage in volts at which a material withstands 50 drops of a test solution without tracking

NOTE 1 The value of each test voltage and the CTI should be divisible by 25.

NOTE 2 This definition reproduces 2.3 of IEC 60112.

A₂ 2.5.66

rated control circuit voltage

U_c

rated voltage which is controlling the input signal of the control device

2.5.67

rated control circuit supply voltage

U_s

rated voltage applied to energize the power supply terminals of the control circuit **A₂**

2.6 Tests

2.6.1

type test

test of one or more devices made to a certain design to show that the design meets certain specifications

2.6.2

routine test

test to which each individual device is subjected during and/or after manufacture to ascertain whether it complies with certain criteria

2.6.3

sampling test

test on a number of devices taken at random from a batch

2.6.4

special test

test, additional to type tests and routine tests, made either at the discretion of the manufacturer or according to an agreement between manufacturer and user

2.7 Ports

2.7.1

port

particular interface of the specified apparatus with the external electromagnetic environment (see Figure 17)

2.7.2

enclosure port

physical boundary of the apparatus which electromagnetic fields may radiate through or impinge on

2.7.3

cable port

port at which a conductor or cable is connected to the apparatus

NOTE Examples are signal ports used for the transfer of data.

2.7.4

functional earth port

cable port other than main, signal or power port, intended for connection to earth for purposes other than electrical safety

2.7.5

signal port

port at which a conductor or cable carrying information for transferring data is connected to the apparatus

NOTE Examples are data buses, communication networks, control networks.

2.7.6

power port (control supply port)

port at which a conductor or cable carrying the primary electrical power needed for the operation (functioning) of an apparatus or associated apparatus is connected to the apparatus

2.7.7

main port

port at which a conductor or cable is connected to a pole of the main circuit of the equipment

NOTE 1 Examples are main circuit terminals of a contactor.

NOTE 2 In some equipment a main port is also a power port.

3 Classification

This clause is intended to list the characteristics of an equipment on which information may be given by the manufacturer and which may not necessarily have to be verified by testing.

This clause is not mandatory in product standards which should, however, leave space for it in order to list, where necessary, classification criteria.

4 Characteristics

Alphabetical list of characteristics (whether rated or not) and symbols

Characteristic	Symbol	Subclause
Conventional enclosed thermal current	I_{the}	4.3.2.2
Conventional free air thermal current	I_{th}	4.3.2.1
Eight-hour duty	–	4.3.4.1
Intermittent duty	–	4.3.4.3
Periodic duty	–	4.3.4.5
A_2 Pole impedance of the switching device	–	4.3.7 A_2
Rated breaking capacity	–	4.3.5.3
Rated conditional short-circuit current	$A_2 I_q A_2$	4.3.6.4
Rated control circuit voltage	U_c	4.5.1
Rated control A_2 circuit A_2 supply volatage	U_s	4.5.1
Rated current	I_n	a
Rated frequency	–	4.3.3
Rated impulse withstand voltage	U_{imp}	4.3.1.3
Rated insulation voltage	U_i	4.3.1.2
Rated making capacity	–	4.3.5.2
Rated operational current	I_e	4.3.2.3
Rated operational power	–	4.3.2.3
Rated operational voltage	U_e	4.3.1.1
Rated rotor insulation voltage	U_{ir}	a
Rated rotor operational current	I_{er}	a
Rated rotor operational voltage	U_{er}	a
Rated service short-circuit breaking capacity	I_{cs}	a
Rated short-circuit breaking capacity	I_{cn}	4.3.6.3
Rated short-circuit making capacity	I_{cm}	4.3.6.2
Rated short-time withstand current	I_{cw}	4.3.6.1
Rated starting voltage of an autotransformer starter	–	a
Rated stator insulation voltage	U_{is}	a
Rated stator operational current	I_{es}	a
Rated stator operational voltage	U_{es}	a
Rated ultimate short-circuit breaking capacity	I_{cu}	A_1 a
Rated uninterrupted current	I_u	4.3.2.4 A_1
Rotor thermal current	I_{thr}	a
Selectivity limit current	I_s	a
Stator thermal current	I_{ths}	a
Take-over current	I_B	2.5.25
Temporary duty	–	4.3.4.4
Uninterrupted duty	–	4.3.4.2
Utilization category	–	4.4

^a This rating is defined in the relevant product standard.

NOTE The above list is not exhaustive.

4.1 General

The characteristics of an equipment shall be stated in the relevant product standard in respect of the following, where applicable:

- type of equipment (4.2);
- rated and limiting values for the main circuit (4.3);
- utilization category (4.4);
- control circuits (4.5);
- auxiliary circuits (4.6);
- relay and releases (4.7);
- co-ordination with short-circuit protective devices (4.8);
- switching overvoltages (4.9).

4.2 Type of equipment

The product standard shall state the following, where applicable:

- kind of equipment: e.g. contactor, circuit-breaker, etc.;
- number of poles;
- kind of current;
- interrupting medium;
- operating conditions (method of operation, method of control, etc.).

NOTE The above list is not exhaustive.

4.3 Rated and limiting values for the main circuit

Ratings are assigned by the manufacturer. They shall be stated in accordance with 4.3.1 to 4.3.6 as required by the relevant product standard, but it is not necessary to establish all the ratings listed.

4.3.1 Rated voltages

An equipment is defined by the following rated voltages:

NOTE Certain types of equipment may have more than one rated voltage or may have a rated voltage range.

4.3.1.1 Rated operational voltage (U_e)

A rated operational voltage of an equipment is a value of voltage which, combined with a rated operational current, determines the application of the equipment and to which the relevant tests and the utilization categories are referred.

For single-pole equipment, the rated operational voltage is generally stated as the voltage across the pole.

For multipole equipment, it is generally stated as the voltage between phases.

NOTE 1 For certain devices and particular applications a different method of stating U_e , may apply: this should be stated in the relevant product standard.

NOTE 2 For multipole equipment for use on polyphase circuits a distinction may be made between

- a) equipment for use on systems where a single fault to earth will not cause the full phase-to-phase voltage to appear across a pole;
 - neutral earthed systems;

- unearthed and impedance earthed systems.

b) equipment for use on systems where a single fault to earth will cause the full phase-to-phase voltage to appear across a pole (i.e. phase earthed systems).

NOTE 3 An equipment may be assigned a number of combinations of rated operational voltages and rated operational currents or powers for different duties and utilization categories.

NOTE 4 An equipment may be assigned a number of rated operational voltages and associated making and breaking capacities for different duties and utilization categories.

NOTE 5 Attention is drawn to the fact that the operational voltage may differ from the working voltage (see 2.5.52) within an equipment.

4.3.1.2 Rated insulation voltage (U_i)

The rated insulation voltage of an equipment is the value of voltage to which dielectric tests and creepage distances are referred.

In no case shall the maximum value of the rated operational voltage exceed that of the rated insulation voltage.

NOTE For equipment not having a specified rated insulation voltage, the highest value of the rated operational voltage is considered to be the rated insulation voltage.

4.3.1.3 Rated impulse withstand voltage (U_{imp})

The peak value of an impulse voltage of prescribed form and polarity which the equipment is capable of withstanding without failure under specified conditions of test and to which the values of the clearances are referred.

The rated impulse withstand voltage of an equipment shall be equal to or higher than the values stated for the transient overvoltages occurring in the circuit in which the equipment is fitted.

NOTE Preferred values of rated impulse withstand voltage are given in Table 12.

4.3.2 Currents

An equipment is defined by the following currents:

4.3.2.1 Conventional free air thermal current (I_{th})

The conventional free air thermal current is the maximum value of test current to be used for temperature-rise tests of unenclosed equipment in free air (see 8.3.3.3).

The value of the conventional free air thermal current shall be at least equal to the maximum value of the rated operational current (see 4.3.2.3) of the unenclosed equipment in eight-hour duty (see 4.3.4.1).

Free air is understood to be air under normal indoor conditions reasonably free from draughts and external radiation.

NOTE 1 This current is not a rating and is not mandatorily marked on the equipment.

NOTE 2 An unenclosed equipment is an equipment supplied by the manufacturer without an enclosure or an equipment supplied by the manufacturer with an integral enclosure which is not normally intended to be the sole equipment protective enclosure.

4.3.2.2 Conventional enclosed thermal current (I_{the})

The conventional enclosed thermal current is the value of current stated by the manufacturer to be used for the temperature-rise tests of the equipment when mounted in a specified enclosure. Such tests shall be in accordance with 8.3.3.3 and are mandatory if the equipment is described as enclosed equipment in the manufacturer's catalogues and normally intended for use with one or more enclosures of specified type and size (see Note 3).

The value of the conventional enclosed thermal current shall be at least equal to the maximum value of the rated operational current (see 4.3.2.3) of the enclosed equipment in eight-hour duty (see 4.3.4.1).

If the equipment is normally intended for use in unspecified enclosures, the test is not mandatory if the test for conventional free air thermal current (I_{th}) has been made. In this case, the manufacturer shall be prepared to give guidance on the value of enclosed thermal current or the derating factor (see Note 1).

NOTE 1 Guidance may be in the form of a publication of the maximum rated current at a specified local ambient (surrounding, in the immediate vicinity of the device) air temperature (example 1: AC-1 $I_e = 45$ A at 40 °C local ambient air, AC-1 $I_e = 40$ A at 60 °C local ambient air – example 2: $I_{th} = 200$ A at 40 °C local ambient air, $I_{th} = 150$ A at 60 °C local ambient air). By publishing such values, the manufacturer informs the user of the limits of application of the product independently of the size or the type of the enclosure.

NOTE 2 This current is not a rating and is not mandatorily marked on the equipment.

NOTE 3 The conventional enclosed thermal current value may be for unventilated equipment, in which case the enclosure used for the test should be of the size stated by the manufacturer, being the smallest that is applicable in service. Alternatively, the value may be for a ventilated equipment according to the manufacturer's data.

NOTE 4 An enclosed equipment is an equipment normally intended for use with a specified type and size of enclosure or intended for use with more than one type of enclosure.

4.3.2.3 Rated operational current (I_e) or rated operational power

A rated operational current of an equipment is stated by the manufacturer and takes into account the rated operational voltage (see 4.3.1.1), the rated frequency (see 4.3.3), the rated duty (see 4.3.4), the utilization category (see 4.4) and the type of protective enclosure, if appropriate.

In the case of equipment for direct switching of individual motors, the indication of a rated operational current may be replaced or supplemented by an indication of the maximum rated power output, at the rated operational voltage considered, of the motor for which the equipment is intended. The manufacturer shall be prepared to state the relationship assumed between the operational current and the operational power, if any.

4.3.2.4 Rated uninterrupted current (I_u)

The rated uninterrupted current of an equipment is a value of current, stated by the manufacturer, which the equipment can carry in uninterrupted duty (see 4.3.4.2).

4.3.3 Rated frequency

The supply frequency for which an equipment is designed and to which the other characteristic values correspond.

NOTE The same equipment may be assigned a number or a range of rated frequencies or be rated for both a.c. and d.c.

4.3.4 Rated duties

The rated duties considered as normal are:

4.3.4.1 Eight-hour duty

A duty in which the main contacts of an equipment remain closed, whilst carrying a steady current long enough for the equipment to reach thermal equilibrium but not for more than eight hours without interruption.

NOTE 1 This is the basic duty on which the conventional thermal currents I_{th} and I_{the} of the equipment are determined.

NOTE 2 Interruption means breaking of the current by operation of the equipment.

4.3.4.2 Uninterrupted duty

A duty without any off-load period in which the main contacts of an equipment remain closed, whilst carrying a steady current without interruption for periods of more than eight hours (weeks, months, or even years).

NOTE This kind of service is set apart from the eight-hour duty because oxides and dirt can accumulate on the contacts and lead to progressive heating. Uninterrupted duty can be taken account of either by a derating factor, or by special design considerations (e.g. silver contacts).

4.3.4.3 Intermittent periodic duty or intermittent duty

A duty with on-load periods, in which the main contacts of an equipment remain closed, having a definite relation to off-load periods, both periods being too short to allow the equipment to reach thermal equilibrium.

Intermittent duty is characterized by the value of the current, the duration of the current flow and by the on-load factor which is the ratio of the in-service period to the entire period, often expressed as a percentage.

Standardized values of the on-load factor are 15 %, 25 %, 40 % and 60 %.

According to the number of operating cycles which they shall be capable of carrying out per hour, equipments are divided into the following classes:

- class 1: 1 operating cycle per hour;
- class 3: 3 operating cycles per hour;
- class 12: 12 operating cycles per hour;
- class 30: 30 operating cycles per hour;
- class 120: 120 operating cycles per hour;
- class 300: 300 operating cycles per hour;
- class 1 200: 1 200 operating cycles per hour;
- class 3 000: 3 000 operating cycles per hour;
- class 12 000: 12 000 operating cycles per hour;
- class 30 000: 30 000 operating cycles per hour;
- class 120 000: 120 000 operating cycles per hour;
- class 300 000: 300 000 operating cycles per hour.

For intermittent duty with a large number of operating cycles per hour, the manufacturer shall indicate, either in terms of the true cycle if this is known, or in terms of conventional cycles designated by him, the values of the rated operational currents which shall be such that:

$$\int_0^T i^2 dt \leq I_{th}^2 \times T \quad \text{or} \quad I_{the}^2 \times T$$

whichever is applicable

where T is the total operating cycle time.

NOTE The above formula does not take account of the switching arc energy.

A switching device intended for intermittent duty may be designated by the characteristics of the intermittent duty.

Example: An intermittent duty comprising a current flow of 100 A for 2 min in every 5 min may be stated as 100 A, class 12, 40 %.

4.3.4.4 Temporary duty

Duty in which the main contacts of an equipment remain closed for periods insufficient to allow the equipment to reach thermal equilibrium, the unload periods being separated by off-load periods of sufficient duration to restore equality of temperature with the cooling medium.

Standardized values of temporary duty are 3 min, 10 min, 30 min, 60 min and 90 min, with contacts closed.

4.3.4.5 Periodic duty

A type of duty in which operation, whether at constant or variable load, is regularly repeated.

4.3.5 Normal load and overload characteristics

This subclause gives general requirements concerning ratings under normal load and overload conditions.

NOTE Where applicable, the utilization categories referred to in 4.4 may include requirements in respect of performance under overload conditions.

Detailed requirements are given in 7.2.4.

4.3.5.1 Ability to withstand motor switching overload currents

An equipment intended for switching motors shall be capable of withstanding the thermal stresses due to starting and accelerating a motor to normal speed and due to operating overloads.

The detailed requirements to meet these conditions are given in the relevant product standard.

4.3.5.2 Rated making capacity

The rated making capacity of an equipment is a value of current, stated by the manufacturer, which the equipment can satisfactorily make under specified making conditions.

The making conditions which shall be specified are:

- the applied voltage (see 2.5.32);
- the characteristics of the test circuit.

The rated making capacity is stated by reference to the rated operational voltage and rated operational current, according to the relevant product standard.

NOTE 1 Where applicable, the relevant product standard states the relationship between rated making capacity and utilization category.

For a.c., the rated making capacity is expressed by the r.m.s. value of the symmetrical component of the current, assumed to be constant.

NOTE 2 For a.c., the peak value of the current during the first half-cycles following the closing of the main contacts of the equipment may be appreciably greater than the peak value of the current under steady-state conditions used in the determination of making capacity, depending on the power-factor of the circuit and the instant on the voltage wave when closing occurs.

An equipment should be capable of closing on a current having the a.c. component equal to that which defines its rated making capacity, whatever the value of the inherent d.c. component, within the limits resulting from the power-factors indicated in the relevant product standard.

4.3.5.3 Rated breaking capacity

The rated breaking capacity of all equipment is a value of current, stated by the manufacturer, which the equipment can satisfactorily break, under specified breaking conditions.

The breaking conditions which shall be specified are:

- the characteristics of the test circuit;
- the power-frequency recovery voltage.

The rated breaking capacity is stated by reference to the rated operational voltage and rated operational current, according to the relevant product standard.

An equipment shall be capable of breaking any value of current up to and including its rated breaking capacity.

NOTE 1 A switching device may have more than one rated breaking capacity, each corresponding to an operational voltage and a utilization category.

For a.c., the rated breaking capacity is expressed by the r.m.s. value of the symmetrical component of the current.

NOTE 2 Where applicable, the relevant product standard states the relationship between rated breaking capacity and utilization category.

4.3.6 Short-circuit characteristics

This subclause gives general requirements concerning ratings under short-circuit conditions.

4.3.6.1 Rated short-time withstand current (I_{cw})

A_2 The rated short-time withstand current of an equipment is the value of short-time current, assigned to the equipment by the manufacturer, that the equipment can carry without damage, under the test conditions specified in the relevant product standard. A_2

4.3.6.2 Rated short-circuit making capacity (I_{cm})

The rated short-circuit making capacity of an equipment is the value of short-circuit making capacity assigned to that equipment by the manufacturer for the rated operational voltage, at rated frequency, and at a specified power-factor for a.c. or time constant for d.c. It is expressed as the maximum prospective peak current, under prescribed conditions.

4.3.6.3 Rated short-circuit breaking capacity (I_{cn})

The rated short-circuit breaking capacity of an equipment is the value of short-circuit breaking capacity assigned to that equipment by the manufacturer for the rated operational voltage, at rated frequency, and at a specified power-factor for a.c. or time constant for d.c. It is expressed as the value of the prospective breaking current (r.m.s. value of the a.c. component in the case of a.c.), under prescribed conditions.

A_2 4.3.6.4 Rated conditional short-circuit current (I_q) A_2

The rated conditional short-circuit current of an equipment is the value of prospective current, stated by the manufacturer, which the equipment, protected by a short-circuit protective device specified by the manufacturer, can withstand satisfactorily for the operating time of this device under the test conditions specified in the relevant product standard.

The details of the specified short-circuit protective device shall be stated by the manufacturer.

NOTE 1 For a.c., the rated conditional short-circuit current is expressed by the r.m.s. value of the a.c. component.

NOTE 2 The short-circuit protective device may either form an integral part of the equipment or be a separate unit.

A_2 4.3.7 Pole impedance of the switching device (Z)

The pole impedance may be stated by the manufacturer and is determined by measuring the voltage drop resulting from the current flowing through the pole. A_2

4.4 Utilization category

The utilization category of an equipment defines the intended application and shall be specified in the relevant product standard; it is characterized by one or more of the following service conditions:

- current(s), expressed as multiple(s) of the rated operational current;
- voltage(s), expressed as multiple(s) of the rated operational voltage;
- power-factor or time-constant;
- short-circuit performance;
- selectivity;
- other service conditions, as applicable.

Examples of utilization categories for low-voltage switchgear and controlgear are given in Annex A.

4.5 Control circuits

A_1 4.5.1 Electrically or electronically controlled circuits

Characteristics of electrical and electronic control circuits:

- type of current;
- rated frequency or d.c.;
- rated control circuit voltage U_c (a.c., d.c.);
- A_2 – rated control circuit supply voltage U_s (a.c., d.c.), where applicable; A_2
- nature of external control circuit devices (contacts, sensors, optocouplers, electronic active components, etc);
- power consumption. A_1

A_2 NOTE 1 Distinction is made between the rated control circuit voltage U_c and the rated control circuit supply voltage U_s which may be different from U_c due to the presence of built-in transformers, rectifiers, resistors, electronic circuitry, etc. A_2

A1 NOTE 2 In case of an electronically control circuit a distinction is made between the control circuit voltage U_c , which is the controlling input signal, and the control supply voltage U_s , which is the voltage applied to energize the power supply terminals of the control circuit equipment and may be different from U_c due to the presence of built-in transformers, rectifiers, resistors, electronic circuitry, etc.

A2 The correct operating conditions are based upon a value of the control circuit supply voltage not less than 85 % of its rated value U_s , with the highest value of control circuit current flowing, nor more than 110 % of its rated value. **A2**

The electronic part of an electronically controlled electromagnet may form an integral part or a separate part provided it is an intrinsic function of the device. In both cases, the device shall be tested with this electronic part mounted as in normal use.

Annex U gives examples and illustrations of different circuit configurations.

The ratings and characteristics of control circuit devices shall comply with the requirements of IEC 60947-5 (see the note of Clause 1). **A1**

4.5.2 Air-supply control circuits (pneumatic or electro-pneumatic)

The characteristics of air-supply control circuits are:

- rated pressure and its limits;
- volumes of air, at atmospheric pressure, required for each closing and each opening operation.

The rated supply pressure of a pneumatic or electro-pneumatic equipment is the air pressure on which the operating characteristics of the pneumatic control system are based.

4.6 Auxiliary circuits

The characteristics of auxiliary circuits are the number and kind of contacts (a-contact, b-contact, etc.) in each of these circuits and their ratings according to IEC 60947-5 (see note of Clause 1).

The characteristics of auxiliary contacts and switches shall comply with the requirements of the above standard.

4.7 Relays and releases

The following characteristics of relays and releases shall be stated in the relevant product standard, where applicable:

- type of relay or release;
- rated values;
- current setting or current setting range;
- time/current characteristics (for presentation of time/current characteristics, see 4.8);
- influence of ambient air temperature.

A1 – extended functions as given in Annex T. **A1**

4.8 Co-ordination with short-circuit protective devices (SCPD)

The manufacturer shall state the type or the characteristics of the SCPD to be used with or within the equipment, as the case may be, and the maximum prospective short-circuit current for which the equipment, including the SCPD, is suitable, at the stated operational voltage(s).

A1 NOTE IEC/TR 61912-1 gives guidance on co-ordination with SCPDs. **A1**

4.9 Switching overvoltages

The manufacturer shall specify the maximum value of switching overvoltages caused by the operation of the switching device, when required by the product standard.

This value shall not exceed that of the rated impulse withstand voltage (see 4.3.1.3).

5 Product information

5.1 Nature of information

The following information shall be given by the manufacturer, when required by the relevant product standard:

Identification:

- manufacturer's name or trademark;
- type designation or serial number;
- number of the relevant product standard, if the manufacturer claims compliance.

Characteristics:

- rated operational voltages (see 4.3.1.1 and note to 5.2);
- utilization category and rated operational currents (or rated powers or rated uninterrupted currents), at the rated operational voltages of the equipment (see 4.3.1.1, 4.3.2.3, 4.3.2.4 and 4.4). In certain cases, this information may have to be completed by the value of the reference ambient air temperature at which the equipment has been calibrated;
- the value of the rated frequency/frequencies, e.g.: 50 Hz, 50 Hz/60 Hz, and/or the indication "d.c." or the symbol **— — —**;
- rated duty, with the indication of the class of intermittent duty, if any (see 4.3.4);
- rated making and/or breaking capacities. These indications may be replaced, where applicable, by the indication of the utilization category;
- rated insulation voltage (see 4.3.1.2);
- rated impulse withstand voltage (see 4.3.1.3);
- A1** – relay or release characteristics (see 4.7); **A1**
- switching overvoltage (see 4.9);
- rated short-time withstand current together with its duration, where applicable (see 4.3.6.1);
- rated short-circuit making and/or breaking capacities, where applicable (see 4.3.6.2 and 4.3.6.3);
- rated conditional short-circuit current, where applicable (see 4.3.6.4);
- IP code, in case of enclosed equipment (see Annex C);
- pollution degree (see 6.1.3.2);
- type and maximum ratings of short-circuit protective device, where applicable;
- class of protection against electric shock (see IEC 61140), where applicable;
- rated control circuit voltage, kind of current and frequency;
- **A2** control circuit supply voltage, kind of current and frequency, if different from those of the control coil; **A2**
- rated supply pressure of the air-pressure and limits of pressure variations (for air-pressure controlled equipment);

- suitability for isolation.
- Ⓐ₂ – pole impedance of the switching device (Z);
- material declaration as per Annex W; Ⓐ₂
- Ⓐ₁ – length of insulation to be removed before insertion of the conductor into the terminal;
- maximum number of conductors which may be clamped.

For non-universal screwless terminals:

- "s" or "sol" for terminals declared for rigid-solid conductors;
- "r" for terminals declared for rigid (solid and stranded) conductors;
- "f" for terminals declared for flexible conductors.

In the case of electronically controlled electromagnets, other information may also be necessary, for example control circuit configuration (see 4.5 and Annex U). Ⓐ₁

NOTE This list is not exhaustive.

5.2 Marking

All relevant information, as detailed in 5.1, which is to be marked on the equipment, shall be specified in the relevant product standard.

Markings shall be indelible and easily legible.

Marking of the manufacturer's name or trademark and type designation or serial number is mandatory on the equipment and preferably on the nameplate, if any, in order to permit the complete data to be obtained from the manufacturer.

NOTE In the USA and Canada, the rated operational voltage U_e , may be marked as follows:

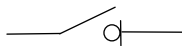
- a) on equipment for use on three-phase – four-wire systems, by both the value of phase-to-earth voltage and that of phase-to-phase voltage, e.g. 277/480 V;
- b) on equipment for use on three-phase – three-wire systems, by the value of phase-to-phase voltage, e.g. 480 V.

The following information shall also be marked and visible after mounting:

- direction of movement of the actuator (see 7.1.5.2), if applicable;
- indication of the position of the actuator (see also 7.1.6.1 and 7.1.6.2);
- approval or certification mark, if applicable;
- for miniaturized equipment, symbol, colour code or letter code;
- terminal identification and marking (see 7.1.8.4);
- IP code and class of protection against electric shock, when applicable (marked preferably on the equipment as far as possible);
- suitability for isolation, where applicable, with the isolation function symbol according to IEC 60617-7, reference 07-01-03, combined with the appropriate function symbol for the equipment, e.g.:



for a circuit-breaker suitable for isolation;



for a switch-disconnector.

This symbol shall be:

- clearly and unmistakably marked;
- visible when the equipment is installed as in service and the actuator is accessible.

This requirement applies whether the equipment is unenclosed, or enclosed according to 7.1.11.

This requirement also applies if the symbol is integrated into a wiring diagram and this diagram is the only marking indicating suitability for isolation.

- Ⓐ₁ In the case of electronically controlled electromagnets, information other than that given in 5.1 may also be necessary (see also 4.5 and Annex U). Ⓐ₁

A1 The indication "s", "sol", "r" or "f" for non-universal screwless terminals shall be marked on the device or, if the space available is not sufficient, on the smallest package unit or in technical information provided with the product.

In the case of a group of terminals located together, a single marking on the device is acceptable. **A1**

5.3 Instructions for installation, operation and maintenance

The manufacturer shall specify in his documents or catalogues the conditions for installation, operation and maintenance, if any, of the equipment during operation and after a fault. **A2** The manufacturer shall also specify the measures to be taken with regard to EMC, if any. **A2**

A2 For equipment only suitable in environment A (see 7.3.1), the manufacturer shall provide the following notice in documentation, available as information to potential customers and with the product for users: **A2**

NOTICE

This product has been designed for environment A. Use of this product in environment B may cause unwanted electromagnetic disturbances in which case the user may be required to take adequate mitigation measures.

If necessary, the instructions for the transport, installation and operation of the equipment shall indicate the measures that are of particular importance for the proper and correct installation, commissioning and operation of the equipment.

These documents shall indicate the recommended extent and frequency of maintenance, if any.

NOTE All equipment covered by this standard is not necessarily designed to be maintained.

A2 5.4 Environmental information

Material declarations according to Annex W shall be provided if required by the relevant product standard. **A2**

6 Normal service, mounting and transport conditions

6.1 Normal service conditions

Equipment complying with this standard shall be capable of operating under the following standard conditions:

NOTE For non-standard conditions in service, see Annex B. These may require agreement between manufacturer and user.

6.1.1 Ambient air temperature

The ambient air temperature does not exceed +40 °C and its average over a period of 24 h does not exceed +35 °C.

The lower limit of the ambient air temperature is –5 °C.

Ambient air temperature is that existing in the vicinity of the equipment if supplied without enclosure, or in the vicinity of the enclosure if supplied with an enclosure.

NOTE 1 Equipment intended to be used in ambient air temperature above +40 °C (e.g. in forges, boiler rooms, tropical countries) or below -5 °C (e.g. -25 °C, as required by ^{A2} IEC 60695-11-5 ^{A2} for outdoor installed low-voltage switchgear and controlgear assemblies) should be designed or used according to the relevant product standard, where applicable, or according to agreement between manufacturer and user. Information given in the manufacturer's catalogue may take the place of such an agreement. ^{A2} The needle flame test is used as an alternative test for addressing flame retardancy requirements for shipboard applications. ^{A2}

NOTE 2 Ambient air temperature(s) for certain types of equipment, e.g. circuit-breakers or overload relays for starters, is indicated in the relevant product standard.

6.1.2 Altitude

The altitude of the site of installation does not exceed 2 000 m.

NOTE For equipment to be used at higher altitudes, it is necessary to take into account the reduction of the dielectric strength and the cooling effect of the air. Electrical equipment intended to operate under these conditions shall be designed or used in accordance with an agreement between manufacturer and user.

6.1.3 Atmospheric conditions

6.1.3.1 Humidity

The relative humidity of the air does not exceed 50 % at a maximum temperature of +40 °C. Higher relative humidities may be permitted at lower temperatures, e.g. 90 % at +20 °C. Special measures may be necessary in cases of occasional condensation due to variations in temperature.

NOTE Pollution degrees, as stated in 6.1.3.2, define the environmental conditions more precisely.

6.1.3.2 Pollution degree

The pollution degree (see 2.5.58) refers to the environmental conditions for which the equipment is intended.

NOTE 1 The micro-environment of the creepage distance or clearance and not the environment of the equipment determines the effect on the insulation. The micro-environment might be better or worse than the environment of the equipment. It includes all factors influencing the insulation, such as climatic and electromagnetic conditions, generation of pollution, etc.

For equipment intended for use within an enclosure or provided with an integral enclosure, the pollution degree of the environment in the enclosure is applicable.

For the purpose of evaluating clearances and creepage distances, the following four degrees of pollution of the micro-environment are established (clearances and creepage distances according to the different pollution degrees are given in Tables 13 and 15):

Pollution degree 1:

No pollution or only dry, non-conductive pollution occurs.

Pollution degree 2:

Normally, only non-conductive pollution occurs. Occasionally, however, a temporary conductivity caused by condensation may be expected.

Pollution degree 3:

Conductive pollution occurs, or dry, non-conductive pollution occurs which becomes conductive due to condensation.

Pollution degree 4:

The pollution generates persistent conductivity caused, for instance, by conductive dust or by rain or snow.

Standard pollution degree of industrial applications:

Unless otherwise stated by the relevant product standard, equipment for industrial applications is generally for use in pollution degree 3 environment. However, other pollution degrees may be considered to apply depending upon particular applications or the micro-environment.

NOTE 2 The pollution degree of the micro-environment for the equipment may be influenced by installation in an enclosure.

Standard pollution degree of household and similar applications:

Unless otherwise stated by the relevant product standard, equipment for household and similar applications is generally for use in pollution degree 2 environment.

6.1.4 Shock and vibration

Standard conditions of shock and vibration to which the equipment can be submitted are under consideration.

6.2 Conditions during transport and storage

A special agreement shall be made between user and manufacturer if the conditions during transport and storage, e.g. temperature and humidity, differ from those defined in 6.1, except that, unless otherwise specified, the following temperature range applies during transport and storage: between $-25\text{ }^{\circ}\text{C}$ and $+55\text{ }^{\circ}\text{C}$ and, for short periods not exceeding 24 h, up to $+70\text{ }^{\circ}\text{C}$.

Equipment subjected to these extreme temperatures without being operated shall not undergo any irreversible damage and shall then operate normally under the specified conditions.

6.3 Mounting

The equipment shall be mounted in accordance with the manufacturer's instructions.

7 Constructional and performance requirements

7.1 Constructional requirements

7.1.1 General

The equipment with its enclosure, if any, whether integral or not, shall be designed and constructed to withstand the stresses occurring during installation and normal use and, in addition, shall provide a specified degree of resistance to abnormal heat and fire.

Glow-wire requirements for non integral enclosure materials are given in relevant standards, e.g. IEC 62208.

NOTE The need to reduce the impact on the natural environment of a product during all phases of its life is recognized. Assistance in the consideration of environmental aspects relating to products according to the IEC 60947 series is given in Annex O.

7.1.2 Materials

7.1.2.1 General materials requirements

A1 Parts of insulating materials which might be exposed to thermal stresses due to electrical effects within the equipment shall not be adversely affected by abnormal heat and by fire. **A1**

The manufacturer shall specify which test method, 7.1.2.2 or 7.1.2.3, is to be used.

A1 Text deleted **A1**

7.1.2.2 Glow wire testing

A1) The suitability of materials used is verified by:

- a) making tests on the equipment; or
- b) making tests on sections taken from the equipment; or
- c) making tests on any parts of identical material having representative thickness; or
- d) providing data from the insulating material supplier fulfilling the requirements according to IEC 60695-2-12.

The suitability shall be determined with respect to resistance to abnormal heat and fire.

The manufacturer shall indicate which methods, amongst a), b), c) and d) shall be used. **A1**

If an identical material having representative cross-sections has already satisfied the requirements of any of the tests of 8.2.1, then those tests need not be repeated.

Tests on equipment shall be made by the glow-wire end-product test of IEC 60695-2-10 and IEC 60695-2-11.

Parts of insulating materials necessary to retain current-carrying parts in position shall conform to the glow-wire tests of 8.2.1.1.1 at a test temperature of 850 °C or 960 °C according to the expected fire hazard. Product standards shall specify the value appropriate to the product, taking into account the Annex A of IEC 60695-2-11.

Parts of insulating materials other than those specified in the previous paragraph shall conform to the requirements of the glow-wire test of 8.2.1.1.1 at a temperature of 650 °C.

NOTE For small parts, as specified in IEC 60695-2-11, the relevant product standard may specify another test (for example needle flame test, according to IEC 60695-2-2). The same procedure may be applicable for other practical reasons when the metal part is large compared to the insulating material (such as terminal blocks).

7.1.2.3 Test based on flammability category

For parts of insulating materials, hot wire ignition and, where applicable, arc ignition tests as specified in 8.2.1.1.2, shall be made based on flammability category.

Tests on materials shall be made in accordance with Annex M. The hot wire ignition (HWI) and arc ignition (AI) test value requirements related to the material flammability category shall conform to Table M.1 or M.2.

A1) Alternatively, the manufacturer may provide data from the insulating material supplier fulfilling the requirements given in Annex M. **A1**

7.1.3 Current-carrying parts and their connections

Current-carrying parts shall have the necessary mechanical strength and current-carrying capacity for their intended use.

For electrical connections, no contact pressure shall be transmitted through insulating material other than ceramic or other material with characteristics not less suitable, unless there is sufficient resiliency in the metallic parts to compensate for any possible shrinkage or yielding of the insulation material.

Compliance shall be verified by inspection and by conducting the test sequences according to the relevant product standard.

NOTE In the USA, the use of clamping units in which pressure is transmitted through insulating materials other than ceramic is permitted only in the following circumstances:

- 1 where the clamping unit is part of a terminal block;

2 where a temperature test demonstrates that the temperature limitations of the insulation material and of the terminals in accordance with the product standard are not exceeded; and

3 resilient metal is used in the clamping unit construction to compensate for loss of clamping pressure due to insulating material deformation.

7.1.4 Clearances and creepage distances

A2 7.1.4.1 General

For equipment tested according to 8.3.3.4 of this standard, minimum values are given in Table 13 and Table 15.

Electrical requirements are given in 7.2.3.

In the other cases, guidance for minimum values is given in the relevant product standard.

NOTE Depending on the risk level (severity of harm and the probability of occurrence), the non-accessibility to hazardous-live parts is considered under normal service conditions (see 6.1) or under single-fault conditions (see 4.2 of IEC 61140:2001, 7.1.10 and Annex N).

7.1.4.2 Insulation coordination barriers for creepage distances

When solid insulation is used as an insulation coordination barrier to comply with required creepage distances, the material used shall comply with the glow wire requirements in 7.1.2.2 or the flammability requirements in 7.1.2.3.

7.1.4.3 Insulation coordination barriers for clearance distances

When solid insulation is used as an insulation coordination barrier to comply with required clearance distances and does not physically support or maintain the relative position of uninsulated parts involved, the barrier material shall comply with the glow wire requirements in 7.1.2.2 and shall conform to the glow-wire test requirements of 8.2.1.1.1 at a temperature of 650 °C or the AI values in Table M.2. Alternatively the material shall comply with the requirements in 7.1.4.2. **A2**

7.1.5 Actuator

7.1.5.1 Insulation

The actuator of the equipment shall be insulated from the live parts for the rated insulation voltage and, if applicable, the rated impulse withstand voltage.

Moreover:

- if it is made of metal, it shall be capable of being satisfactorily connected to a protective conductor unless it is provided with additional reliable insulation;
- if it is made of or covered by insulating material, any internal metal part, which might become accessible in the event of insulation failure, shall also be insulated from live parts for the rated insulation voltage.

7.1.5.2 Direction of movement

The direction of operation for actuators of devices shall normally conform to IEC 60447. Where devices cannot conform to these requirements, e.g. due to special applications or alternative mounting positions, they shall be clearly marked such that there is no doubt as to the "I" and "O" positions and the direction of operation.

7.1.6 Indication of the contact position

7.1.6.1 Indicating means

When an equipment is provided with means for indicating the closed and open positions, these positions shall be unambiguous and clearly indicated. This is done by means of a position indicating device (see 2.3.18).

NOTE In the case of enclosed equipment, the indication may or may not be visible from the outside.

The relevant product standard may specify whether the equipment is to be provided with such an indicating device.

If symbols are used, they shall indicate the closed and open positions respectively, in accordance with IEC 60417-2:

60417-2-IEC-5007 | On (power)

60417-2-IEC-5008 ○ Off (power)

For equipment operated by means of two push-buttons, only the push-button designated for the opening operation shall be red or marked with the symbol "O".

Red colour shall not be used for any other push-button.

The colours of other push-buttons, illuminated push-buttons and indicator lights shall be in accordance with IEC 60073.

7.1.6.2 Indication by the actuator

When the actuator is used to indicate the position of the contacts, it shall automatically take up or stay, when released, in the position corresponding to that of the moving contacts; in this case, the actuator shall have two distinct rest positions corresponding to those of the moving contacts, but for automatic opening a third distinct position of the actuator may be provided.

7.1.7 Additional requirements for equipment suitable for isolation

7.1.7.1 Additional constructional requirements

NOTE 1 In the USA, devices meeting these additional requirements are not accepted as assuring isolation by themselves. Isolation requirements and procedures are covered in the relevant Federal regulations and maintenance standards.

Equipment suitable for isolation shall provide in the open position (see 2.4.21) an isolation distance in accordance with the requirements necessary to satisfy the isolating function (see 7.2.3.1 and 7.2.7). Indication of the position of the main contacts shall be provided by one or more of the following means:

- the position of the actuator;
- a separate mechanical indicator;
- Ⓐ) – visibility of all moving main contacts. Ⓐ)

The effectiveness of each of the means of indication provided on the equipment and its mechanical strength shall be verified in accordance with 8.2.5.

When means are provided or specified by the manufacturer to lock the equipment in the open position, locking in that position shall only be possible when the main contacts are in the open position. This shall be verified in accordance with 8.2.5.

Equipment shall be designed so that the actuator, front plate or cover are fitted to the equipment in a manner which ensures correct contact position indication and locking, if provided.

NOTE 2 Locking in the closed position is permitted for particular applications.

NOTE 3 If auxiliary contacts are provided for interlocking purposes, the operating time of the auxiliary and main contacts should be declared by the manufacturer. More specific requirements may be given in the relevant product standard.

The indicated open position is the only position in which the specified isolation distance between the contacts is ensured.

For equipment provided with positions such as “tripped position” or “standby position”, which are not the indicated open position, those positions shall be clearly identified. The marking of such positions shall not include the symbols “I” or “O”.

An actuator having only one position of rest shall not be considered as appropriate to indicate the position of the main contact.

7.1.7.2 Supplementary requirements for equipment with provision for electrical interlocking with contactors or circuit-breakers

If equipment suitable for isolation is provided with an auxiliary switch for the purpose of electrical interlocking with contactor(s) or circuit-breaker(s) and intended to be used in motor circuits, the following requirements shall apply unless the equipment is rated for AC-23 utilization category.

An auxiliary switch shall be rated according to IEC 60947-5-1 as stated by the manufacturer.

The time interval between the opening of the contacts of the auxiliary switch and the contacts of the main poles shall be sufficient to ensure that the associated contactor or circuit-breaker interrupts the current before the main poles of the equipment open.

Unless otherwise stated in the manufacturer's technical literature, the time interval shall be not less than 20 ms when the equipment is operated according to the manufacturer's instructions.

Compliance shall be verified by measuring the time interval between the instant of opening of the auxiliary switch and the instant of opening of the main poles under no-load conditions when the equipment is operated according to the manufacturer's instructions.

During the closing operation the contacts of the auxiliary switch shall close after or simultaneously with the contacts of the main poles.

A suitable opening time interval may also be provided by an intermediate position (between the ON and OFF positions) at which the interlocking contact(s) is (are) open and the main poles remain closed.

7.1.7.3 Supplementary requirements for equipment provided with means for padlocking the open position

The locking means shall be designed in such a way that it cannot be removed with the appropriate padlock(s) installed. When the equipment is locked by even of a single padlock, it shall not be possible by operating the actuator, to reduce the clearance between open contacts to the extent that it no longer complies with the requirements of 7.2.3.1b).

Alternatively, the design may provide padlockable means to prevent access to the actuator.

Compliance with the requirements to padlock the actuator shall be verified using a padlock specified by the manufacturer or an equivalent gauge, giving the most adverse conditions, to simulate locking. The force F specified in 8.2.5.2.1 shall be applied to the actuator in an attempt to operate the equipment from the open position to the closed position. Whilst the force F is applied the equipment shall be subjected to a test voltage across open contacts. The equipment shall be capable of withstanding the test voltage required according to Table 14 appropriate to the rated impulse withstand voltage.

7.1.8 Terminals

7.1.8.1 Constructional requirements

All parts of terminals which maintain contact and carry current shall be of metal having adequate mechanical strength.

A1 Terminal connections shall be such that the force to connect the conductors may be applied by screws, screwless-type or other equivalent means so as to ensure that the necessary contact pressure is maintained. **A1**

Terminals shall be so constructed that the conductors can be clamped between suitable surfaces without any significant damage either to conductors or terminals.

Terminals shall not allow the conductors to be displaced or be displaced themselves in a manner detrimental to the operation of equipment and the insulation voltage shall not be reduced below the rated values.

If required by the application, terminals and conductors may be connected by means of cable lugs for copper conductors only.

NOTE 1 Examples of overall dimensions of terminal lugs suitable to be directly connected to the stud terminals of equipment are given in Annex P.

A1 Screwless-type clamping units, unless otherwise specified by the manufacturer, shall accept rigid and flexible conductors as indicated in Table 1.

On screwless-type clamping unit, the connection or disconnection of conductors shall be made as follows:

- on universal clamping units by the use of a general purpose tool or a convenient device, integral with the clamping unit to open it for the insertion or withdrawal of the conductors;
- on push-wire clamping units by simple insertion. For the disconnection of the conductors an operation other than a pull only on the conductor shall be necessary. The use of a general purpose tool or of a convenient device, integral with the clamping unit is allowed in order to "open" it and to assist the insertion or the withdrawal of the conductor. **A1**

Examples of terminals are given in Annex D.

The requirements of this subclause shall be verified by the tests of 8.2.4.2, 8.2.4.3 and 8.2.4.4, as applicable.

NOTE 2 North American countries have particular requirements for terminals suitable for aluminium conductors and marking to identify the use of aluminium conductors.

7.1.8.2 Connecting capacity

The manufacturer shall state the type (rigid – solid or stranded – or flexible), the minimum and the maximum cross-sections of conductors for which the terminal is suitable and, if applicable, the number of conductors simultaneously connectable to the terminal. However, the maximum cross-section shall not be smaller than that stated in 8.3.3.3 for the temperature-rise test and the terminal shall be suitable for conductors of the same type (rigid – solid or stranded – or flexible) at least two sizes smaller, as given in the appropriate column of Table 1.

NOTE 1 Conductor cross-sections smaller than the minimum may be required in different product standards.

NOTE 2 Because of voltage drop and other considerations, the product standards may require the terminals to be suitable for conductors of cross-sections larger than those specified for the temperature-rise test. The relationship between conductor cross-sections and rated currents may be given in the relevant product standards.

Standard values of cross-section of round copper conductors (both metric and AWG/kcmil sizes) are shown in Table 1 which also gives the approximate relationship between ISO metric and AWG/kcmil sizes.

7.1.8.3 Connection

Terminals for connection to external conductors shall be readily accessible during installation.

Clamping screws and nuts shall not serve to fix any other component although they may hold the terminals in place or prevent them from turning.

7.1.8.4 Terminal identification and marking

Terminals shall be clearly and permanently identified in accordance with IEC 60445 and Annex L, unless superseded by the requirements of the relevant product standard.

Terminals intended exclusively for the neutral conductor shall be identified by the letter "N", in accordance with IEC 60445.

The protective earth terminal shall be identified in accordance with 7.1.10.3.

7.1.9 Additional requirements for equipment provided with a neutral pole

When an equipment is provided with a pole intended only for connecting the neutral, this pole shall be clearly identified to that effect by the letter N (see 7.1.8.4).

A switched neutral pole shall break not before and shall make not after the other poles.

If a pole having an appropriate short-circuit breaking and making capacity (see 2.5.14 and 2.5.15) is used as a neutral pole, then all poles, including the neutral pole, may operate substantially together.

NOTE The neutral pole may be fitted with an over-current release.

For equipment having a value of conventional thermal current (free air or enclosed, see 4.3.2.1 and 4.3.2.2) not exceeding 63 A, this value shall be identical for all poles.

For higher conventional thermal current values, the neutral pole may have a value of conventional thermal current different from that of the other poles, but not less than half that value or 63 A, whichever is the higher.

7.1.10 Provisions for protective earthing

7.1.10.1 Constructional requirements

The exposed conductive parts (e.g. chassis, framework and fixed parts of metal enclosures) other than those which cannot constitute a danger shall be electrically interconnected and connected to a protective earth terminal for connection to an earth electrode or to an external protective conductor.

This requirement can be met by the normal structural parts providing adequate electrical continuity and applies whether the equipment is used on its own or incorporated in an assembly.

NOTE If needed, requirements and tests may be specified in the relevant product standard.

Exposed conductive parts are considered not to constitute a danger if they cannot be touched on large areas or grasped with the hand or if they are of small size (approximately 50 mm × 50 mm) or are so located as to exclude any contact with live parts.

Examples of these are screws, rivets, nameplates, transformer cores, electromagnets of switching devices and certain parts of releases, irrespective of their size.

7.1.10.2 Protective earth terminal

The protective earth terminal shall be readily accessible and so placed that the connection of the equipment to the earth electrode or to the protective conductor is maintained when the cover or any other removable part is removed.

The protective earth terminal shall be suitably protected against corrosion.

In the case of equipment with conductive structures, enclosures, etc., means shall be provided, if necessary, to ensure electrical continuity between the exposed conductive parts of the equipment and the metal sheathing of connecting conductors.

The protective earth terminal shall have no other function, except when it is intended to be connected to a PEN conductor (see A_1 2.1.15 A_1 – Note). In this case, it shall also have the function of a neutral terminal in addition to meeting the requirements applicable to the protective earth terminal.

7.1.10.3 Protective earth terminal marking and identification


The protective earth terminal shall be clearly and permanently identified by its marking.

The identification shall be achieved by colour (green-yellow mark) or by the notation PE, or PEN, as applicable, in accordance with IEC 60445, subclause 5.3, or by a graphical symbol for use on equipment.

The graphical symbol to be used is the symbol:



in accordance with IEC 60417-2.

NOTE The symbol  (60417-2-IEC-5017), previously recommended, shall be progressively superseded by the preferred symbol 60417-2-IEC-5019 given above.

7.1.11 Enclosures for equipment

The following requirements are only applicable to enclosures supplied or intended to be used with the equipment.

7.1.11.1 Design

The enclosure shall be so designed that, when it is opened and other protective means, if any, are removed, all parts requiring access for installation and maintenance, as prescribed by the manufacturer, are readily accessible.

Sufficient space shall be provided inside the enclosure for the accommodation of external conductors from their point of entry into the enclosure to the terminals to ensure adequate connection.

The fixed parts of a metal enclosure shall be electrically connected to the other exposed conductive parts of the equipment and connected to a terminal which enables them to be earthed or connected to a protective conductor.

Under no circumstances shall a removable metal part of the enclosure be insulated from the part carrying the earth terminal when the removable part is in place.

The removable parts of the enclosure shall be firmly secured to the fixed parts by a device so that they cannot be accidentally loosened or detached owing to the effects of operation of the equipment or vibrations.

When an enclosure is so designed as to allow the covers to be opened without the use of tools, means shall be provided to prevent loss of the fastening devices.

An integral enclosure is considered to be a non-removable part.

If the enclosure is used for mounting push-buttons, removal of buttons should be from the inside of the enclosure. Removal from the outside shall only be by use of a tool intended for this purpose.

7.1.11.2 Insulation

If, in order to prevent accidental contact between a metallic enclosure and live parts, the enclosure is partly or completely lined with insulating material, then this lining shall be securely fixed to the enclosure.

7.1.12 Degrees of protection of enclosed equipment

Degrees of protection of enclosed equipment and relevant tests are given in Annex C.

7.1.13 Conduit pull-out, torque and bending with metallic conduits

Polymeric enclosures of equipment, whether integral or not, provided with threaded conduit entries, intended for the connection of extra heavy duty, rigid threaded metal conduits complying with IEC 60981, shall withstand the stresses occurring during its installation such as pull-out, torque, bending.

Compliance shall be verified by the test of 8.2.7.

7.2 Performance requirements

The following requirements apply to clean new equipment unless otherwise stated in the relevant product standard.

7.2.1 Operating conditions

7.2.1.1 General

The equipment shall be operated in accordance with the manufacturer's instructions or the relevant product standard, especially for equipment with dependent manual operation where the making and breaking capacities may depend on the skill of the operator.

7.2.1.2 Limits of operation of power operated equipment

Unless otherwise stated in the relevant product standard, electromagnetic and electro-pneumatic equipment shall close with any $\overline{A_2}$ control circuit supply voltage $\overline{A_2}$ between 85 % and 110 % of its rated value U_s and an ambient air temperature between $-5\text{ }^\circ\text{C}$ and $+40\text{ }^\circ\text{C}$. These limits apply to d.c. or a.c. as appropriate.

For pneumatic and electro-pneumatic equipment, unless otherwise stated, the limits of the air supply pressure are 85 % and 110 % of the rated pressure.

Where a range of operation is given, the value of 85 % shall apply to the lower limit of the range, and the value of 110 % to the upper limit of the range.

NOTE For latched equipment, operating limits should be agreed upon between manufacturer and user.

For electromagnetic and electro-pneumatic equipment, the drop-out voltage shall not be higher than 75 % of the U_s rated control circuit supply voltage U_s nor lower than 20 % of U_s in the case of a.c. at rated frequency, or 10 % of U_s in the case of d.c.

- \square_{A1} The limits between which an equipment, with an electronically controlled electromagnet, shall drop out and open fully are
- for d.c.: 75 % to 10 % of their U_s rated control circuit supply voltage U_s ,
 - for a.c.: 75 % to 20 % of their U_s rated control circuit supply voltage U_s , or 75 % to 10 % of their U_s rated control circuit supply voltage U_s if specified by the manufacturer. \square_{A1}

For pneumatic and electro-pneumatic equipment, unless otherwise stated, opening shall occur at a pressure between 75 % and 10 % of the rated pressure.

Where a range of operation is given, the value of 20 % or 10 %, as the case may be, shall apply to the upper limit of the range, and the value of 75 % to the lower limit of the range.

In the case of coils, the limiting drop-out values apply when the coil circuit resistance is equal to that obtained at -5°C . This may be verified by a calculation based on the values obtained at normal ambient temperature.

- \square_{A1} The drop out time may need to be specified for particular applications. In this case the drop out time shall be measured during the test associated with the verification of this subclause. \square_{A1}

7.2.1.3 Limits of operation of under-voltage relays and releases

a) Operating voltage

An under-voltage relay or release, when associated with a switching device, shall operate to open the equipment even on a slowly falling voltage within the range between 70 % and 35 % of its rated voltage.

NOTE A no-voltage release is a special form of under-voltage release in which the operating voltage is between 35 % and 10 % of the rated supply voltage.

An under-voltage relay or release shall prevent the closing of the equipment when the supply voltage is below 35 % of the rated voltage of the relay or release; it shall permit closing of the equipment at supply voltages equal to or above 85 % of its rated value.

Unless otherwise stated in the relevant product standard, the upper limit of the supply voltage shall be 110 % of its rated value.

The figures given above apply equally to d.c. and to a.c. at rated frequency.

b) Operating time

For a time-delay under-voltage relay or release, the time-lag shall be measured from the instant when the voltage reaches the operating value until the instant when the relay or release actuates the tripping device of the equipment.

7.2.1.4 Limits of operation of shunt releases

A shunt release for opening shall cause tripping under all operating conditions of an equipment when the supply voltage of the shunt release measured during the tripping operation remains between 70 % and 110 % of the U_s rated control circuit supply voltage U_s and, if a.c., at the rated frequency.

- \square_{A2} Digital inputs and/or digital outputs contained in switchgear and controlgear, and intended to be compatible with programmable logic controllers (PLCs) are covered by Annex S. \square_{A2}

7.2.1.5 Limits of operation of current operated relays and releases

Limits of operation of current operated relays and releases shall be stated in the relevant product standard.

NOTE The term "current operated relays and releases" covers over-current relays or releases, overload relays or releases, reverse current relays or releases, etc.

7.2.2 Temperature-rise

The temperature-rises of the parts of an equipment, measured during a test carried out under the conditions specified in 8.3.3.3, shall not exceed the values stated in this subclause.

NOTE 1 Temperature-rise in normal service may differ from the test values, depending on the installation conditions and size of connected conductors.

NOTE 2 The temperature-rise limits given in Tables 2 and 3 apply to equipment tested in new and clean condition. Different values may be prescribed by product standards for different test conditions and for devices of small dimensions but not exceeding the above values by more than 10 K.

7.2.2.1 Terminals

The temperature-rises of terminals shall not exceed the values stated in Table 2.

7.2.2.2 Accessible parts

The temperature-rises of accessible parts shall not exceed the values stated in Table 3.

NOTE The temperature-rise limits of other parts are given in 7.2.2.8.

7.2.2.3 Ambient air temperature

The temperature-rise limits given in Tables 2 and 3 are applicable only if the ambient air temperature remains within the limits given in 6.1.1.

7.2.2.4 Main circuit

The main circuit of an equipment shall be capable of carrying the conventional thermal current of the equipment without the temperature-rises exceeding the limits specified in Tables 2 and 3 when tested in accordance with 8.3.3.3.4.

7.2.2.5 Control circuits

The control circuits of an equipment, including control circuit devices to be used for the closing and operating operations of an equipment, shall permit the rated duty according to 4.3.4 and also the temperature-rises tests specified in 8.3.3.3.5 to be made without the temperature-rises exceeding the limits specified in Tables 2 and 3.

7.2.2.6 Windings of coils and electromagnets

With current flowing through the main circuit the windings of coils and electromagnets shall withstand their rated voltage without the temperature-rises exceeding the limits specified in 7.2.2.8 when tested in accordance with 8.3.3.3.6.

NOTE This subclause does not apply to pulse-operated coils, whose operating conditions are defined by the manufacturer.

7.2.2.7 Auxiliary circuits

Auxiliary circuits of an equipment including auxiliary switches shall be capable of carrying their conventional thermal current without the temperature-rise exceeding the limits specified in Tables 2 and 3, when tested in accordance with 8.3.3.3.7.

NOTE If an auxiliary circuit forms an integral part of the equipment, it suffices to test it at the same time as the main equipment, but at its actual service current.

7.2.2.8 Other parts

The temperature rises obtained during the test shall not impair the performance of the product. For A_2 insulating parts A_2 , the manufacturer shall demonstrate compliance by reference to the insulation temperature index (determined, for example, by the methods of IEC 60216) or by compliance with IEC 60085.

7.2.3 Dielectric properties

The dielectric properties are based on basic safety publications IEC 60664-1 and IEC 61140. A_1 For reduced clearances and creepage distances through the use of coating see IEC 60664-3; for clearances and creepage distances equal to or less than 2 mm see IEC 60664-5. A_1

- a) The following requirements provide the means of achieving co-ordination of insulation of equipment with the conditions within the installation.
- b) The equipment shall be capable of withstanding:
 - the rated impulse withstand voltage (see 4.3.1.3) in accordance with the overvoltage category given in Annex H;
 - the impulse withstand voltage across the contact gaps of devices suitable for isolation as given in Table 14;
 - the power-frequency withstand voltage.

NOTE The correlation between the nominal voltage of the supply system and the rated impulse withstand voltage of the equipment is given in Annex H.

