**BS EN 13757-3:2013**



BSI Standards Publication

# **Communication systems for and remote reading of meters**

Part 3: Dedicated application layer

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#### **National foreword**

This British Standard is the UK implementation of EN 13757-3:2013. It supersedes [BS EN 13757-3:2004](http://dx.doi.org/10.3403/03164728) which is withdrawn.

The UK participation in its preparation was entrusted to Technical Committee PEL/894, Remote Meter Reading.

A list of organizations represented on this committee can be obtained on request to its secretary.

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# **[EN 13757-3](http://dx.doi.org/10.3403/03164728U)**

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English Version

## Communication systems for and remote reading of meters - Part 3: Dedicated application layer

Systèmes de communication et de télérelevé de compteurs - Partie 3: Couche d'application spéciale

 Kommunikationssysteme für Zähler und deren Fernablesung - Teil 3: Spezielle Anwendungsschicht

This European Standard was approved by CEN on 7 March 2013.

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EUROPEAN COMMITTEE FOR STANDARDIZATION COMITÉ EUROPÉEN DE NORMALISATION EUROPÄISCHES KOMITEE FÜR NORMUNG

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## **Foreword**

This document (EN 13757-3:2013) has been prepared by Technical Committee CEN/TC 294 "Communication systems for meters and remote reading of meters", the secretariat of which is held by DIN.

This European Standard shall be given the status of a national standard, either by publication of an identical text or by endorsement, at the latest by November 2013, and conflicting national standards shall be withdrawn at the latest by November 2013.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CEN [and/or CENELEC] shall not be held responsible for identifying any or all such patent rights.

This document supersedes EN [13757-3:2004](http://dx.doi.org/10.3403/03164728).

It shall be noted that the following significant technical changes compared to the previous edition have been incorporated in this European Standard:

- Extension of existing frames formats for different data protocols to support various wireless transmission schemes (harmonisation with EN13757-4).
- Adding an annex with a Smart Metering profile based on the requirements of the "Smart Meter Coordination Group" of the ESO´s.
- Adding an annex to have a unique translation of M-Bus-data points to OBIS-Codes.
- Update of the encryption methods to the state of the art.
- Enhancement of data points for electricity meter.

This document has been prepared under a mandate given to CEN by the European Commission and the European Free Trade Association.

EN 13757, *Communication systems for meters and remote reading of meters* consists of the following parts:

- *Part 1: Data exchange*
- *Part 2: Physical and link layer*
- *Part 3: Dedicated application layer*
- *Part 4: Wireless meter readout*
- *Part 5: Wireless relaying*
- *Part 6: Local bus*

According to the CEN-CENELEC Internal Regulations, the national standards organisations of the following countries are bound to implement this European Standard: Austria, Belgium, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Finland, Former Yugoslav Republic of Macedonia, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, Netherlands, Norway, Poland, Portugal, Romania, Slovakia, Slovenia, Spain, Sweden, Switzerland, Turkey and the United Kingdom.

#### **Introduction**

This document belongs to a series of parts of EN 13757, which covers communication systems for meters and remote reading of meters. EN [13757-1](http://dx.doi.org/10.3403/02856915U) contains generic descriptions and a communication protocol. EN [13757-2](http://dx.doi.org/10.3403/03164534U) contains a physical and a link layer for twisted pair based Meter-Bus (M-Bus). EN [13757-4](http://dx.doi.org/10.3403/30096182U) describes wireless communication (often called wireless M-Bus or wM-Bus). EN [13757-5](http://dx.doi.org/10.3403/30160774U) describes the wireless network used for repeating, relaying and routing for the different modes of EN [13757-4](http://dx.doi.org/10.3403/30096182U). EN 13757-6 describes a twisted pair local bus for short distance (Lo-Bus).

This dedicated application layer (M-Bus-Protocol) can be used with various physical layers and with link layers and network layers, which support the transmission of variable length binary transparent messages. Frequently, the physical and link layers of EN [13757-2](http://dx.doi.org/10.3403/03164534U) (twisted pair) and EN [13757-4](http://dx.doi.org/10.3403/30096182U) (wireless) as well as EN [13757-5](http://dx.doi.org/10.3403/30160774U) (wireless with routing function) or the alternatives described in EN [13757-1](http://dx.doi.org/10.3403/02856915U) are used. This dedicated application layer has been optimised for minimum battery consumption of meters, especially for the case of wireless communication to ensure long battery lifetimes of the meters. Secondly, it is optimised for minimum message length to minimise the wireless channel occupancy and hence the collision rate. Thirdly, it is optimised for minimum requirements towards the meter processor regarding requirements of RAM size, code length and computational power.

An overview of communication systems for meters is given in EN [13757-1,](http://dx.doi.org/10.3403/02856915U) which also contains further definitions.

This standard concentrates on the meter communication. The meter communicates with one (or occasionally several) fixed or mobile communication partners which again might be part of a private or public network. These further communication systems might use the same or other application layer protocols, security, privacy, authentication, and management methods.

To facilitate common communication systems for CEN-meters (e.g. gas, heat, water meters and heat cost allocators) and for electricity meters, in this standard occasionally electricity meters are mentioned. All these references are for information only and are not standard requirements. The definition of communication standards for electricity meters (possibly by a reference to CEN standards) remains solely in the responsibility of CENELEC.

NOTE 1 Annex L describes how parts of this standard and of FN 13757-2 and FN [13757-4](http://dx.doi.org/10.3403/30096182U) can be used to implement smart meter functionalities. Similar functionalities could also be implemented using other physical and link layers.

NOTE 2 For information on installation procedures and their integration in meter management systems, see Annex M.

#### **1 Scope**

This European Standard applies to communication systems for meters and remote reading of meters.

#### **2 Normative references**

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

[EN 13757-1](http://dx.doi.org/10.3403/02856915U), *Communication system for meters and remote reading of meters ― Part 1: Data exchange*

EN [13757-2](http://dx.doi.org/10.3403/03164534U), *Communication systems for meters and remote reading of meters — Part 2: Physical and link layer*

EN [13757-4](http://dx.doi.org/10.3403/30096182U), *Communication systems for meters and remote reading of meters ― Part 4: Wireless meter readout (Radio meter reading for operation in the 868 MHz to 870 MHz SRD band)*

EN [13757-5](http://dx.doi.org/10.3403/30160774U), *Communication systems for meters and remote reading of meters ― Part 5: Wireless relaying*

EN [62056-21,](http://dx.doi.org/10.3403/02604927U) *Electricity metering ― Data exchange for meter reading, tariff and load control ― Part 21: Direct local data exchange [\(IEC 62056-21](http://dx.doi.org/10.3403/02604927U))*

[EN 62056-5-3](http://dx.doi.org/10.3403/30242643U), *Electricity metering data exchange ― The DLMS/COSEM Suite ― Part 5-3: DLMS/COSEM application layer [\(IEC 62056-5-3:2013](http://dx.doi.org/10.3403/30242643))*

NOTE Further information and examples are available in the download area o[f http://www.m-bus.com.](http://www.m-bus.com/)

#### **3 Terms and definitions, abbreviated terms and numbers**

For the purposes of this document, the following terms and definitions apply.

#### **3.1 Terms and definitions**

**3.1.1 byte** an octet of bits

**3.1.2 datagram** unit of data transferred from source to destination

Note 1 to entry: In previous versions of [EN 13757-3](http://dx.doi.org/10.3403/03164728U) datagram was called telegram.

**3.1.3**

**message**

functional set of data transferred from source to destination

Note 1 to entry: A message may consist of one or more datagrams.

#### **3.2 List of abbreviated terms**

ACC-DMD Access Demand



VIF Value Information Field

VIFE Value Information Field Extensions

#### **3.3 Hexadecimal and binary numbers**

Hexadecimal numbers are designated by a following "h"

Binary numbers are designated by a following "b"

Decimal numbers have no suffix!

### **4 General principles: Cl-field**

#### **4.1 Overview**

All higher protocol layer messages have a variable length. The length information is part of the link layer. It shall be known to the application layer in order to properly terminate its decoding of each datagram. Each message starts with a 1-byte CI (control information) field, which distinguishes between various message types and application functions and header length. It is also used to distinguish between true application layer communication and management commands for lower layers. The meaning of the remaining bytes of the message depends also on the value of the CI-field.

The fixed header structures after CI-fields are:

- No data header (None) (0 bytes), as for CI=78h: If the message contains such a "none" header the meter identification is taken from the link layer; additional control fields for application layer (like configuration field) are non-existent.
- Short data header (4 bytes or more), as for CI=7Ah: If the message contains such a "short" header, the meter identification is taken from the link layer; data header length is at least 4 bytes. Additional bytes may follow in dependency of the selected encryption mode. If no encryption is applied (encryption mode 0), the header has the minimum length of 4 bytes.
- Long data header (12 bytes or more), as for CI=72h: If the message contains such a "long" header, this header contains (independent of transmission direction) the meter identification; data header length is at least 12 bytes. Additional bytes may follow in dependency of the selected encryption mode. If no encryption is applied (encryption mode 0), the header has the minimum length of 12 byte.

When using a long data header, the meter application address is contained in this header, whereas the manufacturer assigned unique link layer address may be different (but still within the common universally unique address structure). This allows, for example, a wired to wireless converter to supply the supported meter application address in the long data header and its own address in the radio link layer. For a simple meter, which doesn't need an additional converter, the short header is sufficient.

Refer to Annex J for the details of the CI-field specific frame structure.

<span id="page-13-0"></span>

<b>CI-field</b>	<b>Direction</b>	Header	<b>Higher layer protocol</b>				
00h-1Fh	Reserved for DLMS-based applications		DLMS (See EN 13757-1)				
20h-4Fh	Reserved						
50h	Application reset or select to device	None	M-Bus				

**Table 1 — CI-field codes used by the master or the slave**



### **Table 1** *(continued)*

## **Table 1** *(continued)*



#### **Table 1** *(continued)*



M-Bus data records, Annex O shall be used.

Every data header for wireless M-Bus (EN [13757-4\)](http://dx.doi.org/10.3403/30096182U) shall contain at least:

- access number;
- status byte;
- configuration field.

Alternatively, the link extension (CI=8Ch – 8Fh) may be applied.

NOTE Multi byte values in short or long header are transmitted with LSB first.

#### **4.2 Application reset and application select (Cl = 50h, 53h) (optional)**

#### **4.2.1 Application reset**

With the CI-field 50h or 53h (without additional parameter), the master can release a reset of the application layer in the slaves. Each slave itself decides which parameters to change, e.g. which data output is default – after it has received such an application reset.

#### **4.2.2 Application select with subcode (optional)**

It is allowed to use optional parameters after  $CI = 50h$  or 53h. In this case, the CI-field acts as application select. If more bytes follow, the first byte is the application select subcode. Further bytes are ignored. The application select subcode defines which message function and which sub message is requested by the master. The data type of this parameter is 8 bit binary. The upper 4 bits define the message type or message application and the lower 4 bits define the number of the sub message or datagram number (the meaning of this number is device specific). The lower 4 bits may be ignored for slaves which provide only a single datagram for each application. The use of the value zero for the number of the sub message means that all datagrams are requested.

Slaves with only one type of message may ignore application select and the added parameters. The following codes can be used for the upper 4 bits of the first parameter:

<span id="page-16-0"></span>

Coding	<b>Description</b>	<b>Examples</b>
0000b	All	
0001b	User data	Consumption
0010b	Simple billing	Current and fixed date values + dates
0011b	Enhanced billing	Historic values
0100b	Multi tariff billing	

**Table 2 — Coding of the upper 4 bits of the first parameter after CI = 50h or 53h**



#### **Table 2** *(continued)*

#### **4.3 Slave select (52h) (optional)**

The CI-field code 52h is used for the management of the optional secondary addressing (see 11.3).

#### **4.4 Synchronise action (Cl = 5Ch) (optional)**

This CI-field can be used for synchronising functions in slaves and masters (e.g. clock synchronisation). Special actions or parameter loads may be prepared but their final execution is delayed until the reception of such a special CI-field command. No data follows this CI-code.

NOTE Wireless M-Bus does not provide broadcast communication. Therefore, this function cannot be used for wireless M-Bus.

#### **4.5 Clock synchronisation (CI = 6Ch, 6Dh) (optional)**

For wireless communication (but not limited to this one), the clock synchronisation is executed by a special protocol for clock synchronisation. For this protocol CI-fields 6Ch and 6Dh are used. Annex H.3 specifies the transmission of clock synchronisation to meter.

Alternatively, the clock may set by an M-Bus-command. The communication partner may send date and time in all command messages to ensure that the meter can detect a replay of an old command. The meter shall not use this time stamp for synchronisation of its clock except when a dedicated action code (see Table 37) was added.

#### **4.6 Report of application errors (slave to master) (Cl = 6Eh, 6Fh and 70h) (optional)**

For details of the report of general application errors, see 8.3. For error reporting of individual data elements, see 8.4.

#### **4.7 Report of alarm status (slave to master) (Cl = 71h, 74h and 75h) (optional)**

For details of the report of alarm status errors, see Annex D.

#### **4.8 Variable Data Send (master to slave) (CI = 51h, 5Ah, 5Bh, 60h, 61h, 64h, 65h)**

These CI-field codes are used to indicate a message of application data sent from master to slave.

The CI-fields CI = 51h, 5Ah and 5B are used to transport the M-Bus protocol as described in this standard starting from Clause 6. For details, refer to Clause 5.

The CI-fields CI = 60h and 61h are used to transport the COSEM-Protocol as described in EN13757-1 and [EN 62056-5-3.](http://dx.doi.org/10.3403/30242643U)

The CI-fields CI = 64h and 65h are reserved so far for an alternative OBIS based protocol.

#### **4.9 Variable Data Respond (slave to master) (Cl = 69h to 6Bh, 72h, 73h, 78h to 7Fh)**

These CI-field codes are used to indicate a message of application data responded from slave to master.

The CI-fields 72h, 78h and 7Ah are used to transport the M-Bus protocol as described in this standard starting from Clause 6. For details, refer to Clause 5.

The CI-fields 69h, 6Ah and 6Bh, as well as 73h, 79h and 7B, are used to transport the M-Bus protocol in the compact format. For details, refer to Annex K.

The CI-fields CI = 7Ch and 7Dh are used to transport the COSEM-Protocol as described in EN13757- 1 and EN [62056-5-3.](http://dx.doi.org/10.3403/30242643U)

The CI-fields CI = 7Eh and 7Fh are reserved so far for an alternative OBIS based protocol.

#### **4.10 Baud rate switch commands B8h – BFh (optional)**

These optional commands can be used by a master to switch the baud rate of a slave. For details, see 11.2.

#### **5 Variable Data Send and Variable Data Respond**

#### **5.1 Introduction**

The data headers of the Variable Data Send with the CI-field codes as listed in 4.8 are used to indicate the variable data structure in long frames (SND\_UD) with optional fixed header.

The data headers of the Variable Data Respond with the CI-field codes as listed in 4.9 are used to indicate the variable data structure in long frames (RSP\_UD) with optional fixed header.

<span id="page-18-0"></span>Table 3 shows the way this data is represented.

			Data header (resp.)   Variable data blocks (records)   MDH(opt.)   Optional manufacturer specific data)
None header			
Short header	Variable number	1 byte	Variable number
Long header			

**Table 3 — Variable data structure in answer send and respond direction**

#### **5.2 Structure of none data header**

This structure has no data header. The first byte following the CI-field is the start of the first data record. This data structure does not support transmission properties like encryption, access number or an additional meter address.

This structure can be used together with the extended link layer of EN [13757-4.](http://dx.doi.org/10.3403/30096182U)

#### **5.3 Structure of short data header**

The first 4 bytes after the CI-field consist of a block with a fixed length and structure (see Table 4).

<span id="page-19-0"></span>The short data header is used for systems supporting the physical and link layer of wireless M-bus communication (refer to EN [13757-4](http://dx.doi.org/10.3403/30096182U)). In this standard, the link layer address contains the information fields of the manufacturer, the device type, the version and the identification number. If the meter address is identical with link layer address or the meter address was clearly selected before, then the 8 bytes of the meter address do not have to be added in the application layer again.

Access No.	<b>Status</b>	Configuration				
1 byte	1 byte	2 byte				

**Table 4 — Short data header** 

The structure of the short header can be enlarged by additional bytes in dependency of the encryption mode (refer to 5.12.6.5).

#### **5.4 Structure of long data header**

<span id="page-19-1"></span>The first 12 bytes after the CI-field consist of a block with a fixed length and structure (see Table 5).



#### **Table 5 — Long data header**

The address fields always contain the address of the meter independent of the transmission direction. In case of wireless communication based on EN [13757-4,](http://dx.doi.org/10.3403/30096182U) this CI-field shall be used when the link layer address differs from meter address.

The structure of the long header can be enlarged by additional bytes in dependency of the encryption mode (refer to 5.12.6.4).

#### **5.5 Identification number**

The **identification number** is either a fixed fabrication number or a number changeable by the customer, coded with 8 BCD packed digits (4 byte), and which thus runs from 00000000 to 99999999. It can be preset at fabrication time with a unique number, but can be changeable afterwards, especially if, in addition, a unique and not changeable fabrication number (DIF =  $0$ Ch, VIF =  $78$ h, see 7.2) is provided.