The rated impulse withstand voltage for a given rated operational voltage (see notes 1 and 2 to 4.3.1.1) shall be not less than that corresponding in Annex H to the nominal voltage of the supply system of the circuit at the point where the equipment is to be used, and the appropriate overvoltage category.

- c) The requirements of this subclause shall be verified by the tests of 8.3.3.4.

7.2.3.1 Impulse withstand voltage

1) Main circuit

- a) Clearances from live parts to parts intended to be earthed and between poles shall withstand the test voltage given in Table 12 appropriate to the rated impulse withstand voltage.
- b) Clearances across the open contacts shall withstand:
 - the impulse withstand voltage specified, where applicable, in the relevant product standard;
 - for equipment designated as suitable for isolation, the test voltage given in Table 14 appropriate to the rated impulse withstand voltage.

NOTE Solid insulation of equipment associated with clearances a) and/or b) above should be subjected to the impulse voltage specified in a) and/or b), as applicable.

2) Auxiliary and control circuits

- a) For auxiliary and control circuits which operate directly from the main circuit at their rated voltage, clearances from live parts to parts intended to be earthed and between poles shall withstand the test voltage given in Table 12 appropriate to the rated impulse withstand voltage of the auxiliary/control circuit and to the appropriate overvoltage category of the main circuit (see also the note of 7.2.3.1, item 1)).

- b) Auxiliary and control circuits which do not operate directly from the main circuit may have an overvoltage withstand capacity different from that of the main circuit. Clearances and associated solid insulation of such circuits, whether a.c. or d.c., shall withstand the appropriate voltage in accordance with Annex H.

7.2.3.2 Power-frequency withstand voltage of the main, auxiliary and control circuits

- a) Power-frequency tests are used in the following cases:

- dielectric tests as type tests for the verification of solid insulation;
- dielectric withstand verification, as a criterion of failure, after switching or short-circuit type tests;
- routine tests.

- b) Type tests of dielectric properties

The tests of dielectric properties, as type tests, shall be made in accordance with 8.3.3.4.

For equipment suitable for isolation, the maximum leakage current shall be in accordance with 7.2.7 and shall be tested according to 8.3.3.4.

- c) Verification of dielectric withstand after switching or short-circuit tests

The verification of dielectric withstand after switching and short-circuit tests as a criterion of failure, is always made at power-frequency voltage in accordance with item 4) of 8.3.3.4.1.

For equipment suitable for isolation, the maximum leakage current shall be in accordance with 7.2.7, shall be tested according to 8.3.3.4 and shall not exceed the values specified in the relevant product standard.

- d) Vacant

- e) Verification of dielectric withstand during routine tests

Tests to detect faults in materials and workmanship are made at power-frequency voltage, in accordance with item 2) of 8.3.3.4.2.

7.2.3.3 Clearances

Clearances shall be sufficient to enable the equipment to withstand the rated impulse withstand voltage, according to 7.2.3.1.

Clearances shall be higher than the values given in Table 13, for case B (homogeneous field) (see 2.5.62) and verified by a sampling test according to 8.3.3.4.3. This test is not required if the clearances, related to the rated impulse withstand voltage and pollution degree, A_2 are equal to or higher than A_2 the values given in Table 13 for case A (inhomogeneous field).

The method of measuring clearances is given in Annex G.

7.2.3.4 Creepage distances

a) Dimensioning

For pollution degrees 1 and 2, creepage distances shall be not less than the associated clearances selected according to 7.2.3.3. For pollution degrees 3 and 4, the creepage distances shall be not less than the case A clearances (Table 13) to reduce the risk of disruptive discharge due to overvoltages, even if the clearances are smaller than the values of case A as permitted in 7.2.3.3.

The method of measuring creepage distances is given in Annex G.

Creepage distances shall correspond to a pollution degree as specified in 6.1.3.2 or to that defined in the relevant product standard and to the corresponding material group at the rated insulation or working voltage given in Table 15.

Material groups are classified as follows, according to the range of values of the comparative tracking index (CTI) (see 2.5.65):

- Material Group I $600 \leq \text{CTI}$
- Material Group II $400 \leq \text{CTI} < 600$
- Material Group IIIa $175 \leq \text{CTI} < 400$
- Material Group IIIb $100 \leq \text{CTI} < 175$

NOTE 1 The CTI values refer to the values obtained in accordance with IEC 60112, method A, for the insulating material used.

NOTE 2 For inorganic insulating materials, for example glass or ceramics, which do not track, creepage distances need not be greater than their associated clearances. However, the risk of disruptive discharge should be considered.

b) Use of ribs

A creepage distance can be reduced to 0,8 of the relevant value of Table 15 by using ribs of 2 mm minimum height, irrespective of the number of ribs. The minimum base of the rib is determined by mechanical requirements (see G.2).

c) Special applications

Equipment intended for certain applications where severe consequences of an insulation fault have to be taken into account shall have one or more of the influencing factors of Table 15 (distances, insulating materials, pollution in the micro-environment) utilized in such a way as to achieve a higher insulation voltage than the rated insulation voltage given to the equipment according to Table 15.

7.2.3.5 Solid insulation

Solid insulation shall be verified by either power-frequency tests, in accordance with item 3) of 8.3.3.4.1, or d.c. tests in the case of d.c. equipment.

^{A2} NOTE For more information on the design of solid insulation, see 5.3.1 of IEC 60664-1:2007. ^{A2}

^{A2} Text deleted ^{A2}

7.2.3.6 Spacing between separate circuits

For dimensioning clearances, creepage distances and solid insulation between separate circuits, the highest voltage ratings shall be used (rated impulse withstand voltage for clearances and associated solid insulation and rated insulation voltage or working voltage for creepage distances).

7.2.3.7 Requirements for equipment with protective separation

Requirements for equipment with protective separation are given in Annex N.

7.2.4 Ability to make, carry and break currents under no-load, normal load and overload conditions

7.2.4.1 Making and breaking capacities

The equipment shall be capable of making and breaking load and overload currents without failure under the conditions stated in the relevant product standard for the required utilization categories and the number of operations stated in the relevant product standard (see also general test conditions of 8.3.3.5).

7.2.4.2 Operational performance

Tests concerning the operational performance of equipment are intended to verify that the equipment is capable of making, carrying and breaking without failure the currents flowing in its main circuit under conditions corresponding to the specified utilization category, where relevant.

Specific requirements and test conditions shall be stated in the relevant product standard and may concern

- the operational performance off-load for which the tests are made with the control circuits energized and the main circuit not energized, in order to demonstrate that the equipment meets the operating conditions specified at the upper and lower limits of supply voltage and/or pressure specified for the control circuit during closing and opening operations;
- the operational performance on-load during which the equipment shall make and break the specified current corresponding, where relevant, to its utilization category for the number of operations stated in the relevant product standard.

The verification of operational performance off-load and on-load may be combined in one sequence of tests if so stated in the relevant product standard.

7.2.4.3 Durability

NOTE The term "durability" has been chosen, instead of "endurance" in order to express the expectancy of the number of operating cycles which can be performed by the equipment before repair or replacement of parts. Moreover the term "endurance" is also commonly used to cover operational performance as defined in 7.2.4.2 and it was deemed necessary not to use the term "endurance" in this standard in order to avoid confusion between the two concepts.

7.2.4.3.1 Mechanical durability

With respect to its resistance to mechanical wear, an equipment is characterized by the number, stated in the relevant product standard, of no-load operating cycles (i.e., without current at the main contacts) which can be effected before it becomes necessary to service or replace any mechanical parts; however, normal maintenance according to the manufacturer's instructions may be permitted for equipment designed to be maintained.

Each operating cycle consists of one closing operation followed by one opening operation.

The equipment shall be mounted for the test according to the manufacturer's instructions.

The preferred number of off-load operating cycles shall be specified in the relevant product standard.

7.2.4.3.2 Electrical durability

With respect to its resistance to electrical wear, an equipment is characterized by the number of on-load operating cycles, corresponding to the service conditions given in the relevant product standard, which can be made without repair or replacement.

The preferred number of on-load operating cycles shall be specified in the relevant product standard.

7.2.5 Ability to make, carry and break short-circuit currents

The equipment shall be so constructed as to be capable of withstanding, under conditions specified in the relevant product standard, the thermal, dynamic and electrical stresses resulting from short-circuit currents. In particular the equipment shall behave in such a manner that it complies with the requirements of 8.3.4.1.8.

Short-circuit currents may be encountered

- during current making;
- during current carrying in the closed position;
- during current interruption.

The ability of the equipment to make, carry and break short-circuit currents is stated in terms of one or more of the following ratings:

- rated short-circuit making capacity (see 4.3.6.2);
- rated short-circuit breaking capacity (see 4.3.6.3);
- rated short-time withstand current (see 4.3.6.1);
- in the case of equipment co-ordinated with short-circuit protective devices (SCPDs):
 - a) rated conditional short-circuit current (see 4.3.6.4),
 - b) other types of co-ordination, specified solely in the relevant product standard.

For ratings and limiting values according to items a) and b) above, the manufacturer shall indicate the type and the characteristics (e.g. current rating, breaking capacity, cut-off current, I^2t) of the SCPD necessary for the protection of the equipment.

7.2.6 Switching overvoltages

Product standards may specify switching overvoltage tests if applicable.

In this case the test procedure and the requirements shall be defined in the product standard.

7.2.7 Leakage currents of equipment suitable for isolation

For equipment suitable for isolation and having a rated operational voltage U_e greater than 50 V, the leakage current shall be measured through each pole with the contacts in the open position.

The value of leakage current, with a test voltage equal to 1,1 times the rated operational voltage shall not exceed

- 0,5 mA per pole for equipment in a new condition;
- 2 mA per pole for equipment having been subjected to the making and breaking operations in accordance with the test requirements of the relevant product standard.

A leakage current of 6 mA at 1,1 times the rated operational voltage is a limiting value for equipment suitable for isolation which value shall not be exceeded under any circumstances. Tests to verify this requirement may be specified in the relevant product standard.

A₂ 7.2.8 Pole impedance

Where the pole impedance is given, it shall be tested according to 8.3.3.8. **A₂**

7.3 Electromagnetic compatibility (EMC)

7.3.1 General

For products falling within the scope of this standard, two sets of environmental conditions are considered and are referred to as

- a) environment A;
- b) environment B.

Environment A relates to low-voltage non-public or industrial networks/locations/installations including highly disturbing sources.

NOTE 1 Environment A corresponds to equipment class A in CISPR 11.

Environment B relates to low-voltage public networks such as domestic, commercial and light industrial locations/installations. Highly disturbing sources such as arc welders are not covered by this environment.

NOTE 2 Environment B corresponds to equipment class B in CISPR 11.

A₁ For the purpose of this standard, the phrase “electronic circuit” excludes circuits in which all components are passive (including diodes, resistors, varistors, capacitors, surge suppressors, inductors). **A₁**

7.3.2 Immunity

7.3.2.1 Equipment not incorporating electronic circuits

Equipment not incorporating electronic circuits is not sensitive to electromagnetic disturbances in normal service conditions, and therefore no immunity tests are required.

7.3.2.2 Equipment incorporating electronic circuits

Equipment incorporating electronic circuits shall have a satisfactory immunity to electromagnetic disturbances.

A₁ *Text deleted* **A₁**

For the appropriate tests to verify the compliance with these requirements, see 8.4.

Specific performance criteria shall be given in the relevant product standard based on the acceptance criteria given in Table 24.

7.3.3 Emission

7.3.3.1 Equipment not incorporating electronic circuits

A₂ The requirements for electromagnetic emissions for equipment not incorporating electronic circuits are deemed to be satisfied, and no verification is necessary. **A₂**

- ^{A2} NOTE For equipment not incorporating electronic circuits, electromagnetic disturbances can only be generated by equipment during occasional switching operations. The duration of the disturbances is less than 200 ms in accordance with CISPR 22.

The frequency, the level and the consequences of these emissions are considered as part of the normal electromagnetic environment of low-voltage installations. ^{A2}

7.3.3.2 Equipment incorporating electronic circuits

7.3.3.2.1 Limits for high-frequency emissions

- ^{A2} The high-frequency (greater than 9 kHz) continuous emissions from equipment incorporating electronic switching circuits shall not exceed the limits specified in the relevant product standard, based on CISPR 11 for environment A and for environment B.

NOTE One-time disturbances no longer than 200 ms need no further evaluation. ^{A2}

The product standard shall detail the test methods.

7.3.3.2.2 Limits for low-frequency emissions

For equipment which generates low frequency harmonics, where applicable, the requirements of IEC 61000-3-2 apply.

For equipment which generates low frequency voltage fluctuations, where applicable, the requirements of IEC 61000-3-3 apply.

8 Tests

8.1 Kinds of test

8.1.1 General

Tests shall be made to prove compliance with the requirements laid down in this standard, where applicable, and in the relevant product standard.

Tests are as follows:

- type tests (see 2.6.1) which shall be made on representative samples of each particular equipment;
- routine tests (see 2.6.2) which shall be made on each individual piece of equipment manufactured to this standard, where applicable, and the relevant product standard;
- sampling tests (see 2.6.3) which are made if called for in the relevant product standard. For sampling tests for clearance verification, see 8.3.3.4.3.

The above tests may consist of test sequences, according to the requirements of the relevant product standard.

Where such test sequences are specified in a product standard, tests, the result of which are not influenced by preceding tests and have no significance for subsequent tests of a given test sequence may be omitted from that test sequence, and made on separate new samples, by agreement with the manufacturer.

The product standard shall specify such tests, where applicable.

The tests shall be carried out by the manufacturer, at his works or at any suitable laboratory of his choice.

Where appropriate, subject to specification in the relevant product standard, and to agreement between manufacturer and user, special tests (see 2.6.4) may also be performed.

8.1.2 Type tests

Type tests are intended to verify compliance of the design of a given equipment with this standard, where applicable, and the relevant product standard.

They may comprise, as appropriate, the verification of

- constructional requirements;
- temperature-rise;
- dielectric properties (see 8.3.3.4.1, where applicable);
- making and breaking capacities;
- short-circuit making and breaking capacities;
- operating limits;
- operational performance;
- degree of protection of enclosed equipment;
- tests for EMC.

NOTE The above list is not exhaustive.

The type tests to which the equipment shall be submitted, the results to be obtained, and, if relevant, the test sequences and the number of samples, shall be specified in the relevant product standard.

8.1.3 Routine tests

Routine tests are intended to detect faults in materials and workmanship and to ascertain proper functioning of the equipment. They shall be made on each individual piece of equipment.

Routine tests may comprise

- a) functional tests;
- b) dielectric tests.

Details of the routine tests and the conditions under which they shall be made shall be stated in the relevant product standard.

8.1.4 Sampling tests

If engineering and statistical analysis show that routine tests (on each product) are not required, sampling tests may be made instead, if so stated in the relevant product standard.

The tests may comprise

- a) functional tests;
- b) dielectric tests.

Sampling tests may also be made to verify specific properties or characteristics of an equipment, either on the manufacturer's own initiative, or by agreement between manufacturer and user.

8.2 Compliance with constructional requirements

The verification of compliance with the constructional requirements stated in 7.1 concerns, for example

- the materials;
- the equipment;
- the degrees of protection of enclosed equipment;
- A_2 the mechanical and electrical properties of terminals A_2
- the actuator;
- the position indicating device (see 2.3.18).

8.2.1 Materials

8.2.1.1 Test of resistance to abnormal heat and fire

8.2.1.1.1 Glow-wire test (on equipment)

The glow-wire test shall be made according to IEC 60695-2-10 and IEC 60695-2-11 under the conditions specified in 7.1.2.2.

For the purpose of this test, a protective conductor is not considered as a current-carrying part.

NOTE If the test is to be made at more than one place on the same sample, care should be taken to ensure that any deterioration caused by previous tests does not affect the test to be made.

8.2.1.1.2 Flammability, hot wire ignition and arc ignition tests (on materials)

Suitable specimens of the material shall be subjected to the following tests:

- a) flammability test, in accordance with IEC 60695-11-10;
- b) hot wire ignition (HWI) test, as described in Annex M;
- c) arc ignition (AI) test, as described in Annex M.

The test c) is required only if the material is located within the 13 mm of arcing parts or live parts which are subject to loosening of connections. Materials located within 13 mm of arcing parts are exempt from this test if the equipment is subjected to make/break testing.

8.2.2 Equipment

Covered by the various subclauses of 8.2.

8.2.3 Enclosures for equipment

For the degrees of protection of enclosed equipment, see Annex C.

A_1 8.2.4 Mechanical and electrical properties of terminals A_1

This subclause does not apply to aluminium terminals nor to terminals for connection of aluminium conductors.

8.2.4.1 General conditions for tests

Unless otherwise stated by the manufacturer, each test shall be made on terminals in a clean and new condition.

When tests are made with round copper conductors, these shall be of copper according to A_2 IEC 60228 A_2 .

When tests are made with flat copper conductors, these shall have the following characteristics:

- minimum purity: 99,5 %;
- ultimate tensile strength: 200-280 N/mm²;
- Vickers hardness: 40 to 65.

8.2.4.2 Tests of mechanical strength of terminals

Tests shall be made with the appropriate type of conductor having the maximum A_1 cross-section. A_1

A_1 Screwless-type clamping unit according to 7.1.8.1 are tested with conductors of the maximum cross-section. A_1

The conductor shall be connected and disconnected five times.

For screw-type terminals, the tightening torque shall be in accordance with Table 4 or 110 % of the torque specified by the manufacturer, whichever is the greater.

The test shall be conducted on two separate clamping units.

Where a screw has a hexagonal head with means for tightening with a screwdriver and the values in columns II and III are different, the test is made twice, first applying to the hexagonal head the torque specified in column III, and then, on another set of samples, applying the torque specified in column II by means of a screwdriver.

If the values in columns II and III are the same, only the test with the screwdriver is made.

Each time the clamping screw or nut is loosened, a new conductor shall be used for each tightening test.

During the test, clamping units and terminals shall not work loose and there shall be no damage, such as breakage of screws or damage to the head slots, threads, washers or stirrups that will impair the further use of the screwed connections.

8.2.4.3 Testing for damage to and accidental loosening of conductors (flexion test)

The test applies to terminals for the connection of unprepared round copper conductors, of number, cross-section and type (flexible and/or rigid (stranded and/or solid)), specified by the manufacturer.

NOTE An appropriate test for flat copper conductors may be made by agreement between manufacturer and user.

The following tests shall be carried out using two new samples with

- a) the maximum number of conductors of the A_1 minimum cross-section A_1 connected to the terminal;
- b) the maximum number of conductors of the A_1 maximum cross-section A_1 connected to the terminal;
- c) the maximum number of conductors of the A_1 minimum and maximum cross-sections A_1 connected to the terminal.

Terminals intended for connection of either flexible or rigid (solid and/or stranded) conductors shall be tested with each type of conductor with different sets of samples.

Terminals intended for connection of both flexible or rigid (solid and/or stranded) conductors simultaneously shall be tested as stated in c) above.

The test is to be carried out with suitable test equipment. The specified number of conductors shall be connected to the terminal. The length of the test conductors should be 75 mm longer than the height H specified in Table 5. The clamping screws shall be tightened with a torque in accordance with Table 4 or with the torque specified by the manufacturer. The device tested shall be secured as shown in Figure 1.

Each conductor is subjected to circular motions according to the following procedure:

The end of the conductor under test shall be passed through an appropriate size bushing in a platen positioned at a height H below the equipment terminal, as given in Table 5. The other conductors shall be bent in order not to influence the result of the test. The bushing shall be positioned in the horizontal platen concentric with the conductor. The bushing shall be moved so that its centreline describes a circle of 75 mm diameter about its centre in the horizontal plane at $10 \text{ rpm} \pm 2 \text{ rpm}$. The distance between the mouth of the terminal and the upper surface of the bushing shall be within 15 mm of the height H in Table 5. The bushing is to be lubricated to prevent binding, twisting or rotation of the insulated conductor. A mass as specified in Table 5 is to be suspended from the end of the conductor. The test shall consist of 135 continuous revolutions.

During the test, the conductor shall neither slip out of the terminal nor break near the clamping unit.

Immediately after the flexion test, each conductor under test shall be submitted in the test equipment to the test of 8.2.4.4 (pull-out test).

8.2.4.4 Pull-out test

8.2.4.4.1 Round copper conductors

Following the test of 8.2.4.3, the pulling force given in Table 5 shall be applied to the conductor tested in accordance with 8.2.4.3.

The clamping screws shall not be tightened again for this test.

A1) The force shall be applied without jerks for 1 min, in the direction of the axis of the conductor. **A1)**

During the test, the conductor shall neither slip out of the terminal nor break near the clamping unit.

8.2.4.4.2 Flat copper conductors

A suitable length of conductor shall be secured in the terminal and the pulling force given in Table 6 applied without jerks for 1 min in a direction opposite to that of the insertion of the conductor.

During the test, the conductor shall neither slip out of the terminal nor break near the clamping unit.

8.2.4.5 Test for insertability of unprepared round copper conductors having the \square_{A1} maximum cross-section \square_{A1}

8.2.4.5.1 Test procedure

The test shall be carried out using the appropriate gauge form A or form B specified in Table 7.

The measuring section of the gauge shall be able to penetrate freely into the terminal aperture to the full depth of the terminal (see also note to Table 7).

Alternatively, the test can be carried out by inserting the largest conductor of type and rated cross-section among those recommended by the manufacturer, the diameter of which corresponds to the theoretical diameter according to Table 7a, after the insulation has been removed and the end has been reshaped. The stripped end of the conductor shall be able to enter completely within the clamping unit aperture, without use of undue force.

NOTE The manufacturer may specify the test method.

8.2.4.5.2 Construction of gauges

The construction of the gauges is shown in Figure 2.

Details of dimensions a and b and their permissible deviations are shown in Table 7. The measuring section of the gauge shall be made from gauge steel.

8.2.4.6 Tests for insertability of flat conductors with rectangular cross-section

Under consideration.

\square_{A1} 8.2.4.7 Electrical performance of screwless-type clamping units

Subclauses 9.8 of IEC 60999-1 and 9.8 of IEC 60999-2 apply.

NOTE 1 The terms “smallest cross-sectional area” and “largest cross-sectional area” of IEC 60999 series are respectively “minimum cross section” (\square_{A2} 2.3.24 \square_{A2}) and “maximum cross section” (\square_{A2} 2.3.35 \square_{A2}) defined in this standard.

\square_{A2} NOTE 2 For the largest cross-sectional area the test current generally applied is I_{th} or I_{the} declared for the product. For the smallest cross-sectional area, the test current is given in Table 4 and Table 5 of IEC 60947-7-1:2009. \square_{A2}

The detailed test requirements may be adapted in the product standards.

NOTE 3 The product standard should consider the practicality of the detailed test requirements.

8.2.4.8 Ageing test for screwless-type clamping units

Subclauses 9.10 of IEC 60999-1 and 9.10 of IEC 60999-2 apply.

NOTE 1 The terms “smallest cross-sectional area” and “largest cross-sectional area” of IEC 60999 series are respectively “minimum cross section” (\square_{A2} 2.3.24 \square_{A2}) and “maximum cross section” (\square_{A2} 2.3.35 \square_{A2}) defined in this standard.

\square_{A2} NOTE 2 For the largest cross-sectional area the test current generally applied is I_{th} or I_{the} declared for the product. For the smallest cross-sectional area, the test current is given in Table 4 and Table 5 of IEC 60947-7-1:2009. \square_{A2}

The detailed test requirements may be adapted in the product standards.

NOTE 3 The product standard should consider the practicality of the detailed test requirements. \square_{A1}

8.2.5 Verification of the effectiveness of indication of the main contact position of equipment suitable for isolation

To verify the effectiveness of the indication of the main contact position as required by 7.1.7, all means of indication of contact position shall continue to function correctly after the operational performance type tests, and special durability tests if performed.

8.2.5.1 Condition of equipment for the tests

The condition of the equipment for the tests shall be stated in the relevant product standard.

8.2.5.2 Method of test

8.2.5.2.1 Dependent and independent manual operation

The force necessary to operate the device to the open position shall be measured at the extremity of the actuator. The measured force F shall be equal to the average value of maximum force obtained from three consecutive operations, with the device in a clean and new condition. This force F shall then be used for the establishment of the test force in Table 17.

With the equipment in the closed position, the fixed and moving contacts of the pole for which the test is deemed to be the most severe shall be fixed together, for example, by welding.

The actuator shall be submitted to a test force of $3F$ but which, however, shall not be less than the minimum nor more than the maximum values given in Table 17, corresponding to the type of actuator.

A1 Where the device has more than one contact system in series, all contact systems that are in series shall be held in the closed position. **A1**

In the case of multiple tip contact systems, the least number of parallel contact tips shall be fixed together as necessary to hold the contact system closed in order to allow the test force to be applied without the contacts separating.

The appropriate means to keep the contact(s) closed and the number of contacts shall be specified by the manufacturer. The number of contacts and the method shall be stated in the report.

The test force shall be applied without shock to the extremity of the actuator, for a period of 10 s, in the direction to open the contacts.

The direction of the test force with respect to the actuator, as shown in Figure 16, shall be maintained throughout the test.

A1 Verification shall be made according to 8.2.5.3.1. **A1**

8.2.5.2.2 Dependent power operation

With the equipment in the closed position, the fixed and moving contacts of the pole for which the test is deemed to be the most severe shall be fixed together, e.g. by welding.

A1 Where the device has more than one contact system in series, all contact systems that are in series shall be held in the closed position. **A1**

In the case of multiple tip contact systems, the least number of parallel contact tips shall be fixed together as necessary to hold the contact system closed in order to allow the test force to be applied without the contacts separating.

The appropriate means to keep the contact(s) closed and the number of contacts shall be specified by the manufacturer. The number of contacts and the method shall be stated in the report.

The supply voltage to the power operator shall be applied at 110 % of its normal rated value to attempt to open the contact system of the equipment.

Three attempts to operate the equipment at 5 min intervals by the power operator shall be made, each for a period of 5 s, unless an associated protective device of the power operator limits the time to a shorter period.

Verification shall be made to 8.2.5.3.2.

NOTE In Canada and the United States of America devices meeting these requirements are not accepted as assuring isolation by themselves.

8.2.5.2.3 Independent power operation

With the equipment in the closed position, the fixed and moving contacts of the pole for which the test is deemed to be the most severe shall be fixed together, e.g. by welding.

A1 Where the device has more than one contact system in series, all contact systems that are in series shall be held in the closed position. **A1**

In the case of multiple tip contact systems, the least number of parallel contact tips shall be fixed together as necessary to hold the contact system closed in order to allow the test force to be applied without the contacts separating.

The appropriate means to keep the contact(s) closed and the number of contacts shall be specified by the manufacturer. The number of contacts and the method shall be stated in the report.

The stored energy of the power operator shall be released to attempt to open the contact system of the equipment.

Three attempts to operate the equipment by releasing the stored energy shall be made.

Verification shall be made to 8.2.5.3.2.

NOTE In Canada and the United States of America devices meeting these requirements are not accepted as assuring isolation by themselves.

8.2.5.3 Condition of equipment during and after test

8.2.5.3.1 Dependent and independent manual operation

After the test, when the test force is no longer applied, the actuator being left free, the open position shall not be indicated by any of the means provided and the equipment shall not show any damage such as to impair its normal operation.

When the equipment is provided with a means of locking in the open position, it shall not be possible to lock the equipment while the test force is applied.

8.2.5.3.2 Dependent and independent power operation

During and after the test, the open position shall not be indicated by any of the means provided and the equipment shall not show any damage such as to impair its normal operation.

When the equipment is provided with means for locking in the open position, it shall not be possible to lock the equipment during the test.

8.2.6 Vacant

8.2.7 Conduit pull-out test, torque test and bending test with metallic conduits

The test shall be made with an appropriate sized metal conduit (300 ± 10) mm long.

The polymeric enclosure shall be installed according to the manufacturer's instructions, in the most unfavourable position.

The tests shall be made on the same conduit entry, this being the most unfavourable entry.

The tests shall be made in the sequence 8.2.7.1, 8.2.7.2 and 8.2.7.3.

8.2.7.1 Pull-out test

The conduit shall be screwed without jerk into the entry with a torque equal to two-thirds of the values given in Table 22. A direct pull shall be applied, without jerk, to the conduit for 5 min.

Unless otherwise specified in the relevant product standard, the pulling force shall be according to Table 20.

After the test, the displacement of the conduit in relation with the entry shall be less than one thread depth and there shall be no evidence of damage impairing further use of the enclosure.

8.2.7.2 Bending test

A slowly increasing bending moment shall be applied without jerk to the free end of the conduit.

When the bending moment results in a deflection of the conduit of 25 mm per 300 mm length, or the bending moment has reached the value given in Table 21, the moment is maintained for 1 min. The test is then repeated in a perpendicular direction.

After the test there shall be no evidence of damage impairing further use of the enclosure.

8.2.7.3 Torque test

The conduit shall be tightened without jerk with a torque according to Table 22.

The torque test does not apply to an enclosure that is not provided with a pre-assembled conduit entry, and that has instructions stating that the conduit entry is to be mechanically connected to the conduit before being connected to the enclosure.

For enclosures provided with a single conduit connection up to and including 16 H, the tightening torque is reduced to 25 N·m.

After the test, it shall be possible to unscrew the conduit and there shall be no evidence of damage impairing further use of the enclosure.

8.3 Performance

8.3.1 Test sequences

Where applicable, the relevant product standard shall specify the test sequences to which the equipment is to be submitted.

8.3.2 General test conditions

NOTE Tests according to the requirements of this standard do not preclude the need for additional tests concerning equipment incorporated in assemblies, for example tests in accordance with [A2](#) IEC 61439 series [A2](#).

8.3.2.1 General requirements

The equipment to be tested shall agree in all its essential details with the design of the type which it represents.

Unless otherwise stated in the relevant product standard, each test, whether individual or test sequence, shall be made on equipment in a clean and new condition.

Unless otherwise stated, the tests shall be made with the same kind of current (and, in the case of a.c., at the same rated frequency and with the same number of phases) as in the intended service.

The relevant product standard shall specify those values of test quantities not specified in this standard.

If, for convenience of testing, it appears desirable to increase the severity of a test (e.g. to adopt a higher rate of operation in order to reduce the duration of the test), this may be done only with the consent of the manufacturer.

Equipment under test shall be mounted complete on its own support or an equivalent support and connected as in normal service, in accordance with the manufacturer's instructions and under the ambient conditions stated in 6.1.

The tightening torques to be applied to the terminal screws shall be in accordance with the manufacturer's instructions or, in the absence of such instructions, in accordance with Table 4.

Equipment having an integral enclosure (see 2.1.17) shall be mounted complete and any opening normally closed in service shall be closed for tests.

Equipment intended for use only in an individual enclosure shall be tested in the smallest of such enclosures stated by the manufacturer.

A2 Text deleted **A2**

All other equipment shall be tested in free air. If such equipment may also be used in specified individual enclosures and has been tested in free air, it shall be additionally tested in the smallest of such enclosures stated by the manufacturer, for specific tests which shall be specified in the relevant product standard and stated in the test report.

However, if such equipment may also be used in specified individual enclosures and is tested throughout in the smallest of such enclosures stated by the manufacturer, the tests in free air need not be made provided that such enclosure is bare metallic, without insulation. Details, including the dimensions of the enclosure, shall be stated in the test report.

For the test in free air, unless otherwise specified in the relevant product standard, for the test concerning making and breaking capacities and performance under short-circuit conditions, a metallic screen shall be placed at all points of the equipment likely to be a source of external phenomena capable of producing a breakdown, in accordance with the arrangements and distances specified by the manufacturer. Details, including distance from the equipment under test to the metallic screen, shall be stated in the test report.

The characteristics of the metallic screen shall be as follows:

- structure: woven wire mesh; or
perforated metal; or
expanded metal;
- material: steel;
- thickness or diameter of material: 1,5 mm minimum;
- ratio hole area/total area: 0,45 – 0,65;
- size of hole: not exceeding 30 mm²;
- coating: bare, or conductive plating;
- resistance: shall be included in the calculation for the prospective fault current in the fusible element circuit (see 8.3.3.5.2 g) and 8.3.4.1.2 d)), measured from the furthest point on the metallic screen likely to be reached by arc emissions.

Maintenance or replacement of parts is not permitted, unless otherwise specified in the relevant product standard.

The equipment may be operated without load prior to beginning a test.

For the tests, the actuating system of mechanical switching devices shall be operated as for the intended use in service stated by the manufacturer and at the rated values of control quantities (such as voltage or pressure), unless otherwise specified in this standard or the relevant product standard.

8.3.2.2 Test quantities

8.3.2.2.1 Values of test quantities

All the tests shall be made with the values of test quantities corresponding to the ratings assigned by the manufacturer, in accordance with the relevant tables and data of the relevant product standard.

8.3.2.2.2 Tolerances on test quantities

The test recorded in the test report shall be within the tolerances given in Table 8, unless otherwise specified in the relevant subclauses. However, with the agreement of the manufacturer, the tests may be made under more severe conditions than those specified.

8.3.2.2.3 Recovery voltage

a) Power-frequency recovery voltage

For all breaking capacity and short-circuit breaking capacity tests, the value of the power-frequency recovery voltage shall be 1,05 times the value of the rated operational voltage as assigned by the manufacturer or as specified in the relevant product standard.

NOTE 1 The value of 1,05 times the rated operational voltage for the power frequency recovery voltage, together with the test voltage tolerance according to Table 8, is deemed to cover the effects of variations of the \overline{U}_m supply network voltage \overline{U}_m under normal service conditions, according to IEC 60038.

NOTE 2 This may require that the applied voltage be increased but the prospective peak making current should not be exceeded without the consent of the manufacturer.

NOTE 3 The upper limit of the power-frequency recovery voltage may be increased with the approval of the manufacturer (see 8.3.2.2.2).

b) Transient recovery voltage

Transient recovery voltages, where required in the relevant product standard, are determined according to 8.3.3.5.2.

8.3.2.3 Evaluation of test results

Behaviour of the equipment during the tests and its condition after the tests shall be specified in the relevant product standard. For short-circuit tests, see also 8.3.4.1.7 and 8.3.4.1.9.

8.3.2.4 Test reports

Written reports on type tests proving compliance with the relevant product standard shall be made available by the manufacturer. The details of test arrangements such as type and size of the enclosure, if any, size of conductors, distance from the live parts to the enclosure or to parts normally earthed in service, method of operation of the actuating system, etc., shall be given in the test report.

Test values and parameters shall form part of the test report.

8.3.3 Performance under no-load, normal load and overload conditions

8.3.3.1 Operation

Tests shall be made to verify that the equipment operates correctly according to the requirements of 7.2.1.1.

8.3.3.2 Operating limits

8.3.3.2.1 Power operated equipment

It shall be verified that the equipment opens and closes correctly within the limiting values of the control quantities, such as voltage, current, air pressure and temperatures, specified in the relevant product standard. Tests are made with no current flowing through the main circuit, unless otherwise specified.

- A1)** In the case of a power operated equipment with electronically controlled electromagnet, supplied with a.c., where a drop out range is declared with limits between 75 % to 10 % of their **A2)** rated control circuit supply voltage $\sqrt{A2}$ U_s , the equipment shall, in addition, be submitted to the capacitive drop out test as follows:

A capacitor C shall be inserted in series in the supply circuit U_s , the total length of the connecting conductors being ≤ 3 m. The capacitor is short-circuited by a switch of negligible impedance. The supply voltage shall then be adjusted to 110 % U_s .

It shall be verified that the equipment drops out when the switch is operated to the open position.

- A2)** The value of the capacitor shall be

$$C = 30 + 200\,000 / (f \times U)$$

where

- C is expressed in nF;
- f is the minimum rated frequency expressed in Hz;
- U is the maximum value of U_s expressed in V. **A2)**

For example for a coil rated 12...24 V – 50 Hz, the capacitor value is 196 nF (calculation made with U_s max).

The test voltage is the highest value of the declared rated supply voltage range U_s .

NOTE The value of the capacitor simulates a typical control wiring of 100 m long cable of 1,5 mm² (0,3 nF/m that is 30 nF for 100 m) connected to a static output having a 1,3 mA leakage current (200 000 in the formula $\approx 10 \text{ E}+9 * 1,3 \text{ E}-3/2*\pi$). **A1)**

8.3.3.2.2 Relays and releases

The operating limits of relays and releases shall comply with the requirements of 7.2.1.3, 7.2.1.4 and 7.2.1.5 and shall be verified according to the test procedure defined in the relevant product standard.

For undervoltage relays and releases, see 7.2.1.3.

For shunt releases, see 7.2.1.4.

For current operated relays and releases, see 7.2.1.5.

8.3.3.3 Temperature-rise

8.3.3.3.1 Ambient air temperature

The ambient air temperature shall be recorded during the last quarter of the test period by at least two temperature sensing means, e.g. thermometers or thermocouples, equally distributed around the equipment at about half its height and at a distance of about 1 m from the equipment. The temperature sensing means shall be protected against air currents, heat radiation and indicating errors due to rapid temperature changes.

- Ⓐ₂ During the test, the ambient temperature shall be between +10 °C and +40 °C and shall not vary by more than 10 K. The ambient temperature shall not vary by more than 3 K during the last quarter of the test or the last hour of the test, whichever is the shorter. The test shall be conducted until this condition is achieved. Ⓐ₂

Ⓐ₂ Text deleted Ⓐ₂

8.3.3.3.2 Measurement of the temperature of parts

For parts other than coils, the temperature of the different parts shall be measured by suitable temperature sensing means at those points most likely to attain the maximum temperature; these points shall be stated in the test report.

The oil temperature of oil-immersed equipment shall be measured at the upper part of the oil; this measurement may be made by means of a thermometer.

The temperature sensing means shall not significantly affect the temperature-rise.

Good thermal conductivity between the temperature sensing means and the surface of the part under test shall be ensured.

- Ⓐ₁ For electromagnet coils, the method of measuring the temperature by variation of resistance shall generally be used. Other methods are permitted only if it is impracticable to use the resistance method, for example for electronically controlled electromagnet. When measured by another method than the resistance method the limits of temperature rise permitted shall be adjusted accordingly. The product standard shall state the method and the limits.

In the case of an electronically controlled electromagnet, coil temperature measuring by variation of resistance may be impracticable; in such a case, other methods are permitted, e.g. thermocouples or other suitable methods. When measured by another method than the resistance method the limits of temperature rise permitted shall be adjusted accordingly. The product standard shall state the method and the limits. Ⓐ₁

The temperature of the coils before beginning the test shall not differ from that of the surrounding medium by more than 3 K.

For copper conductors, the value of the hot temperature T_2 , may be obtained from the value of the cold temperature T_1 , as a function of the ratio of the hot resistance R_2 to the cold resistance R_1 by the following formula:

$$T_2 = \frac{R_2}{R_1}(T_1 + 234,5) - 234,5$$

where T_1 and T_2 are expressed in degrees Celsius.

The test shall be made for a time sufficient for the temperature-rise to reach a steady-state value, but not exceeding 8 h. It is assumed that a steady state is reached when the variation does not exceed 1 K per hour.

8.3.3.3.3 Temperature-rise of a part

The temperature-rise of a part is the difference between the temperature of the part measured in accordance with 8.3.3.2, and the ambient air temperature measured in accordance with 8.3.3.3.1.

8.3.3.3.4 Temperature-rise of the main circuit

The equipment shall be mounted as specified in 8.3.2.1 and shall be protected against abnormal external heating or cooling.

For the conventional thermal current test (free air or enclosed), equipment having an integral enclosure and equipment only intended for use with a specified type of enclosure shall be tested in its enclosure. No opening giving false ventilation shall be allowed.

Equipment intended for use with more than one type of enclosure shall be tested either in the smallest enclosure stated by the manufacturer to be suitable or tested without an enclosure. If tested without an enclosure the manufacturer shall be prepared to state a value of conventional enclosed thermal current (see 4.3.2.2).

For tests with multiphase currents, the current shall be balanced in each phase within $\pm 5\%$, and the average of these currents shall be not less than the appropriate test current.

Unless otherwise specified in the relevant product standard, the temperature-rise test of the main circuit is made at one or both of the conventional thermal currents, as defined in 4.3.2.1 and 4.3.2.2 and may be made at any convenient voltage.

When the heat exchange between the main circuit, the control circuit and the auxiliary circuits may be of significance, the temperature-rise tests stated in 8.3.3.3.4, 8.3.3.3.5, 8.3.3.3.6 and 8.3.3.3.7 shall be made simultaneously, in so far as this is allowed by the relevant product standard.

Tests on d.c. rated equipment may be made with an a.c. supply for convenience of testing, but only with the consent of the manufacturer.

In the case of multipole equipment fitted with identical poles and tested with a.c. the test may be carried out, subject to the manufacturer's agreement, with single-phase current, with all poles connected in series provided that magnetic effects can be neglected.

In the case of three-pole equipment provided with a neutral pole different from the phase poles, the test shall comprise

- a three-phase test on the three identical poles;
- a single-phase test on the neutral pole connected in series with the adjacent pole, the value of the test quantities being determined according to the value of the conventional thermal current (free air or enclosed) of the neutral pole (see 7.1.9).

Equipment provided with short-circuit protective devices shall be tested according to the requirements given in the relevant product standard.

At the end of the test, the temperature-rise of the different parts of the main circuit shall not exceed the values given in Tables 2 and 3, unless otherwise specified in the relevant product standard.

Depending on the value of the conventional thermal current (free air or enclosed), one of the following test connection arrangements shall be used:

- i) For values of test current up to and including 400 A:
 - a) The connections shall be single-core, PVC insulated, copper conductors with cross-sections as given in Table 9.
 - b) The connections shall be in free air, and spaced at approximately the distance existing between the terminals.
 - c) For single-phase or multi-phase tests the minimum length of any temporary connection from an equipment terminal to another terminal or to the test supply or to a star point shall be
 - 1 m for cross-sections up to and including 35 mm² (or AWG 2);
 - 2 m for cross-sections larger than 35 mm² (or AWG 2).
- ii) For values of test current higher than 400 A but not exceeding 800 A:
 - a) The connections shall be single-core, PVC insulated, copper conductors with cross-sectional areas as given in Table 10, or the equivalent copper bars given in Table 11, as recommended by the manufacturer.
 - b) The connections specified in a) shall be spaced at approximately the same distance as that between the terminals. Copper bars shall be painted matt black. Multiple parallel conductors per terminal shall be bunched together and arranged with approximately 10 mm air space between each other. Multiple copper bars per terminal shall be spaced at a distance approximately equal to the bar thickness. If the sizes stated for the bars are not suitable for the terminals, or are not available, other bars having approximately the same cross-sections and approximately the same or smaller cooling areas may be used. Copper conductors or bars shall not be laminated.
 - c) For single-phase or multi-phase tests the minimum length of any temporary connection from the equipment terminal to another terminal or to the test supply shall be 2 m. The minimum length to a star point may be reduced to 1,2 m.
- iii) For values of test current higher than 800 A but not exceeding 3 150 A:
 - a) The connections shall be copper bars of the sizes stated in Table 11 unless the equipment is designed only for cable connection. In this case, the size and arrangement of the cables shall be as specified by the manufacturer.

- b) Copper bars shall be spaced at approximately the same distance as that between the terminals. Copper bars shall be painted matt black. Multiple copper bars per terminal shall be spaced at a distance approximately equal to the bar thickness. If the sizes stated for the bars are not suitable for the terminals, or are not available, other bars having approximately the same or smaller cooling areas may be used. Copper bars shall not be laminated.
 - c) For single-phase or multi-phase tests the minimum length of any temporary connection from an equipment terminal to another terminal or to the supply shall be 3 m, but this can be reduced to 2 m provided that the temperature-rise at the supply end of the connection is not more than 5 K below the temperature-rise in the middle of the connection length. The minimum length to a star point shall be 2 m.
- iv) For values of test current higher than 3 150 A:
Agreement shall be reached between manufacturer and user on all relevant items of the test, such as: type of supply, number of phases and frequency (where applicable), cross-sections of test connections, etc. This information shall form part of the test report.

8.3.3.3.5 Temperature-rise of control circuits

The temperature-rise tests of control circuits shall be made with the specified current and, in the case of a.c., at the rated frequency. Control circuits shall be tested at their rated voltage.

Circuits intended for continuous operation shall be tested for a sufficient time for the temperature-rise to reach a steady-state value.

Circuits for intermittent duty shall be tested as prescribed in the relevant product standard.

At the end of these tests the temperature-rise of the different parts of the control circuits shall not exceed the values specified in 7.2.2.5, unless otherwise specified in the relevant product standard.

8.3.3.3.6 Temperature-rise of coils of electromagnets

Coils and electromagnets shall be tested according to the conditions given in 7.2.2.6.

They shall be tested for a sufficient time for the temperature-rise to reach a steady-state value.

The temperature shall be measured when thermal equilibrium is reached in both the main circuit and the coil of the electromagnet.

Coils and electromagnets of equipment intended for intermittent duty shall be tested as prescribed in the relevant product standard.

At the end of these tests the temperature-rise of the different parts shall not exceed the values specified in 7.2.2.6.

8.3.3.3.7 Temperature-rise of auxiliary circuits

The temperature-rise tests of auxiliary circuits shall be made under the same conditions as those specified in 8.3.3.3.5, but may be carried out at any convenient voltage.

At the end of these tests the temperature-rise of the auxiliary circuits shall not exceed the values specified in 7.2.2.7.

8.3.3.4 Dielectric properties

8.3.3.4.1 Type tests

1) General conditions for withstand voltage tests

The equipment to be tested shall comply with the general requirements of 8.3.2.1.

If the equipment is to be used without an enclosure, it shall be mounted on a metal plate and all exposed conductive parts (frame, etc.) intended to be connected to the protective earth in normal service shall be connected to that plate.

When the base of the equipment is of insulating material, metallic parts shall be placed at all of the fixing points in accordance with the conditions of normal installation of the equipment and these parts shall be considered as part of the frame of the equipment.

Any actuator of insulating material and any integral non-metallic enclosure of equipment intended to be used without an additional enclosure shall be covered by a metal foil and connected to the frame or the mounting plate. The foil shall only be applied to those parts of surface which can be touched with the standard test finger during operation or adjustment of the equipment. If the insulation part of an integral enclosure cannot be touched by the standard test finger due to the presence of an additional enclosure, no foil shall be required.

NOTE 1 This corresponds to accessible parts by the operator during operation or adjustment of the equipment (for example, actuator of a push-button). Annex R gives guidance for application of the metal foil on accessible parts during operation or adjustment.

When the dielectric strength of the equipment is dependent upon the taping of leads or the use of special insulation, such taping or special insulation shall also be used during the tests.

A2 Text deleted **A2**

A1 For the dielectric test between phases, all circuits between these phases may be disconnected for the test.

A2 NOTE 2 **A2** The purpose of this test is to check the functional insulation only.

When the circuits of equipment include devices such as motors, instruments, snap switches, capacitors and solid state devices which, according to their relevant specifications, have been subjected to dielectric test voltages lower than those specified in this standard, such devices shall be disconnected for the test.

Where the control circuit normally connected to the main circuit is disconnected, the method used to maintain the main contacts closed shall be indicated in the test report.

For the dielectric test between phase and earth, all circuits shall be connected.

A2 NOTE 3 **A2** The connection of all circuits for this test takes into account the function of protection against electric shock of the insulation between phase and earth.

Printed circuit boards and modules with multi-point connectors may be disconnected or replaced by dummies during the insulation test. This does not apply, however, to auxiliaries for which, in case of an insulation fault, voltage may pass onto accessible parts not connected to the housing or from the side of higher voltage to the side of lower voltage, e.g. auxiliary transformers, measuring equipment, pulse transformers, the insulation stress of which is equal to that for the main circuit. **A1**

2) Verification of impulse withstand voltage

a) General

The equipment shall comply with the requirements stated in 7.2.3.1.

The verification of the insulation is made by a test at the rated impulse withstand voltage.

If equipment contains any part for which the dielectric properties are not sensitive to altitude (e.g. optocouplers, encapsulated parts), then the verification of the insulation may be alternatively performed by a test at the rated impulse withstand voltage without application of the altitude correction factor. These parts shall then be disconnected and the remainder of the equipment shall be tested with the rated impulse withstand voltage using the altitude correction factor.

A1) Clearances equal to or larger than the values of class A of Table 13 may be verified by measurement, according to the method described in Annex G. **A1)**

b) Test voltage

The test voltage shall be that specified in 7.2.3.1.

For equipment incorporating overvoltage suppressing means, the energy content of the test current shall not exceed the energy rating of the overvoltage suppressing means. The latter shall be suitable for the application.

NOTE 1 Such ratings are under consideration.

The test equipment shall be calibrated to produce a 1,2/50 μ s waveform as defined in IEC 61180. The output is then connected to the equipment to be tested and the impulse applied five times for each polarity at intervals of 1 s minimum. The influence of the equipment under test on the waveshape, if any, is ignored.

If, in the course of a test procedure, repeated dielectric testing is required, the relevant product standard shall state the dielectric test conditions.

NOTE 2 An example of test equipment is under consideration.

c) Application of test voltage

With the equipment mounted and prepared as specified in item a) above, the test voltage is applied as follows:

- i) between all the terminals of the main circuit connected together (including the control and auxiliary circuits connected to the main circuit) and the enclosure or mounting plate, with the contacts in all normal positions of operation;
- ii) between each pole of the main circuit and the other poles connected together and to the enclosure or mounting plate, with the contacts in all normal positions of operation;
- iii) between each control and auxiliary circuit not normally connected to the main circuit and:
 - the main circuit,
 - the other circuits,
 - the exposed conductive parts,
 - the enclosure or mounting plate,which, wherever appropriate, may be connected together;

- iv) for equipment suitable for isolation, across the poles of the main circuit, the line terminals being connected together and the load terminals connected together.

The test voltage shall be applied between the line and load terminals of the equipment with the contacts in the open position and its value shall be as specified in item 1) b) of 7.2.3.1.

For equipment not suitable for isolation, the requirements for testing with the contacts in the open position shall be stated in the relevant product standard.

d) Acceptance criteria

There shall be no unintentional disruptive discharge during the tests.

NOTE 1 An exception is an intentional disruptive discharge, for example by transient overvoltage suppressing means.

NOTE 2 The term "disruptive discharge" related to phenomena associated with the failure of insulation under electrical stress, in which the discharge completely bridges the insulation under test, reducing the voltage between the electrodes to zero or nearly to zero.

NOTE 3 The term "sparkover" is used when a disruptive discharge occurs in a gaseous or liquid dielectric.

NOTE 4 The term "flashover" is used when a disruptive discharge occurs over the surface of a dielectric in a gaseous or liquid medium.

NOTE 5 The term "puncture" is used when a disruptive discharge occurs through a solid dielectric.

NOTE 6 A disruptive discharge in a solid dielectric produces permanent loss of dielectric strength, in a liquid or gaseous dielectric, the loss may be only temporary.

3) Power-frequency withstand verification of solid insulation

a) General

This test applies to the verification of solid insulation and the ability to withstand temporary overvoltages.

A1 The values of Table 12A are deemed to cover the ability to withstand temporary overvoltages (see the footnote b of Table 12A). A1

b) Test voltage

The test voltage shall have a practically sinusoidal waveform and a frequency between 45 Hz and 65 Hz.

A1 NOTE "practically sinusoidal" means that the ratio between the peak value and the r.m.s. value is $\sqrt{2} \pm 3\%$. A1

The high-voltage transformer used for the test shall be so designed that, when the output terminals are short-circuited after the output voltage has been adjusted to the appropriate test voltage, the output current shall be at least 200 mA.

The overcurrent relay shall not trip when the output current is less than 100 mA.

The value of the test voltage shall be as follows:

- i) for the main circuit, and for the control and auxiliary circuits, in accordance with Table 12A. The uncertainty of measurement of the test voltage shall not exceed $\pm 3\%$.
- ii) if an alternating test voltage cannot be applied, for example due to EMC filter components, a direct test voltage may be used having the value of Table 12A, third column. The uncertainty of measurement of the test voltage shall not exceed $\pm 3\%$.

A1 Text deleted A1

c) Application of test voltage

A2 The test voltage shall be applied to for 60 s in accordance with items i), ii) and iii) of 2) c) above.

NOTE For devices already type-tested according to this standard and its Amendment 1 or earlier, a re-testing according to 60 s is not necessary. A2

d) Acceptance criteria

During the test, no flashover, breakdown of insulation either internally (puncture) or externally (tracking) or any other manifestation of disruptive discharge shall occur. Any glow discharge shall be ignored.

Components connected between phase and earth may be damaged during the tests but such failure shall not result in a condition that would lead to a hazardous situation. Product standards may give specific acceptance criteria.

NOTE The voltage levels to earth are based on IEC 60664-1 under worst case conditions which generally do not occur in practice.

4) Power-frequency withstand verification after switching and short-circuit tests

a) General

The test should be performed on the equipment whilst it remains mounted for the switching or short-circuit tests. If this is not practicable, it may be disconnected and removed from the test circuit, although measures shall be taken to ensure that this does not influence the result of the test.

b) Test voltage

The requirements of 3) b) above shall apply except that the value of the test voltage shall be $2 U_e$ with a minimum of 1 000 V r.m.s.

The requirements of 3) b) above shall apply except that the value of the test voltage shall be $2 U_e$ with a minimum of 1 000 V r.m.s. or 1 415 V d.c. if an a.c. voltage test cannot be applied. The value of U_e referred to is that at which switching and/or short-circuit tests have been performed.

NOTE The product standards should be adapted to this decision when reprinted.

c) Application of test voltage

The requirements of 3) c) above shall apply. The application of the metal foil, according to 8.3.3.4.1 1), is not required.

d) Acceptance criteria

The requirements of 3) d) above shall apply.

5) Vacant

6) Verification of d.c. withstand voltage

A2 Equipment with d.c. ratings only shall be tested with d.c. test voltage. **A2**

7) Verification of creepage distances

The shortest creepage distances between phases, between circuit conductors at different voltages and live and exposed conductive parts shall be measured. The measured creepage distance with respect to material group and pollution degree shall comply with the requirements of 7.2.3.4.

8) Verification of leakage current of equipment suitable for isolation

Tests shall be specified in the relevant product standard.

8.3.3.4.2 Routine tests

1) Impulse withstand voltage

The tests shall be performed in accordance with item 2) of 8.3.3.4.1. The test voltage shall be not less than 30 % of the rated impulse withstand voltage (without altitude correction factor) or $2 U_i$ whichever is the higher.

2) Power-frequency withstand voltage

a) Test voltage

The test apparatus shall be the same as that stated in item 3) b) of 8.3.3.4.1 except that the overcurrent trip should be set at 25 mA.

However, at the discretion of the manufacturer for safety reasons, test apparatus of a lower power or trip setting may be used, but the short-circuit current of the test apparatus shall be at least eight times the nominal trip setting of the overcurrent relay, for example for a transformer with a short-circuit current of 40 mA, the maximum trip setting of the overcurrent relay shall be $5 \text{ mA} \pm 1 \text{ mA}$.

NOTE 1 The capacitance of the equipment may be taken into account.

The value of the test voltage shall be $2 U_e$ with a minimum of 1 000 V r.m.s.

NOTE 2 In the case of multiple values, U_e refers to the highest value marked on the equipment or given in the manufacturer's documentation.

b) Application of test voltage

The requirements of item 3) c) of 8.3.3.4.1 shall apply, except that the duration of the test voltage shall be 1 s only.

However, as an alternative, a simplified test procedure may be used if it is considered to subject the insulation to an equivalent dielectric stress.

c) Acceptance criteria

The overcurrent relay shall not trip.

3) Combined impulse voltage and power-frequency withstand voltage

Product standards may specify if the tests of items 1) and 2) above may be replaced by a single power frequency withstand test where the peak value of the sinusoidal wave corresponds to the value stated in items 1) or 2), whichever is the higher.

4) In no case the application of the metal foil according to 8.3.3.4.1 1) is required.

8.3.3.4.3 Sampling tests for verification of clearances

1) General

These tests are intended to verify the maintaining of the design conformity regarding clearances and are only applicable to equipment with clearances smaller than those corresponding to Table 13, case A.

2) Test voltage

The test voltage shall be that corresponding to the rated impulse withstand voltage.

The relevant product standards shall state sampling plans and procedure.

3) Application of test voltage

The requirements of item 2) c) of 8.3.3.4.1 shall apply, except that the metal foil need not be applied to the actuator or the enclosure.

4) Acceptance criteria

No disruptive discharge shall occur.

8.3.3.4.4 Tests for equipment with protective separation

Tests for equipment with protective separation are given in Annex N.

8.3.3.5 Making and breaking capacities

8.3.3.5.1 General test conditions

Tests for verification of making and breaking capacities shall be made according to the general test requirements stated in 8.3.2.

The tolerances for individual phases shall be in accordance with Table 8, unless otherwise stated.

Four-pole equipment shall be tested as three-pole equipment with the unused pole, which in the case of equipment provided with a neutral pole is the neutral pole, connected to the frame. If all poles are identical, one test on three adjacent poles is sufficient. If not, an additional test shall be made between the neutral pole and the adjacent pole, according to Figure 4, at the rated current of the neutral pole and at the phase-to-neutral voltage, with the other two unused poles connected to the frame.

For transient recovery voltages, in the case of breaking capacity tests under normal load and overload conditions, values shall be specified in the relevant product standard.

8.3.3.5.2 Test circuit

- a) Figures 3, 4, 5 and 6 give the diagrams of the circuits to be used for the tests concerning
- single-pole equipment on single-phase a.c. or d.c. (Figure 3);
 - two-pole equipment on single-phase a.c. or d.c. (Figure 4);
 - three-pole equipment or three single-phase equipment on three-phase a.c. (Figure 5);
 - four-pole equipment on three-phase four-wire a.c. (Figure 6);

A detailed diagram of the circuit used for the test shall be given in the test report.

- b) The prospective current at the supply terminals of the equipment shall be not less than 10 times the test current or 50 kA, whichever is the lower.
- c) The test circuit comprises the supply source, the equipment D under test and the load circuit.
- d) The load circuit shall consist of resistors and air-cored reactors in series. Air-cored reactors in any phase shall be shunted by resistors taking approximately 0,6 % of the current through the reactor.

However, where a transient recovery voltage is specified, instead of the 0,6 % shunt resistors, parallel resistors and capacitors shall be included across the load, the complete load circuit being as shown in Figure 8.

NOTE For d.c. tests where $L/R > 10$ ms an iron-cored reactor may be used with series resistors, if necessary, verifying with an oscilloscope that the L/R value is as specified ($^{+15}_0$ %), and that the time required to obtain 95 % of the current made is equal to $3 \times L/R \pm 20$ %.

Where a transient inrush current is specified (e.g. utilization categories AC-5b, AC-6 and DC-6), a different type of load may be specified in the relevant product standard.

- e) The loads shall be adjusted to obtain, at the specified voltage:
- the value of current and power-factor or time-constant specified in the relevant product standard;
 - the value of the power-frequency recovery voltage;
 - where specified, the oscillatory frequency of the transient recovery voltage and the value of the factor γ .

The factor γ is the ratio of the value U_1 of the highest peak of the transient recovery voltage to the instantaneous value U_2 , at the instant of current zero, of the component of the recovery voltage at power frequency (see Figure 7).

- f) The test circuit shall be earthed at one point only. This could be either the load star-point or the supply star-point. The position of this point shall be stated in the test report.

NOTE The sequence of connection of R and X (see Figures 8a and 8b) should not be changed between the adjustment and the test.

- g) All parts of the equipment normally earthed in service, including the enclosure or the screens, shall be insulated from earth and connected as indicated in Figures 3, 4, 5 or 6.

This connection shall comprise a fusible element F consisting of a copper wire 0,8 mm in diameter and at least 50 mm long, or an equivalent fusible element, for the detection of the fault current.

The prospective fault current in the fusible-element circuit shall be $1\,500\text{ A} \pm 10\%$, except as stated in notes 2 and 3. If necessary, a resistor limiting the current to that value shall be used.

NOTE 1 A copper wire of 0,8 mm in diameter will melt at 1 500 A in approximately half a cycle at a frequency between 45 Hz to 67 Hz (or 0,01 s for d.c.).

NOTE 2 In the case of a supply having an artificial neutral, a lower prospective fault current may be accepted, subject to the manufacturer's agreement, with a smaller diameter wire according to the following table.

Diameter of copper wire mm	Prospective fault current in the fusible element circuit A
0,1	50
0,2	150
0,3	300
0,4	500
0,5	800
0,8	1 500

NOTE 3 For the value of the resistance of the fusible element see 8.3.2.1.

8.3.3.5.3 Characteristics of transient recovery voltage

To simulate the conditions in circuits including individual motor loads (inductive loads), the oscillatory frequency of the load circuit shall be adjusted to the value

$$f = 2\,000 \cdot I_c^{0,2} \cdot U_e^{-0,8} \pm 10\%$$

where

f is the oscillatory frequency, in kilohertz;

I_c is the breaking current, in amperes;

U_e is the rated operational voltage of the equipment in volts.

The factor γ shall be adjusted to the value

$$\gamma = 1,1 \pm 0,05$$

The value of reactance necessary for the test may be obtained by coupling several reactors in parallel on condition that the transient recovery voltage can still be considered as having only one oscillatory frequency. This is generally the case when the reactors have practically the same time-constant.

The load terminals of the equipment shall be connected as closely as possible to the terminals of the adjusted load circuit. The adjustment should be made with these connections in place.

Depending on the position of the earthing, two procedures for the adjustment of the load circuit are given in Annex E.

8.3.3.5.4 Vacant

8.3.3.5.5 Test procedure for making and breaking capacities

The number of operations, the "on" and "off" times and the ambient conditions shall be stated in the relevant product standard.

8.3.3.5.6 Behaviour of the equipment during and after making and breaking capacity tests

The criteria for acceptance during and after the tests shall be stated in the relevant product standard.

8.3.3.6 Operational performance capability

Tests shall be made to verify compliance with the requirements of 7.2.4.2. The test circuit shall be in accordance with 8.3.3.5.2 and 8.3.3.5.3.

Detailed test conditions shall be stated in the relevant product standard.

8.3.3.7 Durability

Durability tests are intended to verify the number of operating cycles that an equipment is likely to be capable of performing without repair or replacement of parts.

The durability tests form the basis of a statistical life estimate, where the manufactured quantities permit this.

8.3.3.7.1 Mechanical durability

During the test, there shall be no voltage or current in the main circuit. The equipment may be lubricated before the test, if lubrication is prescribed in normal service.

The control circuit shall be supplied at its rated voltage and, where applicable, at its rated frequency.

Pneumatic and electro-pneumatic equipment shall be supplied with compressed air at the rated pressure.

Manually operated equipment shall be operated as in normal service.

The number of operating cycles shall be not less than that prescribed in the relevant product standard.

For equipment fitted with opening relays or releases, the total number of opening operations to be performed by such relays or releases shall be stated in the relevant product standard.

Evaluation of test results shall be defined in the relevant product standard.

8.3.3.7.2 Electrical durability

The test conditions are those of 8.3.3.7.1 except that the main circuit is energized according to the requirements of the relevant product standard.

Evaluation of test results shall be defined in the relevant product standard.

^{A2} 8.3.3.8 Pole impedance

The pole impedance shall be determined during the test and with the conditions given in 8.3.3.3.4. The test in an enclosure is not deemed necessary even if the switching device can be used in an individual enclosure.

The voltage drop U_d shall be measured between the line and load terminals (terminals included) of the switching device using the same measuring points as for the temperature rise. The measurement shall be performed after a time sufficient for the temperature-rise to reach a steady-state value.

The impedance per pole is defined as follows:

$$Z = U_d / I_{th} [\Omega]$$

The declared value (see 5.1 modified by this Amendment 2), in the case of multiple identical poles, shall be the average value obtained from the tests.

Care should be taken that voltage drop measurement does not significantly affect the temperature rise nor affect significantly the impedance.

NOTE The method is the same irrespective of the number of poles of the switching device. ^{A2}

8.3.4 Performance under short-circuit conditions

This subclause specifies the test conditions for verification of the ratings and limiting values of 7.2.5. Additional requirements regarding test procedure, operating and test sequences, condition of equipment after the tests and tests of co-ordination of the equipment with short-circuit protective devices (SCPD) are given in the relevant product standard.

8.3.4.1 General conditions for short-circuit tests

8.3.4.1.1 General requirements

The general requirements of 8.3.2.1 apply. The control mechanism shall be operated under the conditions specified in the relevant product standard. If the mechanism is electrically or pneumatically controlled, it shall be supplied at the minimum voltage or the minimum pressure as specified in the relevant product standard. It shall be verified that the equipment operates correctly on no-load when it is operated under the above conditions.

Additional test conditions may be specified in the relevant product standard.

8.3.4.1.2 Test circuit

- a) Figures 9, 10, 11 and 12 give the diagrams of the circuits to be used for the tests concerning
- single-pole equipment on single-phase a.c. or d.c. (Figure 9);
 - two-pole equipment on single-phase a.c. or d.c. (Figure 10);
 - three-pole equipment on three-phase a.c. (Figure 11);
 - four-pole equipment on three-phase four-wire a.c. (Figure 12).

A detailed diagram of the circuit used shall be given in the test report.

NOTE For combinations with SCPDs, the relevant product standard should specify the relative arrangement between the SCPD and the equipment under test.

- b) The supply S feeds a circuit including resistors R_1 , reactors X and the equipment D under test.

In all cases the supply shall have sufficient power to permit the verification of the characteristics given by the manufacturer.

The resistance and reactance of the test circuit shall be adjustable to satisfy the specified test conditions. The reactors X shall be air-cored. They shall be connected in series with the resistors R_1 , and their value shall be obtained by series coupling of individual reactors; parallel connecting of reactors is permitted when these reactors have practically the same time-constant.

Since the transient recovery voltage characteristics of test circuits including large air-cored reactors are not representative of usual service conditions, the air-cored reactor in each phase shall be shunted by a resistor taking approximately 0,6 % of the current through the reactor, unless otherwise agreed between manufacturer and user.

- A1** c) In each test circuit (Figures 9, 10, 11 and 12), the resistors and reactors are inserted between the supply source S and the equipment D under test. The positions of the closing device A and the current sensing devices (I_1 , I_2 , I_3) may be different. The closing device A may be located on low voltage side or alternatively on the primary side. In the latter case the testing station has to demonstrate that the voltage wave is not distorted by the residual flux of the short-circuit transformer. The connections of the equipment under test to the test circuit shall be stated in the relevant product standard. **A1**

When tests are made with current less than the rated value, the additional impedances required should be inserted on the load side of the equipment between it and the short circuit; they may, however, be inserted on the line side, in which case this shall be stated in the test report.

This need not apply to short-time withstand current tests (see 8.3.4.3).

Unless a special agreement has been drawn up between manufacturer and user and details noted in the test report, the diagram of the test circuit shall be in accordance with the figures.

There shall be one and only one point of the test circuit which is earthed; this may be the short-circuit link of the test circuit or the neutral point of the supply or any other convenient point, but the method of earthing shall be stated in the test report.

- d) All parts of the equipment normally earthed in service, including the enclosure or the screens, shall be insulated from earth and connected to a point as indicated in Figures 9, 10, 11 or 12.

This connection shall comprise a fusible element F consisting of a copper wire 0,8 mm in diameter and at least 50 mm long, or of an equivalent fusible element for the detection of the fault current.

The prospective fault current in the fusible element circuit shall be $1\,500\text{ A} \pm 10\%$, except as stated in notes 2 and 3. If necessary, a resistor limiting the current to that value shall be used.

NOTE 1 A copper wire of 0,8 mm in diameter will melt at 1 500 A in approximately half a cycle at a frequency between 45 Hz and 67 Hz (or 0,01 s for d.c.).

NOTE 2 In the case of a supply having an artificial neutral, a lower prospective fault current may be accepted, subject to the manufacturer's agreement, with a smaller diameter wire according to the following table.

Diameter of copper wire mm	Prospective fault current in the fusible element circuit A
0,1	50
0,2	150
0,3	300
0,4	500
0,5	800
0,8	1 500

NOTE 3 For the value of the resistance of the fusible element see 8.3.2.1.

8.3.4.1.3 Power-factor of the test circuit

For a.c., the power-factor of each phase of the test circuit should be determined according to an established method which shall be stated in the test report.

Two examples are given in Annex F.

The power-factor of a polyphase circuit is considered as the mean value of the power-factors of each phase.

The power-factor shall be in accordance with Table 16.

The difference between the mean value and the maximum and minimum values of the power-factors in the different phases shall remain within $\pm 0,05$.

8.3.4.1.4 Time-constant of the test circuit

For d.c., the time-constant of the test circuit may be determined according to the method given in Annex F, Clause F.2.

The time-constant shall be in accordance with Table 16.

8.3.4.1.5 Calibration of the test circuit

The calibration of the test circuit is carried out by placing temporary connections B of negligible impedance as close as reasonably possible to the terminals provided for connecting the equipment under test.

For a.c., resistors R_1 and reactors X are adjusted so as to obtain, at the applied voltage, a current equal to the rated short-circuit breaking capacity as well as the power-factor specified in 8.3.4.1.3.

In order to determine the short-circuit making capacity of the device under test from the calibration oscillogram, it is necessary to calibrate the circuit so as to ensure that the prospective making current is achieved in one of the phases.

NOTE The applied voltage is the open-circuit voltage necessary to produce the specified power-frequency recovery voltage (but see also NOTE 1 of 8.3.2.2.3).

For d.c., resistors R_1 and reactors X are adjusted so as to obtain, at the test voltage, a current the maximum value of which is equal to the rated short-circuit breaking capacity as well as the time-constant specified in 8.3.4.1.4.

The test circuit is energized simultaneously in all poles and the current curve is recorded for a duration of at least 0,1 s.

For d.c. switching devices parting their contacts before the peak value of the calibration curve is reached, it is sufficient to make a calibration record with additional pure resistance in the circuit to demonstrate that the rate of rise of the current expressed in amperes/second is the same as for the test current and the time-constant specified (see Figure 15). This additional resistance shall be such that the peak value of the calibration current curve is at least equal to the peak value of the breaking current. This resistance shall be removed for the actual test (see 8.3.4.1.8, item b)).

8.3.4.1.6 Test procedure

After calibration of the test circuit in accordance with 8.3.4.1.5, the temporary connections are replaced by the equipment under test, and its connecting cables, if any.

Tests for the performance under short-circuit conditions shall be made according to the requirements of the relevant product standard.

8.3.4.1.7 Behaviour of the equipment during short-circuit making and breaking tests

There shall be neither arcing nor flashover between poles, or between poles and frame, and no melting of the fusible element F in the leakage detection circuit (see 8.3.4.1.2).

Additional requirements may be stated in the relevant product standard.

8.3.4.1.8 Interpretation of records

a) Determination of the applied voltage and power-frequency recovery voltage

The applied voltage and the power-frequency recovery voltage are determined from the record corresponding to the break test made with the apparatus under test, and evaluated as indicated in Figure 13 for a.c. and in Figure 14 for d.c.

The voltage on the supply side shall be measured during the first complete cycle after arc extinction in all poles and after high-frequency phenomena have subsided (see Figure 13).

If additional information is required regarding, for example, the voltage across individual poles, arcing time, arcing energy, switching overvoltage, etc., this may be obtained by means of additional sensing devices across each pole, in which case the resistance of each of these measuring circuits shall be not less than 100 ohms per volts of the r.m.s. value of voltage across individual poles; this value shall be stated in the test report.

b) Determination of the prospective breaking current

This determination is made by comparing the current curves, recorded during the calibration of the circuit, with those recorded during the break test of the equipment (see Figure 13).

For a.c., the a.c. component of the prospective breaking current is taken as being equal to the r.m.s. value of the a.c. component of the calibration current at the instant which corresponds to the separation of the arcing contacts (value corresponding to $A_2/2\sqrt{2}$ of Figure 13, item a)). The prospective breaking current shall be the average of the prospective currents in all phases with the tolerance according to Table 8; the prospective current in each phase shall be within $\pm 10\%$ of the rated value.

NOTE With the agreement of the manufacturer, the current in each phase may be within $\pm 10\%$ of the average value.

For d.c., the value of the prospective breaking current is taken as being equal to the maximum value A_2 as determined from the calibration curve for equipment breaking before the current has reached its maximum value, and to the value A for equipment breaking after the current has passed its maximum value (see Figure 14, items a) and b)).

For d.c. equipment tested according to the requirements of 8.3.4.1.5, when the calibration of the test circuit has been made at a current I_1 lower than the rated breaking capacity, the test is considered void if the actual breaking current I_2 is higher than I_1 , and it shall be carried out again after a calibration at a current I_3 of a higher value than I_2 (see Figure 15).

The prospective breaking current $A_2 = U/R$ shall be determined by calculating the resistance R of the test circuit from the resistors R_1 of the corresponding calibration circuits. The time-constant of the test circuit is given by

$$T = \frac{A_2}{di / dt}$$

The tolerances shall be in accordance with Table 8.

c) Determination of the prospective peak making current

The prospective peak making current is determined from the calibration record and its value shall be taken as being that corresponding to A_1 of Figure 13, item a) for a.c. and to A_2 of Figure 14 for d.c. In the case of a three-phase test it shall be taken as the highest of the three A_1 values obtained from the record.

NOTE For tests on single-pole equipment, the prospective peak making current determined from the calibration record may differ from the value of the actual making current corresponding to the test, depending on the instant of making.

8.3.4.1.9 Condition of the equipment after the tests

After the tests, the equipment shall comply with the requirements of the relevant product standard.

8.3.4.2 Short-circuit making and breaking capacities

The test procedure for verification of the rated short-circuit making and breaking capacities of the equipment shall be given in the relevant product standard.

8.3.4.3 Verification of the ability to carry the rated short-time withstand current

The test shall be made with the equipment in the closed position, at a prospective current equal to the rated short-time withstand current and the corresponding operational voltage under the general conditions of 8.3.4.1.

In the case of the testing station having difficulty in making this test at the operational voltage, it may be made at any convenient lower voltage, the actual test current being, in this case, equal to the rated short-time withstand current I_{cw} . This shall be stated in the test report. If, however, momentary contact separation occurs during the test, the test shall be repeated at the rated operational voltage.

For this test, over-current releases, if any, likely to operate during the test, shall be rendered inoperative.

a) For a.c.

The tests shall be made at the rated frequency of the equipment with a tolerance of $\pm 25\%$, and at the power-factor appropriate to the rated short-time withstand current in accordance with Table 16.

The value of the current during the calibration is the average of the r.m.s. values of the a.c. components in all phases (see 4.3.6.1). The average value shall be equal to the rated value within the tolerances specified in Table 8.

In each phase the current shall be within $\pm 5\%$ of the rated value.

When making the test at the rated operational voltage, the calibration current is the prospective current.

When making the test at any lower voltage, the calibration current is the actual test current.

The current shall be applied for the specified time during which the r.m.s. value of its a.c. component shall remain constant.

NOTE With the agreement of the manufacturer, the current in each phase may be within $\pm 10\%$ of the average value in case of testing station difficulties.

The highest peak value of the current during its first cycle shall be not less than n times the rated short-time withstand current, the value of n being that corresponding to this value of current according to Table 16.

When, however, the characteristics of the testing station are such that the above requirements cannot be obtained, the following alternatives are permitted provided that

$$\int_0^{t_{\text{test}}} i_{\text{test}}^2 dt \geq I^2 \cdot t_{\text{st}}$$

where

t_{test} is the duration of the test;

t_{st} is the short time;

i_{test} is the calibration current if the a.c. component is not constant or $\geq I_{\text{cw}}$;

I is the actual calibration current assumed to have a constant a.c. component.

If the decrement of the short-circuit current of the testing station is such that the rated short-time withstand current cannot be obtained for the rated time without applying initially an excessively high current, the r.m.s. value of the current may be permitted to fall during the test below the specified value, the duration being increased appropriately, provided that the value of the highest peak current is not less than that specified.

If, in order to obtain the required peak value, the r.m.s. value of the current has to be increased above the specified current, the duration of the test shall be reduced accordingly.

b) For d.c.

The current shall be applied for the specified time and its mean value determined from the record shall be at least equal to the specified value.

When the characteristics of the testing station are such that the above requirements cannot be obtained for the rated time without applying initially an excessively high current, the value of the current may be permitted to fall during the test below the specified value, the duration being increased appropriately, provided that the maximum value of the current is not less than that specified.

If the testing station is unable to make these tests on d.c., they may, if agreed between manufacturer and user, be made on a.c., provided suitable precautions are taken: for instance, the peak value of current shall not exceed the permissible current.

c) Behaviour of the equipment during and after the test

Behaviour of the equipment during the test shall be defined in the relevant product standard.

After the test, it shall be possible to operate the equipment by its normal operating means.

8.3.4.4 Co-ordination with short-circuit protective devices and rated conditional short-circuit current

Test conditions and procedures, where applicable, shall be stated in the relevant product standard.

8.4 Tests for EMC

- A2** Emission and immunity tests are type tests and shall be carried out using the manufacturer's instructions for installation in accordance with the reference EMC standards. The product standard shall specify any particular test condition (e.g. use of an enclosure) and additional measures necessary to verify the performance criteria of the product (e.g. application of dwell times). **A2**

8.4.1 Immunity

8.4.1.1 Equipment not incorporating electronic circuits

No tests are necessary. See 7.3.2.1.

8.4.1.2 Equipment incorporating electronic circuits

8.4.1.2.1 General

Equipment utilizing circuits in which all components are passive (see 7.3.2.2) are not required to be tested.

Performance criteria shall be given in the product standard based on the acceptance criteria given in Table 24.

8.4.1.2.2 Electrostatic discharges

The test shall be performed according to IEC 61000-4-2 with the values given in Table 23 except where a different test level is given and justified in the product standard and shall be repeated 10 times at each measuring point, with a minimum time interval of 1 s between pulses.

The test set-up shall be in accordance with Figure 18.

8.4.1.2.3 Radiated radio-frequency electromagnetic fields

The test shall be performed according to IEC 61000-4-3 with the values given in Table 23 except where a different test level is given and justified in the product standard.

The test set-up shall be in accordance with Figure 19.

The test is performed in two steps: a first step (step 1) where the EUT is tested for resistance to unwanted operation on the whole range of frequencies, and a second step (step 2) where the EUT is tested for correct operation at discrete frequencies.

For step 1, the frequency shall be swept over the ranges of 80 MHz to 1 000 MHz and 1 400 MHz to 2 000 MHz in accordance with Clause 8 of IEC 61000-4-3. The dwell time of the amplitude modulated carrier for each frequency shall be between 500 ms and 1 000 ms unless otherwise stated in the product standard, and the step size shall be 1 % of the previous frequency. The actual dwell time shall be stated in the test report.

For step 2, to verify the functional characteristics at discrete frequencies, the test shall be performed in accordance with the relevant product standard.

8.4.1.2.4 Electrical fast transients/bursts (EFT/B)

The test shall be performed according to IEC 61000-4-4 with the values given in Table 23 with a repetition rate of 5 kHz, except where a different test level and/or repetition rate is given and justified in the product standard.

The test set-up shall be in accordance with Figure 20 for all ports except signal ports.

For the tests on signal ports, the connecting leads shall be placed in a capacitive coupling clamp, with a total cable length between the EFT generator and the capacitive coupling clamp of maximum 1 m.

8.4.1.2.5 Surges

The test shall be performed according to IEC 61000-4-5 with the values given in Table 23, taking into account the footnote d of Tables 2 and 3 of IEC 61000-6-2.

Pulses with both positive and negative polarity shall be applied, the preferred phase angles being 0°, 90° and 270°.

A series of five pulses is applied for each polarity and each phase angle, the interval between two pulses being approximately 1 min.

Where three-phase equipment employs an identical circuit configuration for each phase then tests are required on only one phase.

8.4.1.2.6 Conducted disturbances induced by radio-frequency fields

The test shall be performed according to IEC 61000-4-6 with the values given in Table 23. The tests shall be carried out with the EUT in free air.

The disturbances shall be injected, on power lines, by means of a coupling-decoupling network M1, M2 or M3 as applicable.

On signal lines, disturbances shall be injected by means of coupling-decoupling network. If not feasible, an E.M. clamp may be used.

The particular test set-up shall be in accordance with Figure 21 or Figure 22 and detailed in the test report.

The test is performed in two steps: a first step (step 1) where the EUT is tested for resistance to unwanted operation on the whole range of frequencies, and a second step (step 2) where the EUT is tested for correct operation at discrete frequencies.

For step 1, the frequency shall be swept over the range of 150 kHz to 80 MHz in accordance with Clause 8 of IEC 61000-4-6. The dwell time of the amplitude modulated carrier for each frequency shall be between 500 ms and 1 000 ms unless otherwise stated in the product standard and the step size shall be 1 % of the previous frequency. The actual dwell time shall be stated in the test report.

For step 2, to verify the functional characteristics at discrete frequencies, the test shall be performed in accordance with the relevant product standard.

8.4.1.2.7 Power frequency magnetic fields

This test is applicable only to equipment containing devices susceptible to power frequency magnetic fields as defined by the relevant product standard.

The test method shall be in accordance with IEC 61000-4-8 and the test shall be performed with the EUT in free air unless it is only used in a dedicated enclosure. The test levels are given in Table 23. The field shall be applied to the EUT in the three perpendicular axes (see Figure 23).

8.4.1.2.8 Voltage dips and interruptions

This test is applicable only to equipment susceptible to unwanted operation in case of voltage dips and interruptions as defined by the relevant product standard.

The test shall be performed in accordance with IEC 61000-4-11. The EUT shall be connected to the test generator with the shortest power supply cable as specified by the EUT manufacturer. If no cable length is specified, it shall be the shortest possible length suitable to the application of the EUT. The test levels are given in Table 23, the given percentage means percentage of the rated operational voltage.

A₂ 8.4.1.2.9 Harmonics in the supply

Under consideration. **A₂**

8.4.2 Emission

8.4.2.1 Equipment not incorporating electronic circuits

No tests are necessary. See 7.3.3.1.

8.4.2.2 Equipment incorporating electronic circuits

The product standard shall specify the details of the test methods. See 7.3.3.2.

Table 1 – A_2 Nominal A_2 cross-sections of round copper conductors and approximate relationship between mm² and AWG/kcmil sizes
(see 7.1.8.2)

A_2 Nominal A_2 cross-section mm ²	AWG/kcmil size	Equivalent metric area mm ²
0,2	24	0,205
0,34	22	0,324
0,5	20	0,519
0,75	18	0,82
1	–	–
1,5	16	1,3
2,5	14	2,1
4	12	3,3
6	10	5,3
10	8	8,4
16	6	13,3
25	4	21,2
35	2	33,6
–	1	42,4
50	0	53,5
70	00	67,4
95	000	85,0
–	0000	107,2
120	250 kcmil	127
150	300 kcmil	152
185	350 kcmil	177
–	400 kcmil	203
240	500 kcmil	253
300	600 kcmil	304

NOTE The dash, when it appears, counts as a size when considering connecting capacity (see 7.1.8.2).

Table 2 – Temperature-rise limits of terminals
(see 7.2.2.1 and 8.3.3.3.4)

Terminal material	Temperature-rise limits ^{a, c}
	K
Bare copper	60
Bare brass	65
Tin plated copper or brass	65
Silver plated or nickel plated copper or brass	70
Other metals	b

^a The use in service of connected conductors significantly smaller than those listed in Tables 9 and 10 could result in higher terminals and internal part temperatures and such conductors should not be used without the manufacturer's consent since higher temperatures could lead to equipment failure.

^b Temperature-rise limits to be based on service experience or life tests but not to exceed 65 K.

^c Different values may be prescribed by product standards for different test conditions and for devices of small dimensions, but not exceeding by more than 10 K the values of this table.

Table 3 – Temperature-rise limits of accessible parts
(see 7.2.2.2 and 8.3.3.3.4)

Accessible parts	Temperature-rise limits ^a K
Manual operating means:	
Metallic	15
Non-metallic	25
Parts intended to be touched but not hand-held:	
Metallic	30
Non-metallic	40
Parts which need not be touched during normal operation: ^{A2} Text deleted ^{A2}	
Exteriors of enclosures adjacent to cable entries:	
Metallic	40
Non-metallic	50
Exterior of enclosures for resistors	200 ^b
Air issuing from ventilation openings of enclosures for resistors	200 ^b
^a Different values may be prescribed by product standards for different test conditions and for devices of small dimensions but not exceeding by more than 10 K the values of this table. ^{A2} Text deleted ^{A2}	

Table 4 – Tightening torques for the verification of the mechanical strength of screw-type terminals
 A_2 (see 8.2.4.2 and 8.3.2.1) A_2

Diameter of thread mm				Tightening torque N·m		
Metric standard values	Range of diameter			I	II	III
1,6	≤1,6			0,05	0,1	0,1
2,0	>1,6	up to and including	2,0	0,1	0,2	0,2
2,5	>2,0	up to and including	2,8	0,2	0,4	0,4
3,0	>2,8	up to and including	3,0	0,25	0,5	0,5
–	>3,0	up to and including	3,2	0,3	0,6	0,6
3,5	>3,2	up to and including	3,6	0,4	0,8	0,8
4,0	>3,6	up to and including	4,1	0,7	1,2	1,2
4,5	>4,1	up to and including	4,7	0,8	1,8	1,8
5	>4,7	up to and including	5,3	0,8	2,0	2,0
6	>5,3	up to and including	6,0	1,2	2,5	3,0
8	>6,0	up to and including	8,0	2,5	3,5	6,0
10	>8,0	up to and including	10,0	–	4,0	10,0
12	>10	up to and including	12	–	–	14,0
14	>12	up to and including	15	–	–	19,0
16	>15	up to and including	20	–	–	25,0
20	>20	up to and including	24	–	–	36,0
24	>24			–	–	50,0

Column I Applies to screws without heads which, when tightened, do not protrude from the hole, and to other screws which cannot be tightened by means of a screwdriver with a blade wider than the root diameter of the screw.

Column II Applies to nuts and screws which are tightened by means of a screwdriver.

Column III Applies to nuts and screws which can be tightened by means other than a screwdriver.

Table 5 – Test values for flexion and pull-out tests for round copper conductors
(see 8.2.4.4.1)

Conductor cross-section		Diameter of bushing hole ^{a, b} mm	Height H^a mm	Mass kg	Pulling force N
mm ²	AWG/kcmil				
0,2	24	6,5	260	0,2	10
0,34	22	6,5	260	0,2	15
0,5	20	6,5	260	0,3	20
0,75	18	6,5	260	0,4	30
1,0	–	6,5	260	0,4	35
1,5	16	6,5	260	0,4	40
2,5	14	9,5	280	0,7	50
4,0	12	9,5	280	0,9	60
6,0	10	9,5	280	1,4	80
10	8	9,5	280	2,0	90
16	6	13,0	300	2,9	100
25	4	13,0	300	4,5	135
–	3	14,5	320	5,9	156
35	2	14,5	320	6,8	190
–	1	15,9	343	8,6	236
50	0	15,9	343	9,5	236
70	00	19,1	368	10,4	285
95	000	19,1	368	14	351
–	0000	19,1	368	14	427
120	250 kcmil	22,2	406	14	427
150	300 kcmil	22,2	406	15	427
185	350 kcmil	25,4	432	16,8	503
–	400 kcmil	25,4	432	16,8	503
240	500 kcmil	28,6	464	20	578
300	600 kcmil	28,6	464	22,7	578

^a Tolerances: for height $H \pm 15$ mm, for diameter of the bushing hole ± 2 mm.

^b If the bushing hole diameter is not large enough to accommodate the conductor without binding, a bushing having the next larger hole size may be used.

Table 6 – Test values for pull-out test for flat copper conductors
(see 8.2.4.4.2)

Maximum width of flat conductors mm	Pulling force N
12	100
14	120
16	160
20	180
25	220
30	280

Table 7 – Maximum conductor cross-sections and corresponding gauges
(see 8.2.4.5.1)

Conductor cross-section		Gauge (see Figure 2)					
Flexible conductors	Rigid conductors (solid or stranded)	Form A			Form B		Permissible deviation for a and b
		Marking	Diameter a mm	Width b mm	Marking	Diameter a mm	
mm ²	mm ²						mm
1,5	1,5	A1	2,4	1,5	B1	1,9	0 -0,05
2,5	2,5	A2	2,8	2,0	B2	2,4	
2,5	4	A3	2,8	2,4	B3	2,7	
4	6	A4	3,6	3,1	B4	3,5	0 -0,06
6	10	A5	4,3	4,0	B5	4,4	
10	16	A6	5,4	5,1	B6	5,3	
16	25	A7	7,1	6,3	B7	6,9	0 -0,07
25	35	A8	8,3	7,8	B8	8,2	
35	50	A9	10,2	9,2	B9	10,0	
50	70	A10	12,3	11,0	B10	12,0	0 -0,08
70	95	A11	14,2	13,1	B11	14,0	
95	120	A12	16,2	15,1	B12	16,0	
120	150	A13	18,2	17,0	B13	18,0	
150	185	A14	20,2	19,0	B14	20,0	
185	240	A15	22,2	21,0	B15	22,0	0 -0,09
240	300	A16	26,5	24,0	B16	26,0	

NOTE For conductor cross-sections of differently shaped solid or stranded standard conductors other than those given in this table, an unprepared conductor of appropriate cross-section may be used as the gauge, the force of insertion being not greater than 5 N.

Table 7a – Relationship between conductor cross-section and diameter

Conductor cross-section	Theoretical diameter of the largest conductor						
	Metric			AWG/kcmil			
	Rigid		Flexible	Gauge	Rigid		Flexible Classes I.K.M.
Solid mm	Stranded mm	b mm			b Class B mm		
0,2	0,51	0,53	0,61	24	0,54	0,61	0,64
0,34	0,63	0,66	0,8	22	0,68	0,71	0,80
0,5	0,9	1,1	1,1	20	0,85	0,97	1,02
0,75	1,0	1,2	1,3	18	1,07	1,23	1,28
1,0	1,2	1,4	1,5	–	–	–	–
1,5	1,5	1,7	1,8	16	1,35	1,55	1,60
2,5	1,9	2,2	2,3 ^a	14	1,71	1,95	2,08
4,0	2,4	2,7	2,9 ^a	12	2,15	2,45	2,70
6,0	2,9	3,3	3,9 ^a	10	2,72	3,09	3,36
10,0	3,7	4,2	5,1	8	3,43	3,89	4,32
16,0	4,6	5,3	6,3	6	4,32	4,91	5,73
25,0	–	6,6	7,8	4	5,45	6,18	7,26
35,0	–	7,9	9,2	2	6,87	7,78	9,02
50		9,1	11,0 ^a	0		9,64	12,08
70		11,0	13,1 ^a	00		11,17	13,54
95		12,9	15,1 ^a	000		12,54	15,33
–		–	–	0000		14,08	17,22
120		14,5	17,0 ^a	250		15,34	19,01
150		16,2	19,0 ^a	300		16,80	20,48
185		18,0	21,0 ^a	350		18,16	22,05
–		–	–	400		19,42	24,05
240		20,6	24,0 ^a	500		21,68	26,57
300		23,1	27,0 ^a	600		23,82	30,03

NOTE Diameters of the largest rigid and flexible conductors are based on Table 1 and Table 3 of IEC 60228A and on IEC 60344 and, for AWG conductors, on ASTM B172-71 [1], ICEA Publication S-19-81 [2], ICEA Publication S-66-524 [3] and ICEA Publication S-66-516 [4].

Figures in square brackets refer to the bibliography.

^a Dimensions for class 5 flexible conductors only, according to IEC 60228A.
^b Nominal diameter +5 %.
^c Largest diameter for any of the three classes I, K, M +5 %.

Table 8 – Tolerances on test quantities
(see 8.3.4.3, item a))

All tests	Tests under no-load, normal load and overload conditions	Tests under short-circuit conditions
– Current $+5_0$ %	– Power factor $\pm 0,05$	– Power factor $0_{-0,05}$
– Voltage $+5_0$ % (including power frequency recovery voltage)	– Time-constant $+15_0$ %	– Time-constant $+25_0$ %
	– Frequency ± 5 %	– Frequency ± 5 %

NOTE 1 Where maximum and/or minimum operating limits are stated in the product standard, the above tolerances do not apply.

NOTE 2 By agreement between manufacturer and user, tests made at 50 Hz may be accepted for operation at 60 Hz and vice versa.

Table 9 – Test copper conductors for test currents up to 400 A inclusive
(see 8.3.3.3.4)

Range of test current ^a		Conductor size ^{b, c, d}	
A		mm ²	AWG/kcmil
0	8	1,0	18
8	12	1,5	16
12	15	2,5	14
15	20	2,5	12
20	25	4,0	10
25	32	6,0	10
32	50	10	8
50	65	16	6
65	85	25	4
85	100	35	3
100	115	35	2
115	130	50	1
130	150	50	0
150	175	70	00
175	200	95	000
200	225	95	0000
225	250	120	250 kcmil
250	275	150	300 kcmil
275	300	185	350 kcmil
300	350	185	400 kcmil
350	400	240	500 kcmil

^a The value of test current shall be greater than the first value in the first column and less than or equal to the second value in that column.

^b For convenience of testing and with the manufacturer's consent, smaller conductors than those given for a stated test current may be used.

^c The tables give alternative sizes for conductors in the metric and AWG/kcmil system and for bars in millimetres and inches. Comparison between AWG/ kcmil and metric sizes is given in Table 1.

^d Either of the two conductors specified for a given test current range may be used.

**Table 10 – Test copper conductors for test currents above 400 A
and up to 800 A inclusive
(see 8.3.3.3.4)**

Range of test current ^a A		Conductors ^{b, c, d}			
		Metric		kcmil	
		Number	Size mm ²	Number	Size kcmil
400	500	2	150	2	250
500	630	2	185	2	350
630	800	2	240	3	300

^a The value of test current shall be greater than the first value in the first column and less than or equal to the second value in that column.

^b For convenience of testing and with the manufacturer's consent, smaller conductors than those given for a stated test current may be used.

^c The tables give alternative sizes for conductors in the metric and AWG/kcmil system and for bars in millimetres and inches. Comparison between AWG/ kcmil and metric sizes is given in Table 1.

^d Either of the two conductors specified for a given test current range may be used.

**Table 11 – Test copper bars for test currents above 400 A
and up to 3 150 A inclusive
(see 8.3.3.3.4)**

Range of test current ^a A		Copper bars ^{b, c, d, e, f}		
		Number	Dimensions mm	Dimensions Inches
400	500	2	30 × 5	1 × 0,250
500	630	2	40 × 5	1,25 × 0,250
630	800	2	50 × 5	1,5 × 0,250
800	1 000	2	60 × 5	2 × 0,250
1 000	1 250	2	80 × 5	2,5 × 0,250
1 250	1 600	2	100 × 5	3 × 0,250
1 600	2 000	3	100 × 5	3 × 0,250
2 000	2 500	4	100 × 5	3 × 0,250
2 500	3 150	3	100 × 10	6 × 0,250

^a The value of test current shall be greater than the first value in the first column and less than or equal to the second value in that column.

^b For convenience of testing and with the manufacturer's consent, smaller conductors than those given for a stated test current may be used.

^c The tables give alternative sizes for conductors in the metric and AWG/kcmil system and for bars in millimetres and inches. Comparison between AWG/kcmil and metric sizes is given in Table 1.

^d Either of the two conductors specified for a given test current range may be used.

^e Bars are assumed to be arranged with their long faces vertical. Arrangements with long faces horizontal may be used if specified by the manufacturer.

^f Where four bars are used they shall be in two sets of two bars with not more than 100 mm between pair centres.

Table 12 – Impulse withstand test voltages

Rated impulse withstand voltage U_{imp} kV	Test voltages and corresponding altitudes				
	$U_{1,2/50}$ kV				
	Sea level	200 m	500 m	1 000 m	2 000 m
0,33	0,35	0,35	0,35	0,34	0,33
0,5	0,55	0,54	0,53	0,52	0,5
0,8	0,91	0,9	0,9	0,85	0,8
1,5	1,75	1,7	1,7	1,6	1,5
2,5	2,95	2,8	2,8	2,7	2,5
4,0	4,8	4,8	4,7	4,4	4,0
6,0	7,3	7,2	7,0	6,7	6,0
8,0	9,8	9,6	9,3	9,0	8,0
12	14,8	14,5	14	13,3	12

NOTE Table 12 uses the characteristics of a homogeneous field, case B (see 2.5.62).

Table 12A – Dielectric test voltage corresponding to the rated insulation voltage

Rated insulation voltage U_i V	AC test voltage (r.m.s.) V	DC test voltage ^{b, c} V
$U_i \leq 60$	1 000	1 415
$60 < U_i \leq 300$	1 500	2 120
$300 < U_i \leq 690$	1 890	2 670
$690 < U_i \leq 800$	2 000	2 830
$800 < U_i \leq 1 000$	2 200	3 110
$1 000 < U_i \leq 1 500^a$	–	3 820

^a For d.c. only.

^b Test voltages based on 6.1.3.4.1, fifth paragraph, of IEC 60664-1:2007. A_2

^c A direct current test voltage may be used only if an alternating test voltage cannot be applied. See also 3) b) ii) of 8.3.3.4.1.

Table 13 – Minimum clearances in air

Rated impulse withstand voltage U_{imp} kV	Minimum clearances mm							
	Case A Inhomogeneous field conditions (see 2.5.63)				Case B Homogeneous field ideal conditions (see 2.5.62)			
	Pollution degree				Pollution degree			
	1	2	3	4	1	2	3	4
0,33	0,01				0,01			
0,5	0,04	0,2			0,04	0,2		
0,8	0,1		0,8		0,1		0,8	1,6
1,5	0,5	0,5		1,6	0,3	0,3		
2,5	1,5	1,5	1,5		0,6	0,6		
4,0	3	3	3	3	1,2	1,2	1,2	
6,0	5,5	5,5	5,5	5,5	2	2	2	2
8,0	8	8	8	8	3	3	3	3
12	14	14	14	14	4,5	4,5	4,5	4,5

NOTE The values of minimum clearances in air are based on 1,2/50 μ s impulse voltage, for barometric pressure of 80 kPa, equivalent to normal atmospheric pressure at 2 000 m above sea level.

Table 14 – Test voltages across the open contacts of
equipment suitable for isolation

Rated impulse withstand voltage U_{imp} kV	Test voltages and corresponding altitudes				
	$U_{1,2/50}$ kV				
	Sea level	200 m	500 m	1 000 m	2 000 m
0,33	1,8	1,7	1,7	1,6	1,5
0,5	1,8	1,7	1,7	1,6	1,5
0,8	1,8	1,7	1,7	1,6	1,5
1,5	2,3	2,3	2,2	2,2	2
2,5	3,5	3,5	3,4	3,2	3
4,0	6,2	6,0	5,8	5,6	5
6,0	9,8	9,6	9,3	9,0	8
8,0	12,3	12,1	11,7	11,1	10
12	18,5	18,1	17,5	16,7	15

Table 15 – Minimum creepage distances

Rated insulation voltage of equipment or working voltage a.c. r.m.s. or d.c. ^{b, c}	Minimum creepage distances for equipment subject to long term stress													
	Printed wiring material		Pollution degree											
	1	2	1		2		3			4				
	Material groups													
	All	All except IIIb	All	I	II	III	I	II	IIIa	IIIb	I	II	IIIa	IIIb
V	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm
10	0,025	0,04	0,08	0,4	0,4	0,4	1	1	1	1,6	1,6	1,6		
12,5	0,025	0,04	0,09	0,42	0,42	0,42	1,05	1,05	1,05	1,6	1,6	1,6		
16	0,025	0,04	0,1	0,45	0,45	0,45	1,1	1,1	1,1	1,6	1,6	1,6		
20	0,025	0,04	0,11	0,48	0,48	0,48	1,2	1,2	1,2	1,6	1,6	1,6		
25	0,025	0,04	0,125	0,5	0,5	0,5	1,25	1,25	1,25	1,7	1,7	1,7		
32	0,025	0,04	0,14	0,53	0,53	0,53	1,3	1,3	1,3	1,8	1,8	1,8		
40	0,025	0,04	0,16	0,56	0,8	1,1	1,4	1,6	1,8	1,9	2,4	3		
50	0,025	0,04	0,18	0,6	0,85	1,2	1,5	1,7	1,9	2	2,5	3,2		
63	0,04	0,063	0,2	0,63	0,9	1,25	1,6	1,8	2	2,1	2,6	3,4		
80	0,063	0,1	0,22	0,67	0,95	1,3	1,7	1,9	2,1	2,2	2,8	3,6		
100	0,1	0,16	0,25	0,71	1	1,4	1,8	2	2,2	2,4	3	3,8		
125	0,16	0,25	0,28	0,75	1,05	1,5	1,9	2,1	2,4	2,5	3,2	4		
160	0,25	0,4	0,32	0,8	1,1	1,6	2	2,2	2,5	3,2	4	5		
200	0,4	0,63	0,42	1	1,4	2	2,5	2,8	3,2	4	5	6,3		
250	0,56	1	0,56	1,25	1,8	2,5	3,2	3,6	4	5	6,3	8		
320	0,75	1,6	0,75	1,6	2,2	3,2	4	4,5	5	6,3	8	10		
400	1	2	1	2	2,8	4	5	5,6	6,3	8	10	12,5		
500	1,3	2,5	1,3	2,5	3,6	5	6,3	7,1	8	10	12,5	16		
630	1,8	3,2	1,8	3,2	4,5	6,3	8	9	10	12,5	16	20		a
800	2,4	4	2,4	4	5,6	8	10	11	12,5	16	20	25		
1 000	3,2	5	3,2	5	7,1	10	12,5	14	16	20	25	32		
1 250			4,2	6,3	9	12,5	16	18	20	25	32	40		
1 600			5,6	8	11	16	20	22	25	32	40	50		
2 000			7,5	10	14	20	25	28	32	40	50	63		
2 500			10	12,5	18	25	32	36	40	50	63	80		
3 200			12,5	16	22	32	40	45	50	a	63	80	100	
4 000			16	20	28	40	50	56	63	80	100	125		
5 000			20	25	36	50	63	71	80	100	125	160		
6 300			25	32	45	63	80	90	100	125	160	200		
8 000			32	40	56	80	100	110	125	160	200	250		
10 000			40	50	71	100	125	140	160	200	250	320		

^a Values of creepage distances in this area have not been established. Material group IIIb is in general not recommended for application in pollution degree 3 above 630 V and in pollution degree 4.

^b As an exception, for rated insulation voltages 127 V, 208 V, 415/440 V, 660/690 V and 830 V, creepage distances corresponding to the lower values 125 V, 200 V, 400 V, 630 V and 800 V respectively may be used.

^c The values of creepage distances stated for 250 V can be used for 230 V ($\pm 10\%$) nominal voltage.

NOTE 1 It is appreciated that tracking or erosion will not occur on insulation subjected to working voltages of 32 V and below. However, the possibility of electrolytic corrosion has to be considered and for this reason minimum creepage distances have been specified.

NOTE 2 Voltage values are selected in accordance with the R₁₀ series.

Table 16 – Values of power-factors and time-constants corresponding to test currents, and ratio n between peak and r.m.s. values of current (see 8.3.4.3, item a))

Test current A	Power-factor	Time-constant ms	n
$I \leq 1\,500$	0,95	5	1,41
$1\,500 < I \leq 3\,000$	0,9	5	1,42
$3\,000 < I \leq 4\,500$	0,8	5	1,47
$4\,500 < I \leq 6\,000$	0,7	5	1,53
$6\,000 < I \leq 10\,000$	0,5	5	1,7
$10\,000 < I \leq 20\,000$	0,3	10	2,0
$20\,000 < I \leq 50\,000$	0,25	15	2,1
$50\,000 < I$	0,2	15	2,2

Table 17 – Actuator test force (see 8.2.5.2.1)

Type of actuator ^a	Test force ^a	Minimum test force N	Maximum test force N
Push-button (a)	$3F$	50	150
One-finger operated (b)	$3F$	50	150
Two-finger operated (c)	$3F$	100	200
One-hand operated (d) and (e)	$3F$	150	400
Two-hand operated (f) and (g)	$3F$	200	600

^a F is the normal operating force in new condition. The test force shall be $3F$ with the stated minimum and maximum values and be applied as shown in Figure 16.

Table 18 – Vacant

Table 19 – Vacant

Table 20 – Test values for conduit pull-out test (see 8.2.7.1)

Conduit designation according to IEC 60981	Conduit diameter		Pulling force N
	Inside mm	Outside mm	
12 H	12,5	17,1	900
16 H to 41 H	16,1 to 41,2	21,3 to 48,3	900
53 H to 155 H	52,9 to 154,8	60,3 to 168,3	900

Table 21 – Test values for conduit bending test
(see 8.2.7.2)

Conduit designation according to IEC 60981	Conduit diameter		Bending moment N·m
	Inside mm	Outside mm	
12 H	12,5	17,1	35 ^a
16 H to 41 H	16,1 to 41,2	21,3 to 48,3	70
53 H to 155 H	52,9 to 154,8	60,3 to 168,3	70

^a This value is reduced to 17 Nm for enclosures which have only provision for an incoming conduit, but not for an outgoing conduit.

Table 22 – Test values for conduit torque test
(see 8.2.7.1 and 8.2.7.3)

Conduit designation according to IEC 60981	Conduit diameter		Torque N·m
	Inside mm	Outside mm	
12 H	12,5	17,1	90
16 H to 41 H	16,1 to 41,2	21,3 to 48,3	120
53 H to 155 H	52,9 to 154,8	60,3 to 168,3	180

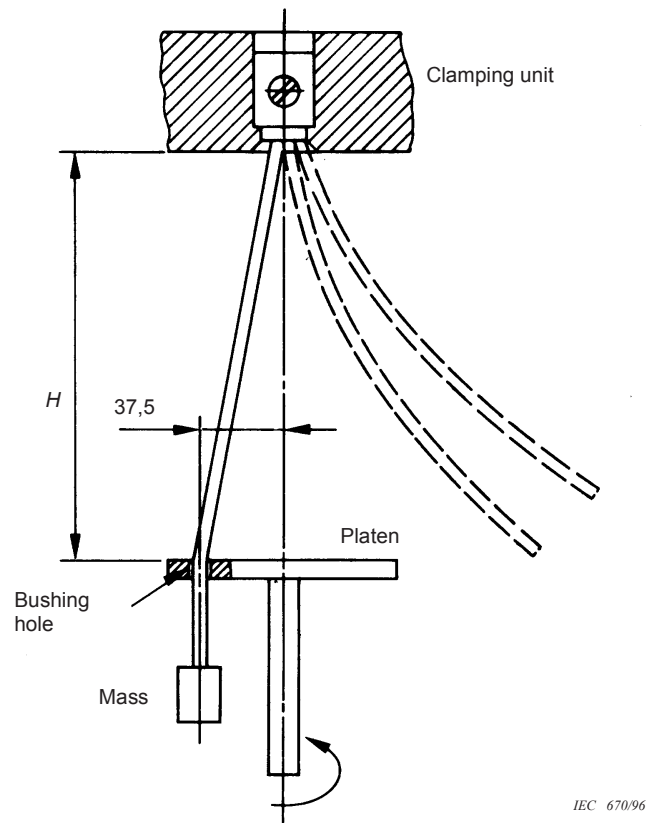
Table 23 – Tests for EMC – Immunity

(see 8.4.1.2)

Type of test	Test level required	
Electrostatic discharge immunity test IEC 61000-4-2	8 kV / air discharge or 4 kV / contact discharge	
Radiated radio-frequency electromagnetic field immunity test 80 MHz to 1 GHz IEC 61000-4-3	10 V/m	
Radiated radio-frequency electromagnetic field immunity test 1,4 GHz to 2 GHz IEC 61000-4-3	3 V/m	
Radiated radio-frequency electromagnetic field immunity test 2 GHz to 2,7 GHz IEC 61000-4-3	1 V/m	
Electrical fast transient/burst immunity test IEC 61000-4-4	2 kV/ 5 kHz on power ports 1 kV/ 5 kHz on signal ports	
1,2/50 μ s – 8/20 μ s surge immunity test ^a IEC 61000-4-5	2 kV (line to earth) 1 kV (line to line)	
Conducted radio-frequency immunity test (150 kHz to 80 MHz) IEC 61000-4-6	10 V	
Power frequency magnetic field immunity test ^b IEC 61000-4-8	30 A/m	
Voltage dips immunity test (50 Hz/ 60 Hz) IEC 61000-4-11 ^e	Class 2 ^{c, d, e} 0 % during 0,5 cycle and 1 cycle 70 % during 25 / 30 cycles	Class 3 ^{c, d, e} 0 % during 0,5 cycle and 1 cycle 40 % during 10/12 cycles 70 % during 25/30 cycles 80 % during 250/300 cycles
Short interruptions immunity test IEC 61000-4-11	Class 2 ^{c, d, e} 0 % during 250/300 cycles	Class 3 ^{c, d, e} 0 % during 250/300 cycles
Immunity to harmonics in the supply IEC 61000-4-13	No requirements ^f	
NOTE Performance criteria are given in the relevant product standard based on the acceptance criteria given in Table 24.		
^a Regarding applicability see 7.2 and 8.2 of IEC 61000-4-5 (Not applicable for low voltage d.c. input/output ports (≤ 60 V), when the secondary circuits (isolated from the a.c. mains) are not subject to transient overvoltages). ^b Applicable only to equipment containing devices susceptible to power frequency magnetic fields (see 8.4.1.2.7). ^c The given percentage means percentage of the rated operating voltage, e.g. 0 % means 0 V. ^d Class 2 applies to points of common coupling and in-plant points of common coupling in the industrial environment in general. Class 3 applies to in-plant couplings in industrial environment only. This class should be considered when a major part of the load is fed through converters; welding machines are present; large motors are frequently started or loads vary rapidly. The product standard shall state the applicable class. ^e The value in front of the slash mark (/) is for 50 Hz and the value behind for 60 Hz tests. ^f Requirements are under study for the future.		

Table 24 – Acceptance criteria when EM disturbances are present

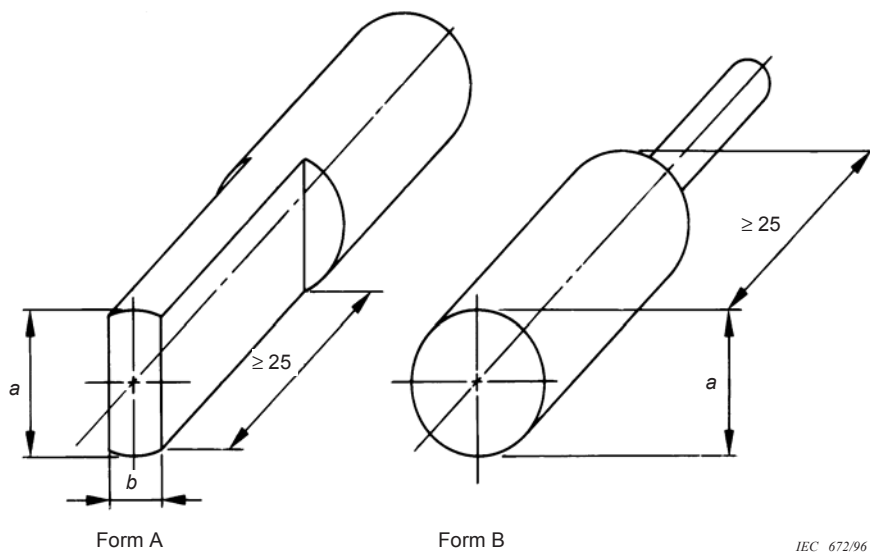
Item	Acceptance criteria (performance criteria during tests)		
	A	B	C
Overall performance	No noticeable changes of the operating characteristic. Operating as intended	Temporary degradation or loss of performance which is self-recoverable	Temporary degradation or loss of performance which requires operator intervention or system reset ^a
Operation of power and control circuits	No unwanted operation	Temporary degradation or loss of performance which is self-recoverable ^a	Temporary degradation or loss of performance which requires operator intervention or system reset ^a
Operation of displays and control panels	No changes to visible display information. Only slight light intensity fluctuation of LEDs, or slight movement of characters	Temporary visible changes or loss of information. Undesired LED illumination	Shut down or permanent loss of display. Wrong information and/or unpermitted operating mode, which should be apparent or an indication should be provided. Not self-recoverable
Information processing and sensing functions	Undisturbed communication and data interchange to external devices	Temporarily disturbed communication, with possible error reports of the internal and external devices	Erroneous processing of information. Loss of data and/or information. Errors in communication. Not self-recoverable
^a Specific requirements shall be detailed in the product standard.			