#### **5.6 Manufacturer identification**

The field **manufacturer** is coded unsigned binary with 2 bytes. This manufacturer ID is calculated from the ASCII code of EN [62056-21](http://dx.doi.org/10.3403/02604927U) manufacturer ID (three uppercase letters) with the following formula:

Man. ID =

\n
$$
[ASCII(1st letter) - 64] \times 32 \times 32
$$
\n
$$
+ [ASCII(2nd letter) - 64] \times 32
$$
\n
$$
+ [ASCII(3rd letter) - 64]
$$
\n
$$
(1)
$$

NOTE The flag association, UK [\(http://www.dlms.com/\)](http://www.dlms.com/) administers these three letter manufacturers ID of EN [62056-21](http://dx.doi.org/10.3403/02604927U).

#### **5.7 Version identification**

The field version specifies the generation or version of the device and depends on the manufacturer. It can be used to make sure that within each version number the identification number is unique.

The value FFh is reserved as a wildcard and shall not be used by any device.

#### **5.8 Device type identification**

The device type is coded as follows:

<span id="page-20-0"></span>



#### **Table 6 — Device type identification**



#### **Table 6** *(continued)*

water flow above a limit temperature in a separate register with an appropriate tariff ID.

b A radio converter at system side operates as radio master like a wireless communication partner.

c A radio converter at meter side operates as radio slave like an RF-meter.

#### **5.9 Access number**

#### **5.9.1 Overview**

The access number is a part of the fixed header. It is used by the extended link layer, the transport layer or the application layer protocol. It is coded as a 1-byte unsigned binary number. It has originally been added to support the wired M-Bus of EN [13757-2](http://dx.doi.org/10.3403/03164534U) and signals to the user that its meter has been read out by the pull-type readout of EN [13757-2.](http://dx.doi.org/10.3403/03164534U) This function supports the detection of unwanted frequent readouts. For the typical push type frequent transmit modes of radio devices based on the EN [13757-4](http://dx.doi.org/10.3403/30096182U), this usage is no longer sensible. Acceptable maximum readout or transmit frequency is either an issue of legal requirements or of a contract between the meter reading organisation and the consumer. For devices based on the EN [13757-4,](http://dx.doi.org/10.3403/30096182U) the access number shall be applied for clear

indication of a new datagram for both pushed data as well as for requested data by strict rules of increments. For the partner-generated datagrams, relaxed generation rules simplify the implementation. The detection rules are identical between meter and partner; i.e. a datagram with an identical access number is considered a repetition of an identical previously already received datagram and shall be ignored. All datagrams with a different access number than the last received datagram are considered as a new data datagram. The term "new data" means that the meter application provides newer measurement values than in the last (old) data datagram.

NOTE 1 This link layer oriented function is not sufficient to uniquely identify messages from an application. If an application requires such a unique identification of a message, a data record with a VIF of =FDh,08h (unique message identification) and a data length of at least 4 bytes is added to each message.

NOTE 2 If both extended link layer and transportation layer exist, then the access number of the extended link layer will be applied for the timing of synchronous transmission, whereas the access number in the transport layer will be used to indicate new data.

#### **5.9.2 Generation of access number for meter initiated datagrams**

If a meter generates a datagram (SND-NR, SND-IR, ACC-DMD or ACC-NR), the access number is incremented (modulo 256) by one before or after each new transmission of the meter.

If the meter supports the feature of synchronised transmission for battery operated receiver (refer to EN [13757-4](http://dx.doi.org/10.3403/30096182U)) then the access number shall be incremented by one and only one with every synchronous transmission. For every asynchronous transmission between two synchronous datagrams, the meter shall use the access number from the last synchronous transmission. To avoid the detection of zero consumption, it is recommended to add a time stamp or an incremental counter (VIFE "unique message identification") to the message content if one or several asynchronous transmissions are sent in the interval between two synchronous transmissions. If such asynchronous transmission contains new data, the extended link layer may be applied to separate the indication of synchronous transmission from the indication of new data.

After the power up of the meter, its value of the access number shall be set by a randomised initial value from 0 to 255. The access number of the meter shall not be resettable.

When the datagram is a response to a datagram of the communication partner (i.e. ACK, RSP-UD or other) then the access number repeats the received access number of the communication partner. Otherwise, the access number of the meter is used.

NOTE Meter initiated datagrams are not allowed by the wired M-Bus standard (refer to EN13757-2).

#### **5.9.3 Generation of access number for partner generated datagrams**

If the communication partner generates a wireless datagram (SND-UD, SND-NKE, REQ-UD1, REQ-UD2), each such datagram shall use a different value of the access number within 300 s or within a frequent access cycle as defined in EN [13757-4.](http://dx.doi.org/10.3403/30096182U) A simple increment is recommended to fulfil this requirement. If the partner transmits an answer to the meter (i.e. ACK or CNF-IR with CI-field), the transmitted access number of the partner repeats the received access number of the meter. After the power up of the communication partner, its value is undefined, but an initial value of zero is recommended. For the usage of the FCB, see E.7.

For the wired communication according to EN13757-2, the meter shall increment its own access number before or after each response (RSP\_UD) to the communication partner. If the communication partner (M-Bus-master) transmits an access number (e.g. SND-UD), it may be ignored.

NOTE The communication partner has to provide an access number in case of encrypted commands.

#### <span id="page-23-0"></span>**5.10 Status byte in meter messages**



#### **Table 7 — Coding of the status field**

#### **Table 8 — Application errors coded with the status field**

<span id="page-23-1"></span>

The status bits shall be used in this meaning:

- Power low Warning The bit "power low" is set only to signal interruption of external power supply or the end of battery life.
- Permanent error Failure The bit "permanent error" is set only if the meter signals a fatal device error (which requires a service action). Error can be reset only by a service action.
- Temporary error Warning The bit "temporary error" is set only if the meter signals a slight error condition (which not immediately requires a service action). This error condition may later disappear.
- Any application error Shall be used to communicate a failure during the interpretation or the execution of a received command, e.g. if a not decrypt able message was received.
- Abnormal conditions Shall be used if a correct working application detects an abnormal behaviour like a permanent flow of water by a water meter.

NOTE More detailed error signalling can be provided by the VIF/VIFE FDh/17h (refer to Annex H) in the message body. If a failure happens because of a wrong command it responds with a message of application error with  $CI = 6Eh$ ,  $6Fh$ ,  $70h$ .

#### <span id="page-24-0"></span>**5.11 Status byte in partner messages**

Bit no.	Value
05	Last received RSSI value from this meter for a reception level in range of:
	$-128$ -6dbm
	Reception level is calculated by -130dbm+2 * RSSI value (1  62) If RSSI value = $0$ no RSSI value or wired communication If RSSI value $= 1$ RSSI value is -128dbm or below If RSSI value = $63$ the reception level is > -6dbm
6	Reserved (0 by default)
	Reserved (0 by default)

**Table 9 — Meaning of status byte for partner messages**

The value of « 0 » in bits 0…5 means either that the partner does not provide RSSI values or that the partner has so far not received any message from the meter. Information about link quality is helpful for the rating of several radio links between a meter and different partners. It will also be used for signalling the link quality to an installation service tool. Therefore, the partner should support a valid RSSI value.

### **5.12 Configuration field (previously: signature field)**

#### **5.12.1 General**

The **configuration field** contains information about the encryption mode and the number of encrypted bytes. Depending on the mode, it may contain additional information about:

- meter accessibility;
- contents of the message;
- repeated wireless datagrams;
- synchronous wireless transmissions.

If no functionality of the configuration field is used, its value shall be 0000h. Table 10 shows where to find the mode bits. The number of encrypted bytes is contained in the low byte of the configuration field (bit  $0 - \text{bit } 7$ ). The exact coding of those bits depends on the mode.

<span id="page-24-1"></span>



#### **5.12.2 Functions**

The use of encryption provides the following functions:

- data privacy for consumption meter values;
- detecting simulated meter transmission;
- preventing later replay of old meter values;
- preventing the detection of zero consumption by comparing messages.

#### **5.12.3 Structure of encrypted messages**

- a) The long or short data header (see 5.3 or 5.4) is always unencrypted. The last word of this block is the configuration field. If the number of encrypted bytes in the configuration field is zero (even if the encryption mode differs from zero) the following data are unencrypted.
- b) If the transmission uses configuration field functionality (like encryption), the method has to be defined with the mode bits in the high byte of configuration field. Table 11 shows the already defined modes.
- c) The encrypted data follow directly after the configuration field, thus forming the beginning of the application data e.g. DIF/VIF-structured part of the message for M-Bus. The calculation of the length of encrypted data is mode specific.

<span id="page-25-0"></span>

#### **Table 11 — Definition of the mode bits (encryption method)**

#### **5.12.4 Partial encryption**

- a) If the number of encrypted bytes is less than the total length of the data in this datagram then unencrypted data may follow after the encrypted data. They shall start at a record boundary, i.e. the first byte after the encrypted data will be interpreted as a DIF.
- b) If a partially encrypted message shall contain encrypted manufacturer specific data, a record with a suitable length DIF (possibly a variable length string DIF) and a VIF =  $7Fh$  (manufacturer specific data record) shall be used instead of the usual MDH-DIF = 0Fh. This is required to enable after decryption standard DIF/VIF-decoding of a previously partially encrypted message containing encrypted manufacturer specific data.

#### **5.12.5 Encryption methods DES (modes 2 and 3)**

<span id="page-26-0"></span>

<b>MS</b> Bit 15	<b>Bit</b> 14	<b>Bit</b> 13	<b>Bit</b> 12	<b>Bit</b> 11	<b>Bit</b> 10	<b>Bit</b> 9	<b>Bit</b> 8	<b>Bit</b> $\overline{7}$	<b>Bit</b> 6	<b>Bit</b> 5	<b>Bit</b> $\boldsymbol{4}$	<b>Bit</b> 3	Bit $\mathbf 2$	<b>Bit</b> 1	LS <b>Bit</b> 0
reserved	reserved	reserved	reserved	က ä mode	$\sim$ ä mode	$\overline{\phantom{0}}$ ä mode	$\circ$ ä mode	number of encr. bytes	bytes encr. $\overline{\mathsf{o}}$ number	bytes encr. $\overline{\sigma}$ number	bytes encr. đ number	bytes encr. $\rm 5$ number	bytes encr. $\overline{\sigma}$ number	bytes encr. number of	number of encr. bytes
$\mathbf 0$	$\boldsymbol{0}$	0	0	M	M	M	M	N	N	N	N	N	N	N	N

**Table 12 — Definition of the configuration field for encryption modes 2 and 3**

- a) Due to the withdrawal of standards ANSI X3.92:1981 and ANSI X3.106:1983, new implementations based on DES are not recommended.
- b) Cipher Block Chaining (CBC) method as described in INCITS/ISO [8372:1987](http://dx.doi.org/10.3403/00238580) with an initial initialisation vector of zero: (encryption method code = 02xxh). In this case, the message should contain the current date before the meter reading data. Thus, the data after the date record changes once per day even if the meter index itself is constant. This prevents an undetectable later replay of stored encrypted meter readings by a hacker.
- c) The initialisation vector with length 64 bits of this standard may alternatively be defined by the first 6 bytes of the identification header in mode 1 sequence, i.e. identification number in the lowest 4 bytes followed by the manufacturer ID in the two next higher bytes and finally by the current date coded as in record structure "G" for the two highest bytes. Thus, all encrypted data change once per day even if the data content itself is constant. This prevents an undetectable later replay of any stored encrypted data by a hacker.

In this case the encryption method is coded as "03xxh".

- d) To simplify the verification of correct decoding and to prevent an undetected change in the identification of the not encrypted header, the encrypted part of the message shall contain at least together with the appropriate application layer coding (DIF and VIF) again the same identification number as in the unencrypted header.
- e) Due to the mathematical nature of the DES-algorithm, the encrypted length contained in the low byte of the configuration field (see Table 12) shall be an integer multiple of 8 byte if the high byte signals DES-Encryption. Unused bytes in the last 8-byte block shall be filled with appropriately structured dummy data records to achieve the required record boundary at the end of the encrypted data. One or several bytes containing the filler  $DIF = 2Fh$  shall be used to fill such gaps.
- f) The application of certain encryption methods might be prohibited by local laws.

#### **5.12.6 Encryption methods AES-128 (mode 5)**

#### **5.12.6.1 General**

Encryption according to the AES-128 (Data Encryption Standard) as described in NIST FIPS 197.

#### **5.12.6.2 Encryption mode 5**

- a) Cipher Block Chaining (CBC) method as described in NIST SP800-38A.
- b) Definition of the configuration field according to Table 13:

<span id="page-27-0"></span>

<b>MS</b> <b>Bit</b> 15	<b>Bit</b> 14	<b>Bit</b> 13	<b>Bit</b> 12	<b>Bit</b> 11	<b>Bit</b> 10	<b>Bit</b> 9	<b>Bit</b> 8	<b>Bit</b> $\overline{7}$	<b>Bit</b> 6	<b>Bit</b> 5	<b>Bit</b> 4	<b>Bit</b> 3	<b>Bit</b> 2	<b>Bit</b> 1	LS <b>Bit</b> 0
bidirectional communication	accessibility	synchronised	reserved	S $\overline{\overline{\textbf{a}}}$ mode	$\sim$ ä mode	$\overline{\phantom{0}}$ ä mode	$\circ$ 运 mode	encr. blocks $\overline{\sigma}$ number	blocks encr. $\overline{\sigma}$ number	blocks encr. ৳ number	blocks encr. $\overline{\sigma}$ number	message $\rm \breve{\sigma}$ content	message $\rm \overline{o}$ content	access repeater	hop counter
B	A	S	$\Omega$	Μ	M	M	M	N	N	N	N	C	C	$\mathsf{R}$	$\mathsf{H}$

**Table 13 — Definition of the configuration field for encryption mode 5**

- c) The coding of the configuration field for the AES encryption mode with a dynamic initialisation vector is 5 (MMMM=0101b). The high nibble "NNNN" of the lower byte declares the number of encrypted 16-byte blocks (see Table 13).
- d) The initialisation vector for encryption mode 5 is (written in low to high order according to the AES standard FIPS 197):

<span id="page-27-1"></span>

<b>LSB</b>			◠ ັ		C	$\sim$ ь		O	9	$\sqrt{2}$	$\overline{A}$	10	12 J	14	<b>MSB</b>
Manuf. (LSB)	Manuf. (MSB)	(LSB)		. .	ID (MSB)	Ver- sion	Device type	Acc.		.	.		. .		Acc.
								no.							no.

**Table 14 — Initialisation vector mode 5 for the CBC-AES-128**

The initialisation vector always contains the address of the meter.

e) Since the meter access number changes with each new transmission, the initialisation vector is different in each new transmission of meter data. Due to the mathematical properties of the encryption algorithm, this changes the complete message even if the unencrypted data (e.g. the meter index) is constant (e.g. because of zero consumption) which might indicate an uninhabited apartment and might hence be some indication for possible burglars. This protection may be increased by using an additional time stamp or an incremental counter (VIFE "unique message identification") in the first block.

- f) To simplify the verification of correct decoding and to prevent an undetected change in the identification of the not encrypted header, the encrypted part of the message shall start with two bytes "2Fh" (see 5.12.6.4).
- g) Due to the mathematical nature of the AES-algorithm, the encrypted length contained in the low byte of the configuration field shall be an integer multiple of 16 bytes if the high byte signals AESencryption. Unused bytes in the last 16-byte block shall be filled with appropriately structured dummy data records to achieve the required record boundary at the end of the encrypted data. One or several bytes containing the filler  $DIF = 2Fh$  shall be used to fill such gaps.
- h) Partial encryption may be used to allow unencrypted access to operational parameters. The encrypted bytes follow as zero, one or several encrypted 16-byte blocks directly after the header. Optional unencrypted bytes may follow the encrypted blocks if the link layer datagram length signals more bytes than the encryption length of 16\*NNNNb bytes in the low byte of the configuration field.
- i) The full 16-byte key shall be assigned by the manufacturer together with the meter identification and safely transferred to its customers. The format is according to FIPS 197.
- j) The application of certain encryption methods might be prohibited by local laws.

#### **5.12.6.3 Additional functionality of configuration field**

The configuration field in general declares the length and method of data encryption. For encryption mode 5, additional communication status bits are defined. For the communication on wired M-Bus, all bits in the configuration field except "MMMM" and "NNNN" shall be set to "0".

Bit 0 (H) and bit 1 (R) of the configuration field are reserved for use in repeated messages (see [EN](http://dx.doi.org/10.3403/30160774U) [13757-5](http://dx.doi.org/10.3403/30160774U)). A meter shall always set H=0b and R=0b in a transmitted message. The meter may ignore these bits in a received message.

Bit 2 and bit 3 (CC) are used to describe the contents of the message (refer to Table 15). The definition distinguishes between a meter and a partner message. The declaration of the authentication methods helps the meter to detect the authentication method used by the message originator (refer to Table16).

<span id="page-28-0"></span>

#### **Table 15 — Contents of meter message**

<span id="page-29-0"></span>

#### **Table 16 — Contents of partner message**

Bit 13 (S) is used to declare a synchronised transmission. If the transmission timing (predictable transmission time) fulfils the requirements of a synchronous transmission as defined in EN [13757-4,](http://dx.doi.org/10.3403/30096182U) it shall mark this transmission with a set bit 13. Otherwise, the bit 13 shall always be 0.

The configuration field bits 14 (A) and 15 (B) (**A**ccessibility and **B**idirectional communication) are used as defined in Table 17 for access control to the meter.

<span id="page-29-1"></span>

#### **Table 17 — Accessibility of a meter**

#### **5.12.6.4 Decryption verification**

In order to verify that the message is decrypted correctly, the encrypted part starts with a known sequence. The header will be expanded by decryption verification in dependency of the selected encryption mode. A device supporting encryption mode 5 shall start with 2 bytes of 2Fh (AES-check) before the first data record.

Since the message must have an encrypted length of an integer multiple of 16 bytes, idle filler bytes often will also be added at the end of the last encrypted block.

NOTE The decryption verification is independent of the wired or wireless transmission.

#### **5.12.7 Examples**

Annex P shows examples with both unencrypted and encrypted data.

#### **5.13 Address structure if used together with the wireless link layer according to EN [13757-4](http://dx.doi.org/10.3403/30096182U)**

The link layer of EN [13757-4](http://dx.doi.org/10.3403/30096182U) contains an 8-byte address, which starts with a 2-byte manufacturer identification according to [EN 62056-21](http://dx.doi.org/10.3403/02604927U) (see 5.6), followed by 6 bytes consisting of the identification number, version and device type, as shown in Table 18.

<b>Manufacturer</b> identification	<b>Identification</b> number	<b>Version</b>	Device type		
2 byte	4 byte(BCD)	1 byte	1 byte		

**Table 18 — Address structure of the wireless link layer**

<span id="page-30-0"></span>The content of the fields shall be according to 5.5, 5.6, 5.7 and 5.8.

The 8-byte address in the long header of this standard uses the same elements but they are structured in a different order (see Table 5 in 5.4).

### **6 Variable data blocks (records)**

#### **6.1 General**

The single datagram has a maximum length of 255 bytes. The data, together with information regarding coding, length and the type of data, is transmitted in data records in arbitrary sequence. According to [EN 13757-2](http://dx.doi.org/10.3403/03164534U), the maximum space for data is 252 bytes. The effective usable space depends on the layers with variable length below the application layer and the applied header type and the encryption method. This restriction is required to enable gateways to other link- and application layers. The Manufacturer Data Header (MDH) is made up by the character 0Fh or 1Fh and indicates the beginning of the manufacturer specific part of the user data and shall be omitted if there is no manufacturer specific data (refer also to 6.4).



<span id="page-30-1"></span>

Each data record consists of a Data Record Header (DRH) and the value (data). The DRH in turn consists of the Data Information Block (DIB) to describe the length, type and coding of the data and the Value Information Block (VIB) to give the value of the unit and the multiplier.

NOTE An application message can contain either just a single data record but also an arbitrary number of such data records in arbitrary order, each describing and containing a data element. For examples of such multi record messages see Annex E, or for further information on M-Bus see Annex G.

#### **6.2 Data Information Block (DIB)**

The DIB contains at least one byte of Data Information Field (DIF), and can be extended by a maximum of ten Data Information Field Extensions (DIFE).

#### **6.3 Data Information Field (DIF)**

The following information is contained in a DIF:

<span id="page-31-0"></span>

#### **Table 20 — Coding of the Data Information Field (DIF)**

#### **6.4 Data field**

The data field shows how the data from the master shall be interpreted in respect of length and coding. The following table contains the possible coding of the data field:

<span id="page-31-1"></span>



For a detailed description of data types, refer to Annex A "Coding of data records" (e. g. BCD = type A, Real = type H). The coding as "integer/binary" implies always type B (signed integer) unless the VIF/- VIFE of the record implies another data type (e.g. date/time).

#### Variable length:

With data field = `1101b' several data types with variable length can be used. The length of the data is given after the DRH with the first byte of real data, which is here called LVAR (e.g. LVAR = 02h: ASCII string with two characters follows).

If LVAR is used as the variable length of a wireless M-Bus data container (see Annex N) it counts the number of bytes inside the container.

LVAR = 00h – BFh 8-bit text string according to ISO 8859–1 with LVAR (0 to 191) characters

NOTE 1 A text string (like all other multibyte data) is transmitted "least significant byte first".



#### $LVAR = F6h$  Binary number with 64 bytes

Others LVAR values : Reserved

Like all multibyte fields the last character is transmitted first.

NOTE 2 In previous versions of [EN 13757-3](http://dx.doi.org/10.3403/03164728U), LVAR=F8h was used for floating point number according to IEEE 754, but it is no longer applicable.

<span id="page-32-0"></span>Special functions (data field  $= 1111b$ ):





If data follows after DIF = 0Fh or 1Fh these are manufacturer specific unstructured data. The number of bytes in these manufacturer specific data can be calculated from the link layer information on the total length of the datagram. The DIF 1Fh signals additionally a request from the slave to the master to readout the slave once again. The master shall readout the slave until there is no DIF = 1Fh inside the responded datagram (multi-datagram message readout) or use an application reset. The variable data block of the next datagram starts with a normal DIF. If a multi-datagram message contains M-Bus records only, but no manufacture specific data, the DIF 1Fh has to be the last byte in the application frame of all except the last datagram.

#### **6.5 Function field**

<span id="page-32-1"></span>The function field gives the type of data as follows:





#### **6.6 Storage number**

The bit 6 of the DIF serves as the LSB of the storage number of the data concerned, and the slave can in this way indicate and transmit various stored metering values or historical values of metering data. This bit is the least significant bit of the storage number and allows therefore the storage numbers 0 and 1 to be coded. If storage numbers higher than "1" are needed, following (optional) DIFE´s contain the higher bits. The storage number 0 signals a current value.

NOTE Each storage number is associated with a dedicated time point. Each data record with the same storage number refers the value to this (common) time point given by this storage number. A time/date record for each storage number can be included somewhere in the message to signal this time point associated with this

storage number. This date or date/time is coded with a data record with a VIF=E110110n. Normally (but not necessarily) higher storage numbers indicate an older time point. A sequential block of storage numbers can be associated with a sequence of equidistantly spaced time points (profile). Such a block can be described by its starting time, by the time spacing, by the first storage number of such a block and by the length of such a block. For an example see Annex I.

### **6.7 Extension bit (E)**

The extension bit (MSBit) signals that more detailed or extended descriptions (data field extension  $=$  $D$  IFE)-bytes follow.  $E = 1$  if other VIFE or DIFE follow.

#### **6.8 Data Information Field Extension (DIFE)**

Each DIFE (maximum ten) contains again an extension bit to show whether a further DIFE is being sent. Besides giving the next most significant bits of the storage number, DIFEs allow the transmission of information about the tariff and the subunit of the device. In this way, exactly as with the storage number, the next most significant bit or bits will be transmitted. Table 24 shows the structure of a DIFE:

<span id="page-33-0"></span>

#### **Table 24 — Coding of the Data Information Field Extension (DIFE)**

With the maximum of ten DIFEs, which are provided, there are 41 bits for the storage number, 20 bits for the tariff and 10 bits for the subunit of the meter. There is no application conceivable in which this immense number of bits could all be used.

#### **6.9 Tariff information**

For each (unique) value type designation given by the following VIB at each unique time point (given by the storage number) of each unique function (given by the function field), there might exist still various different data, measured or accumulated under different conditions. Such conditions could be time of day, various value ranges of the variable (i.e. separate storage of positive accumulated values and negative accumulated values) itself or of other signals or variables or various averaging durations. Such variables, which could not be distinguished otherwise, are made different by assigning them different values of the tariff variable in their data information block.

NOTE This includes but is not necessarily restricted to various tariffs in a monetary sense. It is at the distinction of the manufacturer to describe for each tariff (except 0) what is different for each tariff number. Again, as with the storage numbers, all variables with the same tariff information share the same tariff associating condition.

#### **6.10 Subunit information**

A slave component may consist of several functionally and logically independent subunits of the same or of different functionality. Either such a device uses several different primary and/or secondary addresses or it uses the subunit information field for addressing a logically independent subunit within a device that uses only one primary and/or secondary address. This is recommended for devices which represent a physical collection of several truly independent (often similar or identical) devices. For devices which share common information and values and have logical connections, an approach with a common link layer (i.e. a single address) is recommended. The various subunits can include their specific information into a common message and have them differentiated by the individual subunit number in the subunit-data field of their records.

## **7 Value Information Block (VIB)**

#### **7.1 General**

After a DIF (with the exception of Table 22) or a DIFE without a set extension bit there follows the VIB. This consists at least of the value information field (VIF) and can be expanded with a maximum of 10 VIF-extensions (VIFE). The VIF and also the VIFEs with a set MSBit show that another VIFE will follow. In the value information field VIF, the other seven bits give the unit and the multiplier of the transmitted value.

<span id="page-34-0"></span>



There are five types of coding depending on the VIF:

#### a) **Primary VIF: E000 0000b … E111 1011b**

The unit and multiplier are taken from Table 26 Primary VIF-codes (7.2).

#### b) **Plain-text VIF: E111 1100b**

In case of  $VIF = 7Ch / FCh$ , the true VIF is represented by the following ASCII string with the length given in the first byte.

Annex C.2 shows an example for a plain text VIF.

#### c) **Linear VIF-extension: FDh and FBh**

In case of  $VIF = FDR$  and  $VIF = FBR$  the true  $VIF$  is given by the next byte (i.e. the first  $VIFE$ ) and the coding is taken from Table 28 in 7.4 and Table 29 (for secondary VIF) in 7.5, respectively. This extends the available VIFs by another 256 codes.

#### d) **Any VIF: 7Eh / FEh**

This VIF-Code can be used in direction master to slave for readout selection of all VIFs. See special function in 6.4.

#### e) **Manufacturer specific: 7Fh / FFh**

In this case, the remainder of this data record including VIFEs has manufacturer specific coding.

#### **7.2 Primary VIFs (main table)**

The first section of the main table contains integral values, the second typically averaged values, the third typically instantaneous values and the fourth block contains parameters (E: extension bit).

<span id="page-35-0"></span>

#### **Table 26 — Primary VIF-codes**

For gas it is the temperature converted volume, unless a VIFE signals volume at metering- conditions or volume at baseconditions.

b Meaning depends on data field.
## **7.3 VIF-codes for special purposes**



## **Table 27 — Special VIF-codes**

## **7.4 Main VIFE-code extension table (following VIF = FDh for primary VIF)**





## **Table 28** *(continued)*



## **Table 28** *(continued)*



## **7.5 Alternate VIFE-code extension table (following VIF = FBh for primary VIF)**



### **Table 29 — Alternate extended VIF-code table**

## **7.6 Combinable (orthogonal) VIFE-Code extension table**

This code follows immediately the VIF or the VIFE (in case of code extension) and modifies its meaning.

<b>VIFE-Code</b>	<b>Description</b>
E000 xxxx	Reserved for object actions (master to slave): see Clause 9 or for error codes (slave to master): see 8.4
E001 0100	a Relative deviation
$E0010000 -$	Reserved
E001 0100	
E001 0101-E001 1100	Record error codes (slave to master); (see 8.4)
E001 1101	$\mathbf b$ Standard conform data content
E001 1110	Compact profile with registers
E001 1111	Compact profile without registers <sup>c</sup>
E010 0000	Per second
E010 0001	Per minute
E010 0010	Per hour
E010 0011	Per day
E010 0100	Per week
E010 0101	Per month
E010 0110	Per year
E010 0111	Per revolution / measurement
E010 100p	Increment per input pulse on input channel number p
E010 101p	Increment per output pulse on output channel number p
E010 1100	Per litre
E010 1101	Per $m^3$
E010 1110	Per kg
E010 1111	Per K (Kelvin)
E011 0000	Per kWh
E011 0001	Per GJ
E011 0010	Per kW
E011 0011	Per (K*I) (Kelvin*litre)
E011 0100	Per V (volt)
E011 0101	Per A (ampere)
E011 0110	Multiplied by s
E011 0111	Multiplied by s / V
E011 1000	Multiplied by s / A
E011 1001	Start date(/time) of <sup>d, e</sup>

**Table 30 — Combinable (orthogonal) VIFE-table**

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### **Table 30** *(continued)*

a Use the multiplier VIFE E111 0nnn to generate % or ppm values, e.g. multiplier of 10-2.

b This VIFE shall be attached to a special VIFE if the content of the related data point has not a manufacture specific use but conforms exclusively to the definitions of the Annex H.

c This VIFE declares a series of data points as compact profile. According to Annex I.

d "Date(/time) of" or "Duration of" relates to the information which the whole Data Record Header contains.

e The information about usage of data type F (date and time) or data type G (date) can be derived from the data field (0010b: type G / 0100: type F).

f Used either to indicate that the consumption value is referenced, respectively converted to base conditions (e.g. gas volume at base temperature and base pressure) or for the base condition itself (e.g. reference/ base temperature or reference/ base pressure).

g The additive correction constant is given as a separate data record.

The codes of Table 31 follow immediately after the VIFE=FCh of Table 30.



### **Table 31 — Extension of combinable VIFE-table (following VIFE = FCh of combinable (orthogonal) VIFE-table)**

## **8 Application layer status and error reporting**

### **8.1 General**

The acknowledgement by the data link layer reports only a successful communication. Errors happened by the handling of the transmitted application data are not reported. There are three different techniques for the reporting of application errors.

### **8.2 Status field**

The presence and type of an application error shall be indicated by the status field in the variable data structure (refer to Table 8 in 5.10).

### **8.3 General application layer errors**

For reporting general application errors, a slave can use a RSP\_UD datagram with  $CI = 6Eh$ , 6Fh or 70h and zero, one or several data bytes, which describe the type of error:





#### **Table 33 — Application error (short data header)**



### **Table 34 — Application error (long data header)**



The following values for DATA are defined:



### **Table 35 — First error code byte for general application errors**

a These error codes are applied in [EN 13757-5.](http://dx.doi.org/10.3403/30160774U)

<sup>b</sup> The data point is coded as M-Bus-specific data point with a leading DIF/ VIF. The declaration is vendor specific. The dynamic application error is limited to 7 bytes.

### **8.4 Record errors**

To report errors belonging just to a special record and not to the full application, the slave can add to the defective record a VIFE containing one of the values of Table 36 to code the type of application error, which has occurred for this record.

<b>VIFE-Code</b>	Type of record error	<b>Error group</b>				
E000 0000	None					
E000 0001	Too many DIFEs					
E000 0010	Storage number not implemented					
E000 0011	Unit number not implemented					
E000 0100	Tariff number not implemented	DIF errors				
E000 0101	Function not implemented					
E000 0110	Data class not implemented					
E000 0111	Data size not implemented					
E000 1000 to	Reserved					
E000 1001						
E000 1010	Reserved					
E000 1011	Too many VIFEs					
E000 1100	Illegal VIF-Group					
E000 1101	Illegal VIF-Exponent	VIF errors				
E000 1110	VIF/DIF mismatch					
E000 1111	Unimplemented action					
E001 0000 to	Not used for record errors					
E001 0100						
E001 0101	No data available (undefined value)					
E001 0110	Data overflow					
E001 0111	Data underflow					
E001 1000	Data error	Data errors				
E001 1001 to	Reserved					
E001 1011						
E001 1100	Premature end of record	Other errors				

**Table 36 — Codes for record errors (E = Extension bit)**

In case of record errors the data maybe invalid. The slave has some options to transmit the data:

- $-$  data field = 0000b: no data;
- $-$  data field = 0000b: no data and idle filler (DIF = 02Fh): fill record up to the normal length;
- other data field: dummy data of correct length;
- other data field: unsafe or estimated data.

## **9 Generalised object layer**

The fundamental idea of an object is the encapsulation of data and methods or actions for the data. In case of writing data to a slave the master software can pack data and information about the action, which the slave shall do with this data, in one data record. This variable data record with actions is now called an object. Following any VIF including a VIF = FDh or VIF = FBh with the true value information in the first VIFE, another (usually the last) VIFE can be added which contains a code signalling object actions according to the following table.

<b>VIFE-Code binary</b>	<b>Action</b>	<b>Explanation</b>									
E000 0000	Write (replace)	Replace old with new data									
E000 0001	Add value	Add data to old data									
E000 0010	Subtract value	Subtract data from old data									
E000 0011	OR (set bits)	Data OR old data									
E000 0100	<b>AND</b>	Data AND old data									
E000 0101	XOR (toggle bits)	Data XOR old data									
E000 0110	AND NOT (clear bits)	NOT data AND old data									
E000 0111	Clear	Set data to zero									
E000 1000	Add entry	Create a new data record									
E000 1001	Delete entry	Delete an existing data record									
E000 1010	Delayed action	$ACI = 5Ch$ will follow and execute the desired action									
E000 1011	Freeze data	Freeze data to storage no.									
E000 1100	Add to readout-list	Add data record to RSP UD									
E000 1101	Delete from readout-list	Delete data record from RSP UD									
E000 111x	Reserved										
<b>NOTE</b>	The object action "write/ replace" (VIFE = $E000 0000$ ) is the default and is assumed if there is no VIFE with an object action for this record.										

**Table 37 — Action codes for the generalised object layer (master to slave)**

## **10 Manufacturer specific unstructured data block**

The MDH consists of the character 0Fh or 1Fh (DIF = 0Fh or 1Fh) and indicates that all following data are manufacturer specific. When the total number of bytes given from the link/network layers and the number of record-structured bytes and the length of the fixed header is known, the number of remaining unstructured manufacturer specific bytes can be calculated.