IEC 670/96

Dimensions in millimetres

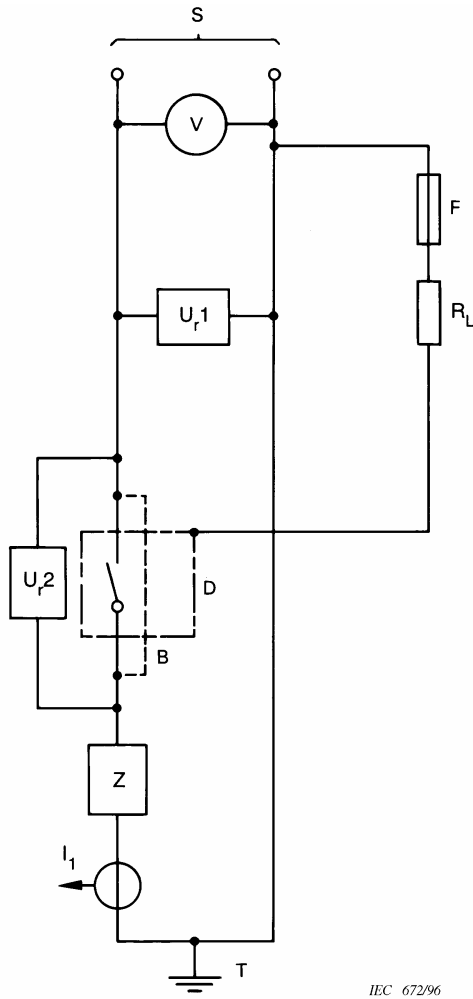
Figure 1 – Test equipment for flexion test
(see 8.2.4.3 and Table 5)



IEC 672/96

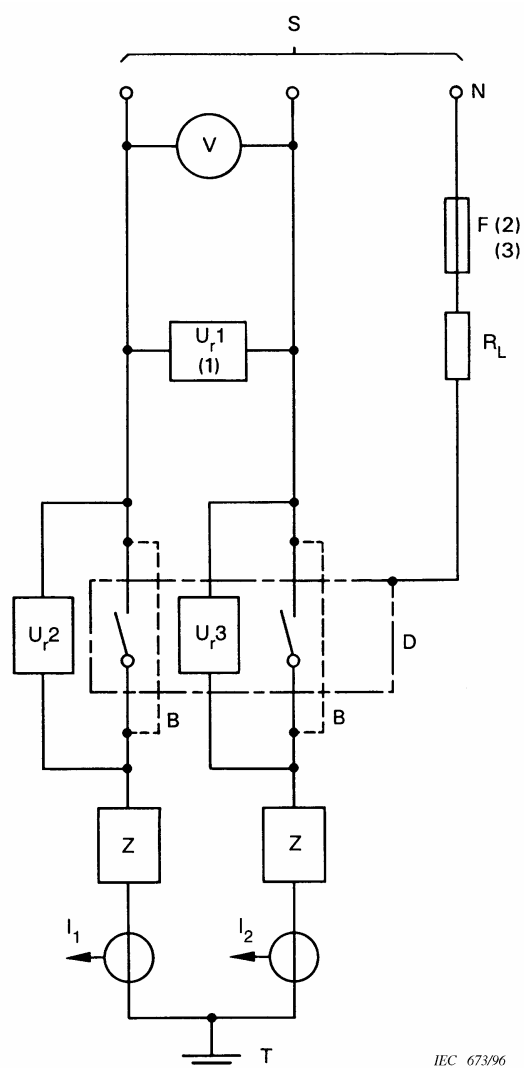
Dimensions in millimetres

Figure 2 – Gauges of form A and form B
(see 8.2.4.5.2 and Table 7)



- S = Supply
- U_{r1}, U_{r2} = Voltage sensors
- V = Voltage measuring device
- F = Fusible element (8.3.3.5.2, item g))
- Z = Load circuit (see Figure 8)
- R_L = Fault current limiting resistor
- D = Equipment under test (including connecting cables)
NOTE – Outline includes metallic screen or enclosure.
- B = Temporary connection for calibration
- I_1 = Current sensor
- T = Earth – One earthing point only (load side or supply side)

Figure 3 – Diagram of the test circuit for the verification of making and breaking capacities of a single-pole equipment on single-phase a.c. or on d.c. (see 8.3.3.5.2)



- S = Supply
- U_{r1}, U_{r2}, U_{r3} = Voltage sensors
- V = Voltage measuring device
- N = Neutral of supply (or artificial neutral)
- F = Fusible element (8.3.3.5.2, item g))
- Z = Load circuit (see Figure 8)
- R_L = Fault current limiting resistor
- D = Equipment under test (including connecting cables)
NOTE – Outline includes metallic screen or enclosure.
- B = Temporary connections for calibration
- I_1, I_2 = Current sensors
- T = Earth – One earthing point only (load side or supply side)

NOTE 1 U_{r1} may, alternatively, be connected between phase and neutral.

NOTE 2 In the case of equipment intended for use in phase-earthed systems or if this diagram is used for the test of the neutral and adjacent poles of a 4-pole equipment, F shall be connected to one phase of the supply.

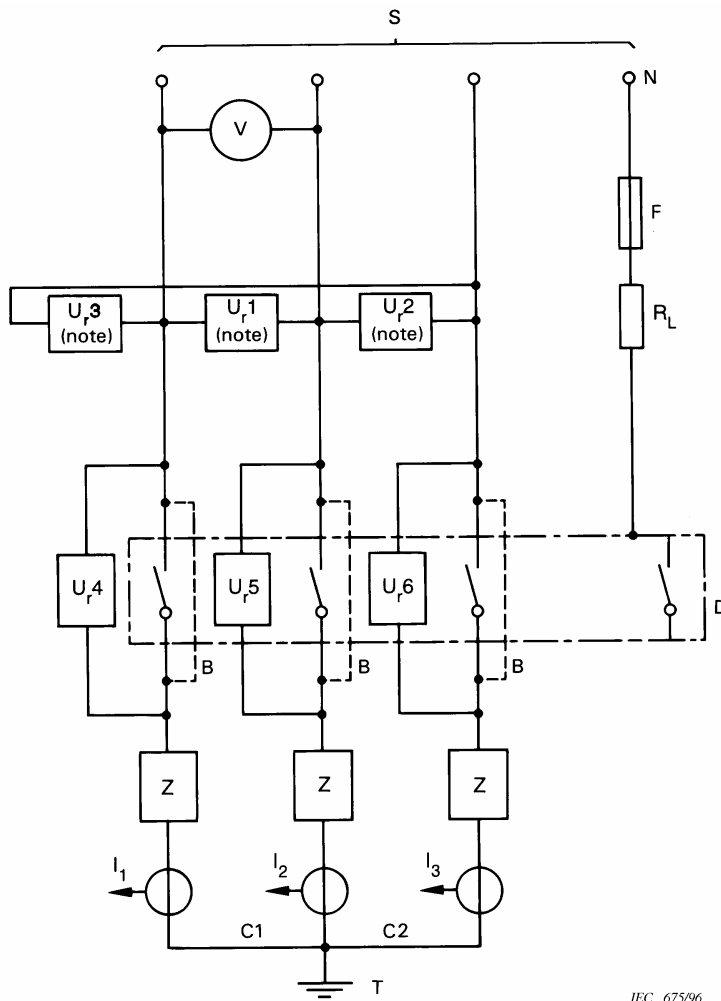
In the case of d.c., F shall be connected to the negative of the supply.

NOTE 3 In the USA and Canada, F shall be connected

- to one phase of the supply for equipment marked with a single value of U_e ;
- to the neutral for equipment marked with a twin voltage (see note to 5.2).

Figure 4 – Diagram of the test circuit for the verification of making and breaking capacities of a two-pole equipment on single-phase a.c. or on d.c.
(see 8.3.3.5.2)

IEC 673/96



- S = Supply
- U_r1, U_r2, = Voltage sensors
- U_r3, U_r4, U_r5, U_r6 = Voltage measuring device
- V = Voltage measuring device
- N = Neutral of supply (or artificial neutral)
- F = Fusible element (8.3.3.5.2, item g))
- Z = Load circuit (see Figure 8)
- R_L = Fault current limiting resistor
- D = Equipment under test (including connecting cables)
NOTE – Outline includes metallic screen or enclosure.
- B = Temporary connections for calibration
- I₁, I₂, I₃ = Current sensors
- T = Earth – One earthing point only (load side or supply side)

NOTE U_r1, U_r2 and U_r3 may, alternatively, be connected between phase and neutral.

Figure 6 – Diagram of the test circuit for the verification of making and breaking capacities of a four-pole equipment
(see 8.3.3.5.2)

IEC 675/96

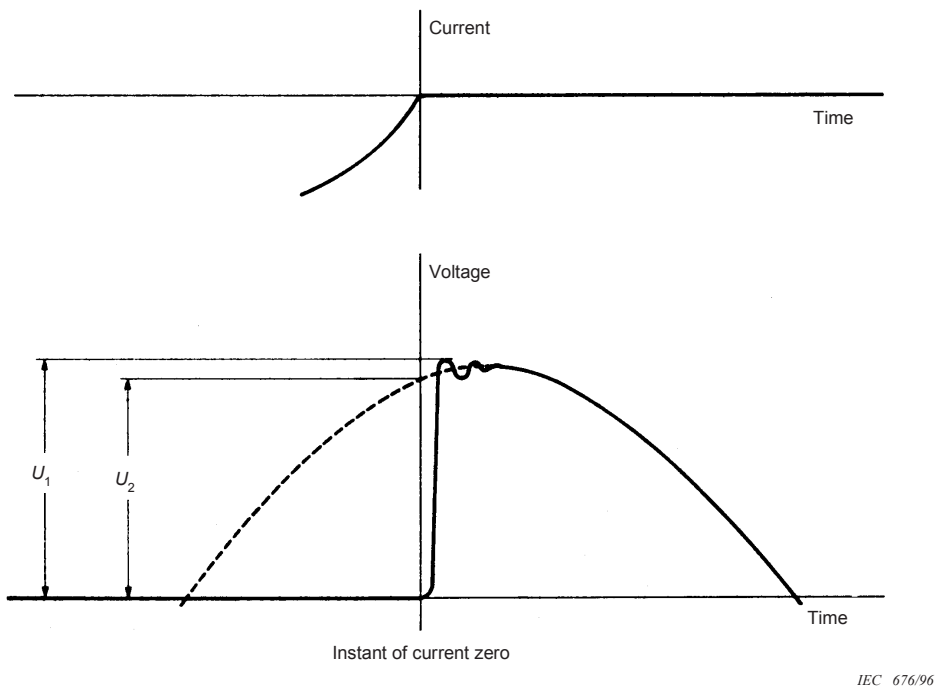
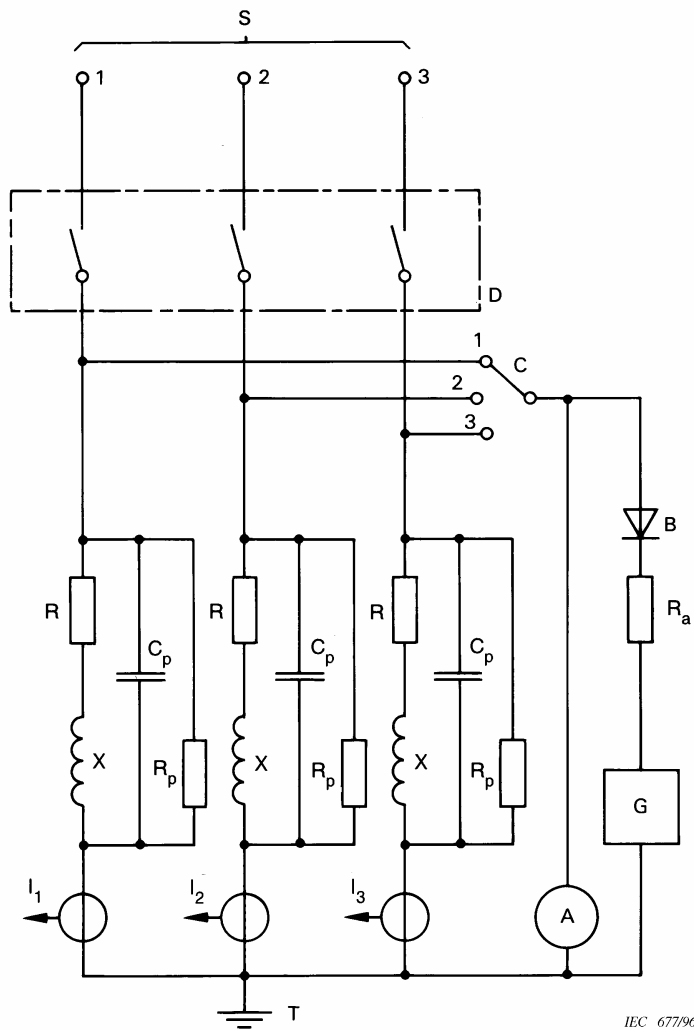


Figure 7 – Schematic illustration of the recovery voltage across contacts of the first phase to clear under ideal conditions (see 8.3.3.5.2, item e))

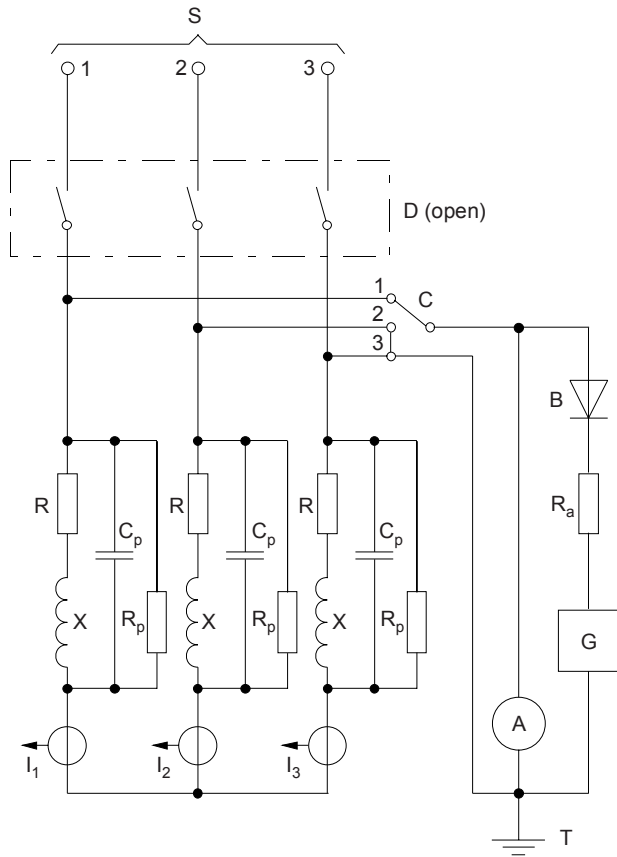


- S = Supply
- D = Equipment under test
- C = Phase adjustment selector switch
- B = Diode
- A = Recorder
- R_a = Resistor
- G = High-frequency generator
- R = Load circuit resistor
- X = Load circuit reactor (8.3.3.5.2, item d))
- R_p = Resistor in parallel
- C_p = Capacitor in parallel
- I_1, I_2, I_3 = Current sensors

The relative positions of the high-frequency generator G and the diode shall be as shown. No other point of the circuit than the one indicated on the figure shall be earthed.

Figure 8a – Diagram of a load circuit adjustment method: load star-point earthed

IEC 67796



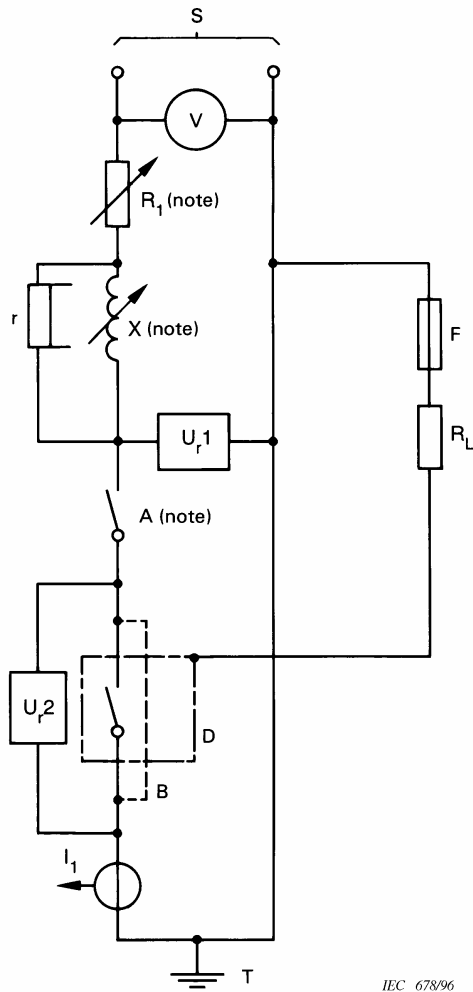
- S = Supply
- D = Equipment under test
- C = Phase adjustment selector switch
- B = Diode
- A = Recorder
- R_a = Resistor
- G = High-frequency generator
- R = Load circuit resistor
- X = Load circuit reactor (8.3.3.5.2 d))
- R_p = Resistor in parallel
- C_p = Capacitor in parallel
- I₁, I₂, I₃ = Currents sensors

IEC 822/98

The relative positions of the high-frequency generator G and the diode shall be as shown. No other point of the circuit than the one indicated on the figure shall be earthed.

In this figure, as an example 1, 2 and 3 are represented in the position corresponding to the adjustment of phase 1 (the first phase to clear) in series with phases 2 and 3 connected in parallel.

Figure 8b – Diagram of a load circuit adjustment method: supply star-point earthed

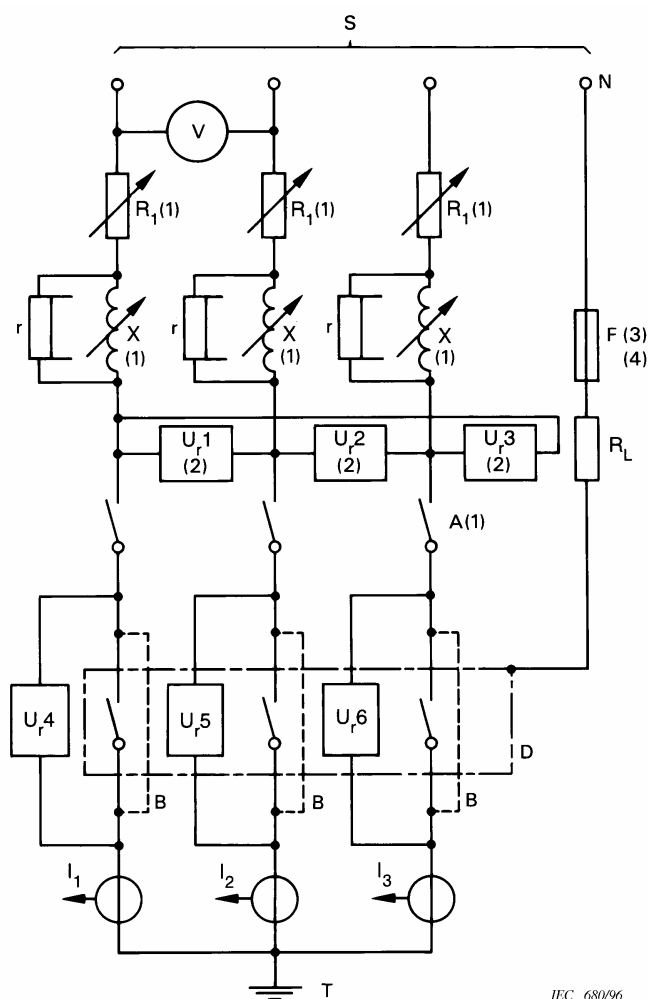


- S = Supply
- U_{r1}, U_{r2} = Voltage sensors
- V = Voltage measuring device
- A = Closing device
- R_1 = Adjustable resistor
- F = Fusible element (8.3.4.1.2, item d))
- X = Adjustable reactor
- R_L = Fault current limiting resistor
- D = Equipment under test (including connecting cables)
NOTE – Outline includes metallic screen or enclosure.
- B = Temporary connections for calibration
- I_1 = Current sensor
- T = Earth – One earthing point only (load side or supply side)
- r = Shunt resistor (8.3.4.1.2, item b))

IEC 678/96

A1 NOTE Adjustable loads X and R_1 may be located either on the high-voltage side or on the low-voltage side of the supply circuit. **A1**

Figure 9 – Diagram of the test circuit for the verification of short-circuit making and breaking capacities of a single-pole equipment on single-phase a.c. or on d.c. (see 8.3.4.1.2)



- S = Supply
 Ur1, Ur2, = Voltage sensors
 Ur3, Ur4, = Voltage sensors
 Ur5, Ur6, = Voltage sensors
 V = Voltage measuring device
 A = Closing device
 R1 = Adjustable resistor
 N = Neutral of supply (or artificial neutral)
 F = Fusible element (8.3.4.1.2, item d))
 X = Adjustable reactors
 RL = Fault current limiting resistor
 D = Equipment under test (including connecting cables)
 NOTE – Outline includes metallic screen or enclosure.
 B = Temporary connections for calibration
 I1, I2, I3 = Current sensors
 T = Earth – One earthing point only (load side or supply side)
 r = Shunt resistor (8.3.4.1.2, item b))

IEC 68096

A1 NOTE 1 Adjustable loads X and R₁ may be located either on the high-voltage side or on the low-voltage side of the supply circuit. **A1**

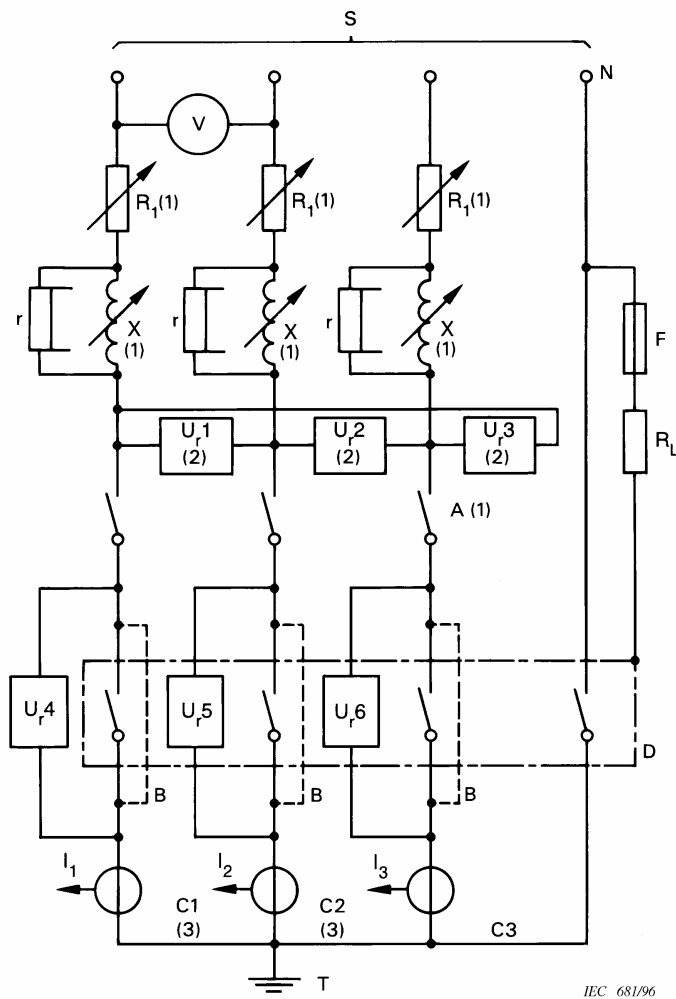
NOTE 2 Ur1, Ur2, Ur3 may, alternatively, be connected between phase and neutral.

NOTE 3 In the case of equipment intended for use in phase-earthed systems or if this diagram is used for the test of the neutral and adjacent pole of a four-pole equipment F, shall be connected to one phase of the supply.

NOTE 4 In the USA and Canada, F shall be connected

- to one phase of the supply for equipment marked with a single value of U_e;
- to the neutral for equipment marked with a twin voltage of U_e (see note to 5.2).

Figure 11 – Diagram of the test circuit for the verification of short-circuit making and breaking capacities of a three-pole equipment
(see 8.3.4.1.2)



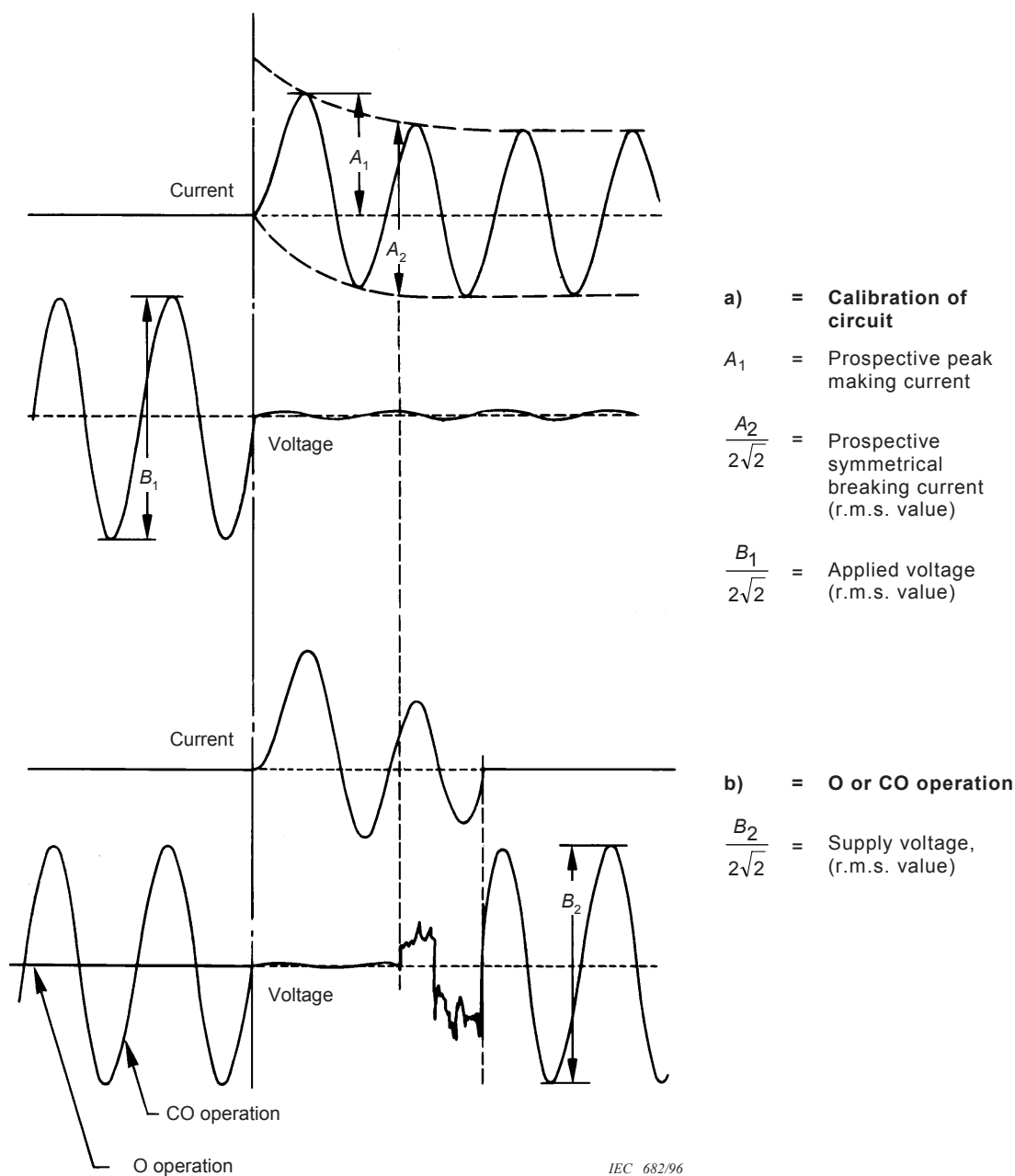
- S = Supply
- U_r1, U_r2, U_r3, U_r4, U_r5, U_r6, V = Voltage measuring device
- R₁ = Adjustable resistor
- N = Neutral of supply
- F = Fusible element (8.3.4.1.2, item d))
- X = Adjustable reactors
- R_L = Fault current limiting resistor
- A = Closing device
- D = Equipment under test (including connecting cables)
NOTE – Outline includes metallic screen or enclosure.
- B = Temporary connections for calibration
- I₁, I₂, I₃ = Current sensors
- T = Earth – One earthing point only (load side or supply side)
- r = Shunt resistor (8.3.4.1.2, item b))

A1 NOTE 1 Adjustable loads X and R₁ may be located either on the high-voltage side or on the low-voltage side of the supply circuit. **A1**

NOTE 2 U_r1, U_r2, U_r3 may, alternatively, be connected between phase and neutral.

NOTE 3 If an additional test is required between the neutral and the adjacent pole, the connections C1 and C2 are omitted.

Figure 12 – Diagram of the test circuit for the verification of short-circuit making and breaking capacities of a four-pole equipment (see 8.3.4.1.2)



Making capacity (peak value) = A_1 (see 8.3.4.1.8, items b) and c))

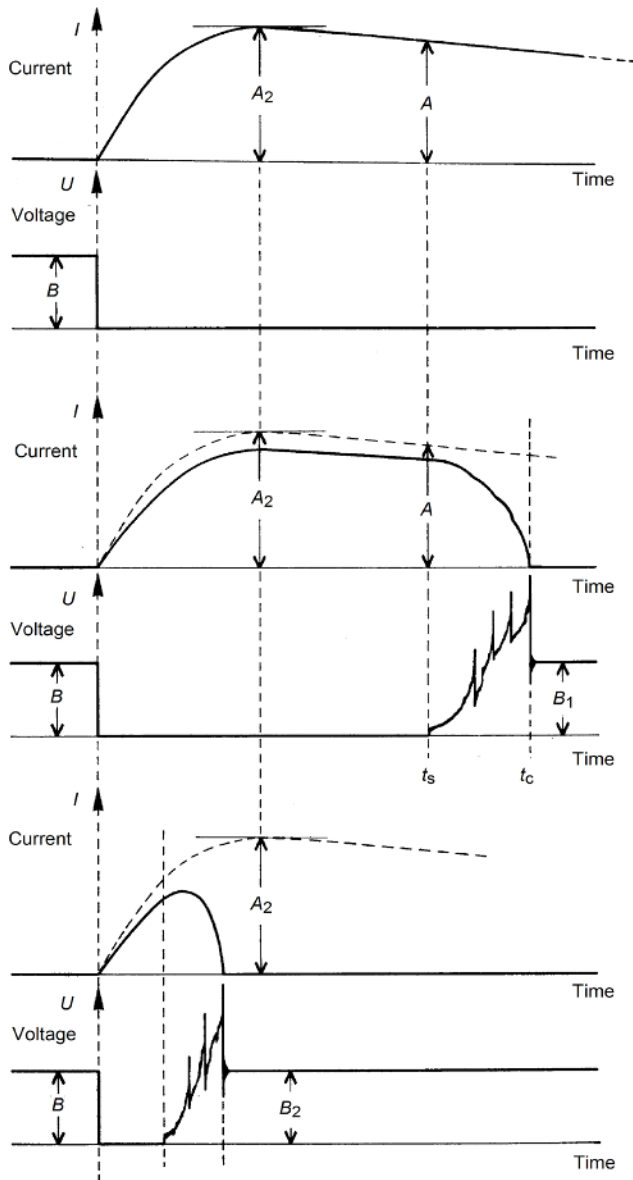
Breaking capacity (r.m.s. value) = $\frac{A_2}{2\sqrt{2}}$ (see 8.3.4.1.8, items b) and c))

NOTE 1 The amplitude of the voltage trace, after initiation of the test current, varies according to the relative positions of the closing device, the adjustable impedances, the voltage sensors and according to the test circuit diagram.

NOTE 2 It is assumed that the instant of making is the same for calibration and test.

Figure 13 – Example of short-circuit making and breaking test record in the case of a single-pole equipment on single-phase a.c.
(see 8.3.4.1.8)

A₂



a) Calibration of the circuit

Prospective peak making current = A_2

b) Oscillogram corresponding to a break after the current has passed its maximum value

Short-circuit breaking capacity:
Current $I = A$ at voltage $U = B_1$

Short-circuit making capacity:
Current $I = A_2$ at voltage $U = B$

c) Oscillogram corresponding to a break before the current has reached its maximum value

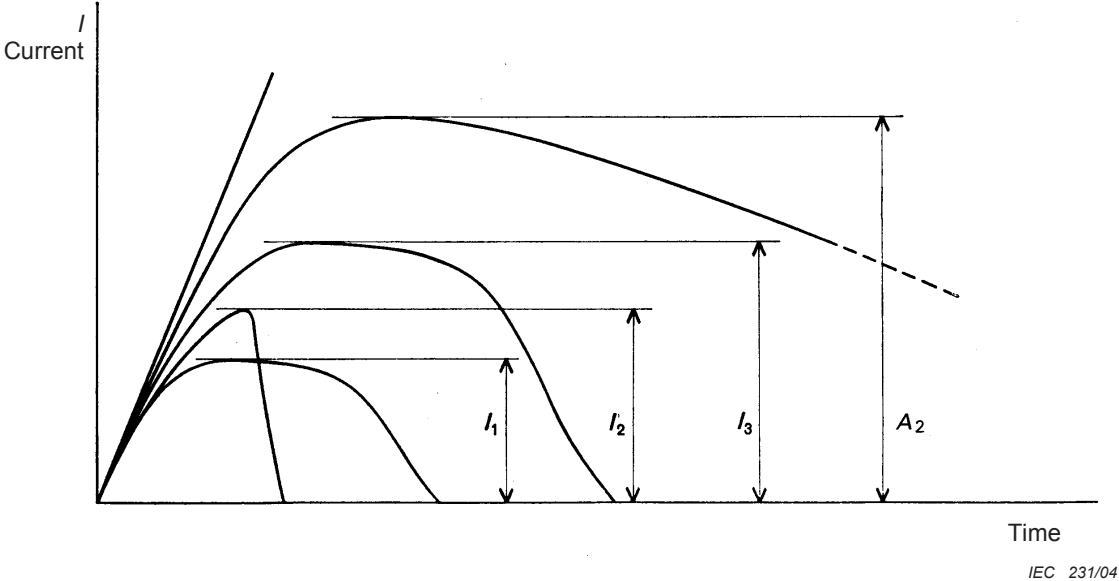
Short-circuit breaking capacity:
Current $I = A_2$ at voltage $U = B_2$

Short-circuit making capacity:
Current $I = A_2$ at voltage $U = B$

IEC

A₂

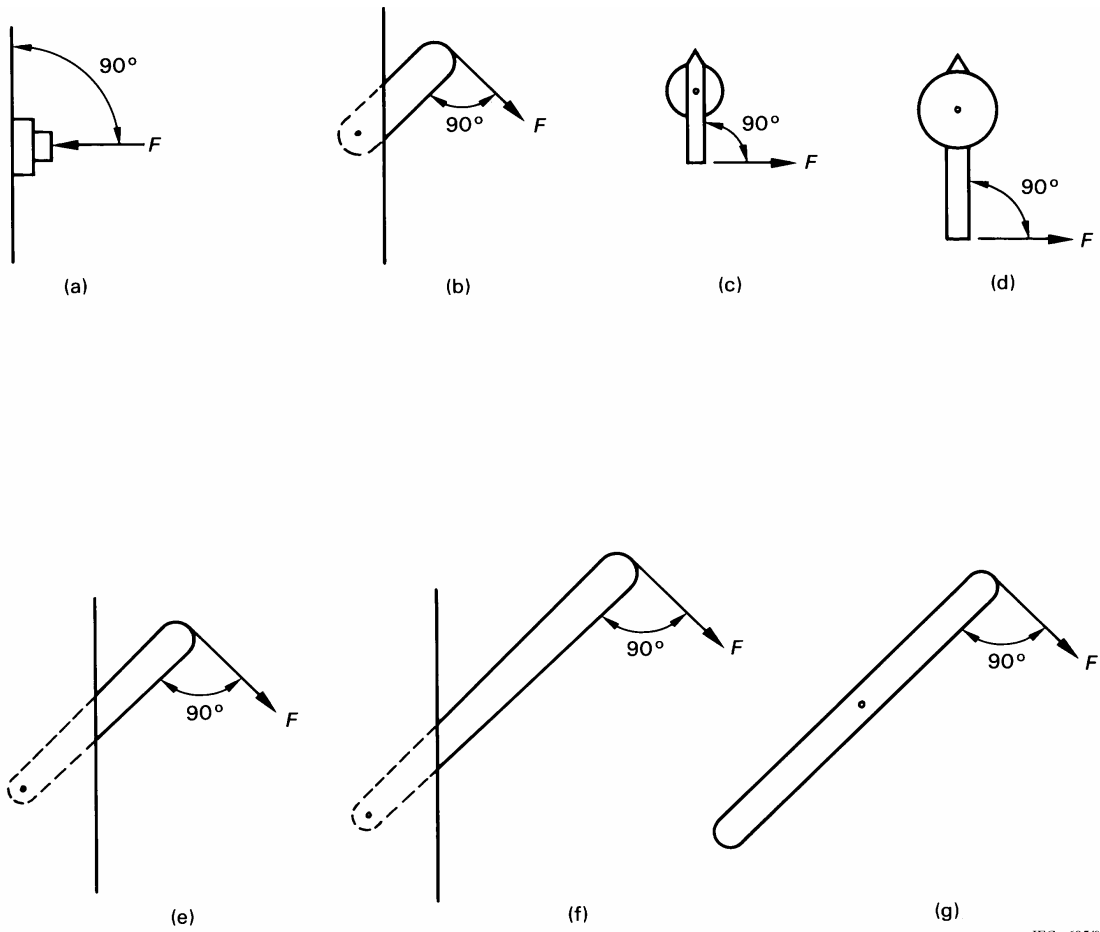
Figure 14 – Verification of short-circuit making and breaking capacities on d.c.
(see 8.3.4.1.8)



IEC 231/04

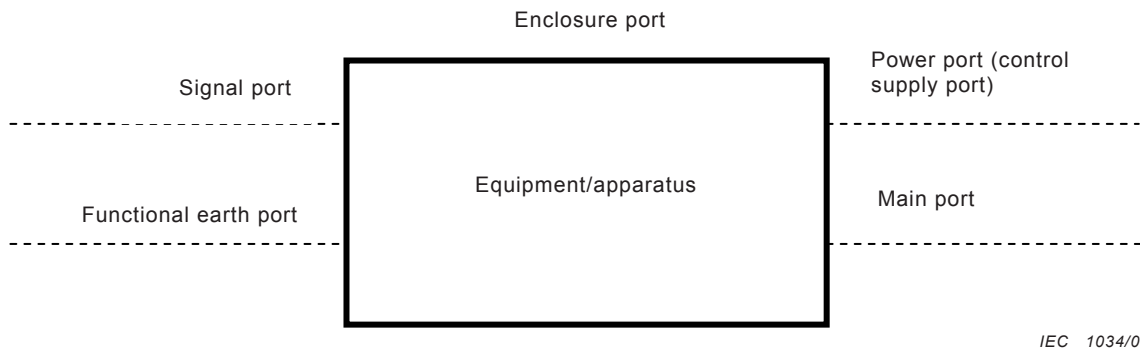
- I_1 First calibration
- I_2 Actual breaking current
- I_3 Second calibration
- A_2 Breaking capacity

Figure 15 – Determination of the prospective breaking current when the first calibration of the test circuit has been made at a current lower than the rated breaking capacity (see 8.3.4.1.8, item b))



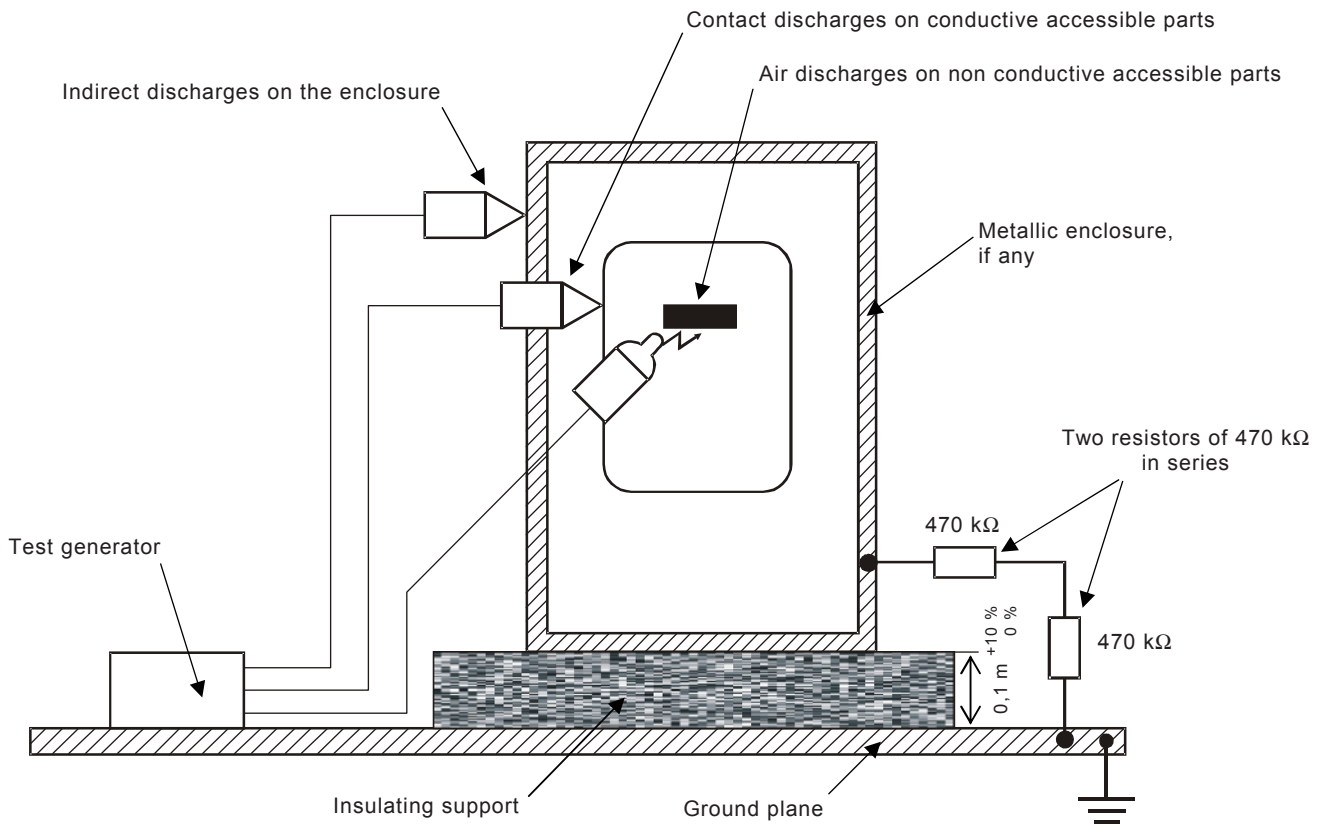
IEC 685/96

Figure 16 – Actuator test force
(see 8.2.5.2.1 and Table 17)



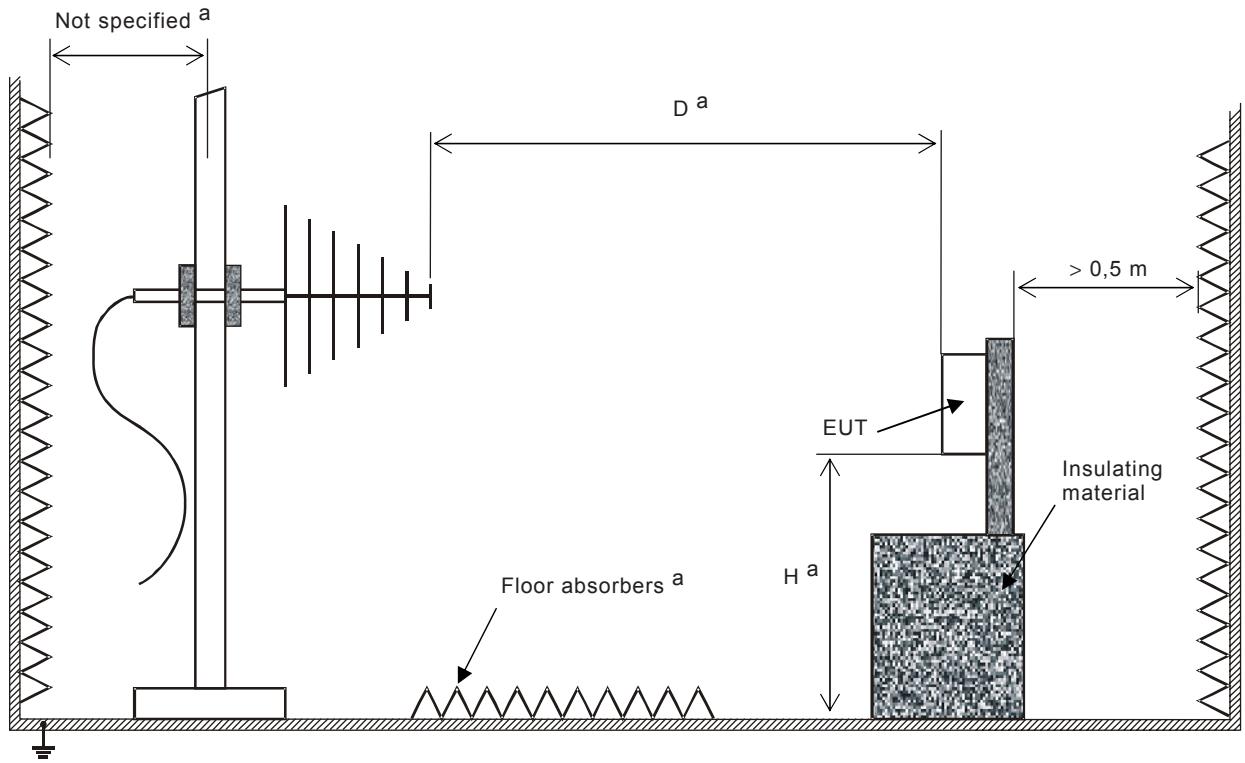
IEC 1034/07

Figure 17 – Examples of ports



IEC 1035/07

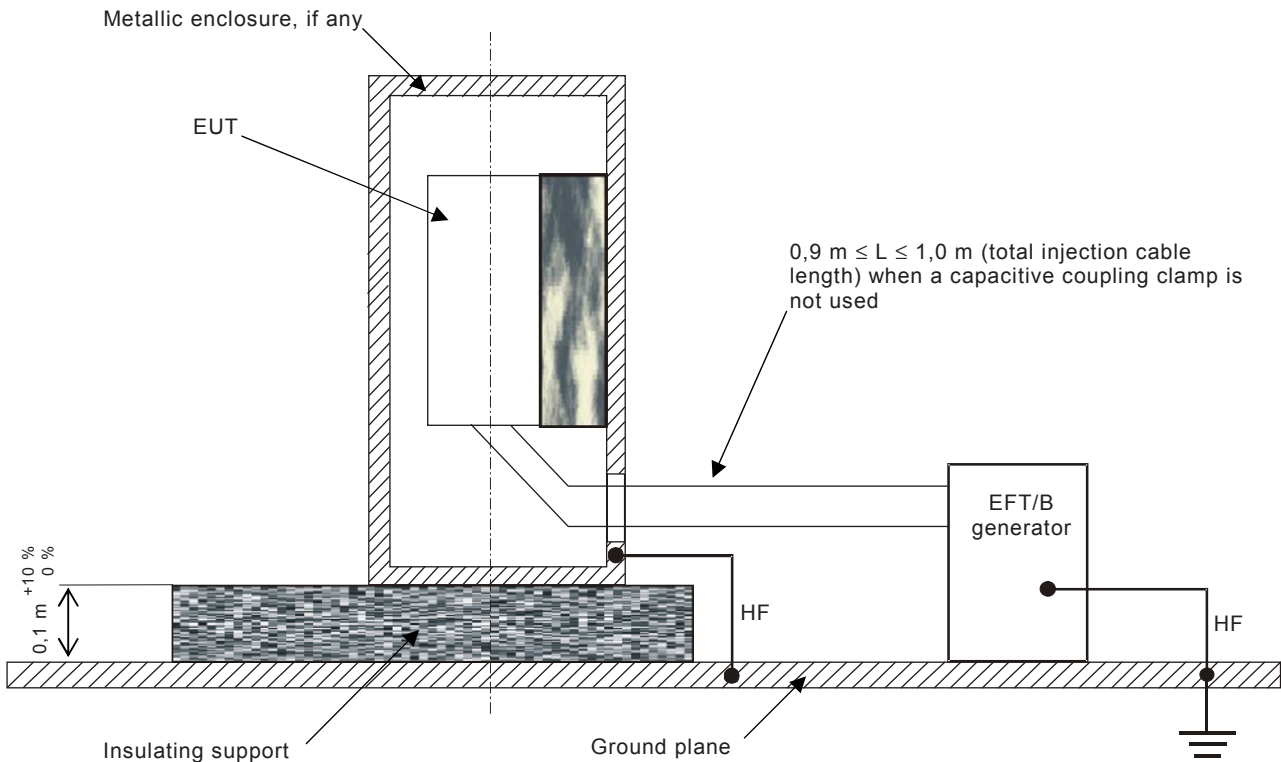
Figure 18 – Test set-up for the verification of immunity to electrostatic discharges



IEC 1036/07

^a See IEC 61000-4-3.

Figure 19 – Test set-up for the verification of immunity to radiated radio-frequency electromagnetic fields

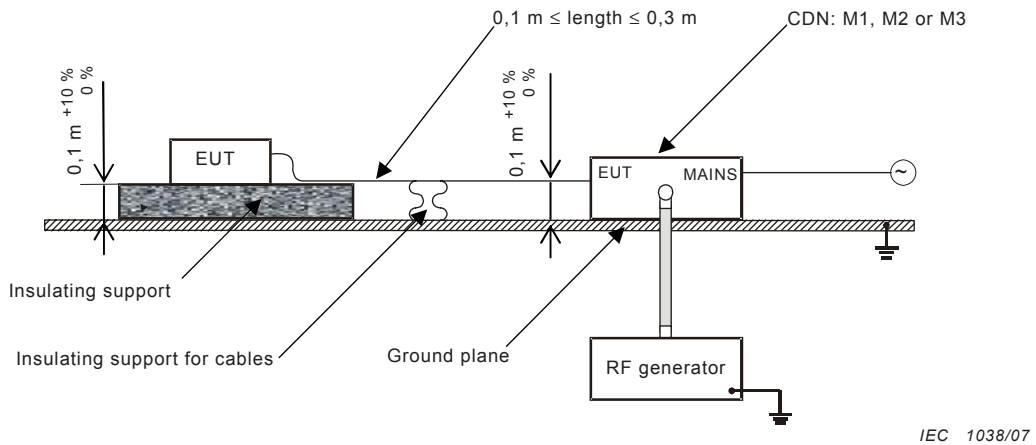


IEC 1037/07

Key

HF high frequency connection

Figure 20 – Test set-up for the verification of immunity to electrical fast transients/bursts

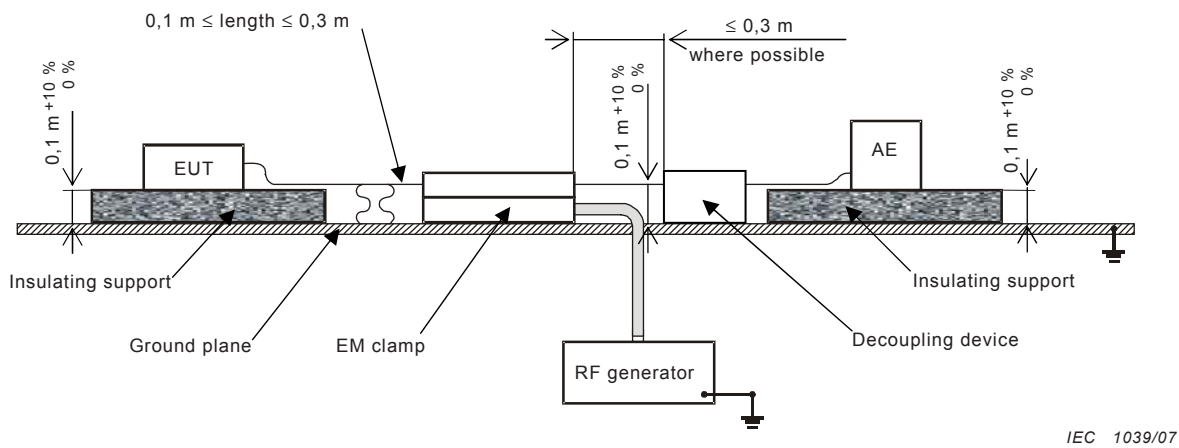


Key

CDN coupling-decoupling network

NOTE As an alternative to the coupling-decoupling network M1, the coupling-decoupling network M2 or M3 may be used in which case the two or three connecting wires, as applicable, are connected to the same point of the EUT.

Figure 21 – Test set-up for the verification of immunity to conducted disturbances induced by r.f. fields on power lines

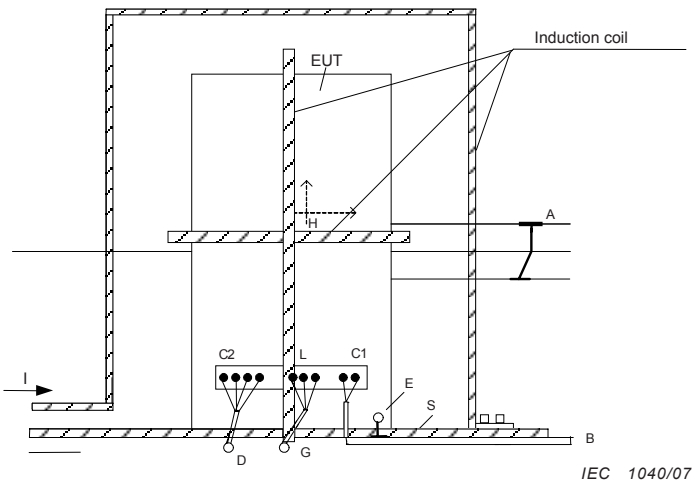


Key

AE auxiliary equipment

EM clamp electromagnetic clamp

Figure 22 – Example of test set-up for the verification of immunity to conducted disturbances induced by r.f. fields on signal lines when CDN's are not suitable



Key

- | | | | | | |
|----|------------------------|---|-----------------------------|---|--------------------|
| A | safety earth | D | to signal source, simulator | I | induction current |
| B | to power supply source | E | earth terminal | L | communication line |
| C1 | power supply circuit | G | to the test generator | S | insulating support |
| C2 | signal circuit | H | magnetic field strength | | |

Figure 23 – Test set-up for the verification of immunity to power frequency magnetic fields

A₂ Annex A
(informative)

**Harmonisation of utilization categories
for low-voltage switchgear and controlgear**

The IEC 60947 series contains different parts specifying requirements for different types of low-voltage switchgear. Standards for products covered by the IEC 60947 series have been developed at different periods of time and by various working groups. It results in many utilization categories for similar applications in the IEC 60947 series.

The objective of this annex is to give the harmonisation framework for the low-voltage switchgear and controlgear as given in Table A.1. A future objective under consideration is to specify a common set of requirements for testing of the products from different parts of the IEC 60947 series.

The intended benefits are to:

- simplify the standards by bringing all similar categories together under one common set of categories;
- help the user in the selection of equipment for specific applications.