NOTE Structured manufacturer specific data (i.e. those with a known data structure including variable length binary or ASCII but with a manufacturer specific meaning or unit) can be described using normal data records with a value information field of  $VIF = E11111111b$ .

The MDH = 1Fh is used for multi datagram messages (refer to 6.4).

### **11 Management of lower layers**

### **11.1 General**

Because changing of parameters like baud rate and address by higher layers is not allowed in the ISO-OSI-Model, a management layer beside and above the three layers of the collapsed model is defined.

	<b>Management layer</b>
Application layer	
Transport layer	Secondary address selection via address 253 and $Cl = 52h$
Data link layer	primary Address + 254 (255)/ 251

**Table 38 — Management layer of the M-Bus link layer according [EN 13757-2](http://dx.doi.org/10.3403/03164534U)**

The addresses 0..250 are used as primary addresses for meters on the M-Bus. The address 254 can be used for addressing a single meter with an unknown primary address (as long as only one meter is connected to the master). The address 255 is applied as broadcast address (without acknowledge). The address 251 is applied for managing the (primary) M-Bus level converter/ bridge and the address 253 (selection) for the optional secondary addressing via the transport layer (see 11.3).

### **11.2 Switching baud rate for M-Bus link layer according to EN [13757-2](http://dx.doi.org/10.3403/03164534U)**

All slaves shall be able to communicate with the master using the minimum transmission speed of 300 Bd. Split baud rates between transmit and receive are not allowed, but there can be devices with different baud rates on the bus.

In point to point connections the slave is set to another baud rate by a control frame (SND UD with L-Field = 3) with address FEh and one of the following CI-field codes.

For safety reasons a baud rate switch command to the (unacknowledged) broadcast address 255 is not recommended.

	<b>CI-field</b>	B <sub>8</sub> h B <sub>9</sub> h		<b>BAh</b>	<b>BBh</b>	<b>BCh</b>	<b>BDh</b>	<b>BEh</b>	<b>BFh</b>					
	Baud	600 <sup>b</sup> 300 <sup>a</sup>		$1200^{\rm b}$	2400 <sup>a</sup>	$4800^{b}$	9600 <sup>a</sup>	19 200 <sup>b</sup>	38 400 <sup>p</sup>					
a	Recommended standard baud rates.													
	These baud rates are reserved for special operator agreement only.													

**Table 39 — CI-field codes for baud rate switching**

The slave always confirms the correctly received datagram by transmitting an E5h with the old baud rate and uses the new baud rate from now on, if it is capable of this. Otherwise the slave stays at its previous baud rate after the E5h acknowledge. To make sure that a slave without auto speed detect has properly switched to the new baud rate and that it can communicate properly at the new baud rate in its segment, it is required that, after a baud rate switch to a baud rate other than 300 Bd, the master attempts immediately (< 2 min) after the baud rate switch command a communication. If (even after the appropriate number of retries) this is not acknowledged by the slave, the master shall issue a baud rate set command (at the attempted new baud rate) back to the previous baud rate. If a slave without auto speed detect does not receive a valid communication at the new baud rate within 2 min to 10 min of the baud rate switch command, the slave shall fall back to its previous baud rate. This is required

individually and sequentially for each addressable slave. For compatibility with older slaves with fall back to 300 Bd, the master should also attempt a communication at 300 Bd if the slave does not answer at its last baud rate.

### **11.3 Selection and secondary addressing**

This technique allows the M-Bus protocol to logically "connect" a slave with a certain (secondary) address and it then associates this selected slave with the primary address of 253 (FDh). So the maximum number of 250 addresses (primary) is extended by this technique to an arbitrary number of possible slaves, effectively increasing the address range of the link layer. This function is only enabled by a SND\_UD with CI-field 52h to address 253.

When addressing in the data link layer with the help of the A-field, the problem of the address allocation could arise. The addresses are normally set to a value of 0 by the manufacturer of the meters, in order to designate them as unconfigured slaves. A very laborious method of address allocation consists of setting the addresses when installing the slaves, for example, with DIP switches. A further method of address allocation is to determine the bus addresses when connecting the equipment to the bus with the master software. This sends a command for address allocation (see E.3) to the address 0. In this case the slaves shall, however, all be successively connected to the bus, which very much gets in the way of a simple installation procedure.

When addressing in the transport layer, however, these disadvantages are avoided and the address region is essentially extended beyond the number of 250 with primary addressing (A-field). The addressing of the slaves takes place with secondary addressing with the help of the following socalled selection.

68h	0Bh	0Bh	68h	53h/ 73h	$ -$ υh -	52h	$\mathbf{A}$ -4	Man $\sim$	Gen	Jev	UC	®6h

**Table 40 —Structure of a datagram for selecting a slave**

The master sends a SND UD with the control information 52h to the address 253 (FDh) and fills the specific meter secondary address (identification number, manufacturer, version and device type) with the values of the slave which is to be addressed. After the reception of the address FDh the selection mode is entered. If then the proper CI-selection code CI = 52h is received, the internal selection bit is set; otherwise, it is reset. If further data bytes follow, they are compared with the corresponding internal addresses respective values of the meter. If they disagree, the selection bit is cleared; otherwise, it is left unchanged. Thus, "selecting" a meter with only a proper CI-field and no further data will select all meters on the bus capable of secondary addressing. A set selection bit means that this slave can be addressed (e.g. REQ UD) with the bus address FDh and in this example will reply with RSP\_UD. In other words, the transport layer has associated this slave with the address FDh.

During selection, individual positions of the secondary addresses can be occupied with wildcards (Fh). Such a wildcard means that this position will not be taken account of during selection, and that the selection will be limited to specific positions, in order to address complete groups of slaves (multicasting). In the identification number, each individual digit can be wildcarded by a wildcard nibble Fh while the fields for manufacturer, version and device type can be wildcarded by a wildcard byte FFh.

The state of the selection remains unchanged until the slave is deselected with a selection command (as described above) with non-matching secondary addresses, or a SND\_NKE to address 253. In case of a SND\_NKE to address 253 a selected slave has to acknowledge the deselection with a single 0E5h. The slave, which uses mode 1 for multibyte records, will be selected by a datagram with the CIfield 52h and the correct secondary address, but it will be deselected by a datagram with any other secondary address.

A slave with implemented primary and secondary addressing shall also answer datagrams to its primary address. A SND\_NKE to its primary address (0..250, 254, 255) will not influence the internal

selection bit for the secondary addressing mode. This is comparable to the FCB management, where primary and secondary addressing is also handled separately.

A slave with only secondary addressing (i.e. internal primary address = 253) shall occupy the address field in the RSP\_UD datagram with FDh to signal that it will not participate in primary addressing.

A slave with implemented primary and secondary addressing shall occupy the address field in the RSP\_UD telegram with its own primary address to signal its accessibility via this primary address. The slave shall ignore the state of the FCB-Bit if it receives a SELECT message (CI-field = 52h).

### **11.4 Generalised selection procedure**

For including new or restructured identification parameters into a selection procedure an enhanced definition of the selection datagram  $(Cl = 52h)$  can be used.

After the 8 byte of the fixed selection header may also follow standard records with data. In this case only those meters will be selected where, in addition to the fixed header, all record data agree. In most but not all cases this means that the DIF and parts of the VIF (not exponent) shall match. Again wildcard rules apply to the record data (digit wildcard for BCD-coded data and byte wildcard for binary or string data).

With this generalised selection it will be possible to select slaves using e.g. additional fabrication number, longer identification numbers, customer location and more information.

After the field "device type" the 8-digit BCD-fabrication number follows. Parts of the fabrication number (Fab1 … Fab4) can be occupied with wildcards (Fh).

#### **Enhanced selection with fabrication number**

The identification number can be used as a customer number and then can be changed by the operator. Therefore, it can be possible that two slaves have the same secondary address. For this reason the selection datagram can be extended by a **fabrication number** to make sure that in any case all slaves are distinguishable. This number is a serial number allocated during manufacture, coded with 8 BCD packed digits (4 byte) like the identification number, and thus runs from 00000000 to 99999999.

The following table shows the structure of an enhanced selection datagram released by the master.



#### **Table 41 — Application layer structure of a datagram for enhanced selection (mode 1)**

After the field device type the new data is given in form of a structured data record with  $DIF = OCh$  and  $VIF = 78h$ . Parts of the fabrication number (Fab1  $\ldots$  Fab4) can be occupied with wildcards (Fh).

If a fabrication number exists and is needed for the selection procedure, the slave shall add this data to the variable data blocks in every RSP-UD datagram. If the fabrication number and enhanced selection is not implemented in a slave this device shall not confirm the enhanced selection datagram and shall be deselected.

Enhanced selection should be used only if the normal kind of selection is not successful.

### **11.5 Searching for installed slaves**

### **11.5.1 Primary addresses**

To read out all installed slaves the master software shall know all the slaves which are connected to the bus. Therefore, the software searches for slaves with primary addressing by sending a REQ\_UD2 to all allowed addresses (1 … 250) with all available baud rates. The master notes used primary addresses with the respective baud rates.

### **11.5.2 Secondary addresses**

The secondary addressing described in the preceding section draws attention to the problem of determining the secondary addresses of slaves connected to the bus. The master can read out the slaves making use of secondary addresses with previous selection (see 11.4). Testing all possible identification numbers with the master software would take years since the identification number offers millions of combinations. For this reason, a procedure was developed for the rapid and automatic determination of already installed slaves.

### **11.5.3 Wildcard searching procedure**

The following wildcard searching procedure uses the occupation of individual parts of the secondary address with wildcards (Fh) for selection.

In this case with the identification number (BCD), each individual position, and by manufacturer, version and device type (binary coding), only one complete byte, can be occupied with wildcards. The master begins the selection using a SND. UD with the control information 52 h (mode 1), and occupies all positions in the identification number, except the top one, with wildcards. The top position is run through in ten selections from 0 to 9 (0FFFFFFF to 9FFFFFFF).

If after such a selection the master receives no acknowledgement, it goes to the next selection. If the master receives an E5h, it sends a REQ\_UD2 and learns the secondary address of the slaves from the reply datagram, as long as no collision occurs. If there is a collision after the selection or the REQ\_UD2, the master varies the next positions and holds the existing one. If there is a collision, for example at 5FFFFFFF, the selection is run through from 50FFFFFF to 59FFFFFF. If in this case collisions again occur, then a change is made to a variation of the next position. After running through a complete position, the next higher position is processed up to 9.

With this wildcard searching procedure, it will be seen that at least the top position shall be run through in order to reach all slaves. Running through further positions may be necessary, depending on the number of the slaves and the distribution of the identification numbers. This procedure allows a statement of the maximum number of selections in relation to the number of slaves, but as a disadvantage frequent collisions may occur. The wildcard searching procedure shall be performed for all used baud rates and both byte sequences (mode 1 and 2).

The search procedure can be extended with searching for manufacturer, generation and finally device types to find slaves, which have the same identification number. It is also possible to search for all slaves of a certain manufacturer or all slaves of a certain device type by setting the corresponding value. With extended selection meters, which differ only in their manufacturer, specific fixed fabrication number can be distinguished.

NOTE For further information on Wildcard search procedure (secondary search), see Annex F.

## **Annex A**

(normative)

## **Coding of data records**

The following data types are used inside the application layer:

**Type A: Unsigned integer BCD := XUI4 [1 to 4] <0 to 9 BCD>**

### **Table A.1 — Type A: Unsigned BCD**



Digits values of Ah – Eh in any digit position signals invalid.

A hex code Fh in the MSD position signals a negative BCD number in the remaining X-1 digits. For details of this coding see Annex B.

**Type B: Binary integer :=**  $I[1..X]$  **<**  $(-2^{X-1}+1)$  **to**  $+(2^{X-1}-1)$ 

## **Table A.2 — Type B: Signed integer**



1B1  $[X] := S = \text{sign: } S \le 0$  := positive  $S \leq 1$  := negative negative values in two's complement

The coding "1000…0000b" signals "invalid"

### **Type C: Unsigned integer:= UI[1..X]** < **0 to 2X-2**>





UI8  $[1 \text{ to } .8]$  < ( 0 to 255)>

NOTE 1 The data field coding as 'integer/binary' always applies to Type B (signed integer) except Type C (unsigned integer) is explicit declared by the special VIF/VIFE.

The coding "1111…1111b" signals "invalid"

### **Type D: Boolean (1 bit binary information)**:= XB1 B1[i] < 0 to 1>



NOTE 2 The data field coding as 'integer/binary' always applies to Type B (signed integer) except Type D (Boolean) is explicit declared by the special VIF/VIFE.

#### **Type E: Obsolete**

#### **Type F: Compound CP32: Date and time**

$2^7$	26	25	2 <sup>4</sup>	$2^3$	$2^2$	2 <sup>1</sup>	2 <sup>0</sup>	Min: UI6 [1 to 6] < 0 to 59>; 63 : every minute						
$2^{15}$	$2^{14}$		11ر 12ر 13ر		$2^{10}$	$2^9$	28	Hour: UI5 [9 to 13] $<$ 0 to 23 $>$ ; 31 : every hour						
$2^2$	22 21		$2^{20}$		2 <sup>19</sup> 2 <sup>18</sup> 2 <sup>17</sup>		216	Day: UI5 [17 to 21] < 1 to 31 > ; 0 : every day						
$2^{31}$	230		229 228 227		226	25 24		Month: UI4 $[25 \text{ to } 28] < 1$ to 12> ; 15 every month						
								Year: UI7 [22 to 24 ; 29 to 32] < 0 to 99> ; 127 every year						
								Hundred year: UI2 $[14$ to $15] < 0$ to 3> this year is 1900+100*hundred year + year						
								IV B1 [8] $IV < 0 >$ = valid $\therefore$ $IV < 1 >$ = invalid						
								SU $IV < 0$ = standard time $\therefore$ IV $< 1$ = summer time B1 [16]						
								RES <sub>1</sub> B1 [7] <0> reserved for future use						

**Table A.5 — Type F: Date and time (CP32)**

For compatibility with old meters with a circular two digit date it is recommended to consider in any master software the years "00" to "80" as the years 2000 to 2080.

#### **Type G: Compound CP16: Date**





For compatibility with old meters with a circular two digit date it is recommended to consider in any master software the years "00" to "80" as the years 2000 to 2080. A value of FFh in both bytes (that means FFh FFh) shall be interpreted as invalid.

### BS EN 13757-3:2013 **EN 13757-3:2013 (E)**

### **Type H: Floating point according to IEEE-standard**





### **Table A.7 — Type H: Floating point**

The following ranges are specified by IEE Std 754–1985 for floating point arithmetic's

Range:( $-2^{128}$  +  $2^{104}$ ) to (+2<sup>128</sup> – 2<sup>104</sup>), that is  $-3.4*10^{38}$  to +3,4\*10<sup>38</sup>

Smallest negative number:-2-149,that is: – 1,4∗10-45

Smallest positive number:+2-149, that is: + 1,4∗10-45

### **Type I: Year down to second**

### Data field =  $0110$  (48 bits)



### **Table A.8 — Type I: Date and time (CP48)**

Local time :



<span id="page-54-1"></span>2) Based on EN [62056-62](http://dx.doi.org/10.3403/02606953U) (COSEM).

-

<span id="page-54-0"></span><sup>1)</sup> Other values reserved for future uses.

<span id="page-54-2"></span> $3)$  Number of hour by which the local time shall be corrected at daylight savings begin.



### **Key**

- Y deviation
- 
- X time<br>1 dayli 1 daylight savings begin<br>2 daylight savings end
- daylight savings end



### **Type J: Time of day**

Data field =  $0011$  (24 bits)

<b>Byte</b> /bit	<b>MSBit</b>							<b>LSBit</b>
<b>LSB</b>	8		6	5	4	3	2	
	16	15	14	13	12	11	10	9
<b>MSB</b>	24	23	22	21	20	19	18	17

**Table A.9 — Type J = Time (CP24)**



000000h: time invalid.

-

<span id="page-55-0"></span><sup>4)</sup> Other values reserved for future uses.

### **Type K: Daylight savings**

Data field = 0100 (32 bits)

<b>Byte/bit</b>	<b>MSBit</b>							<b>LSBit</b>		
<b>LSB</b>	8	$\overline{7}$	6	5	4	3	2	$\mathbf{1}$		
	16	15	14	13	12	11	10	9		
	23 24			21	20	19	18	17		
<b>MSB</b>	32	31	30	29	28	27	26	25		
Daylight savings enable			UI1 [16]		$\leq 0$ to 1> $\sim$			1 enables daylight savings function		
Deviation from local time to the Greenwich Mean Time (hour):					UI5 [6 to 8 + 14 to 15] $\leq 0$ to 23 > $\leq$ 31 > 31 = not specified <sup>6)</sup>					
Daylight savings begin (given in local time):										
	Hour		UI5 [1 to 5]		$\langle$ 0 to 23 $>^{6}$					
	Day		UI5 [9 to 13]		$1$ to 31 $>^{6}$					
	Month		UI4 [25 to 28]		$1$ to 12 $>^{6}$					
Daylight savings end: (given in local time):										
	Day		UI5 [17 to 21]		$1$ to 31 $>^{6}$					
	Month		UI4 [29 to 32]		$1$ to 12 $>^{6}$					
Daylight savings deviation (hour)		6)	UI1[24]		$< 0$ to 1> 1= + 0 = -					
			UI2 [22 to 23]		$<$ 0 to 3> 0 = no daylight savings					

**Table A.10 — Type K: Daylight savings**

-

<span id="page-56-0"></span><sup>5)</sup> Other values reserved for future uses.