Table A.1 – Utilization categories used in the IEC 60947 series

Nature of current	Category		Typical switched load	Relevant IEC product standard
	Proposed ^c	Present ^d		
a.c.	AC-20	AC-20	No-load condition	IEC 60947-3:2008, Amd 1 (2012)
	AC-21	AC-21	Resistive loads, including moderate overloads	
	AC-22	AC-22	Mixed resistive and inductive loads, including moderate overloads	
	AC-23	AC-23	Motor loads or other highly inductive loads	
	AC-1	AC-1	Non-inductive or slightly inductive loads	IEC 60947-4-1:2009, Amd 1 (2012)
	AC-2	AC-2	Slip-ring motors or switching of mixed resistive and inductive loads, including moderate overloads	
	AC-3	AC-3	Squirrel-cage motors	
	AC-4	AC-4	Squirrel-cage motors: plugging ^a , inching ^b	
	AC-5a	AC-5a	Discharge lamp ballasts	
	AC-5b	AC-5b	Incandescent lamps	
	AC-6a	AC-6a	Transformers	
	AC-6b	AC-6b	Capacitor banks	
	AC-8 AC-8	AC-8a AC-8b	Hermetic refrigerant compressor	
	AC-2a	AC-52a	Slip ring motor stators: 8 h duty with on-load currents for start, acceleration, run	IEC 60947-4-2:2011
	AC-2b	AC-52b	Slip ring motor stators: intermittent duty	
	AC-3a	AC-53a	Squirrel-cage motors: 8 h duty with on-load currents for start, acceleration, run	
AC-3b	AC-53b	Squirrel-cage motors: intermittent duty		
AC-8a	AC-58a	Hermetic refrigerant compressor motors with automatic resetting of overload releases: 8 h duty with on-load currents for start, acceleration, run		

Nature of current	Category		Typical switched load	Relevant IEC product standard
	Proposed ^c	Present ^d		
	AC-8b	AC-58b	Hermetic refrigerant compressor motors with automatic resetting of overload releases: intermittent duty	
	AC-1	AC-51	Non-inductive or slightly inductive loads	IEC 60947-4-3:1999 Amd 1 (2006) Amd 2 (2011)
	AC-5a	AC-55a	Discharge lamps ballast	
	AC-5b	AC-55b	Incandescent lamps	
	AC-6a	AC-56a	Transformers	
	AC-6b	AC-56b	Capacitor banks	
	AC-12	AC-12	Resistive loads and solid-state loads with isolation by optocouplers	IEC 60947-5-1:2003 Amd 1 (2009)
	AC-13	AC-13	Solid-state loads with transformer isolation	
	AC-14	AC-14	Small electromagnetic loads	
	AC-15	AC-15	a.c. electromagnetic loads	
	AC-12	AC-12	Resistive loads and solid state loads with optical isolation	IEC 60947-5-2:2007 Amd 1 (2012)
	AC-140	AC-140	Small electromagnetic loads with holding (closed) current $\leq 0,2$ A, e.g. contactor relays	
	AC-1	AC-31	Non inductive or slightly inductive loads	IEC 60947-6-1:2005
	AC-2	AC-32	Slip-ring motors or switching of mixed resistive and inductive loads, including moderate overloads	
	AC-3	AC-33	Squirrel-cage motors	
	AC-5a	AC-35	Discharge lamp ballast	
	AC-5b	AC-36	Incandescent lamps	
	AC-40	AC-40	Distribution circuits comprising mixed resistive and reactive loads having a resultant inductive reactance	IEC 60947-6-2:2002 Amd 1 (2007)
	AC-1	AC-41	Non-inductive or slightly inductive loads	
	AC-2	AC-42	Slip-ring motors or switching of mixed resistive and inductive loads, including moderate overloads	
	AC-3	AC-43	Squirrel-cage motors	
	AC-4	AC-44	Squirrel-cage motors: plugging ^a , inching ^b	
	AC-5a	AC-45a	Discharge lamp ballasts	
	AC-5b	AC-45b	Incandescent lamps	
	AC-7a	AC-7a	Slightly inductive loads for household appliances and similar applications	IEC 61095:2009
	AC-7b	AC-7b	Motor-loads for household applications	
d.c.	DC-20	DC-20	Connecting and disconnecting under no-load conditions	IEC 60947-3:2008, Amd 1 (2012)
	DC-21	DC-21	Resistive loads, including moderate overloads	
	DC-22	DC-22	Mixed resistive and inductive loads, including moderate overloads (e.g. shunt motors)	
	DC-23	DC-23	Highly inductive loads (e.g. series motors)	
	DC-1	DC-1	Non-inductive or slightly inductive loads	IEC 60947-4-1:2009, Amd 1 (2012)
	DC-3	DC-3	Shunt-motors	
	DC-5	DC-5	Series-motors	
	DC-6	DC-6	Incandescent lamps	
	DC-12	DC-12	Control of resistive loads and solid-state loads with isolation by optocouplers	IEC 60947-5-1:2003 Amd 1
	DC-13	DC-13	Control of electromagnets	

Nature of current	Category		Typical switched load	Relevant IEC product standard
	Proposed ^c	Present ^d		
	DC-14	DC-14	Control of electromagnetic loads having economy resistors in circuit	(2009)
	DC-12	DC-12	Control of resistive loads and solid state loads with optical isolation	IEC 60947-5-2:2007 Amd 1 (2012)
	DC-13	DC-13	Control of electromagnets	
	DC-1	DC-31	Non-inductive or slightly inductive loads	IEC 60947-6-1:2005
	DC-3	DC-33	Shunt-motors	
	DC-6	DC-36	Incandescent lamps	
	DC-40	DC-40	Distribution circuits comprising mixed resistive and reactive loads having a resultant inductive reactance	IEC 60947-6-2:2002 Amd 1 (2007)
	DC-1	DC-41	Non-inductive or slightly inductive loads	
	DC-3	DC-43	Shunt-motors	
	DC-5	DC-45	Series-motors Incandescent lamps	
	DC-6	DC-46	Incandescent lamps	
<p>^a By plugging is understood stopping or reversing the motor rapidly by reversing motor primary connections while the motor is running.</p> <p>^b By inching (jogging) is understood energizing a motor once or repeatedly for short periods to obtain small movements of the driven mechanism.</p> <p>^c Utilization categories intended to be harmonized throughout product standards in their future editions.</p> <p>^d Present utilization category as defined in the referred edition of the product standard in the last column until it is changed to the proposed utilization category.</p>				

Annex B (informative)

Suitability of the equipment when conditions for operation in service differ from the normal conditions

If the conditions for operation in service and the application differ from those given in this standard, the user shall state the deviations from the standard conditions and consult the manufacturer on the suitability of the equipment for use under such conditions.

B.1 Examples of conditions differing from normal

B.1.1 Ambient air temperature

The expected range of ambient air temperature can be lower than $-5\text{ }^{\circ}\text{C}$ or higher than $+40\text{ }^{\circ}\text{C}$.

B.1.2 Altitude

The altitude of the place of installation is more than 2 000 m.

B.1.3 Atmospheric conditions

The atmosphere in which the equipment is to be installed may have a relative humidity greater than the values specified in 6.1.3 or contain an abnormal amount of dust, acids, corrosive gases, etc.

The equipment is to be installed near the sea.

B.1.4 Conditions of installation

The equipment may be fitted to a moving device, or its support may assume a sloping position either permanently or temporarily (equipment fitted aboard ships), or it may be exposed in service to abnormal shocks or vibrations.

B.2 Connections with other apparatus

The user shall inform the manufacturer of the type and dimensions of electrical connections with other apparatus in order to enable him to provide enclosures and terminals meeting the conditions of installation and temperature-rise prescribed by this standard and/or the relevant product standard and also to enable him to provide space, where necessary, to spread out conductors within the enclosure.

B.3 Auxiliary contacts

The user shall specify the number and type of auxiliary contacts to be supplied to satisfy requirements such as signalling, interlocking, and similar functions.

B.4 Special applications

The user shall indicate to the manufacturer if the equipment could be used for special applications not covered by this standard and/or the relevant product standard.

Annex C (normative)

Degrees of protection of enclosed equipment

Introduction

Where an IP Code is stated by the manufacturer for enclosed equipment and for a device with integral enclosure it shall comply with the requirements of IEC 60529, and the following modifications and additions.

NOTE Figure C.1 gives further information to facilitate the understanding of the IP code covered by IEC 60529.

Clauses and subclauses of IEC 60529 applicable to enclosed equipment are explicitly detailed in this annex.

Clause and subclause numbers of this annex correspond to the numbers in IEC 60529.

C.1 Scope

This annex applies to the degrees of protection of enclosed switchgear and controlgear at rated voltages not exceeding 1 000 V a.c. or 1 500 V d.c. hereafter referred to as "Equipment".

C.2 Object

Clause 2 of IEC 60529 applies with the additional requirements of this annex.

C.3 Definitions

Clause 3 of IEC 60529 applies except that "Enclosure" (3.1) is replaced by the following, notes 1 and 2 remaining as they are.

"A part providing a specified degree of protection of equipment against certain external influences and a specified degree of protection against approach to or contact with live parts and moving parts."

NOTE This definition given in 2.1.16 of this standard is similar to IEC 441-13-01 which applies to assemblies.

C.4 Designation

Clause 4 of IEC 60529 applies except for letters H, M and S.

C.5 Degrees of protection against access to hazardous parts and against ingress of solid foreign objects indicated by the first characteristic numeral

Clause 5 of IEC 60529 applies.

C.6 Degrees of protection against ingress of water indicated by the second characteristic numeral

Clause 6 of IEC 60529 applies.

C.7 Degrees of protection against access to hazardous parts indicated by the additional letter

Clause 7 of IEC 60529 applies.

C.8 Supplementary letters

Clause 8 of IEC 60529 applies except for letters H, M and S.

C.9 Examples of designations with IP Code

Clause 9 of IEC 60529 applies.

C.10 Marking

Clause 10 of IEC 60529 applies with the following addition:

If the IP Code is designated for one mounting position only, it shall be indicated by the symbol 0623 of ISO 7000 placed next to the IP Code specifying this position of the equipment, e.g. vertical:



C.11 General requirements for tests

C.11.1 Subclause 11.1 of IEC 60529 applies.

C.11.2 Subclause 11.2 of IEC 60529 applies with the following additions:

All tests are made in the unenergized state.

Certain devices (e.g. exposed faces of push-buttons) can be verified by inspection.

The temperature of the test sample shall not deviate from the actual ambient temperature by more than 5 K.

Where equipment is mounted in an empty enclosure which already has an IP Code (see 11.5 of IEC 60529) the following requirements apply.

a) For IP1X to IP4X and additional letters A to D.

This shall be verified by inspection and compliance with the enclosure manufacturer's instructions.

b) For IP6X dust test.

This shall be verified by inspection and compliance with the enclosure manufacturer's instructions.

c) For IP5X dust test and IPX1 to IPX8 water tests.

Testing of the enclosed equipment is only required where the ingress of dust or water may impair the operation of the equipment.

NOTE IP5X dust and IPX1 to IPX8 water tests allow the ingress of a certain amount of dust and water provided that there are no harmful effects. Every internal equipment configuration should, therefore, be separately considered.

C.11.3 Subclause 11.3 of IEC 60529 applies with the following addition:

Drain and ventilating holes are treated as normal openings.

C.11.4 Subclause 11.4 of IEC 60529 applies.

C.11.5 Where an empty enclosure is used as a component of an enclosed equipment, subclause 11.5 of IEC 60529 applies.

C.12 Tests for protection against access to hazardous parts indicated by the first characteristic numeral

Clause 12 of IEC 60529 applies except for 12.3.2.

C.13 Tests for protection against ingress of solid foreign objects indicated by the first characteristic numeral

Clause 13 of IEC 60529 applies except for

C.13.4 Dust test for first characteristic numerals 5 and 6

Enclosed equipment having a degree of protection IP5X shall be tested according to category 2 of 13.4 of IEC 60529.

NOTE 1 A particular product standard for equipment having a degree of protection IP5X may require testing according to category 1 of 13.4 of IEC 60529.

Enclosed equipment having a degree of protection IP6X shall be tested according to category 1 of 13.4 of IEC 60529.

NOTE 2 For enclosed equipment according to this standard, a degree of protection IP5X is generally deemed satisfactory.

C.13.5.2 Acceptance conditions for first characteristic numeral 5

The following text to be added:

Where dust deposits could raise doubts as to the correct functioning and safety of equipment, a preconditioning and a dielectric test shall be conducted as follows:

The preconditioning, after the dust test, shall be verified by test Cab: Damp heat, steady state, according to IEC 60068-2-78, under the following test conditions.

The equipment shall be prepared so that the dust deposits are subject to the test by leaving open the lid and/or removing parts, where possible without the aid of tool.

Before being placed in the test chamber the equipment shall be stored at room temperature for at least 4 h before the test.

The test duration shall be 24 consecutive hours.

- Ⓐ) After this period the equipment is to be removed from the test chamber within 15 min and submitted to a power-frequency dielectric test for 1 min, the value being $2 U_e$ max. with a minimum of 1 000 V. Application of the test voltage and the acceptance criteria shall be as specified in 8.3.3.4.1 item 3) c) and item 3) d). Ⓐ)

C.14 Tests for protection against water indicated by second characteristic numeral

Ⓐ) C.14.1 Test means

Subclause 14.1 of IEC 60529 applies.

C.14.2 Test conditions

Subclause 14.2 of IEC 60529 applies.

C.14.3 Acceptance conditions

Subclause 14.3 of IEC 60529 applies with the following addition:

The equipment is then submitted to a power-frequency dielectric test for 1 min, the value being $2 U_e$ max. with a minimum of 1 000 V. Application of the test voltage and the acceptance criteria shall be as specified in 8.3.3.4.1 item 3) c) and item 3) d). Ⓐ)


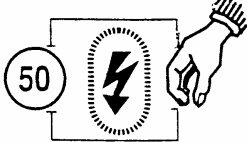
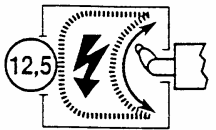
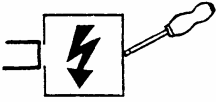

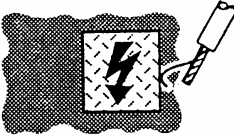
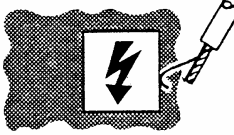
C.15 Tests for protection against access to hazardous parts indicated by additional letter

Clause 15 of IEC 60529 applies.

C.16 Summary of responsibilities of relevant technical committees





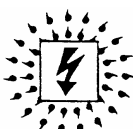
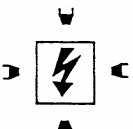
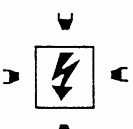

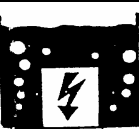
The relevant product standards specify the detailed information listed, as a guide, in Annex B of IEC 60529, taking into account the supplements specified above in this Annex C.

Further illustrations are included to facilitate the understanding of the IP Codes (see Figure C.1).

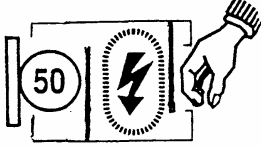
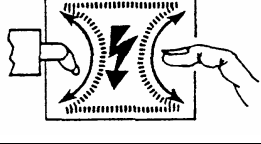

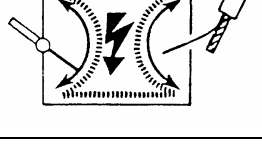
C.1a – FIRST NUMERAL			
Protection against ingress of solid objects			Protection of persons against access to hazardous parts with:
IP	Requirements	Example	
0	No protection		Non-protected
1	Full penetration of 50 mm diameter sphere not allowed. Contact with hazardous parts not permitted		Back of hand
2	Full penetration of 12,5 mm diameter sphere not allowed. The jointed test finger shall have adequate clearance from hazardous parts		Finger
3	The access probe of 2,5 mm diameter shall not penetrate		Tool
4	The access probe of 1,0 mm diameter shall not penetrate		Wire
5	Limited ingress of dust permitted (no harmful deposit)		Wire
6	Totally protected against ingress of dust		Wire

(continued)

Figure C.1 – IP Codes

C.1b – SECOND NUMERAL			
Protection against harmful ingress of water			Protection from water
IP	Prescriptions	Example	
0	No protection		Non-protected
1	Protected against vertically falling drops of water. Limited ingress permitted		Vertically dripping
2	Protected against vertically falling drops of water with enclosure tilted 15° from the vertical. Limited ingress permitted		Dripping up to 15° from the vertical
3	Protected against sprays to 60° from the vertical. Limited ingress permitted		Limited spraying
4	Protected against water splashed from all directions. Limited ingress permitted		Splashing from all directions
5	Protected against jets of water. Limited ingress permitted		Hosing jets from all directions
6	Protected against strong jets of water. Limited ingress permitted		Strong hosing jets from all directions
7	Protected against the effects of immersion between 15 cm and 1 m		Temporary immersion
8	Protected against long periods of immersion under pressure		Continuous immersion

(continued)

C.1c – ADDITIONAL LETTER (optional)			
IP	Requirements	Example	Protection of persons against access to hazardous parts with:
A For use with first numeral 0	Penetration of 50 mm diameter sphere up to barrier must not contact hazardous parts		Back of hand
B For use with first numerals 0 and 1	Test finger penetration to a maximum of 80 mm must not contact hazardous parts		Finger
C For use with first numerals 1 and 2	Wire of 2,5 mm diameter × 100 mm long must not contact hazardous parts when spherical stop face is partially entered		Tool
D For use with first numerals 2 and 3	Wire of 1,0 mm diameter × 100 mm long must not contact hazardous parts when spherical stop face is partially entered		Wire

A1 Annex D
(informative)

Examples of clamping units and relationship between clamping unit and connecting device

D.1 Clamping unit in a connecting device

For clarification of the definitions, see Figure D.8.

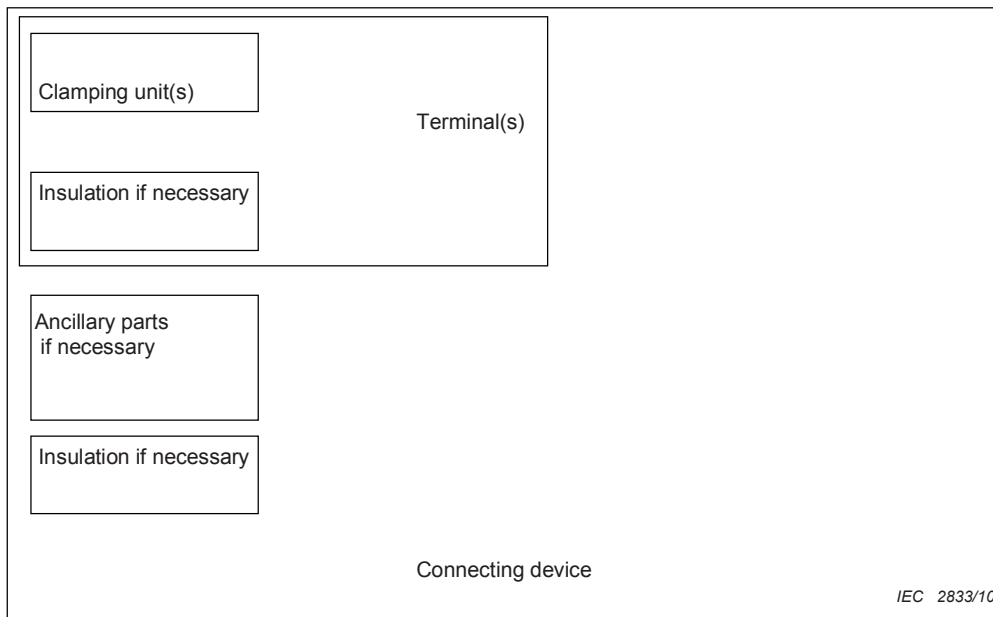
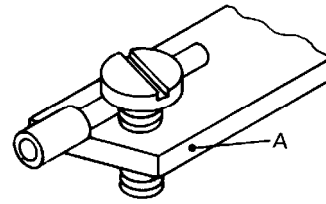
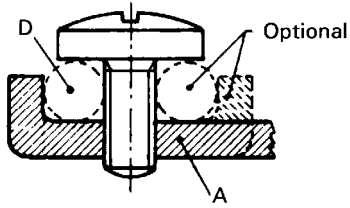
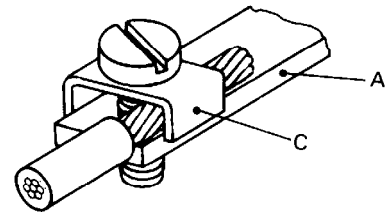
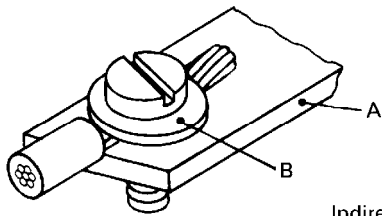
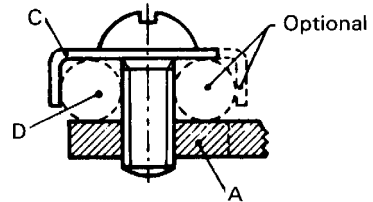
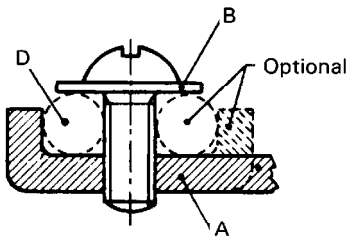


Figure D.8 – Clamping unit in a connecting device **A1**

D.2 Examples of clamping units



Direct pressure through screw head



Indirect pressure through intermediate part

IEC 687/96

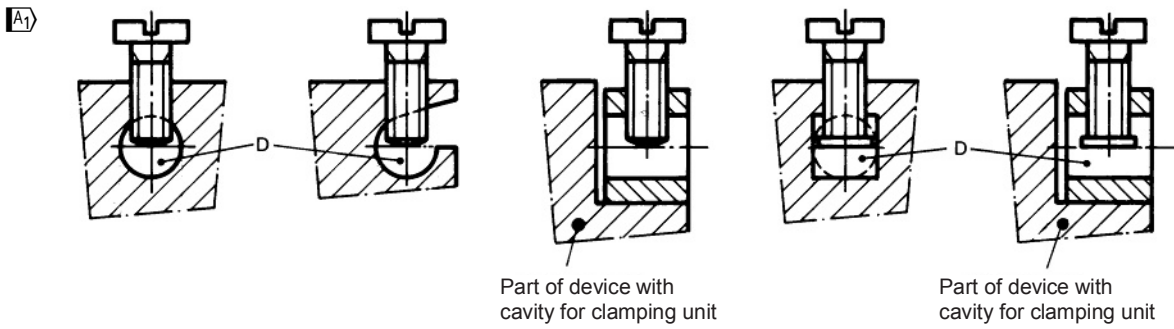
- A Fixed part
- B Washer or clamping plate
- C Anti-spread device
- D Conductor space

NOTE Examples shown here do not prohibit the conductor being divided either side of the screw.

Screw clamping unit

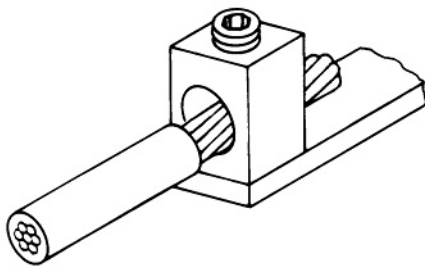
Screw-type clamping unit in which the conductor is clamped under the head of one or more screws. The clamping pressure may be applied directly by the head of the screw or through an intermediate part, such as a washer, clamping plate or anti-spread device.

Figure D.1 – Screw clamping units

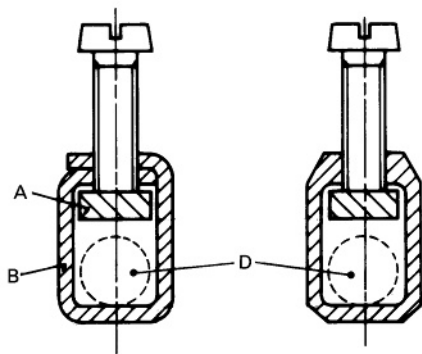
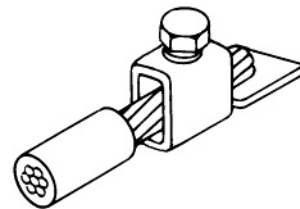


Clamping units without pressure plate

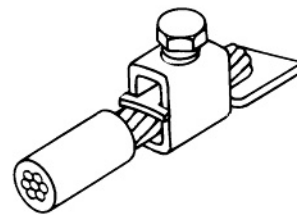
Clamping units with pressure plate



Clamping units with direct pressure



Clamping units with indirect pressure



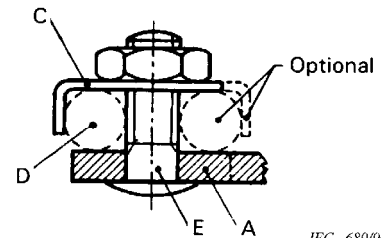
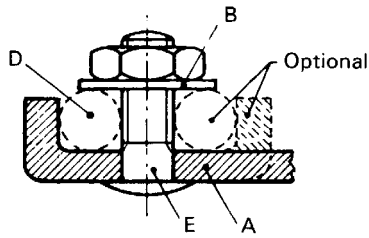
- A Fixed part
- B Body of the clamping unit
- D Conductor space

Pillar clamping unit

Screw-type clamping unit in which the conductor is inserted into a hole or cavity, where it is clamped under the shank of the screw or screws. The clamping pressure may be applied directly by the shank of the screw or through an intermediate part to which pressure is applied by the shank of the screw.

Figure D.2 – Pillar clamping units

A1



IEC 689/96

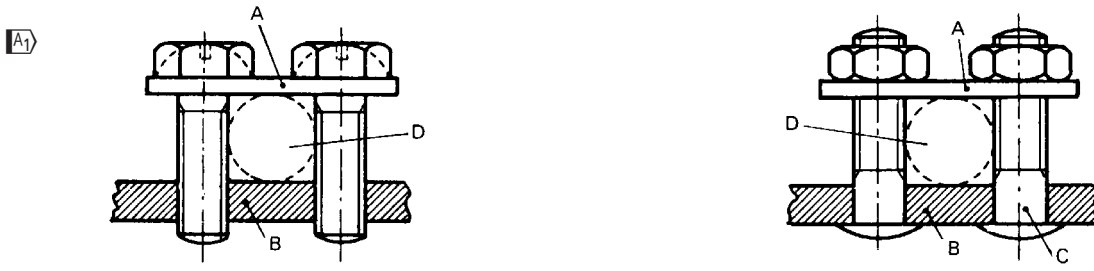
- A Fixed part
- B Washer or clamping plate
- C Anti-spread device
- D Conductor space
- E Stud

NOTE The part which retains the conductor in position may be of insulating material, provided the pressure necessary to clamp the conductor is not transmitted through the insulating material.

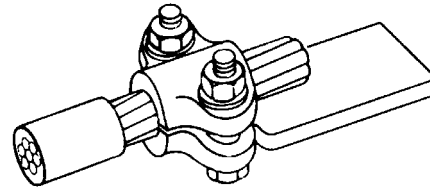
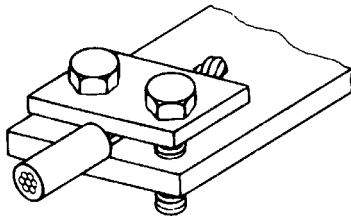
Stud clamping unit

Screw-type clamping unit in which the conductor is clamped under one or two nuts. The clamping pressure may be applied directly by a suitably shaped nut or through an intermediate part, such as a washer, clamping plate or anti-spread device.

Figure D.3 – Stud clamping units A1



- A Saddle
- B Fixed part
- C Stud
- D Conductor space



IEC 690/96

Saddle clamping unit

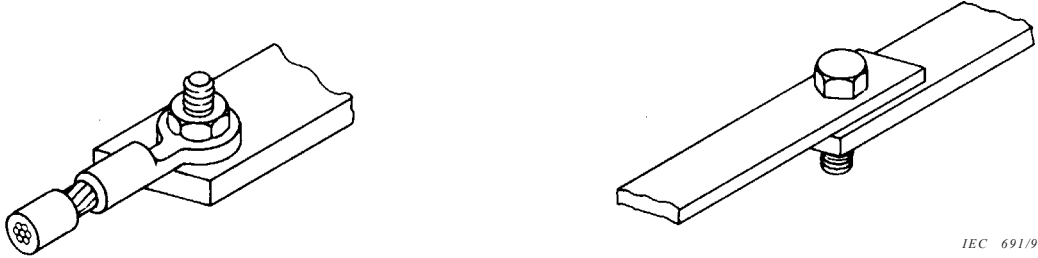
Screw-type clamping unit in which the conductor is clamped under a saddle by means of two or more screws or nuts.

Figure D.4 – Saddle terminals

A1

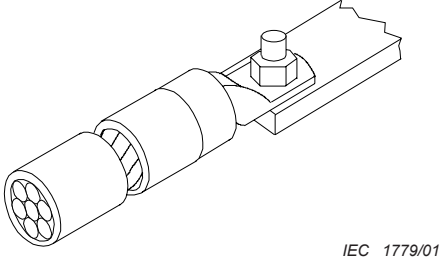


A Locking means
B Cable lug or bar
E Fixed part
F Stud



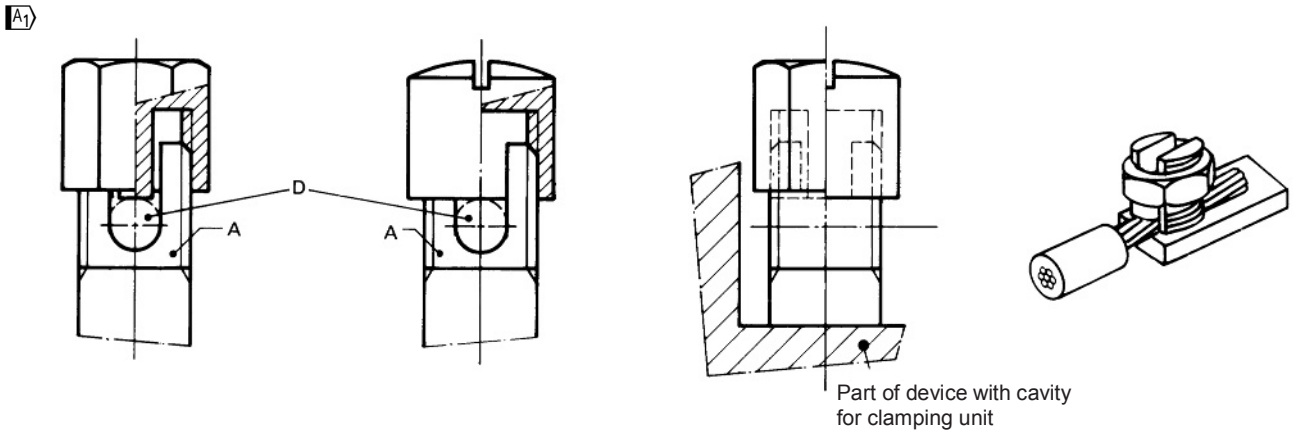
Lug clamping unit

Screw clamping unit or stud clamping unit designed for clamping a cable lug or bar by means of a screw or nut.



NOTE Examples of overall dimensions of cable lugs are given in Annex P.

Figure D.5 – Lug clamping units A1



IEC 2835/10

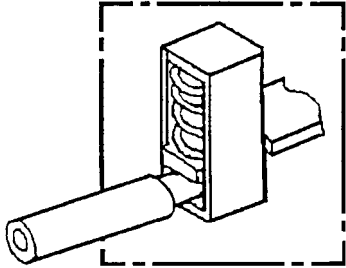
- A Fixed part
- D Conductor space

Mantle clamping unit

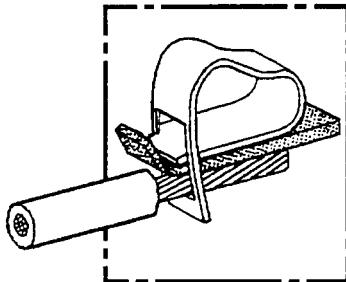
Screw-type clamping unit in which the conductor is clamped against the base of a slot in a threaded stud by means of a nut. The conductor is clamped against the base of the slot by a suitable shaped washer under the nut, by a central peg if the nut is a cap nut, or by equally effective means for transmitting the pressure from the nut to the conductor within the slot.

Figure D.6 – Mantle clamping units A1

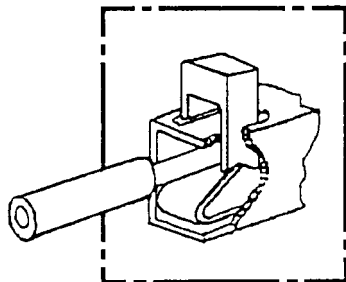
A1



Screwless-type clamping unit with indirect pressure



Screwless-type clamping unit with direct pressure



Screwless-type clamping unit with actuating element

IEC 2836/10

Figure D.7 – Screwless-type clamping units A1

Annex E (informative)

Description of a method for adjusting the load circuit

To adjust the load circuit to obtain the characteristics prescribed above, several methods may be applicable in practice. One of them is described below.

The principle is illustrated in Figure 8.

The oscillatory frequency f of the transient recovery voltage and the value of the factor γ are essentially determined by the natural frequency and the damping of the load circuit. Since these values are independent of the voltage and frequency applied to the circuit, the adjustment can be made by energizing the load circuit from an a.c. power supply, the voltage and frequency of which may be different from those of the supply source utilized for the test of the equipment. The circuit is interrupted at a current zero by a diode, and the oscillations of the recovery voltage are observed on the screen of a cathode-ray oscilloscope, the sweep of which is synchronized with the frequency of the power supply (see Figure E.1).

To permit reliable measurements to be made, the load circuit is energized by means of a high-frequency generator G giving a voltage suitable for the diode. The frequency of the generator is chosen equal to

- a) 2 kHz for test currents up to and including 1 000 A;
- b) 4 kHz for test currents higher than 1 000 A.

Connected in series with the generator are

- a dropping resistor having a resistance value R_a high with respect to the load circuit impedance ($R_a \geq 10 Z$, where $Z = \sqrt{R^2 + (\omega L)^2}$ and where $\omega = 2 \pi \cdot 2\,000 \text{ s}^{-1}$ or $2 \pi \cdot 4\,000 \text{ s}^{-1}$) for cases a) and b) respectively;
- an instantaneously blocking switching diode B; switching diodes commonly used in computers such as diffused junction silicon switching diodes of not over 1 A forward rated current are suitable for this application.

Due to the value of frequency of the generator G, the load circuit is practically purely inductive and, at the instant of current zero, the applied voltage across the load circuit will be at its peak value. To ensure that the components of the load circuit are suitable, it must be checked on the screen that the curve of the transient voltage at its initiation (point A in Figure E.1) has a practically horizontal tangent.

The actual value of the factor γ is the ratio U_{11}/U_{12} ; U_{11} is read on the screen, U_{12} is read between the ordinate of point A and the ordinate of the trace when the load circuit is no longer energized by the generator (see Figure E.1).

When observing the transient voltage in the load circuit with no resistor R_p or capacitor C_p in parallel, one reads on the screen the natural oscillatory frequency of the load circuit. Care should be taken that the capacitance of the oscilloscope or of its connecting leads does not influence the resonant frequency of the load circuit.

If that natural frequency exceeds the upper limit of the required value f , the suitable values of frequency and factor γ can be obtained by connecting in parallel capacitors C_p and resistors R_p of appropriate values. The resistors R_p shall be practically non-inductive.

Depending on the position of the earthing, the following two procedures for the adjustment of the load circuit are recommended.

- a) In the case of the earthed load star-point: each of the three phases of the load circuit shall be adjusted individually as shown in Figure 8a.
- b) In the case of the earthed supply star-point: one phase shall be connected in series with the other two phases in parallel as shown in Figure 8b. The adjustment shall be repeated by successively connecting to the high frequency generator the three phases in all possible combinations.

NOTE 1 A higher value of frequency obtained from the generator G facilitates the observation on the screen and improves the resolution.

NOTE 2 Other methods of determining frequency and factor γ (such as the impression of a square-wave current on the load circuit) may also be used.

NOTE 3 For connecting the load in star, either the R-end or either the X-end of the load could be connected, if the mode of shorting the load (earthed or floating) is not changed between the adjustment and the test.

Reason: Depending on which side of the load is shorted, different oscillatory frequencies occur.

NOTE 4 Care should also be taken that the leakage capacitance to earth of the high-frequency generator does not have any effect on the natural oscillatory frequency of the load circuit.

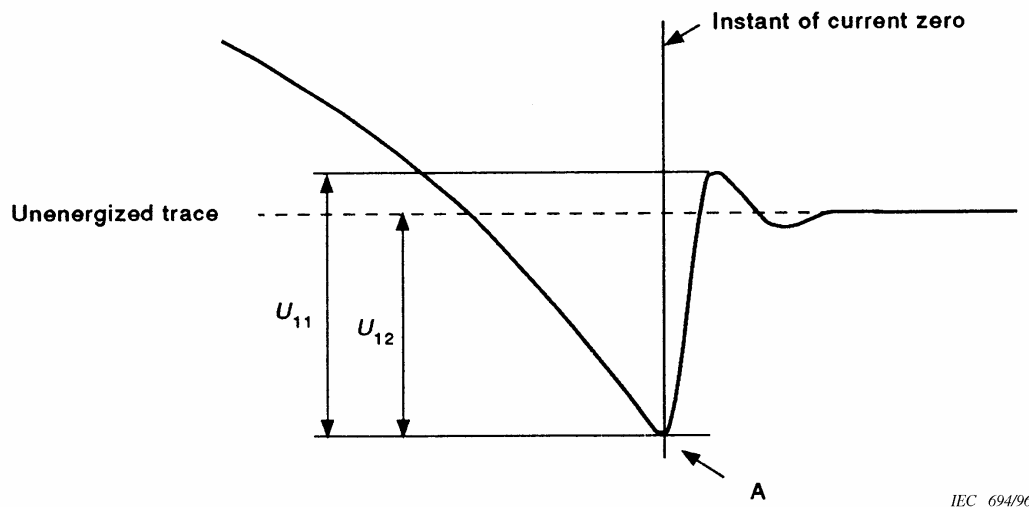


Figure E.1 – Determination of the actual value of the factor γ

Annex F (informative)

Determination of short-circuit power-factor or time-constant

There is no method by which the short-circuit power-factor or time-constant can be determined with precision, but for the purpose of this standard, the determination of the power-factor or the time-constant of the test circuit may be made by one of the following methods.

F.1 Determination of short-circuit power-factor

Method I – Determination from d.c. component

The angle φ may be determined from the curve of the d.c. component of the asymmetrical current wave between the instant of the short circuit and the instant of contact separation as follows:

- 1 To determine the time-constant L/R from the formula for the d.c. component.

The formula for the d.c. component is

$$i_d = I_{d0} e^{-Rt/L}$$

where

- i_d is the value of the d.c. component at the instant t ;
- I_{d0} is the value of the d.c. component at the instant taken as time origin;
- L/R is the time-constant of the circuit, in seconds;
- t is the time, in seconds, taken from the initial instant;
- e is the base of Napierian logarithms.

The time-constant L/R can be determined by

- a) measuring the value of I_{d0} at the instant of short-circuit and the value of i_d at another instant t before contact separation;
- b) determining the value of $e^{-Rt/L}$ by dividing i_d by I_{d0} ;
- c) determining the value of $-\chi$ corresponding to the ratio i_d/I_{d0} , from a table of values of $e^{-\chi}$;

The value χ then represents Rt/L , from which R/L is obtained.

- 2 To determine the angle φ from

$$\varphi = \arctan \frac{\omega L}{R}$$

where ω is 2π times the actual frequency.

This method should not be used when the currents are measured by current transformers, except if suitable precautions are taken to eliminate errors due to

- the time-constant of the transformer and its burden in relation to that of the primary circuit;
- magnetic saturation which can result from the transient flux conditions combined with possible remanence.

Method II – Determination with pilot generator

When a pilot generator is used on the same shaft as the test generator, the voltage of the pilot generator on the oscillogram may be compared in phase first with the voltage of the test generator and then with the current of the test generator.

The difference between the phase angles between pilot generator voltage and main generator voltage on the one hand and pilot generator voltage and test generator current on the other hand gives the phase angle between the voltage and current of the test generator, from which the power-factor can be determined.

F.2 Determination of short-circuit time-constant (oscillographic method)

The value of the time-constant is given by the abscissa corresponding to the ordinate $0,632 A_2$ of the ascending part of the curve of the oscillogram of calibration of the circuit (see Figure 14).

Annex G (informative)

Measurement of creepage distances and clearances

G.1 Basic principles

The widths X of grooves specified in examples 1 to 11 basically apply to all examples as a function of pollution as follows:

Pollution degree	Minimum values of widths X of grooves mm
1	0,25
2	1,0
3	1,5
4	2,5

For creepage distance across the fixed and moving insulation of contact carriers, no minimum value of X is required across insulated parts which move relative to each other (see Figure G.2).

If the associated clearance is less than 3 mm, the minimum groove width may be reduced to one-third of this clearance.

The methods of measuring creepage distances and clearances are indicated in the following examples 1 to 11. These examples do not differentiate between gaps and grooves or between types of insulation.

Furthermore:

- any corner is assumed to be bridged with an insulating link of X mm width moved into the most unfavourable position (see example 3),
- where the distance across the top of a groove is X mm or more, a creepage distance is measured along the contours of the grooves (see example 2);
- creepage distances and clearances measured between parts moving in relation to each other are measured when these parts are in their most unfavourable positions.

G.2 Use of ribs

Because of their influence on contamination and their better drying-out effect, ribs decrease considerably the formation of leakage current. Creepage distances can therefore be reduced to 0,8 of the required value provided the minimum height of the ribs is 2 mm.

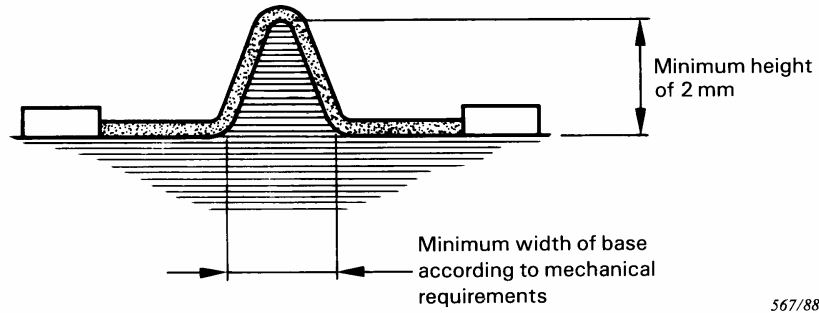
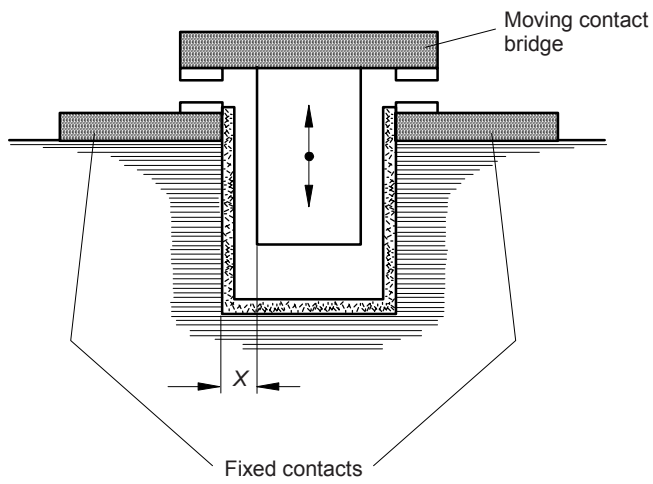


Figure G.1 – Measurement of ribs

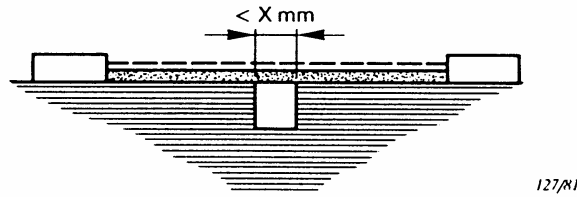


 Creepage distance

IEC 823/98

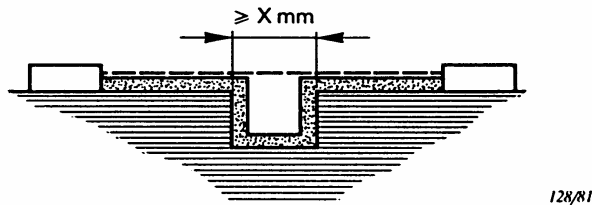
Figure G.2 – Creepage distance across the fixed and moving insulation of contact carriers

Example 1



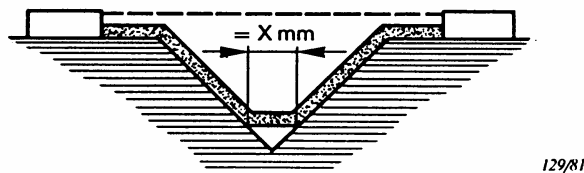
Condition: This creepage distance path includes a parallel- or converging-sided groove of any depth with a width less than X mm. Rule: Creepage distance and clearance are measured directly across the groove as shown.

Example 2



Condition: This creepage distance path includes a parallel-sided groove of any depth and equal to or more than X mm. Rule: Clearance is the "line-of-sight" distance. Creepage distance path follows the contour of the groove.

Example 3

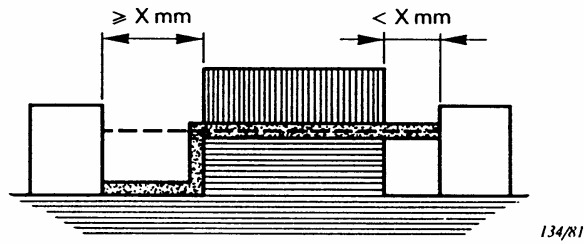


Condition: This creepage distance path includes a V-shaped groove with a width greater than X mm. Rule: Clearance is the "line-of-sight" distance. Creepage distance path follows the contour of the groove but "short-circuits" the bottom of the groove by X mm link.

----- Clearance

██████████ Creepage distance

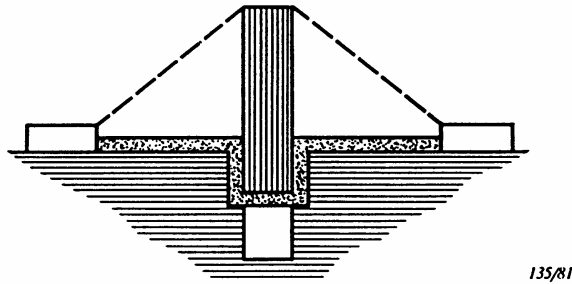
Example 7



Condition: This creepage distance path includes an uncemented joint with a groove on one side less than X mm wide and the groove on the other side equal to or more than X mm wide.

Rule: Clearance and creepage distance paths are as shown.

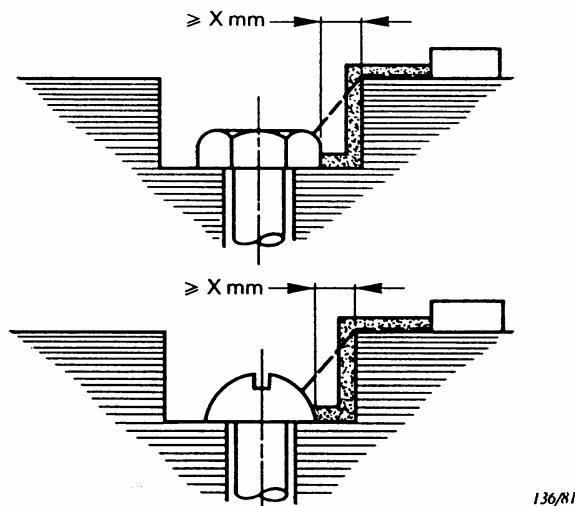
Example 8



Condition: Creepage distance through uncemented joint is less than creepage distance over barrier.

Rule: Clearance is the shortest direct air path over the top of the barrier.

Example 9



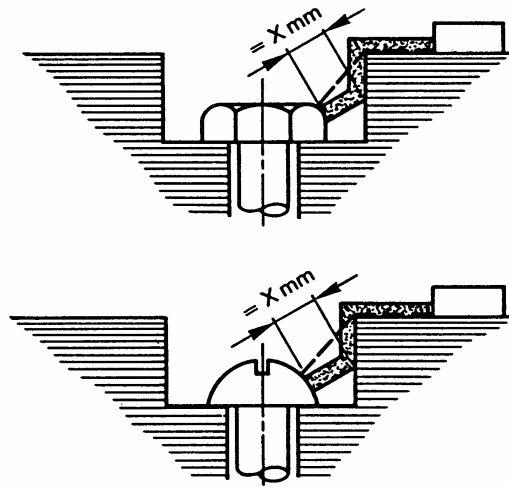
Condition: Gap between head of screw and wall of recess wide enough to be taken into account.

Rule: Clearance and creepage distance paths are as shown.

----- Clearance

██████████ Creepage distance

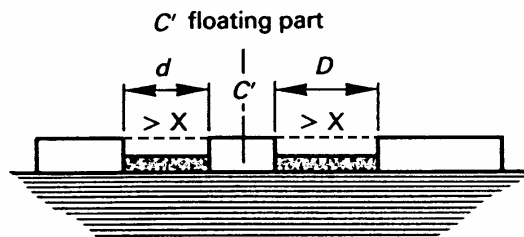
Example 10



137/81

Condition: Gap between head of screw and wall of recess too narrow to be taken into account. Rule: Measurement of creepage distance is from screw to wall when the distance is equal to X mm.

Example 11



IEC 695/96

Clearance is the distance $d + D$

Creepage distance is also $d + D$

----- Clearance

██████████ Creepage distance

Annex H (informative)

Correlation between the nominal voltage of the supply system and the rated impulse withstand voltage of equipment

INTRODUCTION

This annex is intended to give the necessary information concerning the choice of equipment for use in a circuit within an electrical system or part thereof.

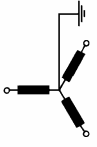
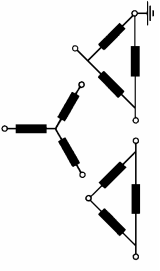


Table H.1 provides examples of the correlation between nominal supply system voltages and the corresponding rated impulse withstand voltage of equipment.

The values of rated impulse withstand voltage given in Table H.1 are based on the performance characteristics of surge arresters.

It should be recognized that control of overvoltages with respect to the values in Table H.1 can also be achieved by conditions in the supply system such as the existence of a suitable impedance or cable feed.

In such cases when the control of overvoltages is achieved by means other than surge arresters, guidance for the correlation between the nominal supply system voltage and the equipment rated impulse withstand voltage is given in IEC 60364-4-443.

Table H.1 – Correspondence between the nominal voltage of the supply system and the equipment rated impulse withstand voltage, in case of overvoltage protection by surge-arresters according to IEC 60099-1

Maximum value of rated operational voltage to earth a.c. r.m.s. or d.c. V	Nominal voltage of the supply system (≤ rated insulation voltage of the equipment)				Preferred values of rated impulse withstand voltage (1,2/50 μs) at 2 000 m kV			
	 a.c. r.m.s. V	 a.c. r.m.s. V	 a.c. r.m.s. or d.c. V	 a.c. r.m.s. or d.c. V	IV Origin of installation (service entrance) level	III Distribution circuit level	II Load (appliance, equipment) level	I Specially protected level
50	–	–	12,5, 24, 25 30, 42, 48	60-30	1,5	0,8	0,5	0,33
100	66/115	66	60	–	2,5	1,5	0,8	0,5
150	120/208 127/220	115, 120 127	110, 120	220-110, 240-120	4	2,5	1,5	0,8
300	220/380, 230/400 240/415, 260/440 277/480	220, 230 240, 260 277	220	440-220	6	4	2,5	1,5
600	347/600, 380/660 400/690, 415/720 480/830	347, 380, 400 415, 440, 480 500, 577, 600	480	960-480	8	6	4	2,5
1 000	–	660 690, 720 830, 1 000	1 000	–	12	8	6	4

Annex J (informative)

Items subject to agreement between manufacturer and user

NOTE For the purpose of this annex:

- “agreement” is used in a very wide sense;
- “user” includes testing stations.

Clause or subclause number in this standard	Item
2.6.4	Special test.
6.1	See Annex B for non-standard conditions in service.
6.1.1	Equipment intended to be used in ambient air temperature above or below the range $-5\text{ }^{\circ}\text{C}$ to $+40\text{ }^{\circ}\text{C}$. See note.
6.1.2	Equipment intended to be used at higher altitudes than 2 000 m. See note.
6.2	Conditions during transport and storage, if different from those specified in this subclause.
7.2.1.2	Operating limits of latched equipment.
7.2.2.1 (Table 2)	Use in service of connected conductors of cross-section significantly smaller than those listed in Tables 9 and 10.
7.2.2.2 (Table 3)	Information to be given by the manufacturer on temperature-rise limits of resistors for enclosures.
7.2.2.6	Operating conditions of pulse-operated coils (to be defined by the manufacturer).
7.2.2.8	Compliance with IEC 60085 and/or IEC 60216 for insulating materials (to be demonstrated by the manufacturer).
8.1.1	Special tests.
8.1.4	Sampling tests.
8.2.4.3	Flexion test on flat copper conductors.
8.3.2.1	To increase the degree of severity of a test for convenience of testing. Smallest enclosure for testing equipment intended for use in more than one type or size of enclosure.
8.3.2.2.2	More severe test conditions (with the manufacturer's agreement). Acceptance of equipment tested at 50 Hz for use at 60 Hz (or vice versa). See note 2 of Table 8.
8.3.2.2.3	Increasing the upper limit of the power-frequency recovery voltage (subject to manufacturer's agreement). See note 3.
8.3.3.3.4 Temperature-rise test of the main circuit	Testing d.c. rated equipment with an a.c. supply (subject to manufacturer's agreement). Testing multipole equipment with single-phase current. Test connection arrangement for values of test current higher than 3 150 A. Use of conductors of smaller cross-section than those specified in Tables 9, 10 and 11 (subject to manufacturer's agreement). See note 2 of note to Tables 9, 10 and 11.
8.3.3.4.1	Dielectric tests at power-frequency or d.c. voltage (subject to manufacturer's agreement).
8.3.3.5.2 (note 3) 8.3.4.1.2 (note 3)	Conditions of acceptance of a prospective fault current $< 1\ 500\ \text{A}$ (with manufacturer's agreement). b) In the test circuit for short-circuit testing, shunting the air-cored reactor by resistors different from those defined in item b); c) Diagram of the test circuit for short-circuit testing, if different from that of Figures 9, 10, 11 or 12.
8.3.4.3	Increase of the value of the test current for I_{CW} Verification of ability to carry I_{CW} on a.c. current for d.c. rated equipment.

A2 Annex K (normative)

Procedure to determine reliability data for electromechanical devices used in functional safety applications

K.1 General

K.1.1 Overview

Provision of these data is optional, at the discretion of the manufacturer.

K.1.2 Scope and object

This annex specifies procedures for the provision of specific data characterising the performance of electromechanical devices in functional safety applications for high demand or continuous mode of operation as defined in IEC 61508.

This method is not applicable to electronic parts.

NOTE 1 Non electromechanical devices should refer to IEC 61508-6 for guidance on the calculation of the probability of failure ratio. Failure rate of electronic parts should be evaluated with reliability data handbook for example IEC/TR 62380.

NOTE 2 The use of reliability data according to this annex is not appropriate for low demand applications. Low demand mode of operation is under consideration.

These data are required by functional safety standards including IEC 61508 series, IEC 62061, ISO 13849-1.

The product standard shall define the function(s) and the failure modes that will be considered.

K.1.3 General requirements

The specific data for functional safety shall be obtained with this procedure.

The procedure is based on statistical analysis of test results in order to generate reliability data.

The requirements of this annex may be further specified by the relevant product standard in terms of relevant tests, failure modes and their ratios.

The confidence level related to failure rate calculation during the useful life of the device shall be at least 60 %.

NOTE The parameters associated with the reliability data are chosen for being consistent with those of other products also used in functional safety applications.

The statistical data obtained according to this annex are valid only during the useful life of the device.

In this annex, to keep statistical consistency, the term "time" can refer to the number of operation cycles.

This annex does not consider replacement of parts of the devices during test and application. **A2**

A₂ K.2 Terms, definitions and symbols

K.2.1 Terms and definitions

K.2.1.1

reliability (performance)

ability of an item to perform a required function under given conditions for a given time interval

[191-02-06, modified]

K.2.1.2

useful life

under given conditions, the time interval beginning at a given instant of time, and ending when the failure rate becomes unacceptable

NOTE The useful life may be expressed in number of operations.

K.2.1.3

constant failure rate period

that period, if any, in the life of a non-repaired item during which the failure rate is approximately constant

[191-10-09]

K.2.1.4

overall lifetime

lifetime of the device which should not be exceeded in order to maintain the validity of the estimated failure rates due to random hardware failures

NOTE 1 Overall lifetime covers also periods of non-use e.g. storage. The overall lifetime is expressed in number of years.

NOTE 2 It corresponds to T_1 according to IEC 62061 and to T_M according to ISO 13849-1.

K.2.1.5

censoring

termination of the test after either a certain number of failures or a certain time at which there are still items functioning

K.2.1.6

suspension

situation in which an item that either has not failed or has not failed in the manner under investigation, i.e. failed due to some other cause, is removed from test

K.2.1.7

no-make-break-current utilization

conditions in which the switching device makes and breaks without load

K.2.1.8

time to failure

operating time accumulated from the first use, or from restoration, until failure

NOTE The time to failure may be expressed in number of operations.

K.2.2 Symbols

n number of samples tested

r number of failures **A₂**

t	number of operating cycles
η	Weibull characteristic life or scale parameter
β	Weibull shape parameter
c	number of operations per hour
λ_u	assessed failure rate (upper limit) at confidence level of 60 % expressed in per operation
λ	failure rate expressed in per hour
λ_D	dangerous failure rate expressed in per hour
r^2	coefficient of determination

K.3 Method based on durability test results

K.3.1 General method

In order to address random hardware failure the method is based on results given by continuous monitoring of the devices under the appropriate durability test.

K.3.2 Test requirements

The test environment shall be in accordance with Clause 6 and any related requirements from the relevant product standard.

Mechanical durability shall be determined in accordance with 7.2.4.3.1. For the no-make-break-current utilization the mechanical durability is applicable.

Electrical durability shall be determined in accordance with 7.2.4.3.2 using the utilization category defined by the product standard or as stated by the manufacturer.

K.3.3 Number of samples

The number of samples to be tested has to be chosen as a matter of engineering judgment according to IEC 61649 and IEC 60300-3-5.

NOTE This determination of number of samples should take into account the statistical method (see Clause 4 of IEC 61649:2008) and the uncertainty of the confidence level of the reliability data to be obtained.

K.3.4 Characterization of a failure mode

If not otherwise specified by the relevant product standard or the manufacturer, the occurrence of one or more of the failure modes listed in Table K.1 shall lead to the conclusion of the test for that sample. These data shall be recorded.

NOTE The attainment of the specified number of operating cycles given by the manufacturer may also lead to the conclusion of the test (censoring or suspension of tests). Nevertheless a sufficient number of failures should be recorded in order to enable the statistical analysis.

Table K.1 – Failure modes of devices

Failure modes	Characteristics for a switching contact
Failure to open	current remaining in one or more poles after the time for normal opening operation
Failure to close	no current in one or more poles after the normal time to close
Insulation failure	insulation failure between two poles or between any pole and any adjacent conductive parts that result in the loss of a safety function

A2 K.3.5 Weibull modelling**K.3.5.1 Evaluation of data**

For the determination of the Weibull characteristic life or scale parameter, the Weibull shape parameter and the failure rates proven statistical software or spreadsheet solutions are available. The following describe the necessary steps.