<span id="page-56-1"></span> $_{6)}$  Number of hour by which the local time shall be corrected at beginning of daylight savings.

### BS EN 13757-3:2013 **EN 13757-3:2013 (E)**

### **Type L: Listening window management**

Data field = 1101 (variable length LVAR=EBh)



#### **Table A.11 — Type L: Listening window management**

This command is used to initialise the window listening management, which defines when the meter is in "normal mode" or "power saved mode".

We choose the week(s) while the meter could be in normal mode. Set to 1 the matching bit(s): bit 1 to bit 53. The first week of the year is represented by bit 1, .. , the 52nd by the bit 52.

We choose the day(s) while the meter could be in normal mode. All the weeks are identical for this choice. Set to 1 the matching bit(s): bit 54 to bit 60. Sunday is represented by bit 54, Monday by bit 55, .. , Saturday by bit 60.

We choose the hour(s) while the meter could be in normal mode. All the days are identical for this choice. Set to 1 the matching bit(s): bit 61 to bit 83. The first hour is represented by bit 61, .. the 24th hour by bit 84.

We choose the quarter(s) of an hour, while the meter could be in normal mode. All the hours are identical for this choice. Set to 1 the matching bit(s): bit 85 to bit 88. The first quarter is represented by bit 85, .. the fourth quarter by the bit 88 .

At one point, the meter is in "normal mode" if the bits for week, day and hour are set to 1. The meter is in "power saved mode" if one or more of the bits for week, day and hour is set to 0.

#### For example:

If bits 3, 55, 56, 61 and 62 are set to 1 and the others are set to 0. The meter is in normal mode between 0 and 2 hour on Monday and Tuesday of the third week of the year.

If bits 3, 55, 56, 61,63, 85 and 86 are set to 1 and the others are set to 0 the meter is in normal mode in the first and second quarter of hour 0 and hour 2 , between 0:00' and 0:30' and between 2:00' and 2:30', on Monday and Tuesday of the third week of the year.

## **Annex B**

## (normative)

## **Interpretation of hex-codes Ah – Fh in BCD-data fields**

## **B.1 General description standard reference**

This standard allows multi-digit BCD-coded data fields. It does, however, not contain information about what happens if a non-BCD hex code  $(Ah - Fh)$  is detected by the master software.

### **B.1.1 Purpose**

a) Define the treatment of non BCD-digits in slave to master RSP\_UD-datagrams.

To fully define a master software including error treatment; such a definition would be desirable.

- b) Utilise these codes for simplified error treatment by slave.
	- 1) Simple visible error signalling.

To simplify the design of slaves with integrated displays, the above mentioned non-BCD states of the variables should be both transmittable in the form of suitable (hex) codes but also be displayable directly from the value codes of a 7-segment (usually LCD) display by extending the normal ten entry BCD to 7-segment decoding a 16-entry decoding table.

## **B.2 Definition**

### **B.2.1 Hex code meanings**

a) Ah – Eh

Such a code in any digit position signals a general error of the complete data field. The display at the meter or a remote readout device should display an appropriate symbol at the appropriate display position. (see Table B.1)

### b) Fh

Such a code in the MSD digit position signals a "minus-sign" in front of the remaining (N–1) digit number. In any other digit position it signals an error.

EXAMPLE A 4-digit BCD code of "F321" will be interpreted by the master software as "– 321" and displayed as "- 321" on a 4-digit only display.

### **B.2.2 LCD-decoding table**

l 0									O - 12	Ah	<b>Bh</b>	Ch	Dh	Eh ——	' Fh
יי∩יי	$H - H$	$\mathsf{H}\cap\mathsf{H}$ _	$\mathsf{H} \cap \mathsf{H}$ u	"4"	"5" J	"6"	サラサ	יי גיי ◡	יים"	"A"	"b"	$n^{\sim}$ ◡	$\mathbf{H}$	" = " -	.

**Table B.1 — Decoding table**

## **Annex C**

(normative)

## **VIF coding for special units**

## **C.1 Non-metric units**

If the VIF-Extension code 3Dh (non-metric units) is used, the standard metric units of the VIF table is substituted as follows:



### **Table C.1 — Metric/non-metric units**

## **C.2 Plain text units**

In case of VIF = 7Ch / FCh the applied unit is represented by the following ASCII string with the length given in the first byte. The rightmost character is transmitted first. This plain text VIF allows the user to code units that are not included in the VIF tables.





### **Example (all values are hex):**



## **C.3 Remote enablement/disablement of valve/breaker**

The device type « breaker » (20h) and « valve » (21h) allows the definition of physically or logically separated media controlled device with separate address. Otherwise, the valve/breaker may be integrated in the metering device. Therefore, the address of the meter has to apply. The VIF/VIFE=FDh 1Fh allows to control both logically integrated and logically separate valve/breaker. If a device has other functions in addition to metering, the device type is set according to the metering function which is associated with the (default) subunit  $=0$  in the DIF. A (secondary) switch function shall be associated with the subunit  $=1$ . Other additional functions may use higher subunit numbers. If detailed functional requirements for the different media are available, more suggestion for the usage of existing element to implement these functions would be possible. To enable/disable a valve the values in the least significant byte after VIF/VIFE=FDh 1Fh shall follows the Table C.3.





It is recommended to apply additional a time stamp or a sequence counter together with the switch command to detect the replay of an expired switch command.

Example to close a valve together with the sequence counter of 3:

04h FDh 08h 03h 00h 00h 00h 01h FDh 1Fh 00

## **Annex D**

(informative)

## **Alarm protocol**

## **D.1 M-Bus according EN13757-2**

The master software polls the maximum 250 alarm devices by requesting time critical data. A slave can transmit an acknowledgement signalling no alarm or a datagram with alarm protocol with the CIfield 71h (no header), 74h (short header) or 75h (long header) to report an alarm state. Refer to Annex J.

The alarm state is coded with data Type D (Boolean; in this case 8 bit). Set bits signal alarm bits or alarm codes. The meaning of these bits is manufacturer specific.

The time out for time critical communication is set to 11 bit … 33 bit periods to ensure a fast poll of all alarm devices. With a baud rate of 9 600 Bd and all 250 slaves reporting an alarm just in time before a timeout occurs each slave will be polled in periods of maximum 5,5 s. This seems to be fast enough for alarms in building control systems and other applications. For faster alarm systems the number of alarm sensors could be limited to 63 (reducing the worst case overall signal delay to less than 1,5 s) or increase the transmission speed to 38 400 Bd and achieve the same speed for up to 250 devices.

The functionality of the FCB- and FCV-bit shall be fully implemented in this alarm protocol to ensure that one-time alarms are safely transmitted to the master. If the slave has reported an one-time alarm and the next REQ\_UD1 has a toggled FCB (with FCV  $= 1$ ) the slave will answer with an ACK (acknowledge) signalling no alarm. Otherwise it will repeat the last alarm frame to avoid that the alarm message gets lost. If the meter does not support the alarm protocol it has always to respond with an ACK.

## **D.2 Wireless M-Bus according to EN [13757-4](http://dx.doi.org/10.3403/30096182U)**

The meter may initiate the transmission of an alarm message or response to the REQ-UD1 of the communication partner. A slave can transmit an acknowledgement signalling no alarm (after REQ-UD1 only) or an alarm message with the CI-field 71h (no header), 74h (short header) or 75h (long header) to report an alarm state. Refer to Annex J.

The alarm state is coded with data Type D (Boolean, in this case 8 bit). Set bits signal alarm bits or alarm codes. The meaning of these bits is manufacturer specific.

## **Annex E** (informative)

## **Examples**

### **E.1 General**

The Application protocol specific data unit begins with the CI-field and does not include checksum and stop byte. The application protocol specific data are transmitted by the other layers of the communication system.

The following examples give the whole datagram for a twisted pair M-Bus link layer (EN [13757-2](http://dx.doi.org/10.3403/03164534U)). Nevertheless other physical and link layers (e.g. EN [13757-4](http://dx.doi.org/10.3403/30096182U)) could also be used.

## **E.2 Example for a RSP\_UD with variable data structure answer:**

(All values are hex.)



### **E.3 Example baud rate switch:**

The master switches the slave (in point-to-point connection) from now 2 400 Bd to 9 600 Bd.

(all values are hex.)

Master to slave: 68 03 03 68 53 FE BD 0E 16 with 2 400 Bd.

Slave to master: E5 with 2 400 Bd.

From that time on the slave communicates with the transmission speed 9 600 Bd, if the slave can handle 9 600 Bd, otherwise it remains at 2 400 Bd.

In bus mode this is followed within  $< 2$  min by an acknowledged communication (i.e. SND NKE) at 9 600 Bd.

Master to slave: 10 40 FE 3E 16.

Slave to master: E5.

## **E.4 Example application select with subcode:**

The master releases an enhanced application select to all slaves. All datagrams of the user data type are requested.

(All values are hex.)

Master to slave: 68 04 04 68 53 FE 50 10 B1 16.

Slave to master: E5.

### **E.5 Writing data to a slave**

The master can send data to a slave using a SND\_UD with CI-field 51h, 5Ah or 5Bh.

The following table shows the data structure for a write message. The order of the first three blocks in the following figure can be turned round, but the write only data record is at the end of the message. All records are optional.

### **Table E.1 — Data structure for writing data**



a) Primary address record.

The primary address record is optional and consists of three bytes:

### **Table E.2 — Coding of primary address**



With this data record a primary address can be assigned to a slave in point to point connections. The master knows all the used addresses on the bus and forbid setting the address of a slave to an already used address. Otherwise, both slaves with the same address could not be read out anymore.

b) Enhanced identification record.

With this optional data record, the identification (secondary address) can be changed. There are two cases to be distinguished:

1) Data is only the identification number





2) Data is the complete identification

### **Table E.4 — Coding of complete secondary address**



The data is packed exactly as in the readout header of a  $CI = 72$  variable protocol with low byte first.

#### **Table E.5 — Structure of secondary address**



Normal data records:

The data records, which can be read out with a REQ\_UD2, are sent back to the slave with the received DIF and VIF and the new data contents. Additional features can be implemented using the generalised object layer (see Clause 9).

Write-only data:

Data, which cannot be read out of the slave with a normal data block, can be transmitted using the VIF = 7Fh for manufacturer specific coding. The DIF has a value corresponding to the type and length of data.

After receiving the SND UD correctly without any error in data link layer, the slave answers with an acknowledgement (E5h). The slave decides whether to change variables or not after a data write from the master. In case of errors in executing parts of or whole write instructions the slave can decide whether to change no variables or single correct variables. The slave can report these errors to the master in the next RSP\_UD datagram using some of the methods which are described in 8.3.

There are some methods for implementing write protect, for example allowing only one write after a hardware reset of the processor or enabling write if a protect disable jumper is set.

Examples (all values are hex.)

EXAMPLE 1 Set the slave to primary address 8 without changing anything else:

68 06 06 68 53 FE 51 01 7A 08 25 16

EXAMPLE 2 Set the complete identification of the slave (ID = 01020304 (BCD), Man = 4024h (PAD), Ver = 1, Dev. Type  $= 4$  (heat):

68 0D 0D 68 53 FE 51 07 79 04 03 02 01 24 40 01 04 95 16

EXAMPLE 3 Set identification number of the slave to "12345678 (BCD)" and the 8 digit BCD-counter (unit 1 kWh) to 107 kWh.

68 0F 0F 68 53 FE 51 0C 79 78 56 34 12 0C 06 07 01 00 00 55 16

## **E.6 Configuring data output**

### **E.6.1 General**

For default, the slave transmits all his data with a RSP\_UD. It could be useful for some applications to read only selected data records out of one or more devices. There are two ways to select data records.

### **E.6.2 Selection without specified data field**

The selection of the wanted data records can be performed with a SND UD (CI-field = 51h/55h) and data records containing the data field 1000b, which means "selection for readout request". The following VIF defines the selected data as listed in EN 1434–3 and no data are transmitted. The answer data field is determined by the slave. The master can select several variables by sending more data blocks with this data field in the same datagram.

Special multiple values can be selected with the following methods:

Any VIF:

The VIF-code 7Eh (any VIF) is especially for readout request of "all VIF" from the slave and can be interpreted as a selection wildcard for the value information field.

- Global readout request:

The DIF-code 7Fh is defined as "selection of all data for readout request", i.e. all storage numbers, units, tariffs and functions. If this DIF is the last byte of user data or the VIF =  $7Eh$ follows, then all data is requested. So the selection of all data of one slave can de done with a SND\_UD and the character 7Fh as the user data. If a DIF unequal to 7Eh follows, then all data records with this VIF are selected for readout.

All tariffs:

The highest tariff number in the selection record is defined as selection of "all tariffs". For example, the tariff 1111b (15) means selection of all tariffs in a record with two DIFE´s.

All storage numbers:

A selection of all storage numbers can be done with the maximum storage number if there is a minimum of one DIFE. For example the highest storage number is 1Fh (31d) with one DIFE and 1FFh (511d) with two DIFE´s.

- All units:

"All units" can be selected by using a Data Record Header with minimum two DIFEs and the highest unit number.

- High resolution readout:

The master can select the slave to answer with the maximum resolution to a given value/unit by a  $VIF$  with "nnn" = 000 (minimum exponent for range coding). The meter may then answer with a resolution of e.g. 1mWh (VIF = 0000000b) or some higher decimal value if required. The unit values have been chosen so that their minimum provides sufficient resolution even for calibration. A readout request for a VIF with "nnn" = max (maximum exponent for range coding) signals a request for the standard resolution of the meter.

After the next REQ\_UD2 the slave answers with the selected data in his own format, if the requested data are available. Otherwise the slave transmits his normal data and the master has to find out that the data are not the requested ones. If there are more than one variables with the selected VIF, the device shall send all these data records.

### **E.6.3 Selection with specified data field**

The master is able to perform a readout request with a specified data field by using the object action "add to readout list" (VIFE = E000 1100b) from VIFE-table for object actions (see Clause 9). The master transmits a SND\_UD (CI-field = 51h/5Ah/5Bh) with a data record which consists of the desired DIF (data field), VIF and the VIFE =  $0$ Ch/ 8Ch. No data follows this VIFE and the slave shall ignore the data field on reception. The slave shall transmit this data record with the requested data field from now on, if he is capable of this. If the slave does not support this data field (data coding), it can report a record error using one of the VIFE =  $E000011x$  (data class not implemented or data size not implemented).

### **E.6.4 Deselection of data records**

The master can release an application reset of the application layer and especially a fall back to the slave standard RSP\_UD datagram by transmitting a SND\_UD with the CI-field 50h.

Single data records can be deselected by transmitting a data record with DIF, VIF and the VIFE for the object action "Delete from readout-list" (VIFE =  $E000$  1101b).

If the selected data is supported by the slave but too long for one RSP\_UD datagram (especially for readout of all historic values), the slave transmits an additional data record consisting only of the DIF=1Fh, which means that more data records follow in the next respond datagram. In this case the master reads out the slave again until the respond datagram is only a 0E5h (no data) or there is no  $DIF = 1Fh$  in the RSP UD.

To avoid loss of respond datagrams the slave shall in this case support the Frame Count Bit (FCB). If the master wants to prematurely end such a multi datagram message sequential readout of the selected data, it may send an application reset with  $CI = 50h$  instead of further REQ UD2's.

EXAMPLE 1 A slave with address 7 is to be configured to respond with the data records containing volume (VIF) = 13h: volume, unit 1l) and flow temperature (VIF = 5Ah: flow temp., unit 0.1 °C):

68 07 07 68 | 53 07 51 08 13 08 5A 28 16

EXAMPLE 2 A slave with address 1 is to be configured to respond with all storage numbers, all tariffs, and all VIF´s from unit 0:

68 06 06 68 53 01 51 C8 3F 7E 2A 16

EXAMPLE 3 A slave with address 3 is to be configured to respond with all data for a complete readout of all available. After that the master can poll the slave to get the data:

68 04 04 68 53 03 51 7F 26 16

With these actions, the master can alter the data of the slaves or configure the output data of the slaves (actions 12 and 13). The actions 0 to 6 alter the data of the slave by replacing the old data (action 0, equals to data write without VIFE) or do arithmetical or logical operations with the old and the transmitted data.

NOTE This method of configuring the readout list (action 12 and 13) allows not only the adding but also the removal of elements in contrast to the method of using the DIF = 1000b-type of readout request (described before).

All these actions can be used for normal slaves and for intelligent masters which are manipulated by a higher order master.

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> The functions "add entry" and "delete entry" are useful to tell an intelligent master to add e.g. a new data record like maximum or minimum values of any slave.

> With the action "freeze data to storage #" the master can tell the slave to freeze the current value corresponding to the transmitted VIF, unit, tariff and function to a certain storage number given in the DIF/DIFE´s. In this case, the data field inside the VIF has got the value 0000b (no data). This action allows freeze of selected values or multiple freeze with VIF = 7Eh (all VIF). The date/time shall also be frozen to the same storage number.