K.3.5.2 Modelling method

The reliability data are obtained by modelling the test result data with the Weibull distribution according to IEC 61649.

The median rank regression (MRR) shall be used if the number of failures is equal or less than 20. If the number of failures is greater than 10, the maximum likelihood estimation (MLE) method can be used to get the point estimates of the distribution parameters β and η . The Kolmogorov-Smirnov goodness-of-fit test (H) with the Fisher distribution (F_γ) at $\gamma = 60\%$ shall be checked with Equation (K.1) to validate the result data:

$$H \geq F_\gamma(2\lfloor(r-1)/2\rfloor, 2\lfloor r/2\rfloor) \quad (\text{K.1})$$

where the symbol $\lfloor x \rfloor$ is used to denote the greatest integer less than or equal to x .

NOTE 1 IEC 61649 provides details and examples of calculation.

NOTE 2 In the case the numbers of failures is between 10 and 20 it is advisable to evaluate with the MRR and the MLE. The more severe result should be taken.

If a test is terminated at a specified time, T , before all items have failed, then the data are said to be time censored. An item on test that has not failed by the failure mode in question is a suspension. Normally, suspensions are included in the analysis by adjustment of the ranking. However this Annex provides a method for the estimation of Weibull parameters that is simplified by the omission of suspensions. Further discussion of censoring and suspension is covered in IEC 60300-3-5 and associated computations are covered by IEC 61649.

NOTE 3 IEC 61649 give further guidance for the evaluation with a spreadsheet.

K.3.5.3 Median rank regression

Median Rank Regression (MRR) is the preferred method for estimating the parameters of the distribution using linear regression techniques with the variables being the median rank and operation cycle.

If a table of median ranks and a means to calculate median ranks using the Beta distribution is not available, Bernard's approximation, Equation (K.2), may be used where:

$$F_i = \frac{(i-0,3)}{(N+0,4)} \times 100\% \quad (\text{K.2})$$

where N is the sample size and i is the ranked position of the data item of interest.

NOTE 1 This equation is mostly used for $N \leq 30$; for $N > 30$ the correction of the cumulative frequency can be neglected: $F_i = (i/N) \times 100\%$. ⁴²

- ^{A2} Small sample size makes it difficult to gauge the goodness-of-fit. The coefficient of determination is the most commonly used for checking the Weibull distribution. This shall be calculated using Equation (K.3):

$$r^2 = \frac{\left(\sum_{i=1}^n x_i y_i - \frac{\sum_{i=1}^n x_i \sum_{i=1}^n y_i}{n} \right)^2}{\left(\sum_{i=1}^n x_i^2 - n(\bar{x})^2 \right) \left(\sum_{i=1}^n y_i^2 - n(\bar{y})^2 \right)} \quad (\text{K.3})$$

where (x_i) and (y_i) , $i=[1..n]$ are the median ranks and the failure time respectively.

r^2 is the proportion of variation in the data that can be explained by the Weibull hypothesis. The closer this is to 1, the better the data are fitted to a Weibull distribution; the closer to 0 indicates a poor fit.

The following are the steps to plot data sets.

- first, rank the times in operation cycle from earliest to latest;
- use Bernard's approximation (Equation (K.2)) to calculate the median ranks;
- plot the failure times (x) versus the median ranks $F_i(y)$ on 1×1 Weibull paper or log-log paper to derive x_{ln} and y_{ln} ;
- calculate a straight regression function to get the equation for the line

$$y_{ln} = \hat{\beta} x_{ln} + b \quad (\text{K.4})$$

- calculate

$$\hat{\eta} = e^{\left(\frac{b}{\hat{\beta}} \right)}; \quad (\text{K.5})$$

- plot the regression line on the graph to verify the fit.

NOTE 2 Normally for an electromechanical devices, $\hat{\beta}$ is greater or equal to 1.

K.3.6 Useful life and upper limit of failure rate

K.3.6.1 Numerical method

Assuming a constant failure rate, the useful life is determined as the lower confidence level of the number of cycles by which 10 % of the device population will have failed ($B_{10|LowerLimit}$).

For 20 or fewer data points, with or without censoring times, the Weibull parameters $\hat{\beta}$ and $\hat{\eta}$ obtained with Median Rank Regression (MRR) in K.3.5.3 shall be used. ^{A2}

K.3.6.2 Point estimate of the fractile (10 %) of the time to failure

Compute \hat{B}_{10} using Equation (K.6), the point estimate of B_{10} , the time by which 10 % of the population will have failed:

$$\hat{B}_{10} = \hat{\eta} \left[\ln \left(\frac{1}{0,9} \right) \right]^{1/\hat{\beta}} \quad (\text{K.6})$$

K.3.6.3 Useful life

Compute the lower $(1 - \gamma)100$ % confidence level of B_{10} using Equations (K.7), (K.8), (K.9) and (K.10):

$$h_1 = \ln [-\ln(0,9)] \quad (\text{K.7})$$

$$\delta_1 = \frac{-A_6 x^2 - r h_1 + x \sqrt{(A_6^2 - A_4 A_5) x^2 + r A_4 + 2 r h_1 A_6 + r A_5 h_1^2}}{r - x^2 A_5} \quad (\text{K.8})$$

where

$$x = u_\gamma$$

is the γ fractile of the normal distribution. Unless otherwise specified by the manufacturer, a 60 % lower confidence level shall be used (hence $\gamma = 0,4$ and $u_\gamma = 0,2533$).

A_4 , A_5 and A_6

are computed as follows, using the ratio $q = r/n$:

$$A_4 = 0,49q - 0,134 + 0,622 q^{-1};$$

$$A_5 = 0,2445 (1,78 - q) (2,25 + q);$$

$$A_6 = 0,029 - 1,083 \ln (1,325q).$$

NOTE For further reference, see 10.4 and 10.5 of IEC 61649:2008.

$$Q_1 = e^{\left(-\frac{\delta_1 + h_1}{\hat{\beta}} \right)} \quad (\text{K.9})$$

$$B_{10|\text{LowerLimit}} = Q_1 \hat{B}_{10} \quad (\text{K.10})$$

This value of $B_{10|\text{LowerLimit}}$ is considered as the useful life.

K.3.6.4 Upper limit of failure rate

The upper limit of failure rate per operation is given by the following Equation (K.11):

$$\lambda_u = \frac{-\ln(0,9)}{B_{10|\text{LowerLimit}}} \approx \frac{1}{10 \times B_{10|\text{LowerLimit}}} \quad (\text{K.11}) \quad \text{A2}$$

A2) K.3.7 Reliability data

The resulting reliability data from the previous evaluations are:

- failure rate per operation: λ_u .
- useful life value = $B_{10|lowerLimit}$

For a given application where the number of operation per hour c is lower than the maximum switching rate, the failure rate, λ , expressed in “per hour”, is given by the failure rate, expressed in “per operation”, λ_u , multiplied by c :

$$\lambda = \lambda_u \times c \quad (\text{K.12})$$

The value for F (ratio between dangerous failures and total failures) for each of the failure modes of Table K.1 is defined by the relevant product standard. When this is available and relevant it shall be used for the evaluation of the dangerous failure rate.

If it can be shown that it is not relevant due to device design characteristics, the manufacturer can determine the value for F by analysis and the evaluation of the statistical data of the failure modes obtained during the tests. In this case the minimum percentage allowed for the value of F shall be 20 %.

In the case where no data are available in the product standard and it is not possible or practicable by these methods to determine the value for F , 50 % of the failures should be selected.

$$\lambda_D = \lambda \times F \quad (\text{K.13})$$

NOTE B_{10} values can be used to provide B_{10D} values:

$$B_{10D} = \frac{B_{10|LowerLimit}}{F}$$

K.4 Data information

A set of reliability data of the product shall include a combination of the following characteristics where relevant:

- failure rate per operation λ_u (see K.3.7);
- useful life (see K.3.6.3);
- confidence level if different from 60 %;
- no-make-break-current or utilization category;
- maximum switching rate;
- maximum voltage if different from U_e ;
- maximum operational current for the specified utilization category, if different from I_e ;
- overall life time = 20 years unless otherwise specified by the manufacturer;

NOTE The overall life time of 20 years is generally used as a statistical reference for reliability analysis.

- environment conditions if different from the normal conditions.

Examples are given in K.5.1 to K.5.3. **A2)**

A2 K.5 Example

K.5.1 Test results

A total of 15 devices ($n = 15$) have been tested at the same time until all have failed. The 15 times to failure ($r = 15$) are ordered with i in the Table K.2.

Table K.2 – Example of 15 sorted ascending times to failure of contactors

<i>i</i>	Cycles t_i
1	1 000 000
2	1 250 000
3	1 400 000
4	1 550 000
5	1 650 000
6	1 750 000
7	1 850 000
8	1 950 000
9	2 050 000
10	2 150 000
11	2 280 000
12	2 420 000
13	2 500 000
14	2 700 000
15	2 800 000

K.5.2 Weibull distribution and median rank regression

The calculation of median ranks gives the following results: **A2**

Table K.3 – Example median rank calculation

<i>i</i>	Cycles t_i	Median ranks
1	1 000 000	4,5 %
2	1 250 000	11,0 %
3	1 400 000	17,5 %
4	1 550 000	24,0 %
5	1 650 000	30,5 %
6	1 750 000	37,0 %
7	1 850 000	43,5 %
8	1 950 000	50,0 %
9	2 050 000	56,5 %
10	2 150 000	63,0 %
11	2 280 000	69,5 %
12	2 420 000	76,0 %
13	2 500 000	82,5 %
14	2 700 000	89,0 %
15	2 800 000	95,5 %

The coefficient of determination $r^2 = 0,998$. This value, close to 1, indicates a good fit to a Weibull distribution.

The linear regression with two natural logarithm scales gives: $y = 3,908 x - 57$.

From this equation, the distribution parameters can be derived: $\hat{\beta} = 3,908$ and $\hat{\eta} = 2\,149\,131$.

The fitting result obtained by MRR gives the assurance of a good Weibull distribution (see Figure K.1).

K.5.3 Useful life and failure rate

To calculate the lower confidence level of the number of cycles by which 10 % of the contactors will have failed, this example follows K.3.5.

The point estimate $\hat{B}_{10} = 1\,212\,879$

The factor $Q_1 = 0,960\,1$ and $B_{10|lowerLimit} = 1\,164\,541$

Finally, the upper limit of the failure rate $\lambda_U = 9,05 \times 10^{-8}$

The result of this numerical method is illustrated by the Figure K.1. 

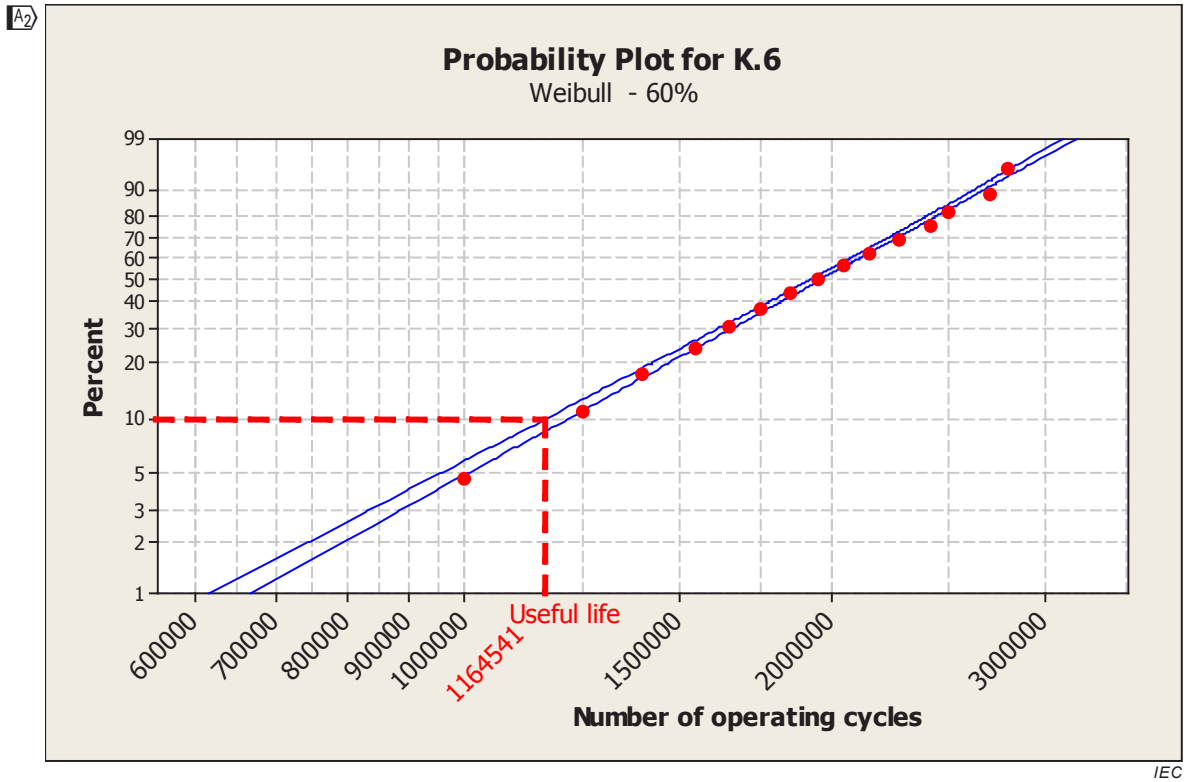


Figure K.1 – Plot of Weibull median rank regression $\overline{A_2}$

IEC

Annex L (normative)

Terminal marking and distinctive number

L.1 General

The purpose of identifying terminals of switching devices is to provide information regarding the function of each terminal, or its location with respect to other terminals, or for other use.

The terminal marking applies to switching devices as delivered by the manufacturer, and shall be free from ambiguity, that is each marking shall occur only once. However, two terminals connected by construction may have the same marking.

The marking of different terminals of a circuit element shall indicate that they are in the same current path.

The marking of the terminals of an impedance shall always be alphanumerical and have one or two letters indicating the function, followed by a number. The letters shall be capitals (upper case) Roman characters only and the numerals shall be Arabic numerals.

For contact element terminals, one of the terminals is marked with an odd number, the other terminals of the same contact element are marked with the immediately higher even numbers.

If incoming and outgoing terminals of an element are to be specifically identified as such, then the lower number shall be chosen for the incoming terminal (thus incoming 11 and outgoing 12, incoming A1 and outgoing A2).

NOTE 1 The equipment dealt with in the following Clauses L.2 and L.3 is also illustrated by graphical symbols in accordance with IEC 60617-7. It should be understood, however, that these symbols are not intended to be used for terminal marking on the equipment.

NOTE 2 The position of the terminals shown in the illustrations is not intended to convey any information on the actual position of the terminals on the device itself.

For low-voltage switchgear not covered by the following clauses or examples, a manufacturer may choose a suitable terminal marking following the principles of this clause.

L.2 Terminal marking of impedances (alphanumerical)

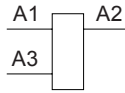
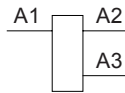
L.2.1 Coils

L.2.1.1 The two terminals of a coil for an electromagnetically operated drive shall be marked by A1 and A2.

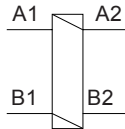


L.2.1.2 For a coil with tapings, the terminals of the tapings are marked in sequential order A3, A4, etc.

Examples:



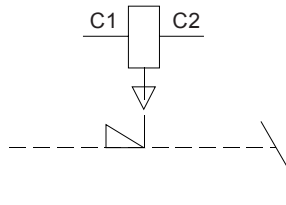
L.2.1.3 For a coil having two windings, the terminals of the first winding shall be marked A1, A2 and of the second winding B1, B2.



L.2.2 Electromagnetic releases

L.2.2.1 Shunt release

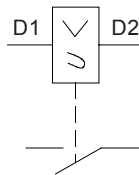
The two terminals of a shunt release shall be marked C1 and C2.



NOTE For a device with two shunt releases (for example with different ratings), the terminal of the second release should be marked preferably C3 and C4.

L.2.2.2 Under-voltage release

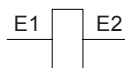
The two terminals of a coil intended to be used exclusively as an under-voltage release shall be marked D1 and D2.



NOTE For a device with two shunt releases (for example with different ratings), the terminal of the second release should be marked preferably D3 and D4.

L.2.3 Interlocking electromagnets

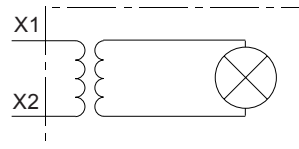
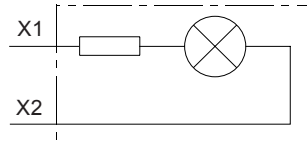
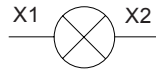
The two terminals of an interlocking electromagnet shall be marked E1 and E2.



L.2.4 Indicating light devices

The two terminals of an indicating light device shall be marked X1 and X2.

Examples:



NOTE The term "indicating light devices" includes any incorporated resistor or transformer.

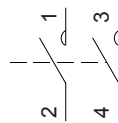
L.3 Terminal marking of contact elements for switching devices with two positions (numerical)

L.3.1 Contact elements for main circuits (main contact elements)

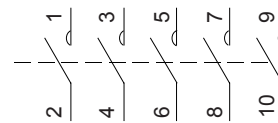
The terminals of main switching elements are identified by single figure numbers.

Each terminal marked by an odd number is associated with that terminal marked by the following even number.

Examples:



Two main contact elements



Five main contact elements

When a switching device has more than five main contact elements, alphanumerical marking shall be chosen, according to IEC 60445.

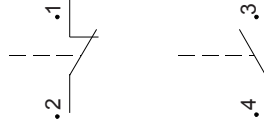
L.3.2 Contact elements for auxiliary circuit (auxiliary contact elements)

The terminals of auxiliary contact elements are identified by two-figure numbers:

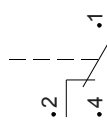
- the figure of the units is a function number;
- the figure of the tens is a sequence number.

L.3.2.1 Function number

L.3.2.1.1 Function numbers 1 and 2 are allocated to break-contact elements and functions 3 and 4 to make-contact elements (break-contact element, make-contact element as defined in IEC 60050(441)).



The terminals of change-over contact elements are marked by the function numbers 1, 2 and 4.



L.3.2.1.2 Auxiliary contact elements with special functions, such as time-delayed auxiliary contact elements, are identified by the function numbers 5 and 6, 7 and 8 for break-contact elements and make-contact elements respectively.

Examples:

Break-contact delayed on closing



Make-contact delayed on closing



The terminals of change-over contact elements with special functions are marked by the function numbers 5, 6 and 8.

Example:

Change-over contact delayed
in both directions

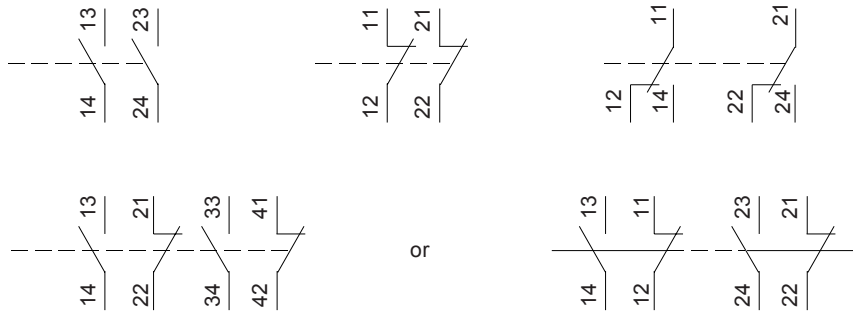


L.3.2.2 Sequence number

Terminals belonging to the same contact elements are marked with the same sequence numbers.

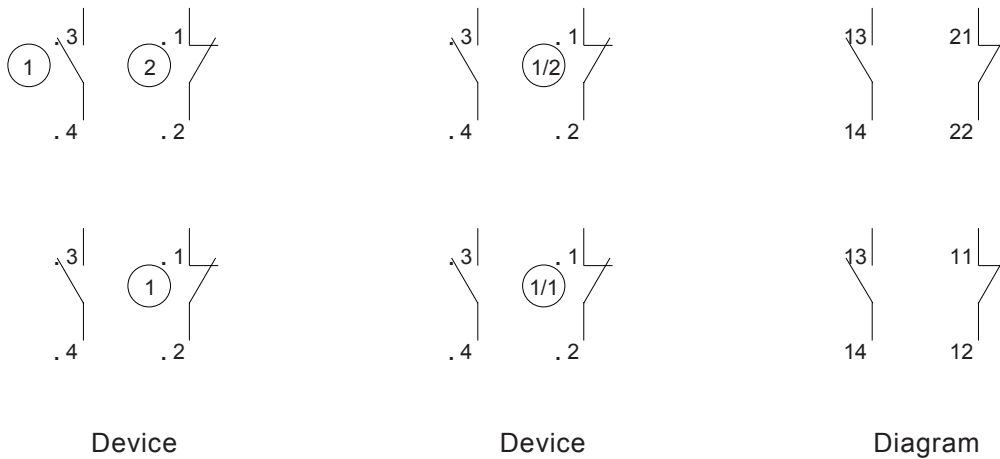
All contact elements having the same function shall have different sequence numbers.

Examples:



L.3.2.2.2 The sequence number may be omitted from the terminals only if additional information provided by the manufacturer or the user clearly gives such a number.

Examples:

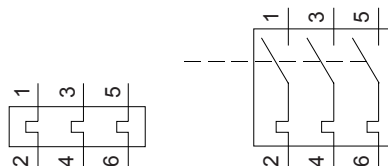


NOTE The dots shown in the examples of L.3.2 are merely used to show the relationship and do not need to be used in practice.

L.4 Terminal marking of overload protection devices

The terminals of the main circuits of an overload protection device are identified in the same manner as the terminals of main switching elements.

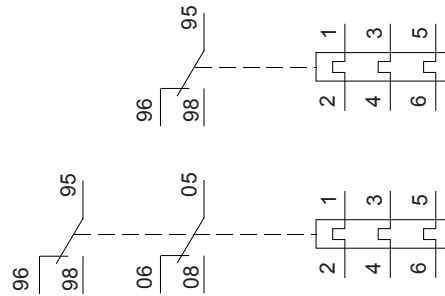
Examples:



The terminals of an auxiliary contact element of an overload protection device are identified in the same manner as the terminals of a special contact element (see L.3.2.1.2) but with the sequence number 9.

If a second sequence number is required, it should be the number 0.

Examples:

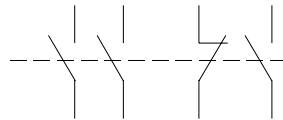


L.5 Distinctive number

A device with a fixed number of make-contact elements and break-contact elements may be allocated a two-figure distinctive number.

The first figure indicates the number of make-contact elements and the second figure the number of break-contact elements.

Distinctive number 31



L.6 Marking of terminals for external associated electronic circuit components, contacts and complete devices

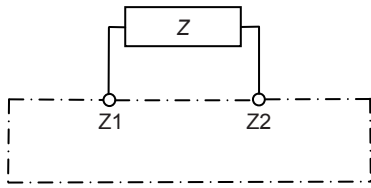
L.6.1 Marking of terminals for external associated electronic circuit components and contacts

L.6.1.1 General

Terminals for external associated electronic circuit components and contacts shall be marked in the following alphanumerical manner.

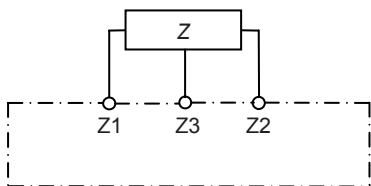
L.6.1.2 Marking of terminals for external associated impedances

L.6.1.2.1 The two terminals for an external associated impedance Z shall be marked $Z1$ and $Z2$.



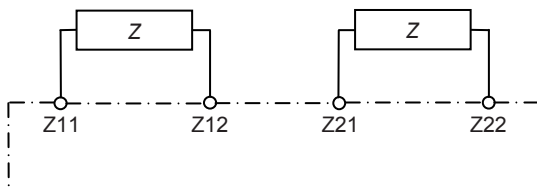
EXAMPLE

L.6.1.2.2 For an impedance Z with tapings, the terminals for the tapings shall be marked in sequential order $Z3$, $Z4$, etc.



EXAMPLE

L.6.1.2.3 In case of more than one impedance, the terminals shall be marked by using the letter Z and two-figure numbers, the first figure being a sequence number.

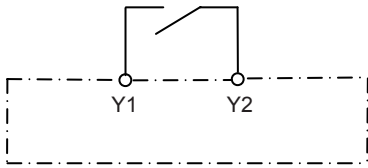


EXAMPLE

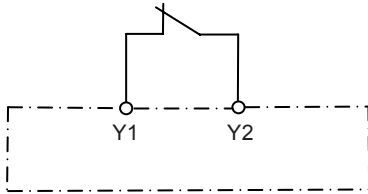
L.6.1.2.4 For particular application to a control system associated with thermistors for built-in thermal protection of rotating electrical machines, the rules for terminal marking $T1$, $T2$, ... or $1T1$, $2T2$, ... and $2T1$, $2T2$, ... are given in IEC 60947-8.

L.6.1.3 Marking of terminals for external associated contacts

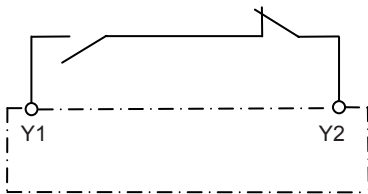
L.6.1.3.1 The two terminals for an external associated make or break contact or a group of contacts shall be marked $Y1$ and $Y2$.



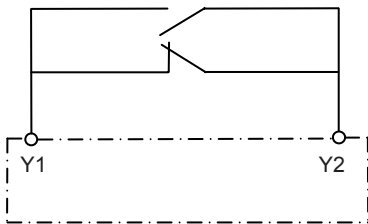
EXAMPLE 1



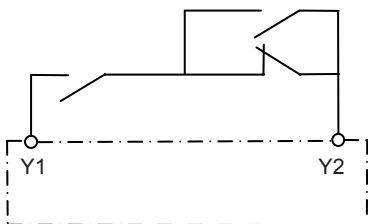
EXAMPLE 2



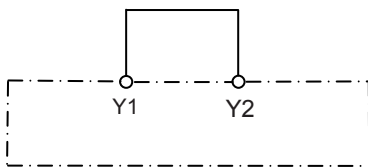
EXAMPLE 3



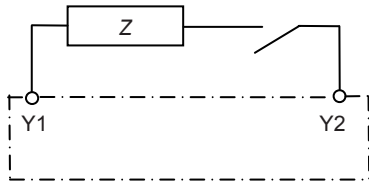
EXAMPLE 4



EXAMPLE 5

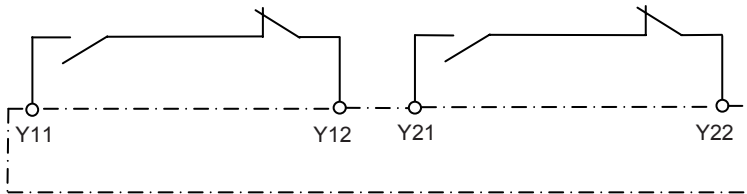


NOTE 1 A bridge between two terminals is considered as a permanently closed contact and the corresponding terminals shall be marked Y1 and Y2.



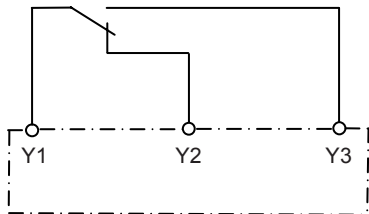
NOTE 2 For an external circuit comprising an association of impedance(s) and contact(s), the corresponding terminals shall be marked Y1 and Y2.

L.6.1.3.2 In the case of more than one contact or one group of contact, the terminals shall be marked by using the letter Y and two-figure numbers, the first figure being a sequence number.

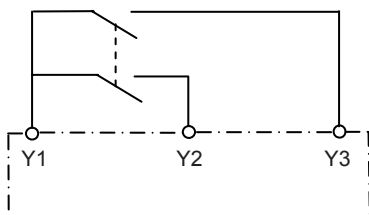


EXAMPLE

L.6.1.3.3 The three terminals necessary for connection of several contacts which operates simultaneously (e.g. forming a change-over contact) shall be marked Y1, Y2 and Y3, Y1 being the common.



EXAMPLE 1



EXAMPLE 2

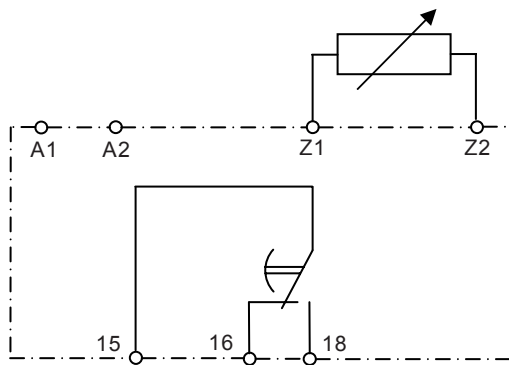
L.6.2 Marking of terminals for external complete devices

To illustrate the association with the general rules, four examples of the terminal marking of a complete device are given hereafter.

EXAMPLE 1

Switching device having:

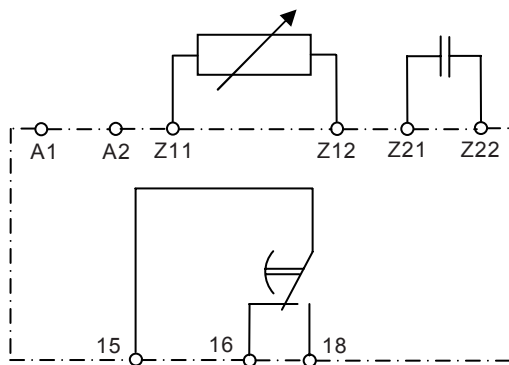
- two control supply terminals A1 and A2,
- two terminals Z1 and Z2, for an external associated variable resistor, and
- three terminals 15, 16 and 18, for an internal delayed change-over contact.



EXAMPLE 2

Switching device having:

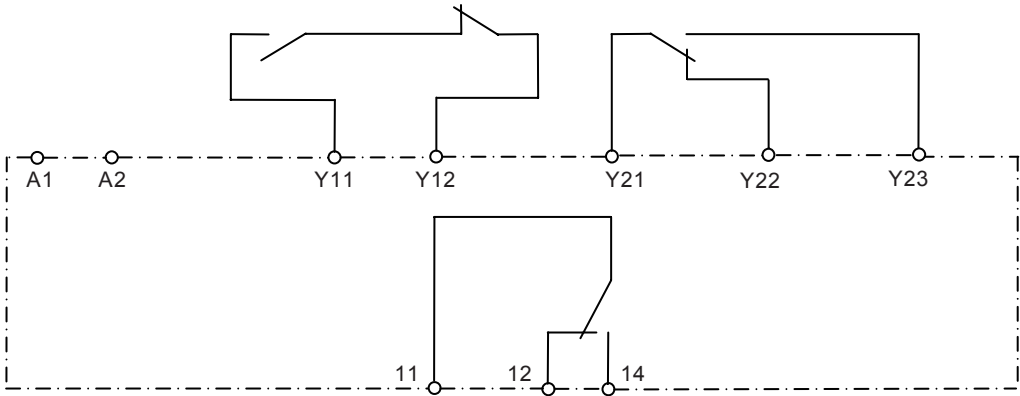
- two control supply terminals A1 and A2,
- four terminals for two external associated impedances (Z11 and Z12 for a variable resistor, and Z21 and Z22 for a capacitor), and
- three terminals 15, 16 and 18, for an internal delayed change-over contact.



EXAMPLE 3

Switching device having:

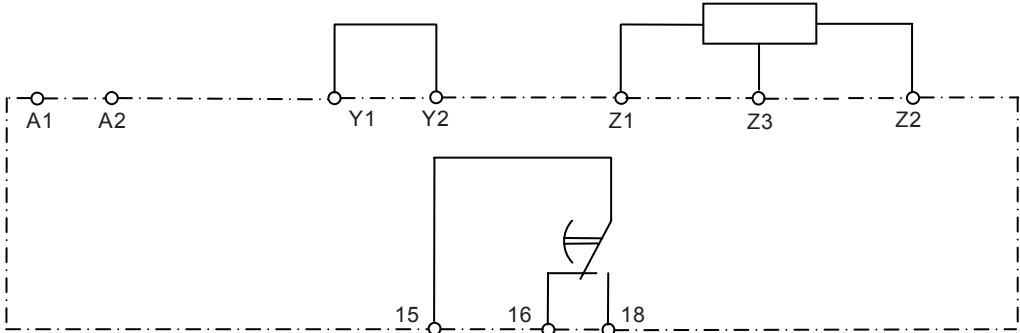
- two control supply terminals A1 and A2,
- two terminals Y11 and Y12, for an external associated group of contacts,
- three terminals Y21, Y22 and Y23, for an external associated change-over contact, and
- three terminals 11, 12 and 14, for an internal change-over contact.



EXAMPLE 4

Switching device having:

- two control supply terminals A1 and A2,
- two terminals Y1 and Y2, for an external bridge,
- three terminals Z1, Z3 and Z2, for an external associated resistor with a tapping, and
- three terminals 15, 16 and 18, for an internal delayed change-over contact.



Annex M (normative)

Flammability test

A1 M.1 Hot wire ignition test (HWI)

M.1.1 Test sample

Five samples of each material shall be tested.

The rectangular bar-shaped samples shall be $125 \text{ mm} \pm 5 \text{ mm}$ long by $13 \text{ mm} \pm 0,5 \text{ mm}$ wide and of uniform thickness stated by the material manufacturer. The test method applies to moulded or sheet materials in thicknesses ranging from 0,25 mm to 6,4 mm.

Edges shall be free from burrs, fins, etc. and the radius on the corners shall not exceed 1,3 mm.

M.1.2 Description of test apparatus

The sample shall be fastened in a fixture which provides two supporting posts positioned 70 mm apart to support the test specimen in a horizontal position, at a height of 60 mm above the bottom of the chamber, in the approximate centre of the test chamber (see Figure M.1).

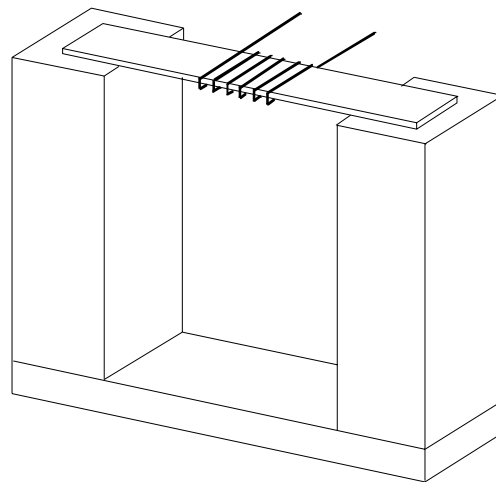


Figure M.1 – Test fixture for hot wire ignition test

A $250 \text{ mm} \pm 5 \text{ mm}$ length of NiCr-wire (80 % nickel, 20 % chromium, iron free) approximately 0,5 mm diameter, having a cold resistance of approximately $5,28 \Omega/\text{m}$ and a length-to-mass ratio of 580 m/kg shall be used. Prior to testing, the wire shall be connected in a straight length to a variable source of power which is adjusted to cause a power dissipation of 0,26 W/mm in the wire for a period of 8 s to 12 s.

After cooling, the wire shall be wrapped around a sample to form five complete turns spaced $6,35 \text{ mm} \pm 0,05 \text{ mm}$ apart. A winding fixture shall be used, which will uniformly position the wire in the centre portion of the sample with a winding force of $5,4 \text{ N} \pm 0,02 \text{ N}$.

The ends of the wire shall be connected to the variable power source. **A1**

A₁ The supply circuit capacity shall be sufficient to maintain a continuous linear 48 Hz to 62 Hz power density of at least 0,31 W/mm over the length of the heater wire at or near unity power factor. The power density of the supply circuit at 60 A and 1,5 V shall be approximate 0,3 W/mm. It shall be possible to adjust the power level, smoothly and continuously and measure the power to within $\pm 2\%$.

M.1.3 Conditioning

Prior to testing, the test samples shall be maintained in a dry-as-moulded condition or alternatively, if this is not practical, the test samples shall be dried in an air-circulating oven at $70\text{ }^{\circ}\text{C} \pm 2\text{ }^{\circ}\text{C}$ for 168 h and cooled over silica-gel or other desiccant for a minimum of 4 h. Immediately prior testing, the specimens shall be conditioned for at least 40 h at $23\text{ }^{\circ}\text{C} \pm 2\text{ }^{\circ}\text{C}$ and $50\% \pm 5\%$ relative humidity.

M.1.4 Test procedure

Start the test by energizing the circuit so that a current is passed through the heater wire yielding a linear power density of 0,26 W/mm over the whole length during the test.

Continue heating until the test specimen ignites. When ignition occurs, shut off power and record the time to ignition. Ignition means an initiation of flaming produced by combustion in the gaseous phase which is accompanied by emission of light. Discontinue the test if ignition does not occur within 120 s. For specimens that melt through the wire without ignition, discontinue the test when the specimen is no longer in intimate contact with all five turns of the heater wire. The test shall be repeated on the remaining samples.

The thickness of each test sample and the time to ignition of each test sample or the time to melt through the wire of each test sample shall be recorded.

The test result for a given material within the tested thickness is the average time in seconds required for ignition.

M.2 Arc ignition test (AI)

M.2.1 Test sample

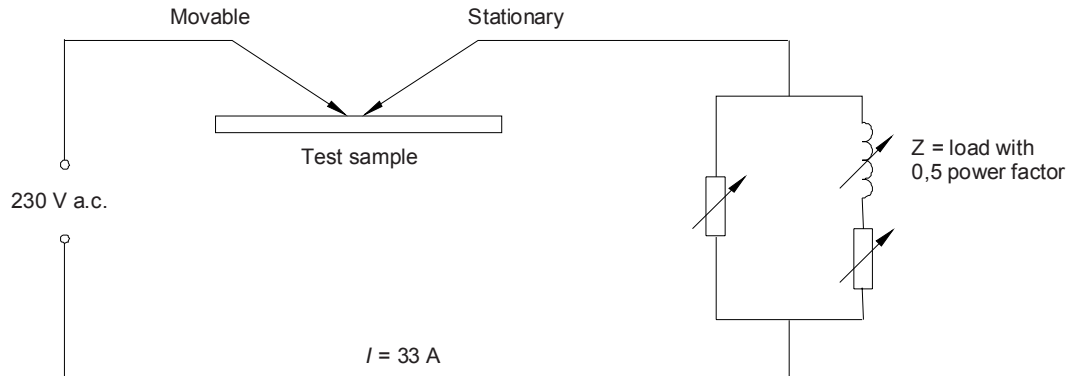
Five samples of each material shall be tested.

The rectangular bar-shaped samples shall be $125\text{ mm} \pm 5\text{ mm}$ long by $13\text{ mm} \pm 0,5\text{ mm}$ wide and of uniform thickness stated by the material manufacturer.

Edges shall be free from burrs, fins, etc. and the radius on the corners shall not exceed 1,3 mm. **A₁**

A1) M.2.2 Description of test apparatus

The test shall be made with a pair of test electrodes and a variable inductive impedance load connected in series to a source of 230 V a.c., 50 Hz or 60 Hz (see Figure M.2).



IEC 2838/10

Figure M.2 – Circuit for arc ignition test

One electrode shall be stationary and the other movable. The stationary electrode shall consist of a solid copper conductor having a horizontal symmetric chisel point with a total angle of 30° . The overall length of this fixed electrode shall be approximately 152 mm with a diameter of 3,2 mm.

The movable electrode shall be a stainless steel rod (X8CrNiS18-9), 3,2 mm diameter and approximately 152 mm long, having a symmetrical conical point with a total angle of 60° , and shall be capable of being moved along its own axis. The radius of curvature for both electrode tips shall not exceed 0,1 mm at the start of a given test. The electrodes shall be located opposing each other, at an angle of 45° to the horizontal in a common vertical plane, orthogonal to the axis of the sample.

With the electrodes short-circuited, the variable inductive impedance load shall be adjusted until the current is 32,5 A at a power factor of 0,5.

M.2.3 Conditioning

Unless otherwise specified, special conditioning is not required.

M.2.4 Test procedure

The sample under test shall be supported horizontally in air on a nonconductive, inflammable basis, so that the electrodes, when touching each other, are in contact with the surface of the sample. The movable electrode shall be manually or otherwise controlled so that it can be withdrawn along its axis from contact with the stationary electrode to break the circuit, and lowered to remake the circuit, so as to produce a series of arcs at a rate of approximately 40 arcs/min, with a separation speed of $254 \text{ mm/s} \pm 25 \text{ mm/s}$. The test is to be continued until ignition of the sample occurs, a hole is burned through the sample, or a total of 200 make and break cycles has elapsed.

If a hole is burned through any sample of the set or ignition occurs, an extra set of three samples shall be tested, but with the electrodes making contact 1,6 mm above the surface of the sample. If ignition or a hole occurs to any of these samples, an additional set of three samples shall be tested with the electrodes making contact 3,2 mm above the surface of the sample. **A1)**

A1 The average number of arcs to ignition or the maximum number of 200 cycles and the thickness of each set of specimen shall be recorded.

M.3 HWI and AI requirements

The hot wire ignition (HWI) and arc ignition (AI) test value requirements related to the material's flammability category are indicated in Table M.1 and Table M.2. Each column represents HWI and AI minimum characteristics related to the flammability category.

NOTE Alternatively, the manufacturer may provide data from the insulating material supplier fulfilling the requirements given in Annex M.

Table M.1 – HWI and AI characteristics for materials necessary to retain current carrying parts in position

Flammability category (IEC 60695-11-10)	V-0	V-1	V-2	HB
Part thickness ^a mm	Any ^b	Any ^b	Any ^b	Any ^b
HWI time to ignite, minimum s	7	15	30	30
AI minimum number of arcs to ignite	15	30	30	60
^a According to 8.2.1.1.2.				
^b According to the smallest thickness in application.				
NOTE 1 There is no direct correspondence between the glow-wire-test temperatures and this table.				
NOTE 2 A manufacturer may use any flammability category of his own choice, but the requirements of HWI and, if applicable, AI should be fulfilled.				
EXAMPLE A material with flammability category V-1 of any thickness shall have a HWI value of at least 15 s and, if applicable, an AI value of at least 30 arcs.				

Table M.2 – HWI and AI characteristics for materials other than those covered by Table M.1

Flammability category (IEC 60695-11-10)	V-0	V-1	V-2	HB
Part thickness mm	Any ^a	Any ^a	Any ^a	Any ^a
HWI time to ignite, minimum s	–	–	7	7
AI minimum number of arcs to ignite	–	–	15	15
^a According to the smallest thickness in application.				

A1

Annex N (normative)

Requirements and tests for equipment with protective separation

This annex applies to a device, one or more circuits of which are intended to be used in a SELV (PELV) circuit (the device by itself may not be class III – see 7.4 of IEC 61140).

N.1 General

The purpose of this annex is to harmonize as far as practicable all rules and requirements applicable to low voltage switchgear and controlgear having a protective separation between parts intended to be used in SELV (PELV) circuits and others, in order to obtain uniformity of requirements and tests and to avoid the need for testing to different standards.

N.2 Definitions

N.2.1

functional insulation

insulation between conductive parts which is necessary only for the proper functioning of the equipment.

N.2.2

basic insulation

insulation of hazardous live parts which provides basic protection against electric shock.

NOTE The term basic insulation does not apply to insulation used exclusively for functional purposes. (See N.2.1)

N.2.3

supplementary insulation

independent insulation applied in addition to basic insulation in order to provide protection against electric shock in the event of a failure of basic insulation.

N.2.4

double insulation

insulation comprising both basic insulation and supplementary insulation.

N.2.5

reinforced insulation

insulation of hazardous live parts which provides a degree of protection against electric shock equivalent to double insulation.

NOTE Reinforced insulation may comprise several layers which cannot be tested singly as basic or supplementary insulation.

N.2.6

(electrically) protective separation

separation of one electric circuit from another by means of:

- double insulation, or
- basic insulation and electrically protective screening (shielding), or
- reinforced insulation

[IEV 195-06-19]

N.2.7

SELV circuit

electrical circuit in which the voltage cannot exceed ELV:

- under normal conditions, and
- under single-fault conditions, including earth faults in other circuits

NOTE Definition adapted from the definition of SELV system given in IEC 61140.

N.2.8

PELV circuit

electrical circuit in which the voltage cannot exceed ELV:

- under normal conditions, and
- under single-fault conditions, except earth faults in other circuits

NOTE Definition adapted from the definition of PELV system given in IEC 61140.

N.2.9

limitation of steady-state touch current and charge

protection against electric shock by circuit or equipment design such that under normal and fault conditions the steady-state touch current and charge are limited to non-hazardous levels

[IEV 826-03-16 modified]

N.2.10

protective impedance device

component or assembly of components the impedance and construction of which are such as to ensure that steady-state touch current and charge are limited to non-hazardous levels

N.3 Requirements

N.3.1 General

Unless otherwise specified in the relevant product standard:

- The ^{A2}Text deleted ^{A2} method considered in this standard to achieve the protective separation is based on double (or reinforced) insulation between SELV (PELV) circuit(s) and other circuits. If any component is connected between the separated circuits, that component shall comply with the requirements for protective impedance devices according to 5.3.4 of IEC 61140 (see Figure N.1).
- The effects of electrical arcs normally produced in the breaking chambers of switchgears and controlgears on insulation are deemed to be taken into account in the dimensioning of creepage distances and no specific verification is required.
- Partial discharge effects are not taken into consideration.

^{A2} NOTE Double insulation may also be appropriate for parts accessible outside of the enclosure of the equipment, as for example HMI accessories. ^{A2}

N.3.2 Dielectric requirements

N.3.2.1 Creepages

It shall be verified that the creepage distances between SELV (PELV) circuit and other circuits are equal or higher than twice those given for basic insulation in Table 15 and corresponding to the voltage of the circuit having the highest rated voltage value.

NOTE This requirement follows the principles given in IEC 60664-1.

The creepage distances shall be verified in accordance with N.4.2.1.

N.3.2.2 Clearances

The clearances between SELV (PELV) circuit and other circuits of the device shall be dimensioned to withstand the rated impulse voltage as determined in accordance with Annex H relevant to the basic insulation for the specific utilisation class but one step higher in the series value (or a value equal to 160 % of the voltage value required for the basic insulation) following the principles A_2 given in 5.1.6 of IEC 60664-1:2007. A_2 The test conditions are given in N.4.2.2.

N.3.3 Construction requirements

Construction measures should be taken regarding:

- materials employed regarding aging;
- thermal stresses or mechanical risks of failure which will impair insulation between circuits;
- risks of electrical contact between different circuits in case of accidental disconnection of wiring.

Subclause N.4.3 gives examples of constructional risks which have to be taken into consideration.

N.4 Tests

N.4.1 General

These tests are normally conducted as type tests. Where the constructional design cannot ensure without doubt that the insulation intended for protective separation cannot be impaired by the effects of product conditions, the manufacturer or the relevant product standard may also conduct all or parts of these tests as routine tests.

Tests verification shall be made between the SELV (PELV) circuit and each other circuits, such as main circuit, control and auxiliary circuits.

Tests shall be done in all operating conditions of the device: open, close, trip positions.

N.4.2 Dielectric tests

N.4.2.1 Creepages verification

Conditions of measuring are those given in 8.3.3.4.1 and Annex G.

N.4.2.2 Clearances verification

N.4.2.2.1 Condition of the device for test

Tests shall be made on devices mounted as for service, including internal wiring and in a clean and dry condition.

N.4.2.2.2 Application of the test voltage

For each circuit of the device under test, external terminals shall be connected together.

N.4.2.2.3 Impulse test voltage

It shall be an impulse test voltage having a 1,2/50 μ s wave form as described in 8.3.3.4.1, the value of which being chosen as defined in N.3.2.2.

N.4.2.2.4 Test

Clearances are verified by application of the test voltage of N.4.2.2.3. The test shall be conducted for a minimum of five impulses of each polarity with an interval of at least 1 s between pulses in accordance with in 8.3.3.4.1.

Application of test voltage may be avoided where clearances are equal or higher than those given in Table 13 for the determined test voltage value.

N.4.2.2.5 Results to be obtained

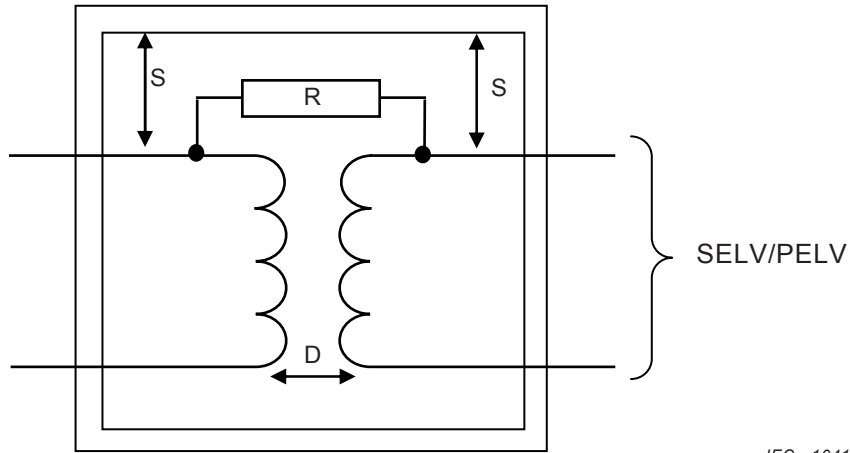
When the voltage is applied, the test is considered to have been passed if there is no puncture or flashover.

N.4.3 Examples of constructional measures

Measures should be taken that a single mechanical fault – e.g. a bent solder pin, a detached soldering point or a broken winding (coil), a loosened and fallen screw – should not have the result of impairing the insulation to such a degree that it no longer fulfils the requirements of the basic insulation; the design, however, should not consider that two or more of these events will appear simultaneously.

Examples of constructional measures:

- sufficient mechanical stability;
- mechanical barriers;
- employment of captive screws;
- impregnation or casting of components;
- inserting pins into an insulating sleeve;
- to avoid sharp-edges in the vicinity of conductors.



IEC 1041/07

Key

- D double (or reinforced) insulation between circuits (including SELV/PELV circuit)
- R component complying with protective impedance devices requirements
- S basic insulation

Figure N.1 – Example of application with component connected between separated circuits

A2 Annex O (informative)

Environmentally-conscious design

O.1 General

Every product has an effect on the environment, which may occur at any or all stages of its life cycle – raw-material acquisition, manufacture, distribution, use, maintenance, re-use and end of life. These effects may range from slight to significant; they may be short-term or long-term; and they may occur at the local, national, regional or global level (or a combination thereof).

The widespread use of electrical and electronic products has drawn increased awareness to their environmental impacts. As a result, legislation, as well as market-driven requirements for environmentally conscious design, is emerging.

The continuous introduction of new products and materials can make evaluation increasingly complex, since additional data shall be gathered to assess the life-cycle impacts of such new products and materials. The gathered data has to be used as a basis for improvement of the products with respect to environmental impacts. Life-Cycle Assessment (LCA) and environmentally conscious design (ECD) principles provide instruments that may be useful in this respect.

The goal of LCA and ECD is the reduction of adverse environmental impacts of a product throughout its entire life cycle. This can involve balancing the environmental aspects of the product with other factors, such as its intended use, performance, cost, safety, marketability, and quality and choosing methods to meet legal and regulatory requirements in an environmentally conscious way. In striving for this goal, multiple benefits can be achieved for the organization, its customers and other stakeholders. The consideration of environmental aspects particularly in the very early stage of the product design process can contribute to cost reduction and to better marketability. Environmentally conscious design is not a separate design activity; rather it is an integral part of the existing design process. The "design" in this context includes the activities associated with the processes of product planning, development and decision making as well as the creation of policies within the organization.

ECD is intended to be used by all those involved in the design and development of electrical and electronic products. This includes all parties in the supply chain regardless of organization type, size, location and complexity. It is applicable for all types of products, new as well as modified. Sector-specific documents may be developed to address needs not covered in this document. The use of this annex as a base reference is encouraged so as to ensure consistency throughout the electrotechnical sector.

This annex provides a set of requirements for the process of environmentally conscious design reflecting the contents of IEC 62430.

O.2 Scope of this annex

This annex specifies requirements and procedures to integrate environmental aspects into design and development processes of products of IEC 60947 series, including combination of products, and the materials and components of which they are composed (hereafter referred to as products), by the process of environmental conscious design (ECD). **A2**

^{A2} NOTE 1 The existence of this annex does not preclude particular product sectors of the IEC 60947 series from generating their own, more specific, standards or guidelines. Where such documents are produced it is recommended that they use this annex or the IEC 62430 standard as the reference in order to ensure consistency throughout the electrotechnical sector.

The term environment, as used in this annex, differs from the term as used in the IEC publications dealing with the impact of environmental conditions on electrotechnical products.

NOTE 2 Regarding the impacts of environmental conditions on the performance of products, reference is made to IEC 60068 series, IEC 60721 series and IEC Guide 106.

O.3 Terms and definitions

For the purposes of this annex, the following terms and definitions apply.

O.3.1

design and development

activities that take an idea or requirement and transform these into a product

NOTE The process of design and development usually follows a series of defined steps starting with an initial idea, transforming that into a formal specification, and resulting in the creation of a working prototype and whatever documentation is required to support production of the goods or provision of the service.

[IEC 62430:2009, 3.1]

O.3.2

environment

surroundings in which an organization operates, including air, water, land, natural resources, flora, fauna, humans and their interrelation

NOTE Surroundings in this context extend from within an organization to the global system.

[ISO 14001:2004, 3.5]

O.3.3

environmental aspect

element of an organization's activities or products that can interact with the environment

NOTE A significant environmental aspect has or can have a significant environmental impact.

[IEC 62430:2009, 3.3]

O.3.4

environmental impact

any change to the environment, whether adverse or beneficial, wholly or partly resulting from an organization's environmental aspects

[ISO 14001:2004, 3.7]

O.3.5

environmental parameter

quantifiable attribute of an environmental aspect

EXAMPLE Environmental parameters include the type and quantity of materials used (mass, volume), power consumption, emissions, rate of recyclability, etc.

[IEC 62430:2009, 3.5] ^{A2}

A₂ **O.3.6**
environmentally-conscious design
ECD

systematic approach which takes into account environmental aspects in the design and development process with the aim to reduce adverse environmental impacts

[IEC 62430:2009, 3.6]

O.3.7
environmentally conscious design tool

formalized method which facilitates qualitative or quantitative analysis, comparison and/or solution finding during the ECD process

[IEC 62430:2009, 3.7]

O.3.8
life cycle

consecutive and interlinked stages of a product system, from raw material acquisition or generation from natural resources to the final disposal

[ISO 14040:2006, 3.1]

O.3.9
life cycle assessment
LCA

compilation and evaluation of the inputs, outputs and the potential environmental impacts of a product system throughout its life cycle

[ISO 14040:2006, 3.2]

O.3.10
life cycle stage
element of a life cycle

NOTE 1 The phrase 'life cycle phase' is sometimes used interchangeably with 'life cycle stage'.

NOTE 2 Examples of life cycle stages are: Raw material acquisition and production; manufacturing; packaging and distribution; installation and use, maintenance and upgrading; and end of life.

[IEC 62430:2009, 3.10]

O.3.11
life cycle thinking
LCT

consideration of all relevant environmental aspects during the entire life cycle of products

[IEC 62430:2009, 3.11]

O.3.12
organization

group of people and facilities with an arrangement of responsibilities, authorities and relationships

[IEC 62430:2009, 3.12]

O.3.13
process

set of interrelated or interacting activities which transform inputs into outputs **A₂**

^{A2} NOTE 1 Inputs to a process are generally outputs of other processes.

NOTE 2 Processes in an organization are generally planned and carried out under controlled conditions to add value.

[IEC 62430:2009, 3.13]

**O.3.14
product**

any goods or service

NOTE This includes interconnected and / or interrelated goods or services.

[IEC 62430:2009, 3.14]

**O.3.15
product category**

group of technologically or functionally similar products where the environmental aspects can reasonably be expected to be similar or can be derived through a certain ratio over some functional aspect of the products (e.g. product weight or performance range)

[IEC 62430:2009, 3.15, modified]

**O.3.16
stakeholder**

individual, group or organization that has an interest in an organization or activity

NOTE Usually a stakeholder can affect or is affected by the organization or the activity.

[IEC 62430:2009, 3.16]

**O.3.17
recycling**

reprocessing in a production process of the waste materials for the original purpose or for other purposes but excluding energy recovery

[IEC Guide 109:2012, 3.16, modified]

**O.3.18
recyclability**

property of a substance or a material and parts/products made thereof that makes it possible for them to be recycled

NOTE The recyclability of a product is not only determined by the recyclability of the materials it contains. Product structure and logistics are also very important factors.

[IEC Guide 109:2012, 3.15, modified]


**O.3.19
end of life
EOL**

state of a product when it is finally removed from its intended use or original purpose

[IEC Guide 109:2012, 3.1, modified]

**O.3.20
energy recovery**

use of combustible waste as a means to generate energy through direct incineration with or without other waste but with recovery of the heat ^{A2}


 [IEC Guide 109:2012, 3.2, modified]

O.4 General considerations

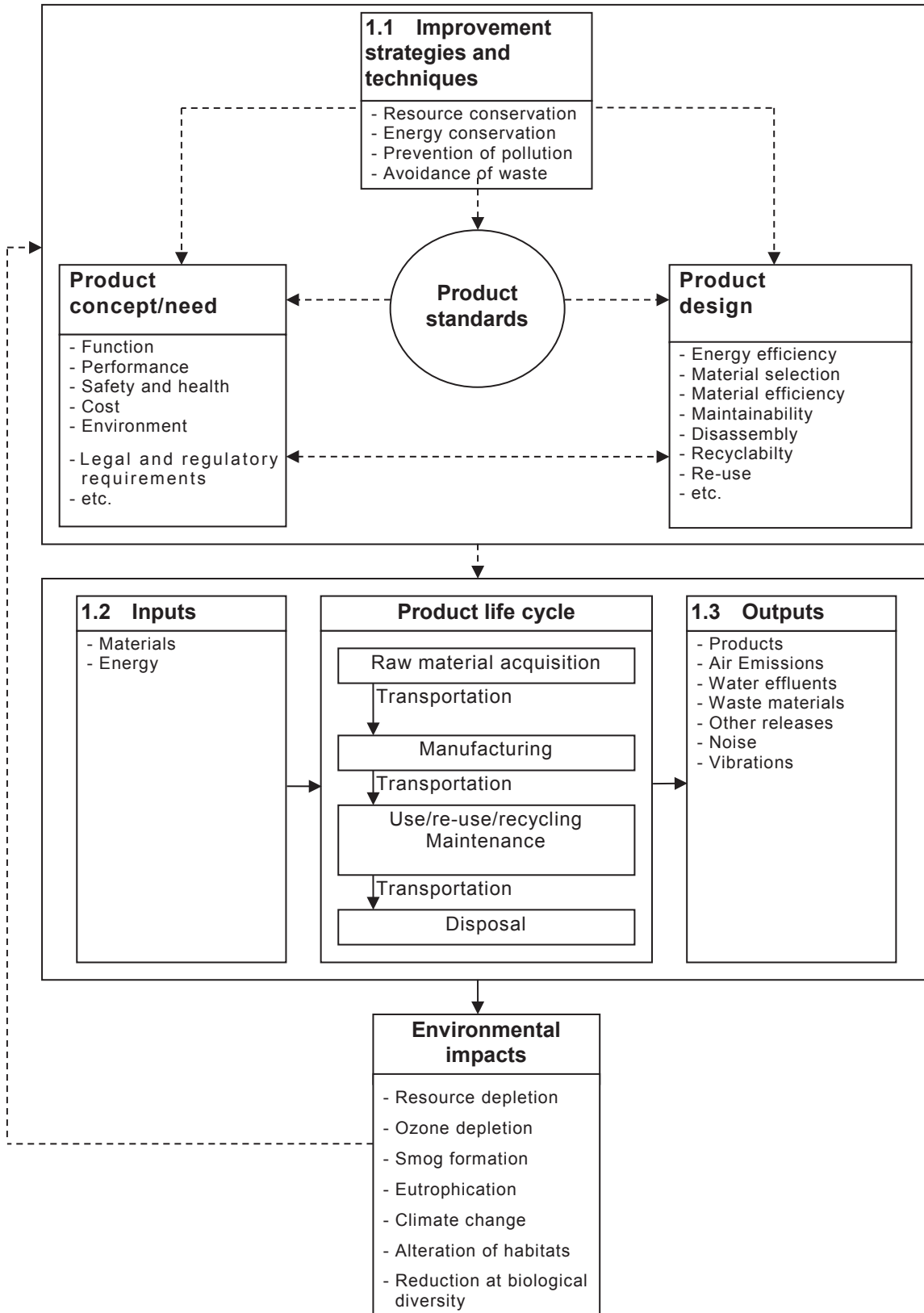
It should be checked that consideration of the following points always leads to a reduction of the adverse environmental impact of the product throughout its life cycle:

- material conservation;
- efficient use of energy and resources;
- reduction of emissions and waste;
- minimum material content of product (including packaging material);
- decreasing the number of different materials;
- substitution or reduction in use of hazardous substances;
- re-use/refurbishing of subassemblies or components;
- possibility of technical upgrading;
- design for maintainability, disassembly and recyclability;
- surface coating or other material combinations enhancing recyclability;
- marking;
- adequate environmental instruction/information for the user.

This leads to the implementation of an adequate process for consideration of the environmental impact of the products. The process should reflect the standardized principle of environmental conscious design based on life cycle thinking.

Clause O.5 describes the fundamental requirements of ECD to be implemented by the organization. Clause O.6 describes the ECD process to be implemented on an operational basis. 

A2



IEC

Figure O.1 – Conceptual relationship between provisions in product standards and the environmental impacts associated with the product during its life cycle ^{A2}

A₂ O.5 Fundamentals requirements of environmentally conscious design (ECD)

Environmentally conscious design shall be based on the concept of life cycle thinking (LCT), which requires consideration during the design and development process of the significant environmental aspects of a product in all life cycle stages.

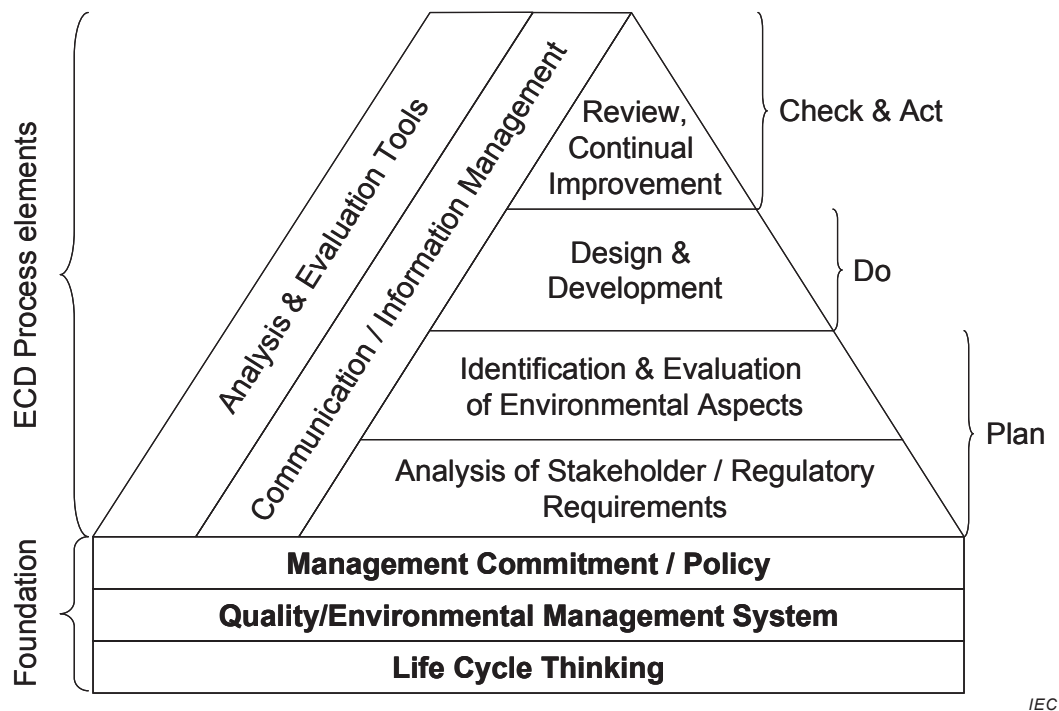


Figure O.2 – Overview of ECD process

Key elements of life cycle thinking are:

- having an objective to minimize the overall adverse environmental impact of the product;
- identifying, qualifying and where feasible, quantifying the significant environmental aspects of the product;
- considering the trade-offs between environmental aspects and life cycle stages.

The above shall be initiated as early as possible in the design and development process, when most opportunities exist to make changes and improvements to the product affecting its overall environmental performance throughout its life cycle.

Environmentally conscious design is performed within the boundaries set by regulatory and stakeholders' requirements. Such requirements shall be regularly reviewed so that relevant changes are understood by the organization undertaking the ECD.

Environmentally conscious design and its objective of minimizing the overall adverse impact of the product shall be reflected in the policies and strategies of the organization. If an organization has a management system which includes the product design and development function, the ECD process shall be an integral part of that documented system.

NOTE 1 As a first step in LCT, the intended function of the product should be determined. In subsequent design and development stages the influence of any applied business model should be recognized.

NOTE 2 When a product is part of a system, the environmental performance of one product during one or more life cycle stages can be altered by other products in that system. **A₂**

A2 NOTE 3 ECD requires collaboration and contributions of all stakeholders along the supply chain.

NOTE 4 Communication regarding the ECD process and its objectives is performed within an organization so that the affected departments understand the rationale for the initiative, leading to their cooperation and collaboration.

NOTE 5 The detailed description of the fundamental requirements of ECD can be found in IEC 62430.

O.6 Environmentally conscious design process (ECD process)

O.6.1 General

Organizations performing environmentally conscious design (ECD) shall establish, document, implement and maintain an ECD process as an integral part of the product design and development process. This ECD process includes the following steps, which are further described in O.6.2:

- a) analysis of the regulatory and stakeholders' environmental requirements;
- b) identification and evaluation of environmental aspects and corresponding impacts;
- c) design and development;
- d) review and continual improvement.

The organization shall, while following the above steps, document the relevant results and the subsequent conclusions and responsibilities assigned.

NOTE The above process from a) to d) corresponds to PDCA cycle as follows:

steps a) and b) to Plan,

step c) to Do, and

step d) to Check and Act.

O.6.2 Process steps of ECD

As an initial step of ECD, to be carried out in conjunction with the identification of environmental aspects, the organization shall understand the relevant regulatory and stakeholders' requirements, both at horizontal and sector specific level. These requirements set the basic framework within which a product is developed.

The organization shall then establish a procedure to identify environmental aspects and corresponding impacts of the product.

NOTE 1 The identification of environmental aspects could be done for a product category.

The choice of a design solution should achieve a balance between the various environmental aspects and other relevant considerations, such as function, technical requirements, quality, performance, business risks and economic aspects. Where certain attributes are required for compliance with regulations (e.g. health and safety, electromagnetic compatibility) these shall be met while taking into account the environmental targets. These considerations also apply to research and development of new technologies.

A procedure for review and continual improvement of the significant environmental aspects of products throughout the entire life cycle shall be established, implemented and maintained.

As part of the ECD process, organizations in the supply chain shall disclose information of their product or product category to organizations involved in design and development to enable them to achieve ECD objectives.

Information on the environmental impact of the products or product categories should be made available to the stakeholders in adequate, standardized form, e.g. compliant to the ISO 14020 series standards – environmental product declarations. **A2**

A2 NOTE 2 The detailed description of the ECD process can be found in IEC 62430.

O.7 Tools for including ECD in product design and development

Identification and assessment of how environmental impacts are influenced by products are complex and need careful consideration; they may also require consultation with experts. Certain tools and techniques are evolving to encourage the inclusion of environmental aspects in product design and development. These can assist in the development of key design items, decision-making, and integration with business and economic factors. Examples of such tools are:

- a) analysis of a product's environmental aspects; for example, LCA (Life Cycle Assessment), ECD checklists and ECD benchmarking based on physical metrics (for example, weight, energy consumption, volume);
- b) determination of a product's environmental strategy: qualitative decision-making tools, for example, Eco-matrices, checklists, Pareto diagrams, SWOT analysis (Strengths, Weaknesses, Opportunities, Threats), spider's-web diagrams and portfolio diagrams;
- c) transfer of environmental aspects into product properties; for example, QFD (Quality Function Deployment) and FMEA (Failure Mode and Effects Analysis) techniques.

When selecting which tools to use, it is helpful to consider the basic product-related concepts for integrating environmental aspects into product design and development.

NOTE Proper tools and tool categories and implementation strategies are described in IEC 62430:2009, Annex C.

O.8 Relevant ISO technical committees

- TC 61 Plastics
- TC 79 Light metals and their alloys
- TC 122 Packaging
- TC 146 Air quality
- TC 147 Water quality
- TC 190 Soil quality
- TC 200 Solid wastes
- TC 203 Technical energy systems
- TC 205 Building environment design
- TC 207 Environmental management
 - SC 1 Environmental management systems
 - SC 2 Environmental auditing and related environmental investigations
 - SC 3 Environmental labelling
 - SC 4 Environmental performance evaluation
 - SC 5 Life cycle assessment
 - SC 6 Terms and definitions
 - WG 1 Environmental aspects in product standards

O.9 Reference documents for environmental conscious design

IEC 62430, *Environmentally conscious design for electrical and electronic products*

IEC 62474, *Material declaration for products of and for the electrotechnical industry*

IEC Guide 109, *Environmental aspects – Inclusion in electrotechnical product standards* **A2**

A₂ ISO/IEC Guide 73, *Risk management – Vocabulary*

ISO 9000, *Quality management systems – Fundamentals and vocabulary*

ISO 9001, *Quality management systems – Requirements*

ISO 14001, *Environmental management systems – Requirements with guidance for use*

ISO 14020, *Environmental labels and declarations – General principles*

ISO 14040, *Environmental management – Life cycle assessment – Principles and framework*

ISO/TR 14062, *Environmental management – Integrating environmental aspects into product design and development*

ISO 14063, *Environmental management – Environmental communication – Guidelines and examples*

ISO Guide 64, *Guide for addressing environmental issues in product standards*

ECODESIGN – *a promising approach to sustainable production and consumption: 1997, United Nations Environmental Programme* **A₂**

Annex P
(informative)

**Terminal lugs for low voltage switchgear and controlgear
connected to copper conductors**

**Table P.1 – Examples of terminal lugs for low voltage switchgear and controlgear
connected to copper conductors**

Conductor cross-sectional area mm ²		Dimensions (see Figure P.1) mm						Clearance hole for mounting bolt
Flexible	Solid or stranded	L max.	N max.	W max.	W Gauge	Z max.	M min.	H
6	10	22	6	10		12	6	M5
10	16	26	6	10		12	6	M5
16	25	28	6	10		12	6	M5
25	35	33	7	12	12,5	17	7	M6
35	50	38	7	12	12,5	17	7	M6
50	70	41	7	12	12,5	17	7	M6
70	95	48	8,5	16	16,5	20	8,5	M8
95	120	51	10,5	20	20,5	25	10,5	M10
120	150	60	10,5	20	20,5	25	10,5	M10
150	185	72	11	25	25,5	25	11	M10
185	240	78	12,5	31	32,5	31	12,5	M12
240	300	89	12,5	31	32,5	31	12,5	M12
300	400	105	17	40	40,5	40	17	M16
400	500	110	17	40	40,5	40	17	M16

NOTE Other different dimensions of cables lugs are available.

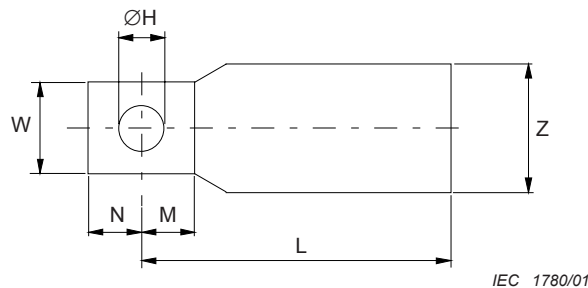


Figure P.1 – Dimensions

Annex Q (normative)

Special tests – Damp heat, salt mist, vibration and shock

Q.1 General

The purpose of this annex is to define the requirements allowing to assess the ability of switchgear and controlgear to perform its function where intended to be used under certain climatic conditions different from normal service conditions as described in 6.1.

This annex states the test conditions and sequences and the results to be obtained.

The following special tests shall be made either at the discretion of the manufacturer or according to an agreement between manufacturer and user (see 2.6.4). As special tests, these additional tests are not mandatory, and it is not necessary for an equipment to satisfy any of these tests to conform to this standard.

Q.2 Classification of equipment

Equipment classification is defined according to six sets of environmental tests, resulting from a combination of different parameter classes (temperature and humidity, vibration, shock, salt mist):

– Temperature and humidity test ranges:

CC1: –5 °C to +55 °C (first range: dry heat test at +55 °C / damp heat test at +40 °C / cold test at –5 °C)

CC2: –25 °C to +70 °C (second range: dry heat test at +70 °C / damp heat test at +55 °C / cold test at –25 °C)

– Vibration and shock levels:

MC1: no vibration

MC2: vibration

MC3: vibration plus shock

– Salt mist:

SC1: no salt mist

SC2: salt mist (test according to IEC 60068-2-52)

The combination of these environmental tests results in the following six categories A, B, C, D, E and F:

- A: controlled environment subject to temperature and humidity (temperature test range –5 °C to +55 °C) = MC1+CC1+SC1

NOTE 1 These environmental conditions may be described as “humid atmosphere”.

- B: environment subject to temperature and humidity (temperature test range –25 °C to +70 °C) = MC1+CC2+SC1

NOTE 2 These environmental conditions may be described as “humid and cold atmosphere”.

- C: environment subject to temperature, humidity and salt mist = MC1+CC2+SC2

NOTE 3 These environmental conditions may be described as "humid and salty atmosphere" or "marinas".

- D: environment subject to temperature, humidity and vibration = MC2+CC2+SC1

NOTE 4 These environmental conditions may be described as "humid and cold atmosphere on board ship, with vibrations".

- E: environment subject to temperature, humidity, vibration and shock = MC3+CC2+SC1

NOTE 5 These environmental conditions may be described as "open deck, humid and cold atmosphere, without salt mist" or "onerous (severe) conditions other than at sea".

- F: environment subject to temperature, humidity, vibration, shock and salt mist = MC3+CC2+SC2

NOTE 6 These environmental conditions may be described as "open deck, humid, cold and salty atmosphere" or "onerous (severe), sea conditions".

Q.3 Tests

Q.3.1 General test conditions

Unless otherwise specified, 8.3.2 applies with the following additions.

These tests demonstrate the ability of the equipment to function as intended under the specified testing conditions. The intended function is defined in the test sequence.

The equipment shall be tested (if applicable) in the open position, this equipment having previously been under a normal atmospheric condition for a minimum time of 24 h. Normal atmospheric condition means:

- temperature: 25 °C ±10 °C;
- relative humidity: 60 % ±30 %;
- air pressure: 96 kPa ±10 kPa.

During the tests inside the climatic oven, the cables shall have at least 5 cm length and, in case of equipment with enclosure, at least 5 cm length outside of the enclosure, and the passage through the enclosure shall be made according the manufacturer's instructions.

With the manufacturer's agreement, it is permitted to use cables with a cross-section lower than those given in Tables 9, 10 and 11 of 8.3.3.3.4. For devices with high current rating, where space is limited in the climatic chamber, it is permissible to omit cable connections.

NOTE As the Subclause 6.1.4 "Shock and vibrations" for normal conditions, is still under consideration, this annex does not prejudice what will be finally considered as normal conditions of shock and vibrations, and may consequently be revised when the Subclause 6.1.4 is completed.

Q.3.2 Test sequences

After selecting the required environment, the relevant tests are to be performed as a test sequence according to Table Q.1. See also footnote f of Table Q.1.

Table Q.1 – Test sequences

Environments	Controlled environment subject to temperature and humidity	Environment subject to temperature and humidity	Environment subject to temperature, humidity and salt mist	Environment subject to temperature, humidity and vibration	Environment subject to temperature, humidity, vibration and shock	Environment subject to temperature, humidity, vibration, shock and salt mist
Categories	A	B	C	D	E	F
Temperature test range	-5 °C/+55 °C	-25 °C/+70 °C	-25 °C/+70 °C	-25 °C/+70 °C	-25 °C/+70 °C	-25 °C/+70 °C
1 Insulation resistance before testing and visual inspection	a	a	a	a	a	a
2 Vibration test	N.A.	N.A.	N.A.	Vibration IEC 60068-2-6 Test Fc ^b	Vibration IEC 60068-2-6 Test Fc ^b	Vibration IEC 60068-2-6 Test Fc ^b
3 Shock test	N.A.	N.A.	N.A.	N.A.	IEC 60068-2-27 Test Ea ^c	IEC 60068-2-27 Test Ea ^c
4 Inclination test	N.A.	N.A.	N.A.	IEC 60092-504 ^l	IEC 60092-504 ^l	IEC 60092-504 ^l
5 Verification of operational capability	N.A.	N.A.	N.A.	According to product standard ^d	According to product standard ^d	According to product standard ^d
6 Dry heat test	IEC 60068-2-2 Test Bd 16 h 55 °C ^e	IEC 60068-2-2 Test Bd 16 h 70 °C ^e	IEC 60068-2-2 Test Bd 16 h 70 °C ^e	IEC 60068-2-2 Test Bd 16 h 70 °C ^{e f}	IEC 60068-2-2 Test Bd 16 h 70 °C ^{e f}	IEC 60068-2-2 Test Bd 16 h 70 °C ^{e f}
7 Damp heat test	Cyclic IEC 60068-2-30 Test Db 2 cycles 40 °C Variant 2 No load	Cyclic IEC 60068-2-30 Test Db 2 cycles 55 °C Variant 2 ^g	Cyclic IEC 60068-2-30 Test Db 2 cycles 55 °C Variant 2 No load	Cyclic IEC 60068-2-30 Test Db 2 cycles 55 °C Variant 2 ^g	Cyclic IEC 60068-2-30 Test Db 2 cycles 55 °C Variant 2 ^g	Cyclic IEC 60068-2-30 Test Db 2 cycles 55 °C Variant 2 ^g
8 Recovery	The recovery shall be made in the normal atmospheric conditions for 24 h ^h	The recovery shall be made in the normal atmospheric conditions for 24 h ^h	The recovery shall be made in the normal atmospheric conditions for 24 h ^h	The recovery shall be made in the normal atmospheric conditions for 24 h ^h	The recovery shall be made in the normal atmospheric conditions for 24 h ^h	The recovery shall be made in the normal atmospheric conditions for 24 h ^h
9 Insulation resistance	i	i	i	i	i	i
10 Low temperature test	IEC 60068-2-1 Test Ab or Ad, depending whether the product is heat dissipating (>5 K) The test chamber shall be lowered from the initial ambient temperature to -5 °C; this temperature shall be maintained within ±3 °C for 16 h	IEC 60068-2-1 Test Ab or Ad, depending whether the product is heat dissipating (>5 K) The test chamber shall be lowered from the initial ambient temperature to -25 °C; this temperature shall be maintained within ±3 °C for 16 h	IEC 60068-2-1 Test Ab or Ad, depending whether the product is heat dissipating (>5 K) The test chamber shall be lowered from the initial ambient temperature to -25 °C; this temperature shall be maintained within ±3 °C for 16 h	IEC 60068-2-1 Test Ab or Ad, depending whether the product is heat dissipating (>5 K) The test chamber shall be lowered from the initial ambient temperature to -25 °C; this temperature shall be maintained within ±3 °C for 16 h	IEC 60068-2-1 Test Ab or Ad, depending whether the product is heat dissipating (>5 K) The test chamber shall be lowered from the initial ambient temperature to -25 °C; this temperature shall be maintained within ±3 °C for 16 h	IEC 60068-2-1 Test Ab or Ad, depending whether the product is heat dissipating (>5 K) The test chamber shall be lowered from the initial ambient temperature to -25 °C; this temperature shall be maintained within ±3 °C for 16 h

Environments	Controlled environment subject to temperature and humidity	Environment subject to temperature and humidity	Environment subject to temperature, humidity and salt mist	Environment subject to temperature, humidity and vibration	Environment subject to temperature, humidity, vibration and shock	Environment subject to temperature, humidity, vibration, shock and salt mist
Categories	A	B	C	D	E	F
11 Recovery	The recovery shall be made in the normal atmospheric conditions for 24 h ^h	The recovery shall be made in the normal atmospheric conditions for 24 h ^h	The recovery shall be made in the normal atmospheric conditions for 24 h ^h	The recovery shall be made in the normal atmospheric conditions for 24 h ^h	The recovery shall be made in the normal atmospheric conditions for 24 h ^h	The recovery shall be made in the normal atmospheric conditions for 24 h ^h
12 Insulation resistance	i	i	i	i	i	i
13 Dielectric test	IEC 60947-1 8.3.3.4 1, item 3)	IEC 60947-1 8.3.3.4.1, item 3)	IEC 60947-1 8.3.3.4 1, item 3)	IEC 60947-1 8.3.3.4.1, item 3)	IEC 60947-1 8.3.3.4 1, item 3)	IEC 60947-1 8.3.3.4.1, item 3)
14 Verification of operational capability	According to product standard ^d	According to product standard ^d	According to product standard ^d	According to product standard ^d	According to product standard ^d	According to product standard ^d
15 Salt mist	N.A.	N.A.	IEC 60068-2-52 Test Kb Severity 2 ^j	N.A.	N.A.	IEC 60068-2-52 Test Kb Severity 1 ^j
16 Insulation resistance	N.A.	N.A.	i	i	i	i
17 Verification of operational capability	N.A.	N.A.	According to product standard ^d	N.A.	N.A.	According to product standard ^d
18 Visual inspection	N.A.	N.A.	k	N.A.	N.A.	k
N.A.: Non applicable.						
NOTE 1 The classification used differs from the classification of IEC 60721-3.						
NOTE 2 Values indicated in footnotes "a" and "i" are in accordance with IEC 60092-504.						

A2	a	Insulation resistance shall be measured between each circuit and between each circuit and earth with testing equipment complying with IEC 61557-2 (certain components, e.g. for transient suppression, may be required to be disconnected for this test).		
		Maximum of the rated operational voltages	Test voltage d.c.	Minimum insulation resistance
		Up to 65 V	2 × supply voltage (minimum 24 V)	10 MΩ
		Over 65 V	500 V	100 MΩ
	b	Parameters for the vibration test:		
		Frequency range	Displacement	Acceleration
		2 ⁺³ ₋₀ Hz to 13,2 Hz	±1 mm	
		13,2 Hz to 100 Hz		±0,7 g
		<ul style="list-style-type: none"> – duration in case of no resonance condition: 90 min at 30 Hz; – duration at each resonance frequency at which Q is ≥ 2 is recorded: 90 min; – during the vibration test, operational conditions shall be demonstrated; – tests shall be carried out in three mutually perpendicular planes; – it is recommended, as guidance, that Q does not exceed 5; – critical frequencies are range of resonance frequencies where the amplification factor is greater than 2 without interruption; – in case of several resonance frequencies within a range of 0,8 and 1,2 (sweep) of the critical frequencies, the duration of the test shall be 120 min at acceleration of 0,7 g. 		
		Results to be obtained: during the vibration test, an unintended opening and closing of the contacts of more than 3 ms is considered a failure, unless a longer time is stated by the manufacturer in his literature.		
		The defined interruption time (bouncing) may cause problems in some applications (e.g. PLC-monitoring with high speed inputs), this characteristic will need to be taken into account in the application.		
	c	Three positive and negative shocks, applied in each direction along three mutually perpendicular axes:		
		<ul style="list-style-type: none"> – pulse shape: half-sine; – peak acceleration: 150 m/s², (this value should be considered and different values may be defined by the product committee, if applicable) – duration of the pulse: 11 ms. 		
		After the test, the verification made according to row 5 shall demonstrate that relevant operating characteristics stated in the product standard have not been changed.		
	d	The test is intended to check that the equipment ensures some minimal characteristics of operation, and shall be defined by the product standard.		
	e	The relevant product standard shall define equipment operating during conditioning, testing and functional test. The recovery shall be made in the normal atmospheric conditions during 1 h to 2 h or more according to the product standard. Subclause 5.3 of IEC 60068-1 (standard atmospheric conditions) applies.		
	f	The tests from row 6 to 18 may be carried out on a new sample. All samples shall be submitted to the appropriate initial and final verifications according to rows 1, 16 and 17. The number of samples used shall be stated in the test report.		
	g	A functional test shall be done during the first 2 h of the first cycle at the test temperature and during the last 2 h of the second cycle at the test temperature.		
	h	The relevant product standard may state another recovery time.		
	i	Insulation resistance test shall be done within 1 h after the recovery time. Insulation resistance shall be measured between each circuit and between each circuit and earth with testing equipment complying with IEC 61557-2 (certain components, for example for transient suppression, may be required to be disconnected for this test).		
		Maximum of the rated operational voltages	Test voltage d.c.	Minimum insulation resistance
		Up to 65 V	2 × supply voltage (minimum 24 V)	1 MΩ
		Over 65 V	500 V	10 MΩ

A2	<p>j After salt mist test – Recovery: Clause 10 of IEC 60068-2-52 applies with the following addition:</p> <p>After the washing, the device is air-dried either 24 h in free air or 1 h at $+55\text{ °C} \pm 2\text{ °C}$, at the discretion of the manufacturer, then stored in controlled recovery conditions (5.4.1 of IEC 60068-1) for not less than 1 h and not more than 2 h.</p> <p>For some products, washing may impair the operation. In this case, arrangements shall be given in the product standard.</p> <p>k Visual inspection:</p> <p>The aspect of mechanical parts having a functional or a safety role shall be verified regarding the oxidation: rotating pins, magnets, hinges, locks, etc.</p> <p>Moreover, a visual inspection of user's removable parts for maintenance purpose shall be made. Markings shall remain legible.</p> <p>The following limited damages are allowed:</p> <ul style="list-style-type: none">– traces of iron stains on the magnetic circuit;– occurrence of corrosion dots on screws;– occurrence of verdigris dots on copper alloys electrical contact supports;– dots of white corrosion on coated pieces. <p>The relevant product standard may additionally specify the safety relevant criteria to decide, whether the sample has passed or failed the test.</p> <p>l Inclination test:</p> <p>The inclination tests are not required for equipment of low-voltage switchgear if the manufacturer declares that the installation orientation of the device in the application covers the required angles of the test.</p>
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Annex R A₂ (normative) A₂

Application of the metal foil for dielectric testing on accessible parts during operation or adjustment

Introduction

Within a lot of countries, there are a number of legal obligations which impact upon electrical equipment with regard to the health and safety of the users and others when at work. A set of criteria are to be observed and the list below contains examples which A₂ shall be A₂ applied in the case of switchgear and controlgear and their operation:

- a) Remove the danger in the case of switchgear and controlgear where access inside for the operation of certain controls is required. This can be achieved by either making switchgear and controlgear DEAD before access is permitted or ensuring that the degree of protection of the operating surface both external (enclosure or equipment closed) and internal (enclosure or equipment opened) is not less than IP XXB according to IEC 60529.

Or, if this is not practicable

- b) Separate the person from the danger by means of screens, barriers or obstacles.

Or, if this is not practicable

- c) Provide personal protective equipment to ensure the health and safety of the person. This is a measure of last resort and is not considered suitable for this standard.

The preferred approach is to ensure that switchgear and controlgear has a degree of protection not less than IP XXB at the operating surfaces. Alternatively switchgear and controlgear should be designed and constructed so that the controls are set in a safe location within the equipment where there are no hazardous-live-parts. It should be noted that the Basic Safety Publication (see 8.1.2 of IEC 61140) sets a minimum level of protection against electric shock of IP XXB for equipment.

NOTE There is a difference between the requirements of IEC 60529 and this Annex R for the application of the metal foil.

R.1 Object

The purpose of this annex is to clarify where to place the metal foil in order to verify compliance during dielectric tests.

The description given in this annex is not deemed to cover all situations in the field and product standard may specify more precisely the normal operating and installation conditions (e.g. operating handle on the outside of an enclosure while the other part of the device is inside).

The manufacturer may give additional information in which case laboratories should test accordingly (e.g. equipment intended to be installed without an additional enclosure; in such case the parts to be considered for the application of the metal foil are not limited to those accessible during operation or adjustment).

R.2 Definition of zones

R.2.1 General

In order to recognize the existence of accessible parts during operation or adjustment for dielectric tests, three zones are identified for the application of the metal foil:

- a) manual operating or adjustment means,
- b) parts intended to be touched during normal operation or adjustment, but not hand-held,
- c) parts which need not be touched during normal operation or adjustment.

NOTE This is a similar approach to that used for temperature rise limits.

If necessary, the product standard may give additional information.

R.2.2 Application of metal foil on accessible parts during normal operation or adjustment

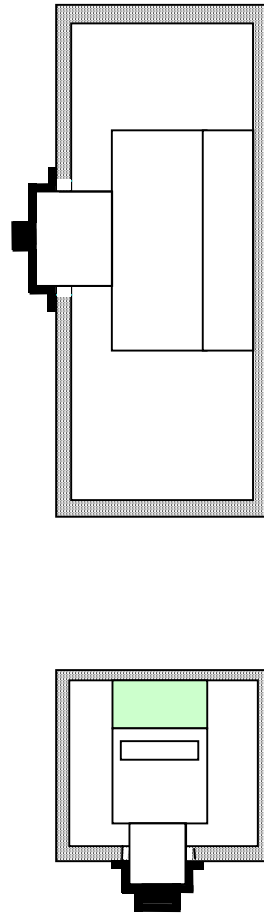
Unless otherwise specified in the product standard, only parts intended to be touched during operation or adjustment are considered.

Parts intended to be outside of the enclosure need to be covered by the metal foil (see Figure R.1).

The metallic foil is applied within a geometrical zone as follows (see also Figures R.2, R.3 and R.4):

- a) Within an area defined by a plane extending 30 mm from all edges of an actuator or/and adjustment means and on all surfaces within that area to a depth of 80 mm.
- b) Within an area defined by a plane extending 100 mm from all edges of an actuator or/and adjustment means and on all surfaces within that area to a depth of 25 mm.

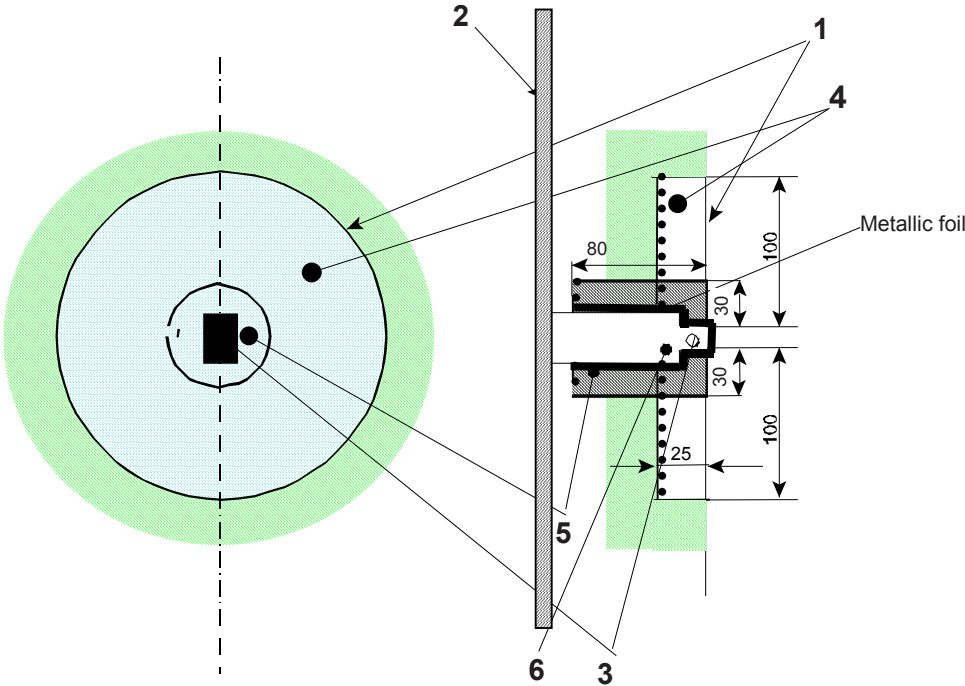
The metal foil shall not be depressed into any holes and grooves (see Figure R.3).



— Metallic foil

IEC 1043/07

Figure R.1 – Operating mechanism outside the enclosure



IEC 1044/07

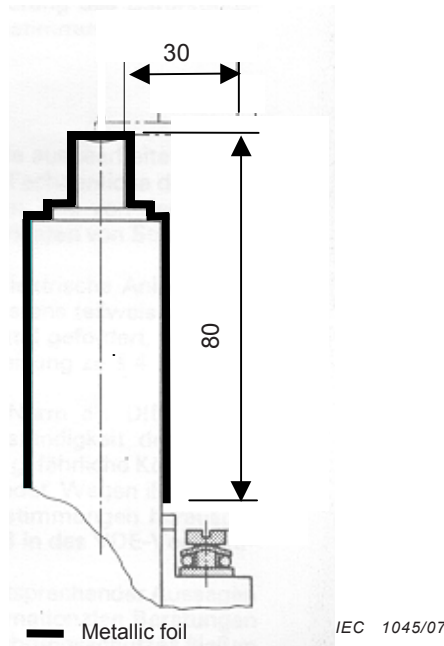
Dimensions in mm

— or - - - - - Metallic foil

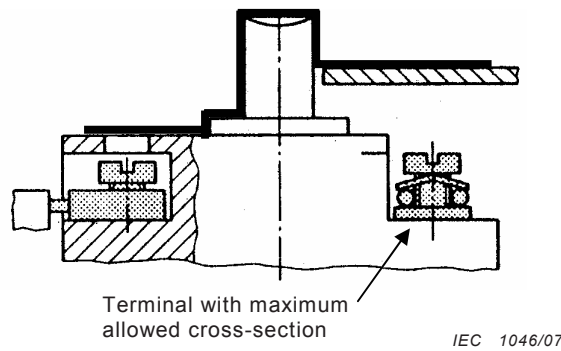
Key

- 1 base area determined from the surface of the actuator
- 2 mounting plate
- 3 push-button
- 4 area with back of the hand protection
- 5 area with finger protection
- 6 switch socket

Figure R.2 – Operating space for push-button actuation



Dimensions in mm



NOTE Alternatively, the holes where the test finger cannot penetrate may not be covered by the metal foil. It is at the discretion of the manufacturer.

Figure R.3 – Examples of finger protected location for hazardous-live-parts in push-button vicinity (approximately 25 mm)

Annex S (normative)

Digital inputs and outputs

NOTE For the purpose of IEC 60947-1, this annex collects relevant extracts from the second edition of IEC 61131-2 for which a French version does not exist. It was therefore considered as not appropriate to issue a French text not prepared by the subcommittee in charge of the IEC 61131-2 (except for Clause S.1).

S.1 Scope

This annex is intended to cover digital inputs and/or digital outputs contained in switchgear and controlgear, and intended to be compatible with programmable controllers (PLCs). It is based on relevant clauses of IEC 61131-2.

S.2 Definitions

For the purpose of this annex, the following definitions apply.

S.2.1

digital input, type 1

device for sensing signals from mechanical contact switching devices, such as relay contacts, push-buttons, switches, etc. Converts an essentially two-state signal to a single-bit binary number

NOTE Type 1 digital inputs may not be suitable for use with solid-state devices such as sensors, proximity switches, etc.

S.2.2

digital input, type 2

device for sensing signals from solid-state switching devices such as two-wire proximity switches. Converts an essentially 2-state signal to a single-bit binary number

NOTE 1 Two-wire proximity switches described here are designed to IEC 60947-5-2.

NOTE 2 This class could also be used for type 1 applications.

S.2.3

digital output

device which converts a single-bit binary number to a 2-state signal

S.2.4

current sinking

property of receiving current

S.2.5

current sourcing

property of supplying current

S.3 Functional requirements

S.3.1 Rated values and operating ranges

Externally powered I/O modules shall be as shown in Table S.1.

Table S.1 – Rated values and operating ranges of incoming power supply

Voltage		Frequency		Recommended use (R)		Normative items and note ^c
Rated (U_e)	Tolerance (min./max.)	Rated (F_n)	Tolerance (min./max.)	Power supply	I/O signals	
DC 24 V	-15 %/+20 %			R	R	^a
DC 48 V				R	R	a, b
DC 125 V				–	–	–
AC 24 V r.m.s.	-15 %/+10 %	50 Hz or 60 Hz	-6 %/+4 %	–	–	(see note)
AC 48 V r.m.s.				–	–	(see note)
AC 100 V r.m.s.				R	R	–
AC 110 V r.m.s.				R	R	(see note)
AC 120 V r.m.s.				R	R	–
AC 200 V r.m.s.				R	R	(see note)
AC 230 V r.m.s.				R	R	–
AC 240 V r.m.s.				R	R	(see note), ^d
AC 400 V r.m.s.				R	–	–

^a In addition to the voltage tolerances, a total a.c. component having a peak value of 5 % of the rated voltage is allowed. The absolute limits are d.c. 30/19,2 V for d.c. 24 V and d.c. 60/38,4 V for d.c. 48 V.

^b See footnote ^e of Table S.2 if type 2 digital inputs are likely to be used.

^c For incoming voltages other than those given in the table such as d.c. 110 V etc., the tolerances given in the table and footnote ^a apply. These voltage tolerances shall be used to calculate the input limits of Table S.2, using the equations given in S.6.

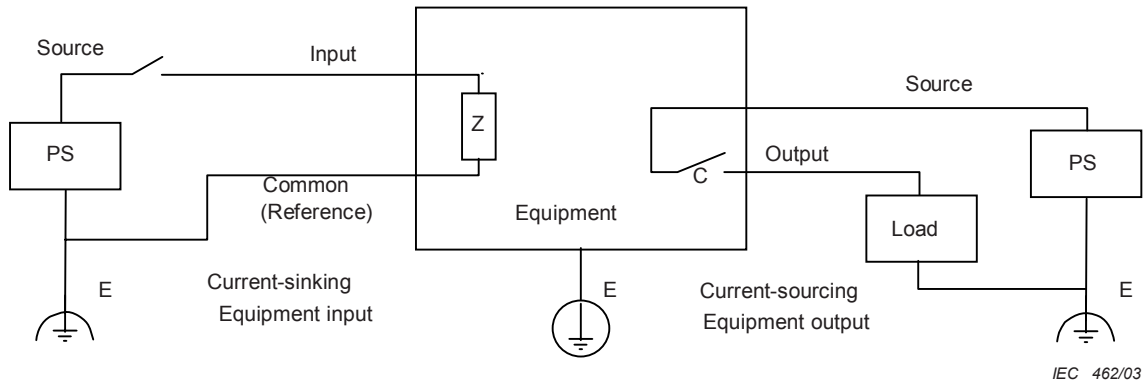
^d Three-phase supply.

NOTE The rated voltages are derived from IEC 60038.

S.3.2 Digital I/Os

S.3.2.1 General

Figure S.1 gives an illustration of definitions of some I/O parameters.



Key

- C output
Mechanical or static contact (for example dry relay contact, triac, transistor or equivalent).
- E earthings
the earths shown are original.
earthing is dependent on national regulations and/or application needs.
- Z input
input impedance
- PS external power supplies

NOTE Some applications may use only one PS common to inputs, outputs and equipment.

Figure S.1 – I/O parameters

Digital I/Os shall comply with the following requirements.

Digital inputs shall comply with the requirements of the standard voltage ratings given in S.3.2.2.

Digital outputs shall comply with the requirements of the standard ratings given in S.3.2.3.2 for a.c. or S.3.2.4.2 for d.c..

It shall be possible to interconnect inputs and outputs by means of a correct selection of other I/Os, resulting in proper operation (additional external load shall be specified by the manufacturer if necessary).

The circuit shall comply with the clearance and creepage distance requirements and the dielectric test corresponding to the voltage between phases.

NOTE Current-sourcing inputs and current-sinking outputs which may be required for certain applications are not covered in this annex. Special care should be exercised in their use. (Where positive logic, current-sinking inputs and current-sourcing outputs are used, any short-circuit to the reference potential and wire-breakage are interpreted by the inputs and loads as the “off state”; on the other hand, for current-sourcing inputs and current-sinking outputs, earth faults are interpreted as the “on state”) (see Figure S.1).

S.3.2.2 Digital inputs (current sinking)

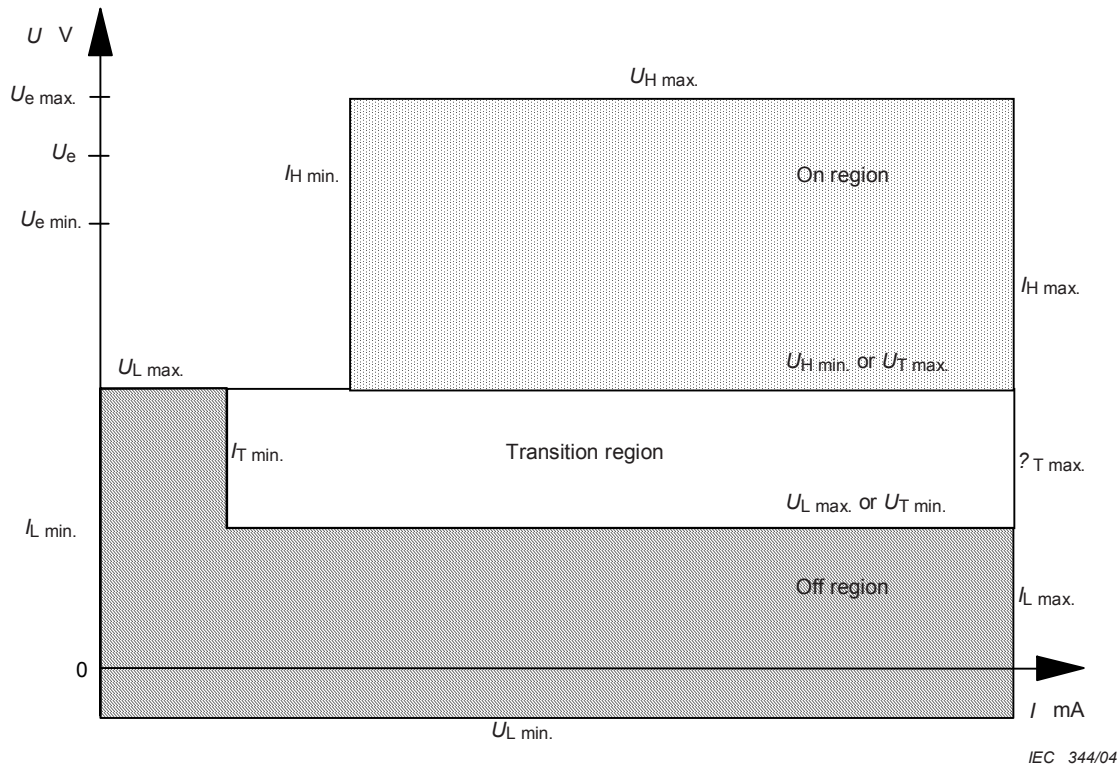
S.3.2.2.1 General

Requirements of this subclause are verified in accordance with S.4.2.

S.3.2.2.2 Terminology (U/I operation regions)

Figure S.2 represents graphically the limits and operating ranges which are used herein to characterize current sinking digital input circuits.

The operating region consists of “on region”, “transition region” and “off region”. It is necessary to exceed both U_T min. and I_T min. to leave the “off region”, and to exceed I_H min. before U_H min. to enter the “on region”: all input U-I curves shall remain within these boundary conditions. The region below zero volts is a valid part of the “off region” for d.c. inputs only.



NOTE

U_{Hmax} and U_{Hmin} are the voltage limits for the on conditions (state 1)

I_{Hmax} and I_{Hmin} are the current limits for the on conditions (state 1)

U_{Tmax} and U_{Tmin} are the voltage limits for the transition state (on or off)

I_{Tmax} and I_{Tmin} are the current limits for the transition state (on or off)

U_{Lmax} and U_{Lmin} are the voltage limits for the off conditions (state 0)

I_{Lmax} and I_{Lmin} are the current limits for the off conditions (state 0)

U_{Lmax} equals U_{Hmin} to I_{Tmin} and equals U_{Tmin} above I_{Tmin}

U_e , $U_{e max}$ and $U_{e min}$ are the rated voltage and its limits for the external power supply voltage

Figure S.2 – U-I operation regions of current-sinking inputs

S.3.2.2.3 Standard operating ranges for digital inputs (current sinking)

Current-sinking digital inputs shall operate within the limits presented in Table S.2.

Table S.2 – Standard operating ranges for digital inputs (current sinking)

Rated voltage U_e	Rated frequency F_n Hz	Type of limit	Type 1 limits ^g						Type 2 limits ^g (see note)						Normative items
			State 0		Transition		State 1		State 0		Transition		State 1		
			U_L V	I_L mA	U_T V	I_T mA	U_H V	I_H mA	U_L V	I_L mA	U_T V	I_T mA	U_H V	I_H mA	
DC 24V	—	Max. Min.	15/5 -3	15 ND	15 5	15 0,5	30 15	15 2	11/5 -3	30 ND	11 5	30 2	30 11	30 6	a, b, d, e
DC 48V	—	Max. Min.	34/10 -6	15 ND	34 10	15 0,5	60 34	15 2	30/10 -6	30 ND	30 10	2 2	60 30	30 6	a, b, d
AC 24V V r.m.s.	50/60	Max. Min.	14/5 0	15 0	14 5	15 1	27 14	15 2	10/5 0	30 0	10 5	30 4	27 10	30 6	a, c
AC 48 V r.m.s.	50/60	Max. Min.	34/10 0	15 0	34 10	15 1	53 34	15 2	29/10 0	30 0	29 10	4 4	53 29	30 6	a, c
AC 100 AC 110 AC 120 V r.m.s.	50/60	Max. Min.	79/20 0	15 0	79 20	15 1	1,1 U_e 79	15 2	74/20 0	30 0	74 20	30 4	1,1 U_e 74	30 6	a, c, d, f
AC 200 AC 230 AC 240 V r.m.s.	50/60	Max. Min.	164/40 0	15 0	164 40	15 2	1,1 U_e 164	15 3	159/40 0	30 0	159 40	30 5	1,1 U_e 159	30 7	a, c, d, f

- ^a All logic signals are in positive logic. Open inputs shall be interpreted as state 0 signal. See S.6 for equations and assumptions used in developing values in this table and for additional comments.
- ^b The given voltage limits include all alternating voltages components.
- ^c Static switches may affect the total r.m.s. content of true harmonics of the input signals and therefore affect the compatibility of the input interface with proximity switches, especially for type 2, a.c. 24 V r.m.s. See S.3.1 for requirements.
- ^d Recommended for common usage and future designs.
- ^e The minimum external power supply voltage for type 2, d.c. 24 V inputs connected to 2-wire proximity switches should be higher than d.c. 20 V or U_H min lower than d.c. 11 V to allow sufficient safety margin.
- ^f As allowed by current technology, and to encourage the design of single input modules compatible with all commonly used rated voltages, limits are absolute and independent of rated voltage (except U_H max) and based on equations given in T.6 and respectively a.c. 100 V r.m.s. and a.c. 200 V r.m.s.
- ^g See definitions S.2.1, S.2.2. and S.2.3.

NOTE Compatibility with 2-wire proximity switches according to IEC 60947-5-2 is possible with type 2, see also footnote ^c).
ND = Not defined.

S.3.2.2.4 Additional requirements

Each input channel shall be provided with a lamp or equivalent means to indicate the state 1 condition when the indicator is energized.

S.3.2.3 Digital outputs for alternating currents (current sourcing)

S.3.2.3.1 General

Requirements of this subclause are verified in accordance with S.4.3.

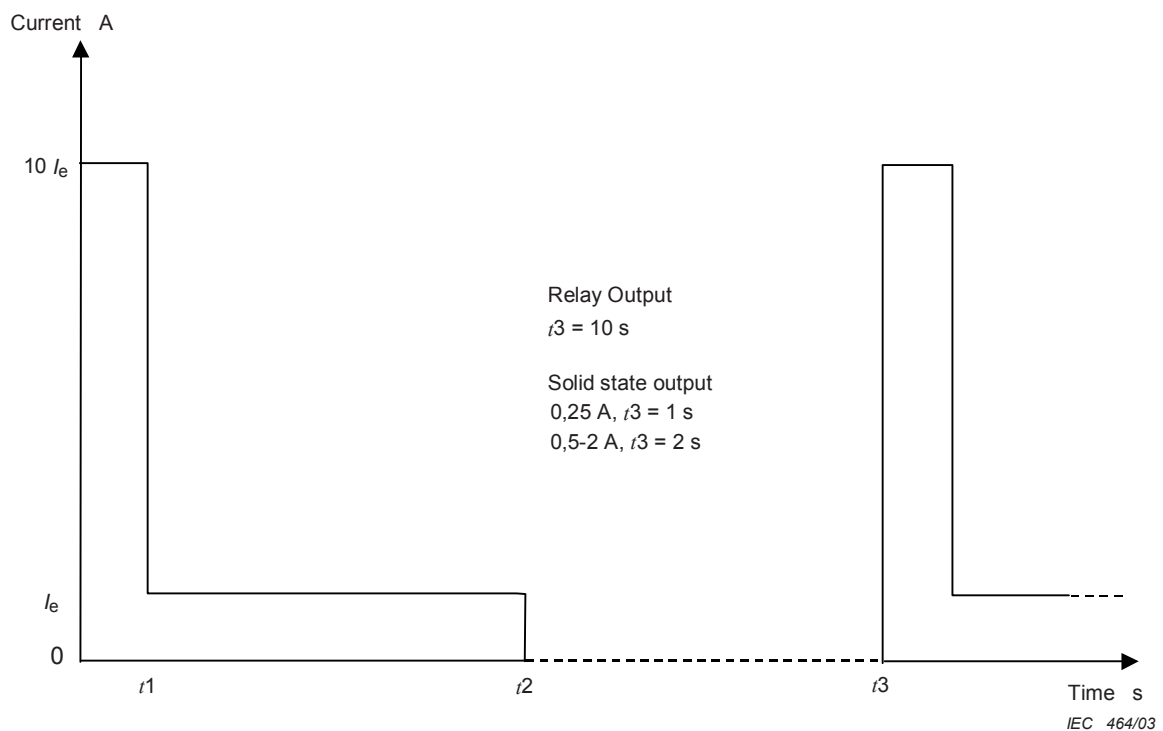
S.3.2.3.2 Rated values and operating ranges (a.c.)

Digital a.c. outputs shall comply with the ratings given in Table S.3, at the output voltage(s) stated by the manufacturer according to S.3.1.

Table S.3 – Rated values and operating ranges for current sourcing digital a.c. outputs

Rated current (state 1)	I_e A	0,25	0,5	1	2	Normative items
Current range for state 1 (continuous at max. voltage)	Min. (mA)	10 [5]	20	100	100	a, b
	Max. (A)	0,28	0,55	1,1	2,2	a
Voltage drop, U_d for state 1	U_d	–	–	–	–	–
	– Non protected output Max. (V)	3	3	3	3	a
	– Protected and short-circuit proof Max. (V)	5	5	5	5	a
Leakage current for state 0		–	–	–	–	–
	– Solid-state outputs Max. (mA)	5 [3]	10	10	10	a, b, c
	– Electromechanical outputs Max. (mA)	2,5	2,5	2,5	2,5	a, c
Repetition rate for temporary overload (see Figure S.3)	Operating cycle time (s)	–	–	–	–	
	– Solid-state outputs Max.	1	2	2	2	
	– Relay-based outputs Max.	10	10	10	10	

a RMS currents and voltages.
b Figures in square brackets apply to a module not equipped with RC network or equivalent surge suppressers. All other values apply to modules with suppression.
c Leakage current for solid-state outputs greater than 3 mA imply the use of additional external loads to drive type 2 digital inputs.



- t1 2 cycles at F_n (F_n = rated line frequency)
- t2 ON time
- t3 - t2 OFF time (OFF time = ON time)
- t3 Operation time

Figure S.3 – Temporary overload waveform for digital a.c. outputs

S.3.2.3.3 Additional requirements

S.3.2.3.3.1 Output indicators

Each output channel shall be provided with a lamp or equivalent means to indicate the output state 1 condition when the indicator is energized.

S.3.2.3.3.2 Protected outputs

For outputs stated by the manufacturer to be protected

- the output shall either withstand and/or the associated protective device shall operate to protect the output for all steady-state values of output current greater than 1,1 times the rated value;
- after resetting or replacement of the protective device alone, as applicable, the equipment shall return to normal operation;
- optional restart capabilities may be selected among the three following types:
 - automated restart protected output: a protected output which automatically recovers after the overload is removed;
 - controlled restart protected output: a protected output which is reset through signals (for example, for remote control);
 - manual restart protected output: a protected output which implies a human action to recover (the protection may be fuses, electronic interlocks, etc.).

Requirements of this subclause are verified in accordance with S.4.3.2.

NOTE 1 Operation under overload condition for an extended period of time may affect the operating life of the module.

NOTE 2 The protected outputs will not necessarily protect the external wiring. It is the user's responsibility to provide that protection when it is needed.