> EXAMPLE 4 Set the 8 digit BCD-Counter (instantaneous, current value, no tariff, unit 0) with VIF = 06 (1kWh) of the slave with address 1 to 107 kWh:

> > 68 0A 0A 68 53 01 51 0C 86 00 07 01 00 00 3F 16

EXAMPLE 5 Same as in example 1) but add 10 kWh to the old data:

68 0A 0A 68 53 01 51 0C 86 01 10 00 00 00 48 16

EXAMPLE 6 Add an entry with an 8 digit BCD-Counter (instantaneous, current value, no tariff, unit 0, 1kWh) with the start value of 511 kWh to the data records of the slave with address 5:

68 0A 0A 68 53 05 51 0C 86 08 11 05 00 00 59 16

EXAMPLE 7 Freeze actual flow temperature (0.1 °C: VIF = 5Ah) of the slave with address 1 into the storage number 1:

68 06 06 68 53 01 51 40 DA 0B CA 16

### **E.7 FCB and selection**

#### **E.7.1 FCB-implementation slave**

A slave with implemented secondary addressing and with implemented FCB-administration has a "Last received FCB"-memory bit for the communication via the pseudo primary address 253 (FDh). If it can communicate also alternatively over some other primary address (except the special addresses 254 and 255) an additional "Last received FCB"-memory bit for each of these primary addresses is required. A valid selection datagram will not only set the internal selection bit but will also clear the internal "Last received FCB"-memory bit associated with secondary addressing via the pseudo primary address 253 (FDh). The master will start the communication (REQ\_UD2 or SND\_UD) after any selection datagram  $(Cl = 52h)$  with the FCV-bit set and the FCB-bit set. If a slave has more than one alternative secondary address, only a single "Last received FCB"-memory bit for all secondary addresses is required.

#### **E.7.2 FCB-implementation master**

The master implements a "Next FCB image"-bit for each primary address and for the pseudo primary address 253 (FDh). Although these "Next FCB image"-bit might be used for many slaves, no confusion exists, since for accessing another slave a selection datagram is required which will define the future FCB sequence both for slave and master.

If the master applies one of the new application frames with a short or long data header (refer to chapter 5.2, 5.3 and 5.4), it shall increase the access number each time when the FCB was changed.

EXAMPLE

Master> SND\_NKE 10 40 FD 3D 16

*SND-NKE clears the FCB*

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### **E.8 Special slave features**

### **E.8.1 General**

Some optional or recommended features of the slaves will be described in this sub-clause.

### **E.8.2 Use of the fabrication number**

The fabrication number is a serial number allocated during manufacture. It is part of the variable data block (DIF = 0Ch and VIF = 78h) and coded with 8 BCD packed digits (4 byte).

#### EXAMPLE

68 15 15 68header of RSP\_UD datagram (length 1Fh = 31d bytes)

08 02 72 C-field = 08 (RSP), address 2, CI field 72H (var.,LSByte first)

78 56 34 12identification number = 12345678

24 40 01 07manufacturer ID = 4024h (PAD in [EN 61107\)](http://dx.doi.org/10.3403/00285857U), generation 1, water

13 00 00 00TC = 13h = 19d, Status = 00h, Configuration = 0000h

0C 78 04 03 02 01 fabrication number = 01020304

9D 16 checksum and stop sign

The use of this number is recommended if the identification number is changeable. In this case, two or more slaves can get the same secondary address and cannot be uniquely selected. The fabrication number together with manufacturer, version and device type field build a unique number instead. Suitable masters use this number for an enhanced selection method if two or more slaves have the same identification number (see 9.3).

## **Annex F** (informative)

## **Secondary search**

### **F.1 General**

The search procedure has been simulated to find the minimum, the average and the maximum number of selections as a function of the number of slaves. For the minimum number of attempts the optimum distribution of the identification numbers, for the maximum number the most unfavourable, and for the average number of attempts a random distribution was chosen. The following diagram shows the result of these calculations:



### **Key**

- 1 number of selections (worst case)
- 2 number of selections (best case/random case)
- 3 number of slaves

**Figure F.1 — Number of selections with wildcard searching procedure**

## **F.2 Instructions for implementation of wildcard search**

The following program flow diagram shows the realisation of the wildcard searching procedure, whereby the search is made only with the identification number. The codes for manufacturer, version and device type are in general specified with wildcards, but can be changed by the user in order (for example) to locate all meters from a particular manufacturer. In order to avoid the categorisation by a factor of eight of the "For-To" loops for the eight positions, the array "Value" is defined with 8 byte numbers, which are intended to define the contents of the positions. The digit number of the identification number which is presently running is noted in the variable "Pos" of type byte.



**Figure F.2 — Flow diagram for slave search with wildcards**

The routine begins at the first position, and implements the following actions for the value of this position from 0 to 9:

selection with the ID-Nr. Pos 1, Pos 2, ..., Pos 8;
- $-$  if no reply, Value [Pos] is raised by 1;
- if there is a reply, a REQ\_UD2 is sent to address 253, and if the datagram is correctly received the secondary address is learnt and the Value [Pos] raised by 1;
- if there is a collision a jump is made to the next position (Pos increased by 1), as long as the last position has not yet been reached;
- after going through a complete position from 0 to 9 the subroutine proceeds to the next lower position, or ends the search if the position Nr. 1 has already been processed.

The following table shows an example for secondary addresses in order from top to bottom as they will be found by the master software:



4 76 543 210 2010 1 01 03

**Table F.1 — Secondary addresses found with a wildcard search of four slaves**

Search Process:

- 1) Start with  $ID = OFFFFFF$ ; no reply
- 2) ID = 1FFFFFFF: collision between Nr.1 and Nr.2
- 3) ID = 10FFFFFF, 11FFFFFF, 12FFFFFF, 13FFFFFF: no reply
- 4) ID = 14FFFFFF: collision between Nr.1 and Nr.2
- 5) Repeated steps 3 to 4 up to the  $ID = 1449100F$
- 6) Learn ID = 14491001 and 14491008
- 7) Go backwards to 19999999
- 8) ID = 2FFFFFFF: no reply
- 9) ID = 3FFFFFFF: learn ID = 32104833
- 10) .ID = 4FFFFFFF, 5FFFFFFF, 6FFFFFFF: no reply
- 11) ID = 7FFFFFFF: learn ID = 76543210
- 12) ID = 8FFFFFFF, 9FFFFFFF: no reply
- 13) End of the search

## **Annex G**

(informative)

## **International reference works**

WWW-server operated by the M-Bus user group at "http://www.m-bus.com" provides information on the M-Bus.

## **Annex H**

## (informative)

## **Special sequences for wireless M-Bus devices**

## **H.1 VIF/VIFE/VIFE = FDh 97h 1Dh (error flag)**

If the data point VIF/VIFE/VIFE = FDh 97h 1Dh is used, then the two least significant bytes of error flag have the following meaning:





### **Table H.2 — Meaning of error bits in the least significant error byte (EF1)**







The meaning of the second least significant error byte is reserved for future extensions. Additional bytes may follow. The use of these following bytes is manufacturer specific.

If the meter detects an error and marks this condition in this data point it also has to set the related bit in the status byte. If the meter receives a command clearing one or several bits of this error flag then the related bits of the status byte have to be cleared too.

1 | 1 | increase power (one step)

## **H.2 VIF/VIFE/VIFE = FDh 9Fh 1Dh for passing remote control on a node**

If the data point VIF/VIFE/VIFE = FDh 9Fh 1Dh for a wireless M-Bus device is used the least significant byte of remote control has the following meaning:







### **Table H.5 — Remote control (RC1): adjust power**





### **Table H.7 — Remote control (RC1): power save mode**







The meaning of following bytes is reserved for future extensions.

## **H.3 Clock synchronisation**

Two additional CI-fields (6Ch and 6Dh) shall be used to set a new date/time, or to do an incremental time correction independent of the application layer used otherwise. Since these are essentially SND UD-type datagrams they shall be acknowledged by the meter with an ACK. They use the full long header that contains the application address of the slave (in addition to the partner address in the link layer). The commands should be encrypted to prevent unauthorised date/time changes in the meter. The last four 2Fh filler bytes should be used for additional command verification. The date and time uses data formats I and J as specified in Annex A. The TC-field is used for control timing actions and is specified as:

#### **Table H.9 — Structure of TC-field**



a) Set new date and time

### **Table H.10 — Application frame "time setting" with CI=6Ch (Set date and time)**



Under metrological aspects, this command is always considered as a clock reset by the slave.

b) Add/Subtract Time Offset

Add/Subtract Time Offset to the current slave time to either correct a slave clock drift or to correct a possible slave time error due to a communication delay of a previous set date/time command.





If this command is either received by the slave more than 60 s after the last command or the partner access number is different from the last command, then the add/subtract time command shall be executed, otherwise it is considered as a repetition of the last time correction command and shall be ignored.

The communication partner shall provide the correct time (UTC) for every bidirectional meter both periodically and on event. In the following cases, a clock synchronisation shall be applied:

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- once every day (as long as the partner has a valid time);
- when the partner gets back to the valid time;
- after the installation of a new meter; and
- after a communication interrupt for more than 24 h.

The time service of the communication partner is not an obligatory command. The change of the meter clock is in the responsibility of the meter itself and shall consider device type specific requirements as defined in dedicated standards and references. An example of clock synchronisation datagram is listed in Annex P.6.

## **Annex I**

## (normative)

## **Transmission of profiles**

## **I.1 The standard load profile**

When a meter generates a lot of periodical consumption values in one transmission it may be more efficient to transport a load profile instead of a list with pairs of consumption data and consumption value.

Example: load profile of consumption values for a water meter



### **Table I.1 — Example for load profile: plain data**

This load profile shall be transmitted as follows:





The first transmitted data points are the profile parameter count, data and interval. Thereafter follows the cumulated consumption value per interval starting from the storage number #8. The lower storage numbers remain reserved for single values like the current consumption or the consumption at the due day etc.

## **I.2 The M-Bus compact profile**

### **I.2.1 General**

The M-Bus compact profiles are used to transport a series of values with a fix space between each value. In addition to the compact profile, a base value and a base time is required to declare a start time and the value of the profile. Additional base parameters like the OBIS-declaration may be added as well. The base time is chained with the compact profile by using the same storage number in the DIF/DIFE. The base value and the base parameters are chained with the compact profile by using the same storage-, tariff- and subunit numbers in the DIF/DIFE of the data record. If one of these numbers differs from the compact profile, it has to be assumed that the base value or base parameters are missed.

### **I.2.2 The base value and base parameter**

The data point base value is the eldest value of the data series. It shall always exist unless the increment mode "Absolute value" (00b) is used. In the absence of the base value, the first entry in the profile is used as the first value of the data series instead. The base value and the base parameters may be used with any DIF/DIFE and VIF/VIFE.

#### **Table I.3 — Base value record (connected via storage-, tariff-, subunit number and VIF/ VIFEx)**



### **I.2.3 The base time**

The base time shall be encoded with one of the Types F to J (refer to Annex A). It corresponds to the base value, even if it does not exist. Therefore, the first entry in the compact profile is always related to the base time added by one space interval.

### **Table I.4 — Base time record (connected via the storage number)**



### **I.2.4 Structure of the compact profile**

The compact profile record itself starts (like each M-bus data point) with a DIF (DIFE) and a VIF (VIFE) but with an additional (new) orthogonal VIFE signalling a "compact profile".

The profile record uses a data structure with variable length (DIF= xDh) followed by a length byte with values between 3 and 191 (0BFh). The whole length is accumulated by two control bytes plus N\*(element length), where N is the number of elements of the profile. Consequently, the length of "2" signals an empty profile.





NOTE For the binary integers (low nibble of the DIF=1 to 4, 6 or 7) the incremental modes 01b and 10b use unsigned integers (data type C), whereas the increment modes 00b and 11b use signed integers (data type B). Refer to Annex A.

The first byte (spacing control byte) of this variable length record structure contains the data size of each individual element in the lower four bits (as in the lower nibble of the DIF definitions, but excluding variable length elements). The next higher two bits signal the time spacing units (00b = sec,  $01b = min$ ,  $10b = hours$  and  $11b = days$ ). The highest two bits signal the increment mode of the profile  $(00b = absolute$  value (signed),  $01b =$  positive (unsigned) increments,  $10b =$  negative (unsigned) increments, 11b = signed difference (deviation of last value – next value)). All values of the profile are initially preset with the coding for "illegal", e.g. -128 for signed byte, 255 for unsigned byte, -32768 for signed word etc. (refer to Annex A, type B and C). Invalid values shall also be used in case of an overflow of an incremental value.





#### **Table I.7 — Structure of spacing control byte**



After the space control byte follows the space value byte (single byte) giving the number of the time spacing units between the profile values. It allows between 1 and 250 time units (s,m,h,d) as time spacing. The values 251, 252 and 255 are reserved. To be able to additionally code monthly and halfmonthly profile spacing, the value 253 is used for half-monthly spacing and the value 254 is used for monthly spacing. Both are used together with the spacing unit "days/month". Spacing unit 0 is used to code a list of values which are not spaced in time. This could be any type of table with up to four columns.



by formular spacing unit +1 (e.g. spacing unit 01b indicates column 2).

#### **Table I.8 — Spacing value byte**

These first two fixed bytes are followed by the oldest value of the profile, the next oldest value etc., until the end of the variable length structure is reached. Note that if each profile value uses a DIF- data format with a length of more than one byte, each individual profile value is in the "least significant byte first" order.

## **I.2.5 Types of Compact profile**

The M-Bus supports two types of compact profiles:

- "Compact profile with registers" for the transport of a limited number of values with an assigned register number (e.g. recent value);
- "Compact profile without registers" for the transport of an unlimited number of values as a series with no assignment to a register (e.g. load profile).

The definition of both compact profile types is identical with an exception in the use of the storage number. The transmission of several profiles (e.g. for two tariffs) in parallel is possible, but it requires a different coding in the DIF/DIFE or the VIF/VIFE e.g. by the use of different tariff numbers. As long as the storage numbers are identical, all compact profiles are related to the same base time.

### **I.2.6 Compact profile with registers (orthogonal VIFE=1Eh)**

This compact profile has to be selected if the assignment of a historical value to a cumulation register is required.

The first requested register number is coded by the storage number, which is used for the base time, the base value and the compact profile. The first value inside the compact profile is related to the second requested register number, the second value to the third register and so on. To support up to 125 registers, a fix coding with a DIF and two DIFEs shall always be used.

A data series may also contain non-periodic entries, e.g. in the case of a changed device status. Such a case can be transmitted by chaining several profiles (see example).

Example: absolute profile of monthly consumption values (Tariff 1) of an electricity meter

Event	<b>OBIS-Code</b>	Date/Time	Value
Periodic value	$1.8.1*32$	01.01.2010 00:00	150 kWh
Periodic value	$1.8.1*33$	01.02.2010 00:00	100 kWh
Periodic value	$1.8.1*34$	01.03.2010 00:00	130 kWh
Non-periodic value	$1.8.1*35$	25.03.2010 13:12	90 kWh
Periodic value	$1.8.1*36$	01.04.2010 00:00	50 kWh
Periodic value	$1.8.1*37$	01.05.2010 00:00	160 kWh

**Table I.9 — Example of compact profile with registers: Plain data** 



### **Table I.10 — Example of compact profile with registers: M-Bus data records**

### **I.2.7 Compact profile without registers (orthogonal VIFE=1Fh)**

The compact profiles without registers shall start with the storage number #8. They may use a flexible number of DIF's and DIFE's. Chained compact profiles without registers use (unlike the compact profiles with registers) the next higher storage number. The use of the storage number #0 is not permitted for compact profiles without registers.

Example: incremental load profile; 3 hourly volume values after midnight coded with BCD.









## **Annex J**

(informative)

## **The structure of higher protocol layers**

This annex shows the frame structure of none, short and long header after CI-field:

### **Application layer without a fixed header (none)**

- The length of this header is limited to the one byte of CI-field.
- Applied in direction downwards to the meter with  $CI = 50h$ ; 51h; 52h.
- $-$  Applied in direction upwards from the meter with CI = 69h; 70h; 71h; 78h; 79h.

### **Table J.1 — Application layer without a fixed header (none)**



NOTE 1 This frame neither supports access number nor encryption.

### **Application layer with a short header**

- The length of the short header is 4 byte (without AES-Check).
- $-$  Applied in direction downwards to the meter with CI = 5Ah; 61h; 65h.
- Applied in direction upwards from the meter with CI = 6Ah; 6Eh; 74h; 7Ah; 7Bh; 7Dh; 7Fh.

### **Table J.2 — Application layer with a short header**



NOTE 2 The AES-Check is only available if encryption mode 5 is used.

### **Application layer with a long header**

- The length of the long header is 12 byte (without AES-Check).
- $-$  Applied in direction downwards to the meter with CI = 53h; 5Bh; 60h; 64h; 6Ch, 6Dh.
- $-$  Applied in direction upwards from the meter with CI = 6Bh; 6Fh; 72h; 73h; 75h; 7Ch; 7Eh.

### **Table J.3 — Application layer with a long header**



- NOTE 3 The long header is typically used if the meter address itself is not available in the link layer.
- NOTE 4 The AES-Check is only available if encryption mode 5 is used.