S.3.2.3.3.3 Short-circuit-proof outputs

For outputs stated by the manufacturer to be short-circuit-proof:

- for all output currents greater than $I_{e \max}$ and up to 2 times the rated value I_e , the output shall operate and withstand temporary overload(s). Such temporary overload(s) shall be specified by the manufacturer.
- for all output currents prospectively above 20 times the rated value, the protective device shall operate. After resetting or replacement of the protective device alone, the equipment shall return to normal operation.
- for output currents in the range of 2 times to 20 times I_e , or for temporary overload(s) beyond the limits specified by the manufacturer (item 1 above), the module may require repair or replacement.

Requirements of this subclause are verified in accordance with S.4.3.2.

S.3.2.3.3.4 Non-protected outputs

For outputs stated by the manufacturer to be non-protected, if the manufacturer recommends an external protection device, then the outputs shall meet all the requirements stated for the short-circuit-proof outputs.

S.3.2.3.3.5 Electromechanical relay outputs

Electromechanical relay outputs shall be capable of performing at least 0,3 million operations with the load specified for AC-15 utilization category (durability class 0.3) according to IEC 60947-5-1.

The type test is not required if the relay components have been shown to comply with the requirements of IEC 60947-5-1.

S.3.2.4 Digital outputs for direct current (current sourcing)

S.3.2.4.1 General

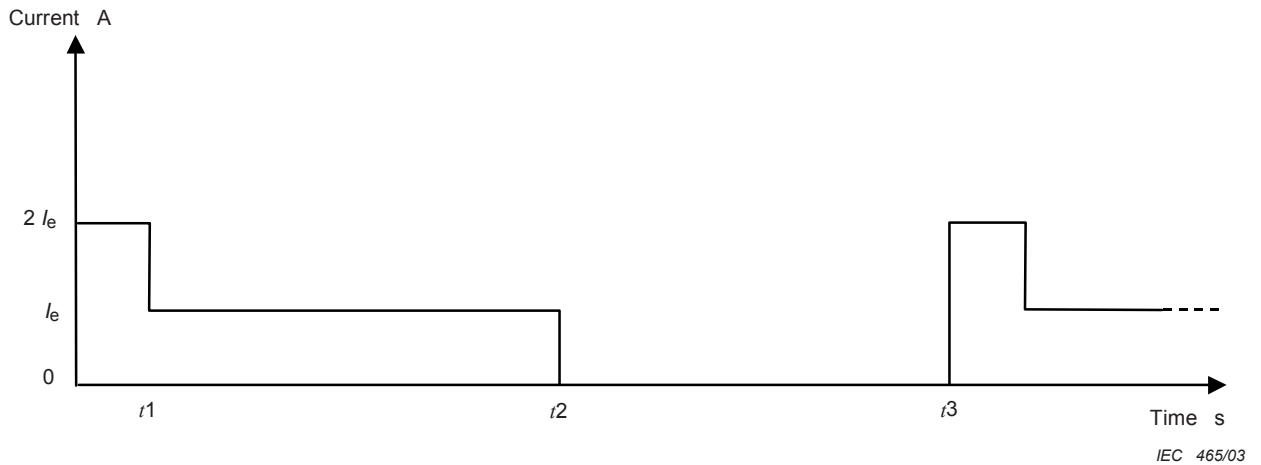
Requirements of this subclause are verified in accordance with S.4.3.

S.3.2.4.2 Rated values and operating ranges (d.c.)

Digital outputs shall comply with the ratings given in the following Table S.4, at the output voltage(s) stated by the manufacturer according to S.3.1.

**Table S.4 – Rated values and operating ranges (d.c.)
for current-sourcing digital d.c. outputs**

Rated current for state 1	I_e (A)	0,1	0,25	0,5	1	2	Normative items																		
Current range for state 1 at maximum voltage (continuous)	Max. (A)	0,12	0,3	0,6	1,2	2,4																			
Voltage drop, U_d	U_d	–	–	–	–	–	–																		
Non-protected output	Max. (V)	3	3	3	3	3	–																		
Protected and short-circuit-proof		3	3	3	3	3	a																		
Leakage current for state 0	Max. (mA)	0,1	0,5	0,5	1	1	b, c																		
Temporary overload	Max. (A)	See Figure S.2 or as specified by manufacturer																							
<p>^a For 1 A and 2 A rated currents, if reverse polarity protection is provided, a 5 V drop is allowed. This makes the output incompatible with a type 1 input of the same voltage rating.</p> <p>^b The resulting compatibility between d.c. outputs and d.c. inputs, without additional external load, is as follows:</p> <table style="margin-left: 20px;"> <tr> <td>Rated output current I_e (A):</td> <td>0,1</td> <td>0,25</td> <td>0,5</td> <td>1</td> <td>2</td> </tr> <tr> <td> Type 1: yes</td> <td>yes</td> <td>yes</td> <td>yes</td> <td>no</td> <td>no</td> </tr> <tr> <td> Type 2: yes</td> <td>yes</td> <td>yes</td> <td>yes</td> <td>yes</td> <td>yes</td> </tr> </table> <p>^c With adequate external load, all d.c. outputs may become compatible with all type 1 and type 2 d.c. inputs.</p>								Rated output current I_e (A):	0,1	0,25	0,5	1	2	Type 1: yes	yes	yes	yes	no	no	Type 2: yes	yes	yes	yes	yes	yes
Rated output current I_e (A):	0,1	0,25	0,5	1	2																				
Type 1: yes	yes	yes	yes	no	no																				
Type 2: yes	yes	yes	yes	yes	yes																				



- t_1 = surge time = 10 ms
- t_2 = ON time
- $t_3 - t_2$ = OFF time (OFF time=ON time)
- t_3 = operation time = 1 s

Figure S.4 – Temporary overload waveform for digital d.c. outputs

S.3.2.4.3 Additional requirements

Other requirements are the same as for current sourcing outputs for a.c. as defined in S.3.2.3.3, except for:

- protected outputs: the limit is $1,2 I_e$ instead of $1,1 I_e$.
- electromechanical relay outputs: AC-15 is replaced by DC-13.

S.4 Verification of input/output requirements

S.4.1 General

Test procedures are not defined in detail hereinafter. Detailed procedures shall be agreed upon by the user and the manufacturer and shall be such that the conditions defined in S.4.4 shall not be impaired.

Though test procedures are not defined in detail, all tests which are referenced shall be performed.

Unless otherwise specified in this subclause, all tests shall be carried out twice on the same I/O channel(s):

- First test: at minimum service temperature.
- Second test: at maximum service temperature.

It is not required to test more than one digital input of each type.

S.4.2 Verification of digital inputs

S.4.2.1 Operating range test

Verify that all requirements are met.

Test procedures: To be agreed upon by the user and manufacturer.

S.4.2.2 Reversal of signal polarity test (withstand test)

Test procedure: A signal of reverse polarity for digital inputs shall be applied for 10 s.

Verification:

The equipment shall comply with the requirements specified in S.4.4.

S.4.3 Verification of digital outputs

S.4.3.1 Operating range test

Verify that all requirements are met.

Test procedures:

Current range: To be agreed upon by the user and manufacturer.

Voltage drop: To be agreed upon by the user and manufacturer.

Leakage current: Devices/circuits intended for output protection shall not be removed.

Temporary overload: According to IEC 60947-5-1, (AC-15 or DC-13, as applicable). For short-circuit proof outputs, the current values shall be respectively $2 I_e$ to $20 I_e$ (as given in S.3.2.3.3.3).

S.4.3.2 Test of protected, not-protected, and short-circuit proof outputs

Table S.5 – Overload and short-circuit tests for digital outputs

Reference test	None				
EUT configuration	According to manufacturer's specifications				
Details of mounting/support	According to manufacturer's specifications				
Loading	It is sufficient to check one I/O channel of each type under test				
Initial measurements	See S.4.4				
Description of the tests	A	B	C	D	E
Prospective currents ($k \times I_e$)	1,2/1,3 ^a	1,5	2	5	21
Duration of test (min)	5	5	5	5	5
Order of trials	–	–	–	–	–
First series (at T_{min})	1	2	3	4	5
Second series (at T_{max})	6	7	8	9	10
Time intervals between tests	10 min \leq time intervals \leq 60 min				
Application of the test protected outputs	Yes	Yes	Yes	Yes	Yes
Short-circuit proof outputs	No	No	Yes ^b	No	Yes ^d
Not-protected outputs ^c	No	No	Yes ^b	No	Yes ^d
Measurement and verification	See requirements in S.3.2.3.3 and S.3.2.4.3				
during the overload	See S.4.4				
immediately after overload	See S.4.4				
after overload and proper resetting	See S.4.4				
^a 1,2 for a.c. outputs, 1,3 for d.c. outputs. ^b For currents in the range of 2 times to 20 times I_e , the module may require repair or replacement. ^c Protective device(s) to be provided or specified by the manufacturer shall be installed. ^d Protective device(s) shall operate. They shall be reset or replaced as applicable for the following test.					

S.4.3.3 Reversal of signal polarity test (withstand test)

If the equipment is designed to prevent reversal of signal polarity, the withstand test may be not carried out and replaced by proper visual inspection.

Test procedure:

A signal of reverse polarity for digital d.c. outputs shall be applied for 10 s.

Verification:

The equipment shall comply with the requirements specified in S.4.4.

S.4.4 Behaviour of the equipment

The verification of general requirements for digital I/Os under S.3.2 shall be met.

The behaviour of the digital I/Os shall be as expected regarding the functional conditions of the equipment. If appropriate, the product standard may specify additional requirements.

The verification of the EMC requirements shall be performed according to 8.4. Concerning immunity, the values of Table 23 apply.

S.5 General information to be provided by the manufacturer

S.5.1 Information on digital inputs (current sinking)

The manufacturer shall provide the following information:

- volt-ampere curve over the full operating range, with tolerances or equivalent;
- digital input delay time for 0 to 1 and 1 to 0 transitions;
- existence of common points between channels;
- effect of incorrect input terminal connection;
- isolation potentials between channel and other circuits (including ground) and between channels under normal operation;
- type of input (type 1 or type 2);
- monitoring point and binary state of visual indicator;
- effects when withdrawing/inserting input module under power;
- additional external load when interconnecting inputs and outputs, if needed;
- explanation of signal evaluation (for example, static/dynamic evaluation, interrupt release, etc.);
- recommended cable and cord lengths depending on cable type and electromagnetic compatibility;
- terminal arrangements;
- typical example(s) of external connections.

S.5.2 Information on digital outputs for alternating currents (current sourcing)

The manufacturer shall provide the following information with respect to digital outputs for a.c. operation:

- type of protection (i.e. protected, short-circuit-proof, non-protected output), and
- for protected outputs: operating characteristics beyond $1,1 I_e$ including the current(s) level(s) at which the protecting device energizes, the current behaviour beyond, and the time(s) involved;
- for short-circuit-proof outputs: information for replacement or resetting the protective device as required;
- for non-protected outputs: specification for protective device to be provided by the user, as required;
- output delay time for state 0 to state 1 and state 1 to state 0 transitions;
- commutation characteristics and turn-on voltage with respect to zero-voltage crossing;
- existence of common points between channels;
- terminal arrangements;
- typical example(s) of external connections;
- number and type of outputs (for example, NO/NC contacts, solid state, individually isolated channels, etc.);
- for electromechanical relays, the rated current and voltage complying with S.3.2.3.3.5;
- output ratings for the other loads such as incandescent lamps;
- characteristics of suppresser networks incorporated into the output circuit against voltage peaks due to inductive kickback;
- type of external protective networks, if required;
- effects of incorrect output terminal connection;

- isolation potentials between channel and other circuits (including ground) and between channels under normal operation;
- monitoring points of visual indicators in the channel (for example, MPU side/load side);
- recommended procedures for changing output modules;
- way of operation (i.e. latching/non-latching type);
- effects of multiple overloads on isolated multi-channel modules.

S.5.3 Information on digital outputs for direct current (current sourcing)

Information to be provided by the manufacturer for digital outputs for d.c. shall be the same as for digital outputs for a.c., as defined in S.5.2. However, the specification of commutation for zero-voltage crossing does not apply, and with regard to electromechanical relay outputs, AC-15 is replaced by DC-13 in S.3.2.3.3.5.

S.6 Digital input standard operating range equations

The following equations were used to generate Table S.2 (with some exceptions explained in the notes).

DC equations

$$U_{H \max} = 1,25 U_e$$

$$U_{H \min} = 0,8 U_n - U_d - 1 \text{ V}$$

$$U_{T \max} = U_{H \min}$$

$$U_{L \max} = U_{H \min} \text{ for } I \leq I_{T \min}$$

$$U_{T \min} = 0,2 U_n$$

$$U_{L \max} = U_{T \min} \text{ for } I > I_{T \min}$$

$$U_{L \min} = -3 \text{ V (DC 24 V)}$$

$$U_{L \min} = -6 \text{ V (DC 48 V)}$$

$$I_{L \min} = \text{ND (Not defined)}$$

Type 1 inputs:

$$I_{H \max} = I_{T \max} = I_{L \max} = 15 \text{ mA}$$

$$I_{H \min} \approx I_{T \min} + 1 \text{ mA}$$

$$I_{T \min} \approx U_{H \max}/Z$$

$$U_d = 3 \text{ V (Table T.4)}$$

Type 2 inputs:

$$I_{H \max} = I_{T \max} = I_{L \max} = 30 \text{ mA}$$

$$I_{H \min} = I_m + 1 \text{ mA} = 6 \text{ mA}$$

$$I_{T \min} = I_r = 1,5 \text{ mA}$$

$$U_d = \text{d.c. } 8 \text{ V}$$

AC equations

$$U_{H \max} = 1,1 U_e$$

$$U_{H \min} = 0,85 U_n - U_d - 1 \text{ V} \quad (\text{NOTES 1, 2})$$

$$U_{T \max} = U_{H \min}$$

$$U_{L \max} = U_{H \min} \text{ for } I \leq I_{T \min}$$

$$U_{T \min} = 0,2 U_n \quad (\text{NOTE 1})$$

$$U_{L \max} = U_{T \min} \text{ for } I > I_{T \min}$$

$$U_{L \min} = 0$$

$$I_{L \min} = 0$$

Type 1 inputs:

$$I_{H \max} = I_{T \max} = I_{L \max} = 15 \text{ mA}$$

$$I_{H \min} \approx I_{T \min} + 1 \text{ mA } (U_e \leq 120 \text{ V r.m.s.}) \text{ or}$$

$$I_{H \min} \approx I_{T \min} + 2 \text{ mA } (U_e > 120 \text{ V r.m.s.})$$

$$I_{T \min} \approx U_{H \max}/Z \quad (\text{NOTE 5})$$

$$U_d = 5 \text{ V (Table T.3)} \quad (\text{NOTE 3})$$

Type 2 inputs:

$$I_{H \max} = I_{T \max} = I_{L \max} = 30 \text{ mA}$$

$$I_{H \min} \approx I_m + 1 \text{ mA} = 6 \text{ mA}$$

$$I_{T \min} \approx I_r = 3 \text{ mA} \quad (\text{NOTE 4})$$

$$U_d = \text{a.c. } 10 \text{ V r.m.s.} \quad (\text{NOTE 4})$$

NOTE 1 For all a.c. 100/110/120 V r.m.s. and all a.c. 200/220/230/240 V r.m.s. inputs, U_n has been respectively selected as a.c. 100 V r.m.s. and a.c. 200 V r.m.s., in order to allow compatibility with various supply voltages.

NOTE 2 1 V drop (a.c. or d.c.) is assumed for the connecting leads.

NOTE 3 Maximum values of voltage drops, U_d , of digital outputs for d.c. and a.c.

NOTE 4 These values of I_r , U_d and I_m correspond to those adopted in IEC 60947-5-2.

NOTE 5 Z = Empirical worst-case relay contact, open-contact impedance = 100 k Ω

A₁ **Annex T**
(normative)

Extended functions within electronic overload relays

T.1 Scope

T.1.1 General

This annex is intended to cover extended functions included in electronic overload relays not directly related to the overload protection. Extended functions may also ensure some control functions. Control functions are under consideration.

NOTE Electronic relay with extended functions may also be called in the field with other designation such as: "motor management system", "motor protector"...

This annex applies only to electronic relays intended for use in a.c. circuits.

T.1.2 Ground/earth fault detection function

Devices reacting to ground/earth fault currents are used as protective systems. Such devices are frequently used in conjunction with or as an integral part of electronic overload relays to detect ground/earth fault current in equipment in order to provide additional protection against fire and other hazards which may develop as a result of an ground/earth fault of a lasting nature which cannot be detected by the over-current protective function. The behaviour due to the presence of a d.c. component is not considered.

NOTE This ground/earth fault detection protection is not intended to provide protection against electric shock

T.2 Definitions

For the purposes of this annex, the following definitions apply.

T.2.1

electronic overload relay with ground/earth fault detection function

multipole electronic relay which operates when the vectorial sum of the currents flowing in the main circuit has increased above a predetermined value in accordance with specified requirements

T.2.2

electronic overload relay with current or voltage asymmetry function

electronic overload relay which operates in the case of current or voltage magnitude unbalance in accordance with specified requirements

T.2.3

electronic overload relay with phase reversal function

multipole electronic overload relay which operates in the case of improper phase sequence at the line side of the equipment in accordance with specified requirements

T.2.4

electronic overload relay with over voltage function

electronic overload relay which operates in the case of overload and when the voltage has increased above a predetermined value in accordance with specified requirements **A₁**

A1 T.2.5
inhibit current

I_{ic}
fault current above which a switching device is not initiated to open by the electronic overload relay

T.2.6
electronic overload relay with under power function

electronic overload relay which operates in response to a power magnitude below a predetermined value in accordance with specified requirements

T.3 Classification of electronic overload relays

- a) Current and voltage asymmetry relay or release.
- b) Over-voltage relay or release.
- c) Ground/earth fault sensing relay or release.
- d) Phase reversal relay or release.

T.4 Types of relays with ground/earth fault detection function

Type CI-A and CI-B: a Type CI electronic overload relay will initiate opening of the switching device at all levels of fault current.

Type CII-A and CII-B: a Type CII electronic overload relay will not initiate opening of the switching device above a current setting level I_{ic} (inhibit current).

NOTE 1 Type CII(-A or -B) relays are typically used in conjunction with switching devices having a breaking capacity lower than the maximum expected fault current. The current setting I_{ic} (inhibit current) is adjusted according to the maximum breaking capacity of the switching device.

NOTE 2 Types (CI or CII)-A differentiate to types (CI or CII)-B according to their operating characteristics (see Table T.1).

T.5 Performance requirements

T.5.1 Limits of operation of ground/earth fault electronic overload relays

A ground/earth fault overload relay, when associated with a switching device, shall operate to open the switching device according to the requirements given in Table T.1. For relays or releases with a ground/earth fault current setting range, the limit of operation of the relay shall be verified at the lowest and highest settings.

Table T.1 – Operating time of ground/earth fault electronic overload relays

Type	Multiples of ground/earth fault current setting	Tripping time T_p ms
CI-A and CII-A	$\leq 0,9$	No trip
	1,1	$10 < T_p \leq 1\ 000^a$
CI-B and CII-B	$\leq 0,75$	No trip
	1,25	$10 < T_p \leq 5\ 000^a$

^a Test to be done with test current $< I_{ic}$ (inhibit current); see T.6.1.



**A1) T.5.2 Limits of operation of ground/earth fault current sensing electronic relays
Type CII(-A and -B)**

Subclause T.5.1 applies with the following addition.

A ground/earth fault current sensing electronic relay CII, when associated with a switching device, shall not initiate operation of the switching device, in the presence of a ground/earth fault current, when the fault current in any phase reaches or exceeds 95 % the current setting I_{ic} (see T.4) and shall operate to open the equipment when the fault current in any phase is 75 % or less of I_{ic} .

T.5.3 Limits of operation of voltage asymmetry relays

A voltage asymmetry relay, when associated with a switching device, shall operate to open the switching device within 120 % of the time setting and shall operate to prevent the closing of the switching device when the voltage asymmetry is above 1,2 times the voltage asymmetry setting.

T.5.4 Limits of operation of phase reversal relays

A phase reversal relay, when associated with a switching device, shall permit the closing of the equipment when the voltage sequence of phases on the line side of the starter is the same as the voltage sequence setting. After interchanging two phases, the phase reversal relay shall prevent the completion of the closing operation of the switching device.

T.5.5 Limits of operation of current imbalance relays

A2) A current imbalance relay, when associated with a switching device, shall operate to open the equipment within 80 % to 120 % of the time setting where the current imbalance, defined as the ratio (T.1) between the maximum current deviation of any phase from average current and the average current I_{avg} (T.2), is above 1,2 times the current imbalance setting, the general tripping requirements of overload relays given in the product standard being maintained.

$$\text{Ratio} = \frac{\max_{i=1}^n |I_i - I_{avg}|}{I_{avg}} \quad (\text{T.1})$$

$$I_{avg} = \frac{\sum_{i=1}^n I_i}{n} \quad (\text{T.2})$$

where

n is the number of phases;

I_i is the r.m.s value of the current in each phase. A2)

T.5.6 Limits of operation of over-voltage relays and releases**a) Operating voltage**

An over-voltage relay or release, when associated with a switching device, shall operate to open the equipment and shall operate to prevent the closing of the equipment when the supply voltage is above the set value, if any, or above 110 % of the rated voltage of the relay or release for a defined duration.

b) Operating time

For a time-delay over-voltage relay or release, the time-lag shall be measured from the instant when the voltage reaches the operating value until the instant when the relay or release actuates the tripping device of the equipment. A1)

A1 T.6 Tests

T.6.1 Limits of operation of ground/earth fault current sensing electronic relays Type CI and CII (-A and -B)

The limits of operation shall be in accordance with T.5.1 and verified as follows.

For overload relays with an adjustable ground/earth fault current setting, the test shall be made at the minimum and at the maximum current settings. The test circuit shall be in accordance with Figure T.1. The test shall be made at any convenient voltage and power factor.

The test circuit being calibrated at each of the values of the ground/earth fault operating current specified in the Table T.1, as applicable, and the switch S1 being in the closed position, the test current is suddenly established by closing switch S2.

For ground fault current sensing electronic relay type CII, the inhibit current shall be set to a value at least 30 % higher than the maximum ground/earth fault current setting.

T.6.2 Verification of inhibit function of ground/earth fault current sensing electronic relays Type CII (-A and -B)

For overload relays with an adjustable ground/earth fault current setting, the test shall be made at the lowest setting.

For overload relays with an adjustable inhibit current setting I_{ic} , the test shall be made at the minimum and at the maximum I_{ic} settings.

NOTE When the minimum ground/earth fault current setting is higher or equal to the minimum inhibit current setting, the inhibit current setting may be set to a slightly higher value.

The impedance Z is adjusted so as to let a current flow in the circuit equal to:

a) 95 % the inhibit current I_{ic}

The switch S1 being in the closed position, the test current is established by closing switch S2.

The overload relay shall not initiate the opening of the switching device.

b) 75 % the inhibit current I_{ic}

The switch S1 being in the closed position, the test current is established by closing switch S2.

The overload relay shall initiate the opening of the switching device.

Each phase has to be tested separately.

T.6.3 Current asymmetry relays

The limits of operation shall be verified in accordance with T.5.5.

T.6.4 Voltage asymmetry relays

The limits of operation shall be verified in accordance with T.5.3.

T.6.5 Phase reversal relays

The limits of operation shall be verified in accordance with T.5.4. **A1**

T.6.6 Over-voltage relays

The limits of operation shall be verified in accordance with T.5.6.

T.7 Routine and sampling tests

Electronic overload relays with extended functions shall be, in addition to tests of 8.1.3 or 8.1.4, submitted to additional tests to verify the proper operation of their relevant additional functions, according to T.5.

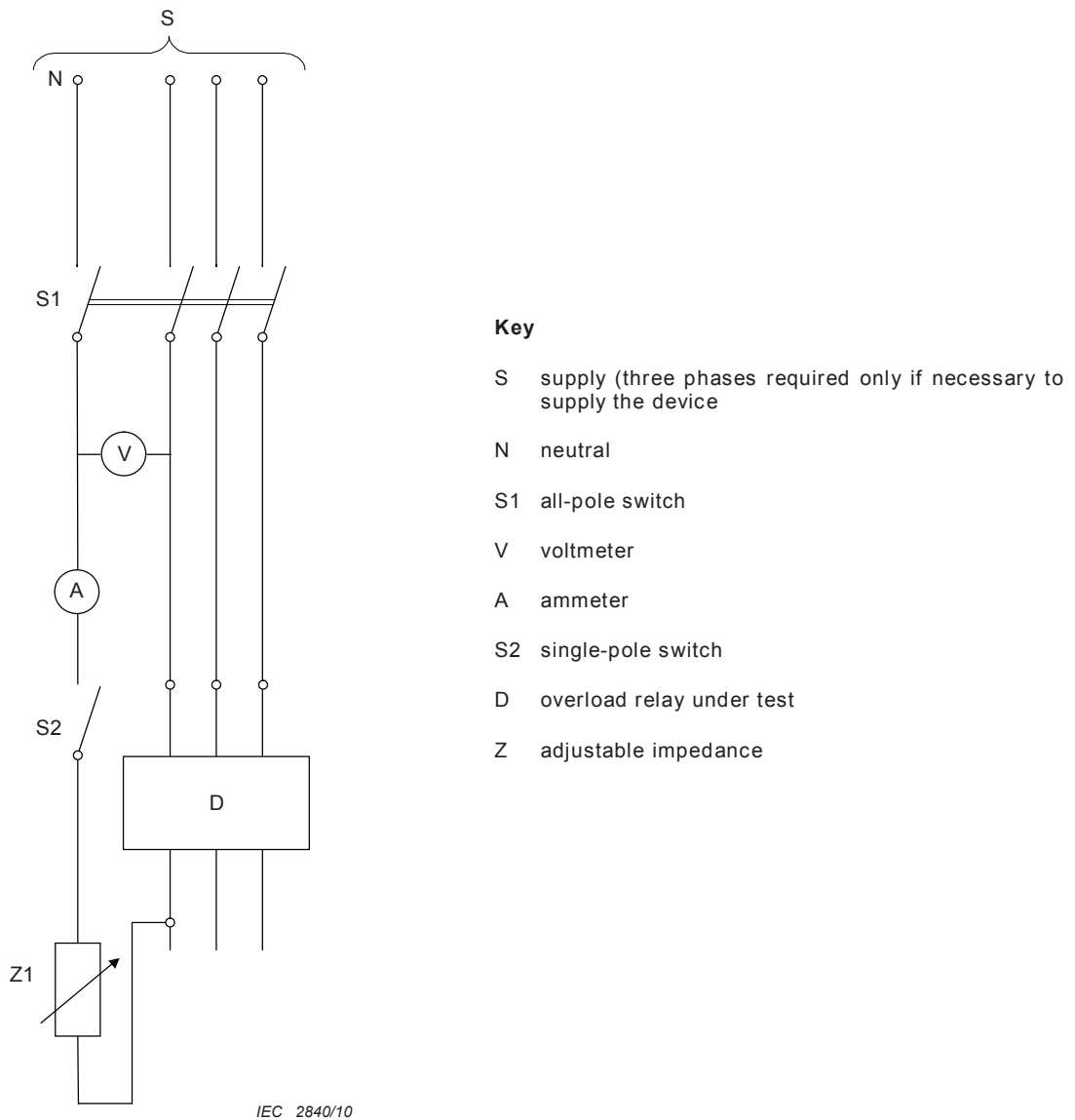


Figure T.1 – Test circuit for the verification of the operating characteristic of a ground/earth fault current sensing electronic relay \triangleleft

A1 Annex U (informative)

Examples of control circuit configurations

U.1 External control device (ECD)

U.1.1 Definition

external control device

A2 Text deleted **A2**

external element which serves to effect the control of the equipment

U.1.2 Diagrammatic representation of an **A2** external control device **A2**

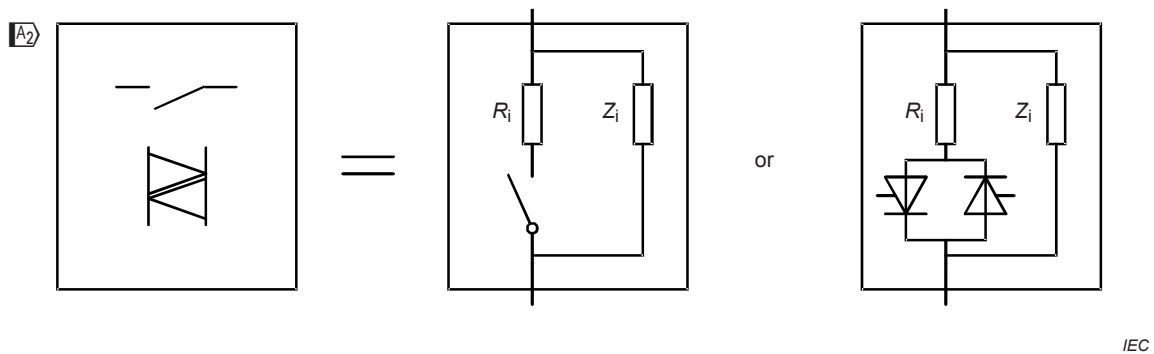


Figure U.1 – Diagrammatic representation of an external control device **A2**

U.1.3 Parameters of an **A2** external control device **A2**

- R_i : internal resistance;
- Z_i : internal leakage impedance.

NOTE In the case where **A2** external control device **A2** is a mechanical push button, R_i is often neglected and Z_i is often taken as infinity (∞). **A1**

A1 U.2 Control circuit configurations

U.2.1 Equipment with external control supply

U.2.1.1 Single supply and control input

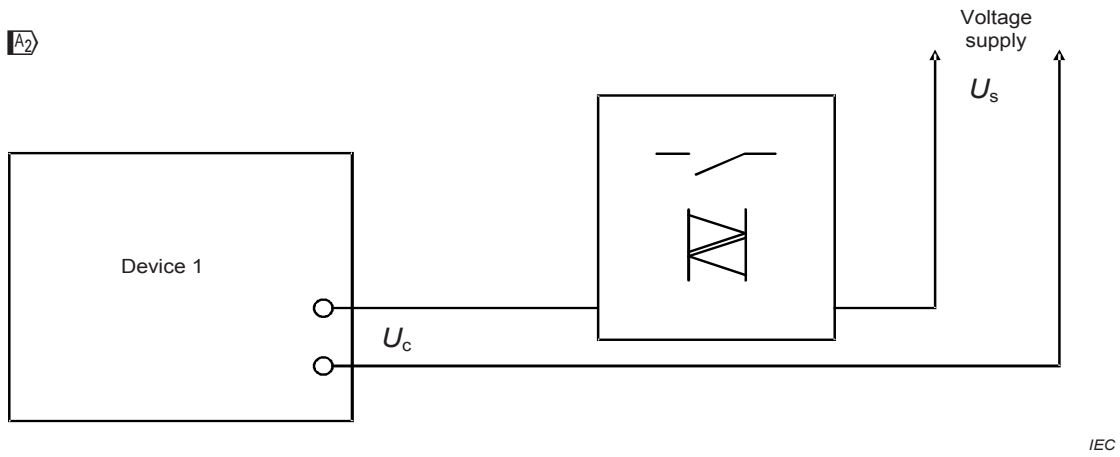


Figure U.2 – Single supply and control input **A2**

U.2.1.2 Separate supply and control inputs **A1**

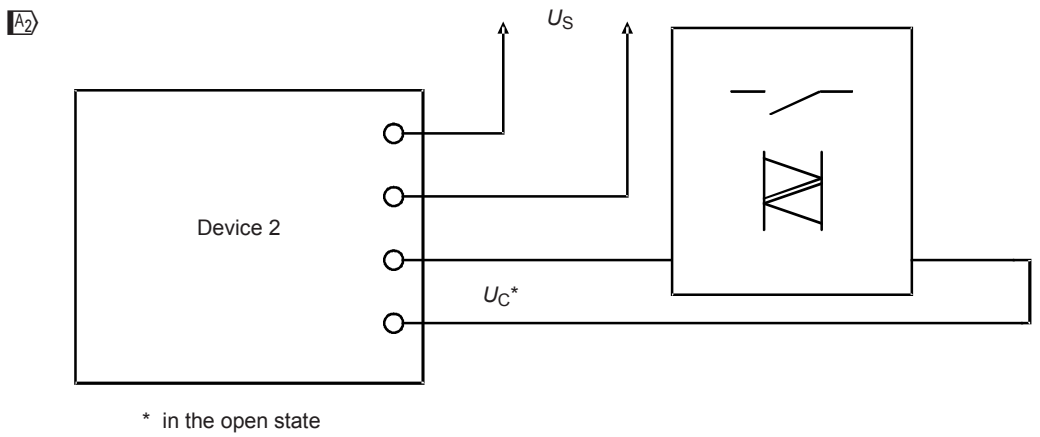
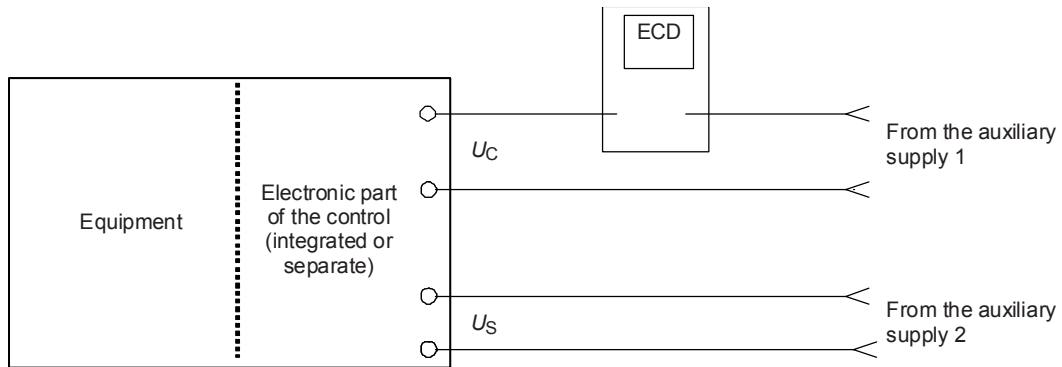


Figure U.3 – Separate supply and control inputs **A2**

A2 U.2.2 (Void) **A2**

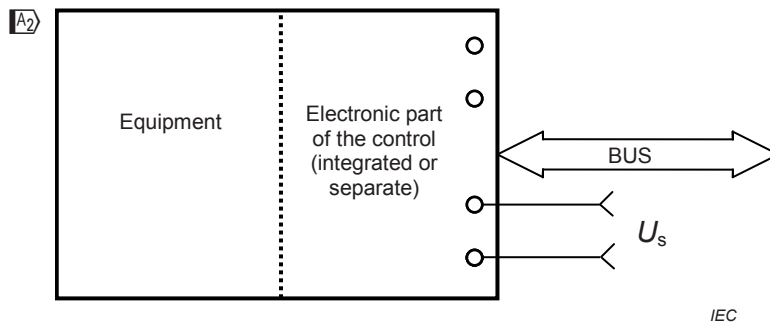
A1 U.2.3 Equipment with several external control supplies



IEC 2845/10

Figure U.5 – Equipment with several external control supplies

U.2.4 Equipment with bus interface
(may be combined with other circuit configurations) **A1**



IEC

Figure U.6 – Equipment with bus interface **A2**

A₂ Annex V
(informative)

**Power management with switchgear and controlgear
for electrical energy efficiency**

V.1 General

The energy efficiency of an application can be improved not only by using more efficient devices and loads, but also by improving the management of energy. The management of energy is performed through measurement, monitoring and control of the energy consuming loads aiming at consuming the just enough energy required for the application. Switchgear and controlgear are part of the energy management system which can be implemented also by using their communication capability.

V.2 Scope of this annex

This annex provides guidance for using switchgear and controlgear for controlling the loads in a way providing saving of energy. The principle developed in this annex is based on power management.

V.3 Terms and definitions

**V.3.1
energy management**

coordinated activities directing and controlling the energy use of an entity

[CEN/CLC/TR 16103]

**V.3.2
energy management system
EnMS**

set of interrelated or interacting elements to establish an energy policy and energy objectives, and processes and procedures to achieve those objectives

[ISO 50001:2011, 3.9]

**V.3.3
electrical energy efficiency**

various measures adopted within the electrical system or application in order to optimize the total electrical energy consumption needed during either the normal operation or the stand-by operation

**V.3.4
energy efficiency**

ratio or other quantitative relationship between an output of performance, service, goods or energy, and an input of energy

[ISO 50001:2011, 3.8] **A₂**

A2 V.3.5

load

current-using equipment

electric equipment intended to convert electric energy into another form of energy, for example light, heat, mechanical energy

[IEC 60050-826:2004, 826-16-02]

V.3.6

peak shaving

process in an electrical system intended to not exceed a maximum overall energy demand

NOTE Peak shaving can be obtained by planning of energy needs within the manufacturing system or load shedding or autonomous energy production.

V.3.7

load shedding

process of deliberately disconnecting preselected loads from a power system in response to an abnormal condition in order to maintain the integrity of the remainder of the system

[IEC 60050-603:1987, 603-04-32]

V.4 Electrical energy efficiency and safety

Safety of persons and of property remains of prime importance compared to energy efficiency statements. Consequently, all guidance to achieve energy efficiency will not impair the safety requirements included in relevant standards.

V.5 Principles on electrical energy efficiency (system approach)

V.5.1 General

The electrical energy optimization needs a global approach of the management of the electrical energy consumption, including consideration of all operation modes.

V.5.2 Strategy of energy management

Energy efficiency should firstly be applied to loads and their usage. Motors account for 70 % of the electricity consumed by the industry (figure from the European Community Commission Regulation No 640/2009). The electrical distribution architecture (generation and transmission) should also be considered, as well as power supplies and wiring systems.

V.5.3 Power management with automation and control

Power management through automation is the key for energy efficiency. Automation design of the past decades is being revisited in this perspective to integrate new modes that are now relevant due to the increasing importance of energy savings (availability and cost).

Status information, measurements from sensors, commands from the operator and information from the environment are necessary inputs to the energy management system (EnMS). The automation function of the energy management system shall ensure that the energy is consumed at the right moment, for the right purpose and in the right quantity. It may be very simple to complex (contactor relays, simple control loop, extended functions of circuit-breakers or of motor management systems, programmable logical controllers, etc). Contactors and starters are essential for managing power by switching remotely individual loads or groups of loads without adding significant power losses.

It applies in all sectors including manufacturing, process control, industrial facility management, building automation. **A2**

A2 EXAMPLE 1 In building automation, it is a common idea that the management system optimizes the usage of energy taking into account the occupancy schedule, the outside conditions (temperature, light) and the real presence of persons. From the idea to the effective realization, it might be a gap due for example to the difficult modelling of the thermal response of the building, to inaccurate detection of individuals, to not interoperable communication interfaces.

EXAMPLE 2 In discrete manufacturing industry, saving the useless consumption of the stand-by energy of the loads is an important field of improvement. It consists in switching off totally or partially the loads during short, long or unscheduled breaks. The challenge is to ensure a restart in the time constraints for the production facility.

V.6 Energy efficiency application

V.6.1 Saving of semiconductor losses

Contactors may also be used with semiconductor control devices like semiconductor contactors or starters. The bypassing of power semiconductor components by a contactor (e.g. for contactors or starters covered by IEC 60947-4-2) when at full speed will avoid losses in the semiconductor circuits. This limits the higher energy losses of a semiconductor contactor or starter to the starting and stopping time.

NOTE Typically, the energy saving is 90 % of the semiconductor losses.

Moreover, the addition of a contactor in series with a semiconductor device will avoid leakage currents in the OFF position, contributing consequently to saving energy.

V.6.2 Power factor correction

Power factor correction has a major impact on the energy efficiency of an installation. Thus, the power factor has to be maintained close to 1. As power factor depends on the nature of the loads switched on, an automatic capacitor bank (with or without detuned reactor depending on the level of harmonic) controlled by AC-6b rated contactors will optimize the energy efficiency.

V.6.3 Load shedding

When load shedding is initiated, the total load is systematically reduced until the required level is obtained, either by manually reducing or by shutting off individual loads, or by an automated system. All loads in a facility shall be defined in different categories including critical, essential, and nonessential loads. Usually only nonessential loads are shed, and the order of shedding can be configured.

V.6.4 Motor control for fixed speed applications

AC induction motor is the most common motor used in industry and mains powered home appliances.

An a.c. induction motor can consume more energy than it actually needs to perform its work, especially when operated with less than 30 % of the rated load or by unnecessary idling and jogging. A better choice of the motor and of the applied motor control will improve the global energy efficiency of the electric motor system.

NOTE The power dissipation of the various fuseless switching devices is in the range of 0,5 % of the power of the load to be switched.

Induction motors are basically designed as fixed speed devices. There are practically only two methods to change the rotation speed of a.c. induction motor (squirrel cage): use frequency converter or use motor with separate winding for different speeds. For the applications where speed control is needed, a frequency converter with a three phase a.c. motor should be used.

For fixed speed applications, the motor starter (direct on line, star-delta, two-step, soft starter) is the most energy efficient solution. **A2**

Annex W (normative)

Procedure to establish material declaration

W.1 General

Manufacturers are often requested by their customers to communicate and declare information about the material composition of their products. The main intended uses of this information are:

- enabling assessment of product compliance with substance-restriction requirements;
- use in environmentally conscious design processes.

Such communication and declaration of material composition information is usually known as material declaration.

Providing the material declaration is at discretion of the manufacturer.

IEC 62474 is intended to establish requirements for material declarations, standardize protocols, and facilitate transfer and processing of data. Compilation of material declarations of products is easier if IEC 62474 is thoroughly applied throughout the supply chain.

W.2 Scope of this annex

This annex specifies the procedure, content, and form relating to material declarations for low-voltage switchgear and controlgear. Process chemicals and emissions during product use are not in the scope of this annex.

W.3 Reference documents

IEC 62474:2012, *Material declaration for products of and for the electrotechnical industry*

W.4 Terms and definitions

W.4.1

declarable substance

substance that meets the criteria stated in IEC 62474 and is included in the IEC DB 62474

NOTE Substance is a single CAS# (for example. Lead (Pb) CAS # 7439-92-1)

[IEC 62474:2012, 3.2, modified]

W.4.2

declarable substance group

group of substances that meet the criteria stated in IEC 62474 and are included in the IEC DB 62474

NOTE Substance group is multiple CAS # (for example. Lead compounds)

[IEC 62474:2012, 3.2, modified] **A2**

A2 **W.4.3**

homogeneous material

one material of uniform composition throughout or a material, consisting of a combination of materials, that cannot be disjointed or separated into different materials by mechanical actions such as unscrewing, cutting, crushing, grinding and abrasive processes

NOTE Definition in accordance with EU DIRECTIVE 2011/65/EU.

W.4.4

material class

defined classification of materials that are established in referenced IEC 62474 database for purposes of inventorying aspects of a product, such that no two classes contain the same materials

[IEC 62474:2012, 3.5]

W.4.5

material declaration

communication of information about material composition of the product and declaration thereof, made in conformity with the requirements of IEC 62474

W.5 Material declaration

The material declaration shall be made in full compliance with IEC 62474, especially reporting criteria and format.

NOTE 1 Examples of material declaration are given in the IEC 62474.

NOTE 2 Specific examples for low-voltage switchgear and controlgear are under consideration.

NOTE 3 A single material declaration can be made for a family of products when the composition is the same for all the products thereof. **A2**

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- [8] IEC 60695-11-5, *Fire hazard testing – Part 11-5: Test flames – Needle-flame test method – Apparatus, confirmatory test arrangement and guidance*
- [9] IEC 60947-3:2008, *Low-voltage switchgear and controlgear – Part 3: Switches, disconnectors, switch-disconnectors and fuse-combination units*
Amendment 1 (2012)
- [10] IEC 60947-4-1:2009, *Low-voltage switchgear and controlgear – Part 4-1: Contactors and motor-starters – Electromechanical contactors and motor-starters*
Amendment 1 (2012)
- [11] IEC 60947-4-2:2011, *Low-voltage switchgear and controlgear – Part 4-2: Contactors and motor-starters – AC semiconductor motor controllers and starters*
- [12] IEC 60947-4-3:1999, *Low-voltage switchgear and controlgear – Part 4-3: Contactors and motor-starters – AC semiconductor controllers and contactors for non-motor loads*
Amendment 1 (2006)
Amendment 2 (2011)
- [13] IEC 60947-5-2:2007, *Low-voltage switchgear and controlgear – Part 5-2: Control circuit devices and switching elements – Proximity switches*
Amendment 1 (2012)
- [14] IEC 60947-6-1:2005, *Low-voltage switchgear and controlgear – Part 6-1: Multiple function equipment – Transfer switching equipment*
Amendment 1 (2013)
- [15] IEC 60947-6-2:2002, *Low-voltage switchgear and controlgear – Part 6-2: Multiple function equipment – Control and protective switching devices (or equipment) (CPS)*
Amendment 1 (2007) ^{A2}
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Annex ZA
(normative)

**Normative references to international publications
with their corresponding European publications**

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

NOTE When an international publication has been modified by common modifications, indicated by (mod), the relevant EN/HD applies.

<u>Publication</u>	<u>Year</u>	<u>Title</u>	<u>EN/HD</u>	<u>Year</u>
IEC 60050-151	2001	International Electrotechnical Vocabulary (IEV) - Part 151: Electrical and magnetic devices	-	-
IEC 60050-441 + A1	1984 2000	International Electrotechnical Vocabulary (IEV) - Chapter 441: Switchgear, controlgear and fuses	-	-
IEC 60050-604 + A1	1987 1998	International Electrotechnical Vocabulary (IEV) - Chapter 604: Generation, transmission and distribution of electricity - Operation	-	-
IEC 60050-826	2004	International Electrotechnical Vocabulary - Part 826: Electrical installations	-	-
IEC 60060	Series	High-voltage test techniques	EN 60060	Series
IEC 60068-1 + corr. October + A1	1988 1988 1992	Environmental testing - Part 1: General and guidance	EN 60068-1	1994
IEC 60068-2-1 A1 A2	1990 1993 1994	Environmental testing - Part 2: Tests - Tests A: Cold	EN 60068-2-1 ¹⁾ A1 A2	1993 1993 1994
IEC 60068-2-2 A1 A2	1974 1993 1994	Environmental testing - Part 2: Tests - Tests B: Dry heat	EN 60068-2-2 ²⁾ A1 A2	1993 1993 1994
IEC 60068-2-6	1995 1995	Environmental testing - Part 2: Tests - Test Fc: Vibration (sinusoidal)	EN 60068-2-6	1995
IEC 60068-2-27	1987	Basic environmental testing procedures - Part 2: Tests - Test Ea and guidance: Shock	EN 60068-2-27	1993
IEC 60068-2-30	2005	Environmental testing - Part 2-30: Tests - Test Db: Damp heat, cyclic (12 h + 12 h cycle)	EN 60068-2-30	2005
IEC 60068-2-52	1996	Environmental testing - Part 2: Tests - Test Kb: Salt mist, cyclic (sodium chloride solution)	EN 60068-2-52	1996

¹⁾ EN 60068-2-1 is superseded by EN 60068-2-1:2007, which is based on IEC 60068-2-1:2007.

²⁾ EN 60068-2-2 includes supplement A:1976 to IEC 60068-2-2.

<u>Publication</u>	<u>Year</u>	<u>Title</u>	<u>EN/HD</u>	<u>Year</u>
IEC 60068-2-78	2001	Environmental testing - Part 2-78: Tests - Test Cab: Damp heat, steady state	EN 60068-2-78	2001
IEC 60071-1	1993	Insulation co-ordination - Part 1: Definitions, principles and rules	EN 60071-1 ³⁾	1995
IEC 60073	2002	Basic and safety principles for man-machine interface, marking and identification - Coding principles for indicators and actuators	EN 60073	2002
IEC 60085	2004	Electrical insulation - Thermal classification	EN 60085	2004
IEC 60092-504	2001	Electrical installations in ships - Part 504: Special features - Control and instrumentation	-	-
IEC 60112	2003	Method for the determination of the proof and the comparative tracking indices of solid insulating materials	EN 60112	2003
IEC 60216	Series	Electrical insulating materials - Properties of thermal endurance	EN 60216	Series
IEC 60228	2004	Conductors of insulated cables	EN 60228 + corr. May	2005 2005
IEC 60269-1 A1	1998 2005	Low-voltage fuses - Part 1: General requirements	EN 60269-1 ⁴⁾ A1	1998 2005
IEC 60269-2 A1 A2	1986 1995 2001	Low-voltage fuses - Part 2: Supplementary requirements for fuses for use by authorized persons (fuses mainly for industrial application)	EN 60269-2 ⁵⁾ A1 A2	1995 1997 2002
IEC 60300-3-5	2001	Dependability management - Part 3-5: Application guide - Reliability test conditions and statistical test principles	-	-
IEC 60344 A1	1980 1985	Guide to the calculation of resistance of plain and coated copper conductors of low-frequency cables and wires	-	-
IEC 60364-4-44	2001	Electrical installations of buildings - Part 4-44: Protection for safety - Protection against voltage disturbances and electromagnetic disturbances	-	-
IEC 60364-4-44/A1 (mod)	2003	Electrical installations of buildings - Part 4-44: Protection for safety - Protection against voltage disturbances and electromagnetic disturbances - Clause 443: Protection against overvoltages of atmospheric origin or due to switching	HD 60364-4-443	2006
IEC 60417	Data-base	Graphical symbols for use on equipment	-	-

 Text deleted 

³⁾ EN 60071-1 is superseded by EN 60071-1:2006, which is based on IEC 60071-1:2006.

⁴⁾ EN 60269-1 is superseded by EN 60269-1:2007, which is based on IEC 60269-1:2006.

⁵⁾ EN 60269-2 is superseded by HD 60269-2:2007, which is based on IEC 60269-2:2006.

<u>Publication</u>	<u>Year</u>	<u>Title</u>	<u>EN/HD</u>	<u>Year</u>
IEC 60445	1999	Basic and safety principles for man-machine interface, marking and identification - Identification of equipment terminals and of terminations of certain designated conductors, including general rules for an alphanumeric system	EN 60445 ⁶⁾	2000
IEC 60447	2004	Basic and safety principles for man-machine interface, marking and identification - Actuating principles	EN 60447	2004
IEC 60529	1989	Degrees of protection provided by enclosures (IP Code)	EN 60529	1991
A1	1999		+ corr. May A1	1993
				2000
IEC 60617	Data-base	Graphical symbols for diagrams	-	-
IEC 60664-1	2007	Insulation coordination for equipment within low-voltage systems - Part 1: Principles, requirements and tests	EN 60664-1	2007
IEC 60664-3	2003	Insulation coordination for equipment within low-voltage systems - Part 3: Use of coating, potting or moulding for protection against pollution	EN 60664-3	2003
IEC 60664-5	2007	Insulation coordination for equipment within low-voltage systems - Part 5: Comprehensive method for determining clearances and creepage distances equal to or less than 2 mm	EN 60664-5	2007
IEC 60695-2-2	1991	Fire hazard testing -	EN 60695-2-2 ⁸⁾	1994
A1	1994	Part 2: Test methods - Section 2: Needle-flame test	A1	1995
IEC 60695-2-10	2000	Fire hazard testing - Part 2-10: Glowing/hot-wire based test methods - Glow-wire apparatus and common test procedure	EN 60695-2-10	2001
IEC 60695-2-11	2000	Fire hazard testing -	EN 60695-2-11	2001
	2001	Part 2-11: Glowing/hot-wire based test methods - Glow-wire flammability test method for end-products		
IEC 60695-2-12	-	Fire hazard testing - Part 2-12: Glowing/hot-wire based test methods - Glow-wire flammability index (GWFI) test method for materials	EN 60695-2-12	-
IEC 60695-11-10	1999	Fire hazard testing -	EN 60695-11-10	1999
A1	2003	Part 11-10: Test flames - 50 W horizontal and vertical flame test methods	A1	2003

⁶⁾ EN 60445 is superseded by EN 60445:2007, which is based on IEC 60445:2006.

^{A2} Footnote deleted ^{A2}

⁸⁾ EN 60695-2-2 is superseded by EN 60695-11-5:2005, which is based on IEC 60695-11-5:2004.

<u>Publication</u>	<u>Year</u>	<u>Title</u>	<u>EN/HD</u>	<u>Year</u>
IEC 60947-5-1	2003	Low-voltage switchgear and controlgear - Part 5-1: Control circuit devices and switching elements - Electromechanical control circuit devices	EN 60947-5-1 + corr. November + corr. July +A1	2004 2004 2005 2009
+A1	2009			
IEC 60947-8 A1	2003 2006	Low-voltage switchgear and controlgear - Part 8: Control units for built-in thermal protection (PTC) for rotating electrical machines	EN 60947-8 A1	2003 2006
IEC 60981	2004	Extra-heavy duty electrical rigid steel conduits -		-
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IEC 60999-2	2003	Connecting devices - Electrical copper conductors - Safety requirements for screw-type and screwless-type clamping units - Part 2: Particular requirements for clamping units for conductors above 35 mm ² up to 300 mm ² (included)	EN 60999-2	2003
IEC 61000-3-2 +A1 +A2	2005 2008 2009	Electromagnetic compatibility (EMC) - Part 3-2: Limits - Limits for harmonic current emissions (equipment input current ≤ 16 A per phase)	EN 61000-3-2 +A1 +A2	2006 2009 2009
IEC 61000-4-2	2008	Electromagnetic compatibility (EMC) - Part 4-2: Testing and measurement techniques - Electrostatic discharge immunity test	EN 61000-4-2	2009
IEC 61000-4-3 +A1 +A2	2006 2007 2010	Electromagnetic compatibility (EMC) - Part 4-3: Testing and measurement techniques - Radiated, radio-frequency, electromagnetic field immunity test	EN 61000-4-3 +A1 +A2	2006 2008 2010
IEC 61000-4-4	2004	Electromagnetic compatibility (EMC) - Part 4-4: Testing and measurement techniques - Electrical fast transient/burst immunity test	EN 61000-4-4	2004
IEC 61000-4-5	2005	Electromagnetic compatibility (EMC) - Part 4-5: Testing and measurement techniques - Surge immunity test	EN 61000-4-5	2006
IEC 61000-4-6	2013	Electromagnetic compatibility (EMC) - Part 4-6: Testing and measurement techniques - Immunity to conducted disturbances, induced by radio-frequency fields	EN 61000-4-6	2014
IEC 61000-4-8	2009	Electromagnetic compatibility (EMC) - Part 4-8: Testing and measurement techniques - Power frequency magnetic field immunity test	EN 61000-4-8	2010

<u>Publication</u>	<u>Year</u>	<u>Title</u>	<u>EN/HD</u>	<u>Year</u>
IEC 61000-4-11	2004	Electromagnetic compatibility (EMC) - Part 4-11: Testing and measurement techniques - Voltage dips, short interruptions and voltage variations immunity tests	EN 61000-4-11	2004
IEC 61000-4-13 +A1	2002 2009	Electromagnetic compatibility (EMC) - Part 4-13: Testing and measurement techniques - Harmonics and interharmonics including mains signalling at a.c. power port, low frequency immunity tests	EN 61000-4-13 +A1	2002 2009
IEC 61000-6-2	2005	Electromagnetic compatibility (EMC) - Part 6-2: Generic standards - Immunity for industrial environments	EN 61000-6-2 + corr. September	2005 2005
IEC 61131-2	2003	Programmable controllers - Part 2: Equipment requirements and tests	EN 61131-2 + corr. August	2003 2003
IEC 61140 A1 (mod)	2001 2004	Protection against electric shock - Common aspects for installation and equipment	EN 61140 A1	2002 2006
IEC 61180	Series	High-voltage test techniques for low-voltage equipment	EN 61180	Series
IEC 61508	Series	Functional safety of electrical/electronic/programmable electronic safety-related systems	EN 61508	Series
IEC 61649	2008	Weibull analysis	EN 61649	2008
IEC 62061	2005	Safety of machinery - Functional safety of safety-related electrical, electronic and programmable electronic control systems	EN 62061 + corr. February	2005 2010
IEC 62430	2009	Environmentally conscious design for electrical and electronic products	EN 62430	2009
IEC 62474	2012	Material declaration for products of and for the electrotechnical industry	EN 62474	2012
ISO 13849-1	2006	Safety of machinery - Safety-related parts of control systems - Part 1: General principles for design	EN ISO 13849-1	2008
IEC 61557-2	-	Electrical safety in low voltage distribution systems up to 1 000 V a.c. and 1 500 V d.c. - Equipment for testing, measuring or monitoring of protective measures - Part 2: Insulation resistance	EN 61557-2	-
CISPR 11 (mod) +A1	2009 2010	Industrial, scientific and medical equipment - Radio-frequency disturbance characteristics - Limits and methods of measurement	EN 55011 +A1	2009 2010

Annex ZZ
(informative)

Coverage of Essential Requirements of EU Directives

This European Standard has been prepared under a mandate given to CENELEC by the European Commission and the European Free Trade Association and within its scope the standard covers protection requirements of Annex I Article 1 of the EU Directive 2004/108/EC.

Compliance with this standard provides presumption of conformity with the specified essential requirements of the Directives concerned.

NOTE: Other requirements and other EU Directives may be applicable to the products falling within the scope of this standard.

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