#### **Transport layer with a short header (no user data)**

- The length of the short header is 4 byte (encryption is not applied).
- $\implies$  Applied in direction upwards from the meter with CI = 8Ah.

#### **Table J.4 — Transport layer with a short header**



### **Transport layer with a long header (no user data)**

- The length of the long header is 12 byte (encryption is not applied).
- $\mu$  Applied in direction downwards to the meter with CI = 80h; 84h; 85h.
- $\implies$  Applied in direction upwards from the meter with CI = 8Bh.

#### **Table J.5 — Transport layer with a long header**



NOTE 5 The long header is typically used if the meter address itself is not available in the link layer.

#### **Explanation:**



## **Annex K**

(normative)

## **Compact M-Bus frame**

### **K.1 General**

Communication channels like radio are limited in capacity of data transfer. The new optional M-Bus-Compact frame provides an extension of the existing M-Bus Application protocol. It reduces size of transmitted data up to 40 %, by the separation of the Data Information Fields (DIF/DIFE) and Value Information Fields (VIF/VIFE) from the M-Bus-data. This is achieved by adding two additional fFrame types to the traditional full M-Bus frame

- M-Bus Compact frame (for the transmission of compact data)
- M-Bus Format frame (for the transmission of Data Information Fields and Value Information Fields)

The receiver of the M-Bus-Compact frame uses the stored DIF/VIF of an M-Bus-Format frame or full M-Bus frame in context with the values of the received M-Bus-Compact frame to generate an updated full M-Bus frame. The suitable M-Bus Format frame can be detected by the Format Signature transmitted in the M-Bus-Compact frame. The M-Bus-Compact frame shall be used only if the frame structure (order and coding of data points) remains unchanged for a certain time. If the frame structure changes, an M-Bus Format frame or a full M-Bus frame shall be transmitted repeatedly until the communication partner has reliably received it. The communication partner shall check if the stored M-Bus format frame is outdated by verifying the Full-Frame-CRC with every recovered full M-Bus frame. The original Full-Frame-CRC is transmitted inside the M-Bus compact frame. It is recommended to repeat the full M-Bus frame periodically even if the DIF/VIFs of the full M-Bus frame do not change. This provides a backward compatibility to communication partners that do not support compact M-Bus frames.

The use of the M-Bus-Compact or the M-Bus-Format frame is limited to wireless transmission based on [EN 13757-4](http://dx.doi.org/10.3403/30096182U).

NOTE The separation of the DIF/VIF (describing unit and resolution of consumption data) from measured values might be in contradiction with local regulations.

The partial encryption of messages can also be applied for the Compact and Format frame. Be aware that both the Full-Frame-CRC and the Format Signature are always located in the encrypted part of the message and will be not readable as long as the applied encryption key is unknown. In case of partial encryption, the first DIF of the unencrypted part of the message shall not be an idle filler 2Fh.

## **K.2 CI-fields of the Full and the Compact M-Bus frame**

The partner may request one of the available frame formats of the wireless meter by applying a special CI-field (see Table K.1) within the request of user data (REQ-UD2).



### **Table K.1 — CI-fields for the request of Full and Compact and Format M-Bus frame format**

The Full M-Bus frame shall be supported by each meter, which conforms to this European Standard. The support of the M-Bus Compact and the M-Bus Format frame is optional. If the meter does not support the requested frame format it shall response an application error instead (see Table 35).

For the response to a request or for an unsolicited transmission of the wireless meter it marks the applied frame format by a special CI-field too. Table K.2 shows the related CI-fields for the Full M-Bus frame as well as for the M-Bus-Compact and the M-Bus-Format frame with all variants of the application layer header. The content of the short and long header is listed in Annex J.

**Table K.2 — CI-fields for the full and Compact and Format M-Bus frame format** 

	No data-header	Short data-header	Long data-header
Full M-Bus frame	78h	7Ah	72h
M-Bus-Compact frame	79h	7Bh	73h
M-Bus-Format frame	69h	6Ah	6Bh

### **K.2.1 Full M-Bus frame**

### **Table K.3 — Structure of full M-Bus frame**



The Full M-Bus frame contains all Information of a full M-Bus frame. It can be used to derive an M-Bus Format frame including the Format Signature (refer to K.4). The Full M-Bus frame can be transmitted alternative to an M-Bus-Format frame. It provides full backward compatibility but it is even longer than an M-Bus Format frame.

### **K.2.2 M-Bus- Compact frame**





The M-Bus Compact frame contains only the data without any Data Information Fields or Value Information Fields. Immediately after the data header (if existing) follows a 2 byte Format-Signature for the detection of the related M-Bus Format frame and a 2 byte Full-Frame-CRC for the verification of the recovered full M-Bus frame. The M-Bus compact frame is intended to be transmitted frequently to update the communication partner with the current consumption data.

In case of block cipher encryption the remaining bytes of the last block in the M-Bus-Compact frame shall be filled with value 2Fh.

NOTE The data header contains the AES check bytes if applicable (refer to Annex J).

### **K.2.3 M-Bus-Format frame**





The M-Bus Format frame contains no data but Data Information Fields or Value Information Fields of the M-Bus frame. It shall be transmitted either in case of changed M-Bus format or periodically with a rare interval. The Format Signature shall be used as identifier to this format frame.

In case of block cipher encryption the remaining bytes of the last block in the M-Bus-Format frame shall be filled with the value 2Fh. These filler bytes are not included in the length field (LF).

The length field (LF) counts the number of bytes (including the Format Signature) before the idle filler, which were inserted by the block cipher of the format frame. The default value of the length field is zero. If no application layer encryption is applied, the length field remains unchanged.

- NOTE 1 The length field is in the responsibility of the encryption module.
- NOTE 2 The data header contains the AES check bytes if applicable (refer to Annex J).

## **K.3 Calculation of the Full-Frame-CRC**

The M-Bus-Compact frame contains a Full-Frame–CRC. The checksum shall be calculated over the full M-Bus-frame from the first byte of the application data to the end of the last data record (excluding data header, any AES check bytes in the header and link layer CRC).

The CRC polynomial is:  $x^{16} + x^{13} + x^{12} + x^{11} + x^{10} + x^{8} + x^{6} + x^{5} + x^{2} + 1$ 

The initial value is: 0

The final CRC is complemented

## **K.4 Calculation of the Format Signature**

The M-Bus Compact frame and the M-Bus Format frame contain a Format Signature. This is a CRC-Checksum. It shall be calculated only over the M-Bus-Format frame from the first DIF to the last VIF or DIF (excluding data header, any AES check bytes in the header, Format Signature, length field, any data bytes, encryption filler bytes in the end and link layer CRC). If the Format Signature is derived from a full M-Bus frame then an M-Bus Format frame has to be generated first.

The CRC polynomial is:  $x^{16} + x^{13} + x^{12} + x^{11} + x^{10} + x^8 + x^6 + x^5 + x^2 + 1$ 

The initial value is: 0

The final CRC is complemented

### **K.5 Frame examples**

#### **K.5.1 General**

The following different examples are given to show the relations between the three frame types: Full M-Bus frame, M-Bus Compact frame and M-Bus Format frame. The meter transmits the following three data sets:

- $\equiv$  Energy = 123,4 Wh;
- $-$  Volume = 567,8 m<sup>3;</sup> and
- $\frac{1}{2}$  Power = 901,2 W.

#### **K.5.2 Example without data header**

In this example, the frames use the CI-fields without data header. FOS refers to Format Signature, FFC refers to Full-Frame-CRC and LF refers to length field.

Full M-Bus frame  $(Cl = 78h)$ :

CI DIF VIF Data DIF VIF Data DIF VIF Data

78h 02h 02h D2h 04h 02h 15h 2Eh 16h 02h 2Ah 34h 23h

 $M-Bus-Format frame (Cl = 69h):$ 

CI LF FOS FOS DIF VIF DIF VIF DIF VIF

69h 008h FOS FOS 02h 02h 02h 15h 02h 2Ah

M-Bus-Compact frame (CI = 79h):

CI FOS FOS FFC FFC Data Data Data

79h FOS FOS FFC FFC D2h 04h 2Eh 16h 34h 23h

#### **K.5.3 Example with short data header, no encryption**

In this example, the frames use the CI-fields with short data header but no encryption is used. FOS refers to Format Signature, FFS refers to Full-Frame-CRC and LF refers to length field.

Full M-Bus frame  $(Cl = 7Ah)$ :

CI ACC STS ConfFLD DIF VIF Data DIF VIF Data DIF VIF Data

7Ah 01h 00h 00h 00h 02h 02h D2h 04h 02h 15h 2Eh 16h 02h 2Ah 34h 23h

 $M-Bus-Format frame (Cl = 6Ah):$ 

CI ACC STS ConfFLD LF FOS FOS DIF VIF DIF VIF DIF VIF

6Ah 01h 00h 00h 00h 008h FOS FOS 02h 02h 02h 15h 02h 2Ah

M-Bus-Compact frame (CI = 7Bh):

CI ACC STS ConfFLD FOS FOS FFC FFC Data Data Data

7Bh 01h 00h 00h 00h FOS FOS FFC FFC D2h 04h 2Eh 16h 34h 23h

#### **K.5.4 Example with short data header, encryption mode 5**

In this example, the frames use the CI-fields with short data header with the use of encryption mode 5. FOS refers to Format Signature, FFS refers to Full-Frame-CRC and LF refers to length field. The fields included in brackets [ ] show the block to be encrypted using encryption mode 5. This example further shows how partial encrypted frames are handled in M-Bus-Format frames and M-Bus-Compact frames.

Full M-Bus frame  $(Cl = 7Ah)$ :

CI ACC STS ConfFLD AES-CHK DIF VIF Data DIF VIF Data ...

7Ah 01h 00h 10h 05h[2Fh 2Fh 02h 02h D2h 04h 02h 15h 2Eh 16h ...

Filler DIF 111 DIF VIF Data

2Fh 2Fh 2Fh 2Fh 2Fh 2Fh]02h 2Ah 34h 23h

 $M-Bus-Format frame (Cl = 6Ah):$ 

CI ACC STS ConfFLD AES-CHK LF FOS FOS DIF VIF DIF VIF DIF ...

6Ah 01h 00h 10h 05h[2Fh 2Fh 0Ch FOS FOS 02h 02h 02h 15h 2Fh ...

DIF DIF DIF DIF DIF Filler DIF DIF VIF

2Fh 2Fh 2Fh 2Fh 2Fh 2Fh] 02h 2Ah

#### M-Bus-Compact frame (CI = 7Bh):

CI ACC STS ConfFLD AES-CHK FOS FOS FFC FFC Data Data ...

7Bh 01h 00h 10h 05h[2Fh 2Fh FOS FOS FFC FFC D2h 04h 2Eh 16h ...

Filler DIF Data

2Fh 2Fh 2Fh 2Fh 2Fh 2Fh]34h 23h

As shown in the example above, the filler bytes of the Full M-Bus frame are included in the M-Busformat frame. This makes it possible to reconstruct the original Full M-Bus frame including filler bytes and partial encrypted frames.

## **Annex L**

## (informative)

## **Use of standards for smart metering applications**

## **L.1 General**

If this informative Annex is applied, all requirements of Annex L shall be fulfilled.

This annex shows the preferred methods of using the standards [EN 13757-2](http://dx.doi.org/10.3403/03164534U), EN [13757-3](http://dx.doi.org/10.3403/03164728U), EN [13757-4](http://dx.doi.org/10.3403/30096182U) and [EN 13757-5](http://dx.doi.org/10.3403/30160774U) for implementing the required functionalities of smart metering applications as suggested by the Smart Meter Coordination Group (SMCG) of CEN, CENELEC and ETSI. For twisted pair connection of meters the physical and link layer of EN13757-2 is suggested. For wireless connection, the physical and link layer of EN [13757-4](http://dx.doi.org/10.3403/30096182U) is suggested. For wireless communication, it is distinguished between "meters" and "communication partner". Such a communication partner might be a dedicated receiver, an apartment oriented display, a concentrator, a multi-utility server for several media or another (possibly electricity) meter. In any case, the partners are located in fixed locations and are usually mains powered.

## **L.2 Data integrity**

All data integrity is based on the European Standards of [EN 60870-5-1](http://dx.doi.org/10.3403/00375625U).

For twisted pair connection, [EN 13757-2](http://dx.doi.org/10.3403/03164534U) ensures integrity class I2.

For wireless communication [EN 13757-4](http://dx.doi.org/10.3403/30096182U) ensures integrity class I3. This is required for the possibly extremely noisy wireless communication channel.

## **L.3 Privacy**

For data privacy it is required to use the (symmetrical) AES-128 encryption for all messages carrying consumer data. Each meter shall be given an individual encryption key at the time of manufacture. Since each meter shall also have a unique identification number, this pair of numbers shall be safely transferred to the customer of the meter (often the utility). The safe distribution of this meter associated pair of numbers to other participants of smart metering is then the task of this primary customer.

NOTE The aim of this encryption is only privacy (not signature or authentication). The communication partner(s) of such a meter communication can decode the encryption if he (or they) have a copy of the encryption key of each of the meters associated with him and then recode it with other encryption techniques or with other encryption keys.

## **L.4 Signature**

Mainly for possible legal requirements, it has been suggested that meter messages whose data are used for billing might require a legally safe signature.

NOTE According to the European Cooperation in Legal Metrology (WELMEC), even if a signature is used in doubt still the value visible at the meters display has priority. Thus, the use of signed values does currently not improve the legal situation of the billing. No strict legal requirements for the use of only signed values for billing purposes are known.

## **L.5 Authentication**

If some external device wants to send critical commands to the meter such a command might require a safe authentication. As far as no metering critical data or commands are transmitted, a symmetrical key might be sufficient, if the key is unique to the meter and if the key can be safely transmitted (i.e. not over an open wireless link) between the partners. This is a typical situation for a remotely controlled valve, which is installed by a net operator who receives the key associated with a given valve via a safe communication channel from the valve manufacturer.

## **L.6 Billing**

For billing purposes, the required values and transmit intervals (for unidirectional wireless communication in push-mode) or wakeup/receive time intervals (for bidirectional wireless communication) are a question of the standards for the meter devices. For offline tariffing, especially for unidirectional transmitting meters, a higher readout frequency is required.

To support battery operated repeater, the transmission timing of the radio device shall be as for synchronised meters, conforming to EN [13757-4](http://dx.doi.org/10.3403/30096182U).

## **L.7 Consumer feedback**

### **L.7.1 Introduction**

For a consumer feedback both about the meter index (or accumulated cost) and the instantaneous power or flow rate, a more frequent transmission of such values (than required for billing) might be necessary. In addition, it is distinguished between the case where the meter itself generates and transmits the instantaneous power/flow rate values and the case where the consumer display or some other device will generate these instantaneous values from index differences and time differences. In the last case, the index values need a sufficient resolution (usually much higher than useful for billing). If the index value can be generated internally synchronously with the wireless transmit time points the receiving device can calculate the required time difference with sufficient accuracy and resolution. Even in the case of a fixed delay between value generation and transmission there will be no problem. Also if the time difference is sufficiently small (i.e. less than 1 s or 1 % of the transmit interval) there would be no problem. In the remaining cases (longer or variable delay), a meter (usable for consumer feedback of instantaneous values) shall include a record with the time delay in its message.

The following paragraphs demonstrate possible definitions in future meter standards: As long as meter standards do not provide requirements for the different situations in a meter the following requirements shall be used. If the applicable meter standard contains different requirements for one or several parameters, the meter standard shall have priority.

### **L.7.2 Required values and their resolution and accuracy**

### **L.7.2.1 General**

Each message for billing purposes shall at least contain the current metered value with the meter accuracy and sufficient resolution for billing. Each message for consumer information shall contain sufficient information and accuracy to enable the consumer unit to display the power/flow with sufficient accuracy and resolution. This can either be implemented via extra data points for flow/power or by sufficient resolution of the meter index and sufficient information about the time between indexed values. Unified messages for both purposes may be used if both requirements are met.

### **L.7.2.2 Required resolution if an extra data point for flow/power) is transmitted.**

The required value resolutions for meter with additional data points for flow/power are:

<b>Medium</b>	<b>Billing</b>	<b>Power/flow</b> resolution
Electricity	$\leq$ 1 kWh	$\leq 1 W$
Water	$\leq 1 \text{ m}^3$	No requirement
Gas QMax $\leq 6$ m <sup>3</sup> /h	$\leq 1 \text{ m}^3$	≤ 10 l/h
Gas QMax $\leq 60$ m <sup>3</sup> /h	$\leq 1 \text{ m}^3$	≤ 100 l/h
Gas $OMax > 60$ m <sup>3</sup> /h	$\leq 1 \text{ m}^3$	≤ 1000 l/h
Heat / Cold $Qp < 10$ m <sup>3</sup> /h	$\leq$ 1 kWh	No requirement
Heat / Cold $Qp < 100$ m <sup>3</sup> /h	$\leq 10$ kWh	No requirement
Heat / Cold $Qp \ge 100$ m <sup>3</sup> /h	$\leq 100$ kWh	No requirement
Heat cost allocation	No requirement	No requirement

**Table L.1 — Required value resolution for meter with power/flow data**

It is recommended that the averaging duration for power/flow values is similar to the average update interval (mean time between two transmissions of messages with updated consumption data). A shorter averaging period might produce strongly variant snapshot values with little user information (especially for gas and water meters with a typically strongly fluctuating flow), a longer averaging period will produce only time delayed display values. If the meters averaging duration is below 50 % or above 200 % of the average update interval the meter documentation shall point this out.

### **L.7.3 Required resolution if no extra data point for flow (respectively power) is transmitted.**

### **L.7.3.1 General**

If the meter transmits only index values, the consumer unit shall be able to calculate the flow respectively power with sufficient resolution and accuracy from the index value and the time interval between the index values. This requires the following index resolutions.



### **Table L.2 — Required value resolution without power/flow data**

### **L.7.3.2 Required time information**

In addition, if there is no power/flow information present there are requirements for the accuracy and resolution of the current time difference between the index values to ensure a time interval accuracy and resolution of ≤ 1 %. These requirements can be fulfilled by one of the following alternatives.

#### **L.7.3.3 Correlated transmission**

If the meter spontaneously transmits the index value with a fixed delay of less than half the transmission interval and if such a delay varies by less than 1 % of the transmission interval then the consumer unit can calculate the index time difference from the message arrival times with sufficient resolution and accuracy.

### **L.7.3.4 Uncorrelated transmission**

If the difference of delays of transmission time points varies by more than 1 % of the transmission interval, each message shall contain sufficient time information to calculate this time difference. This can either be implemented with a (date)/time data point with a resolution of 1 s in each message or with a data point signalling the current time delay between index time and transmit time with a resolution of 1 s.

### **L.7.4 Transmission on request**

If the meter transmits the index value due to a request it has to refer to the time of the value generation at the moment of the first transmission of the request (REQ\_UD2) by the consumer unit. The meter may generate the response with a fixed delay, which shall not vary by more than 1 s. A potential runtime of the request from the consumer unit to the meter shall be considered. Hence, a unique reference time is given even when the response is repeated several times.

### **L.8 Advanced tariffing and prepayment**

### **L.8.1 General**

In contrast to electricity, almost all media (gas, heat and water) can be stored or at least buffered. This reduces the attractiveness and possible generation of savings via time or load dependent tariffs. For the cases where multi-tariffing is still required the field tariff in the DIF record descriptor provides the option to associate any type of value (i. e. any VIF) with a tariff index. Considering the options of DIF

extension an almost unlimited number of tariffs can be implemented. The VIFs for management of tariff time windows (period, start, duration) allow flexible definition of multiple tariffs. The association with of a tariff with a tariff number is flexible. In addition, the use of separate registers for each flow direction is supported via a suitable orthogonal VIF. A detailed logging of error and limit exceeds and the registration of maxima/minima and registration during some error state is also supported.

### **L.8.2 Prepayment**

The addition of currency units to the VIF table allows the support of prepayment functions. A prepayment value can be read, written, added or subtracted. For security aspects such commands may require authentication. A simple symmetrical encryption method can be used for this if there is a safe key transport between the meter and the prepayment authority is implemented. A separate key for prepayment functions is suggested. Other prepayment functionalities might be implemented using existing DIF/VIF combinations or other may be added if detailed requirements from the device side are available.

## **Annex M**

(informative)

## **Installation and registration**

### **M.1 General**

The way to equip a building with new meters or exchange existing ones differs significantly depending on the history and the working process of the meter site operator. This standard intends to support different installation processes. The answers to the following questions decide on the installation procedure.

- Who defines the pairing of the meter and the gateway?
- Is an online connection to the back office of the Meter Site Operator necessary or possible?
- $-$  Is a fast feedback after the installation to the local service technician required?

To readout a meter, the operator needs the address of the meter and the communication address of the meter site, e.g. IP-Address of the host gateway. The operator has to register all gateways as well as all meter addresses and their host gateway. The pairing of a meter and a gateway or another partner device may be done

- a) either automatically (no predefinition),
- b) predefined by the operator,
- c) or predefined by the [service](http://pda.leo.org/ende?lp=ende&p=5tY9AA&search=service) [technician.](http://pda.leo.org/ende?lp=ende&p=5tY9AA&search=technician)

Solution a) requires an online connection to the Meter Site Operator to assign a detected meter during or after the installation to one of the partner devices in range.

Solution b) loads meter parameters into the partner device before the installation. This can be done via online connection or already be preconfigured in the partner device before its installation.

Solution c) does not need an online connection. The service technician assigns the meter to the partner device directly on site.

Besides the pairing of the meter and the partner device, the related keys for encryption and/or authentication have to be allocated to the concerning partner device.

The assignment procedure may be independent of the communication type like uni- or bidirectional communication or the selected communication mode. But in small details differences may exist. The assignment of a meter with exactly one communication partner is always required for bidirectional wireless meters, at least for transmitting information or commands to a meter. For a unidirectional transmitting meter, it is not required to have only one single communication partner. In fact, it could be helpful for a wireless diversity to register the meter in each communication partner which is able to receive this meter. Otherwise, a bidirectional meter allows the test of the operational reliability of the communication link or encryption key immediately after the registration.

For some pairing methods, additional meter functionality is required. This optional functionality is described below.

## **M.2 Registration with meter support**

### **M.2.1 Introduction**

Some meters support the functionality of installation messages (« SND-IR »). These messages can be manually initiated only either by a push button (or similar event) or via a command communicated by some mobile service device to the meter. Thereafter the meter sends several installation messages in short intervals. For structure and timing of these messages, refer to EN [13757-4](http://dx.doi.org/10.3403/30096182U). The receiving partner device takes these installation messages as a request for registration. The reaction of the partner device depends on whether it was enabled for the registration of new meters (Registration Mode). The Registration Mode has to be set before the meter installation by a service technician. If the Registration Mode was enabled and an installation message was received, the partner device registers the new device and responds a Registration Feedback. Independent of the Registration Mode, the partner device has always to respond an RF-Link Feedback after the reception of an installation message.

The "registration with meter support" does not require an online link to the meter site operator during the installation phase and provides a feedback to the service technician immediately after the meter installation.

## **M.2.2 RF-Link feedback**

Every communication partner device which receives installation messages (« SND-IR ») from a meter shall respond to such messages by emitting a « SND\_NKE »-datagram which contains the meter's link address and the partner's unique ID. For complete structure and timing of these messages, see EN [13757-4](http://dx.doi.org/10.3403/30096182U). This message is not intended for the meter but for reception via an optional mobile service receiver. For that reason, the link feedback is transmitted outside of the usually very limited reception timeslot of the bidirectional battery driven meter. Such an RF-link feedback message may also contain the RF reception level for this meter. The mobile reception tool is able to display and/or store the meter link address and the reception level (if available) for each meter, whose partner device could establish a radio link with the meter. A possible missing answer signals to the installer that another communication partner or some repeater has to be installed. This can then be done immediately. Hence, the service technician leaves the building, no second access is necessary.

### **M.2.3 Registration feedback**

For a direct (i.e.) offline registration of a meter without the assistance of the Meter Site Operator the concerning partner shall be set for a limited time into the Registration Mode. The installer shall insure that only one communication partner within the maximum communication distance of the meter is set simultaneously into such a Registration Mode. In this case, these registration confirmation messages (« CNF-IR ») are transmitted in the small dedicated reception windows of bidirectional meters to give a registration confirmation to the meter, so it may stop transmitting installation messages. For a complete structure and timing of these messages, see EN [13757-4.](http://dx.doi.org/10.3403/30096182U) These registration confirmation messages might also be received by some mobile installation support receiver and further signalled to the installer and stored there. Further actions can be controlled remotely.

## **M.3 Registration without meter support**

To reduce the meter requirements and the service actions of the installer, the support of installation messages may not be provided by all meters. Meters for such a remote based registration start transmitting directly after the mechanical installation or even transmit always. No special functionality of the meter for registration is required. If a possible communication partner receives meter messages from a meter so far unknown it enters the meter-ID together with the reception time in a special list. The back office of the Meter Site Operator may be notified via push mode or it might be queried occasionally. There may be special rules for a backbone meter installation process (either for any newly detected meters or for predefined meters only). The back office of the Meter Site Operator may assign (register) such a meter to a single communication partner. If the Meter Site Operator already knows the meter ID, it also knows the associated meter encryption key, which (if required) might then be downloaded to this communication partner or to another system component where decryption is required. This key download requires a high-level privacy link, which is often possible in the private or public networks for such system level communication which is outside the scope of this standard. The advantage of this method without meter support is, besides speed and simplicity of the installation process, the flexibility to add or change communication partner(s) without requiring access to the meter which might be located within an apartment. Another advantage is that both installation sequences (meter first or partner first) can be realised. This method is therefore often used when the communication partner is located outside the apartments, e.g. for partners communicating with meters of several apartments. The drawback of this method is the missing feedback to the service technician at installation time about the existence and the quality of the wireless link.

This method may also be applied for meters which actually support installation messages, e.g. when the communication partner was replaced or updated.

# **Annex N**

## (informative)

## **M-Bus data container**

### **N.1 Explanation**

The M-Bus data container is used to pack a full wireless M-Bus frame into a wired M-Bus message. It comes into action for instance in a radio to M-Bus adapter. This is a device which receives frames in any format and provides the data on a wired M-Bus interface.

The benefit of this method is that the original radio frame can be passed through to the communication end points. So any functionality (i.e. data decryption) is easily possible and can be done in a common way.

## **N.2 Definition**

The M-Bus data container is defined as an independent data record and can be positioned anywhere inside the M-Bus variable data block.



#### **Table N.1 — Structure of data record**

The Data Information Field (DIF) is always 0Dh, which shows the variable length of the record. The Value Information Field (VIF) is FDh with a specific VIFE for protocol definition. The length is coded as  $LVAR = 00h - BFh$ .

Two possibilities are defined:

- 3Bh used for wireless M-Bus protocol;
- 76h used for manufacturer specific protocol.

These are enhancements of Table 28 and are called respectively "Data container for wireless M-Bus protocol" and "Data container for manufacturer specific protocol". The LVAR byte, which is advertised with DIF 0Dh, shows in this case the number of bytes inside the data container and shall not be interpreted as an 8-bit text string.

For the wireless M-bus protocol (VIFE 3Bh), the data block contains the original radio frame starting with the L and the C field as stated in the EN [13757-4](http://dx.doi.org/10.3403/30096182U). The CRC blocks of the radio frame are not included in the wireless M-Bus data container.

For the manufacturer specific protocol (VIFE 76h), the content of the data block is not predefined and can be used complying to manufacturers requests.

The maximum length of a wired M-Bus datagram is limited. Therefore, the possibility to split the radio frame in two or more parts is given. In this case, the DIF 1Fh shall be used at the end of the variable

data block. It shows more bytes are transferred in the next datagram. With a toggled FCB of the C field this can be verified.

## **N.3 Example**

Wired M-Bus communication between a master and a radio to M-Bus adapter

SA = ID of the radio device; Fa = ID of the radio to M-Bus adapter

#### **Slave select from master**

68 11 11 68 73/53 FD 52 SA0 SA1 SA2 SA3 Man0 Man1 Ver Med 0C 78 Fa0 Fa1 Fa2 Fa3 Ch 16

#### **Answer**

E5

#### **Request (REQ-UD2) from master**

10 7B/5B FD ChS 16

#### **Answer (RSP-UD) from radio to M-Bus adapter**

68 LL LL 68 08 FD 72 SAd0 SAd1 SAd2 SAd3 Man0 Man1 Ver Med



0D FD 3B 57 **56 44 Man0 Man1 SAd0 SAd1 SAd2 SAd3 Gen Med 7A 34 00 40 05 F7 9F C4 79 E7 16 8F F2 82 BF 4D 4F 41 28 ... B9 17 E7** CS 16

## **Annex O**

## (normative)

## **Translating M-Bus type record descriptors to OBIS-type record descriptors**

The following tables are declared to be normative in the sense that if a translation from VIF/DIF values to OBIS codes is necessary, exactly that translation given in the table must be used. It is not meant that VIF/DIF values must be used under any circumstances, as OBIS codes can also be transmitted as such.

## **O.1 Translation of predefined data record types**

This list describes how a communication partner can "translate" received M-Bus record into OBIS type records.

The B-Field of the OBIS Code shall be build from the subunit in related DIFE of data point (refer to chapter 6.10). If the meter uses one channel only then the subunit and also the B-Field of the OBIS Code is 0 (as listed in this table). If a meter uses more than one channel then the subunit and also B-Field of OBIS Code 5 is declared channel number which starts with 1.



#### **Table O.1 — M-Bus-OBIS-Translation: legend**







## **Table O.3 — M-Bus-OBIS-Translation: electricity meter**

## **Table O.3** *(continued)*





## **Table O.4 — M-Bus-OBIS-Translation: heat cost allocator**



## **Table O.5 — M-Bus-OBIS-Translation: cooling meter**

## **Table O.5** *(continued)*


	<b>Type</b>	<b>OBIS-Code</b>	<b>Description</b>	DIF/DIFE or fixed fields [binary]	<b>VIF/VIFE</b> [binary]
	Cooling	5	$ODh$ (cooling) (see Table 6)	(Combined heat/cooling)	
M	Meter count	5-0:1.0.0*255	Energy (A), total, current value		
	Ξ.	<b>kWh</b>	$10e-610e+1$	1000 cccc 0001 0000	0000 0nnn
		<b>kWh</b>	$10e + 2$ $10e + 3$	1000 cccc 0001 0000	1111 1011 0000 000n
		kWh	$10e+510e+6$	1000 cccc 0001 0000	1111 1011 1000 000n 0111 1101
		kWh	10e-6  10e+1	0000 cccc	1000 0nnn 0011 1100
		kWh	$10e+210e+3$	0000 cccc	1111 1011 1000 000n 0011 1100
		<b>kWh</b>	$10e+510e+6$	0000 cccc	1111 1011 1000 000n 1111 1101 0011 1100
		GJ	10e-9  10e-2	1000 cccc 0001 0000	0000 1nnn
		GJ	10e-1  10e+0	1000 cccc 0001 0000	1111 1011 0000 100n
		GJ	$10e+210e+3$	1000 cccc 0001 0000	1111 1011 1000 100n 0111 1101
		GJ	10e-9  10e-2	0000 cccc	1000 1nnn 0011 1100
		GJ	10e-1  10e+0	0000 cccc	1111 1011 1000 100n 0011 1100
		GJ	$10e + 2$ $10e + 3$	0000 cccc	1111 1011 1000 100n 1111 1101 0011 1100
$\circ$	Meter count	5-0:1.2.0*255	Energy (A), total, set date value		
	<u>.</u>	<b>kWh</b>	10e-6  10e+1	1100 cccc 0001 0000	0000 0nnn
		kWh	$10e + 2$ $10e + 3$	1100 cccc 0001 0000	1111 1011 0000 000n
	-	kWh	$10e+510e+6$	1100 cccc 0001 0000	1111 1011 1000 000n 0111 1101
		kWh	$10e-610e+1$	0100 cccc	1000 0nnn 0011 1100
		kWh	$10e + 2$ $10e + 3$	0100 cccc	1111 1011 1000 000n 0011 1100
		kWh	10e+5  10e+6	0100 cccc	1111 1011 1000 000n 1111 1101 0011 1100
		GJ	10e-9  10e-2	1100 cccc 0001 0000	0000 1nnn

**Table O.6 — M-Bus-OBIS-Translation: combined heat and cooling meter**

### **Table O.6** *(continued)*



This table consists of the cooling meter counts of combined heat/cooling meters (Device Type = 0Dh). Refer to heat meter for heat meter counts.



### **Table O.7 — M-Bus-OBIS-Translation: heat meter**

## **Table O.7** *(continued)*



	<b>Type</b>	<b>OBIS-Code</b>	<b>Description</b>	DIF/DIFE or fixed fields [binary]	<b>VIF/VIFE</b> [binary]	
	Gas	$\overline{7}$	$03h$ (see Table 6)	$\sim$		
A1	Meter count	7-0:3.0.0*255	Volume (meter), metering conditions $(V_m)$ , forward, absolute, current value			
		m <sup>3</sup>	$10e-6$ $10e+1$	0000 cccc	1001 0nnn 0011 1010	
		m <sup>3</sup>	$10e-3$ $10e+4$	0000 cccc	1001 0nnn 1111 1101 0011 1010	
A1	Meter count	7-0:3.1.0*255		Volume (meter), temperature converted $(V_{tc})$ , forward, absolute, current value		
		m <sup>3</sup>	$10e-6$ $10e+1$	0000 cccc	0001 0nnn	
		m <sup>3</sup>	$10e-3$ $10e+4$	0000 cccc	1001 0nnn 0111 1101	
A <sub>1</sub>	Meter count	7-0:3.2.0*255		Volume (meter), base conditions $(Vb)$ , forward, absolute, current value		
		m <sup>3</sup>	$10e-6$ $10e+1$	0000 cccc	1001 0nnn 0011 1110	
		m <sup>3</sup>	$10e-3$ $10e+4$	0000 cccc	1001 0nnn 1111 1101 0011 1110	
$\circ$	Meter count	7-0:3.0.0*VZ		Volume (meter), metering conditions $(V_m)$ , forward, absolute, recent value		
		m <sup>3</sup>	$10e-6$ $10e+1$	1x00 cccc 1000 xxxx 0000 00xx	1001 0nnn 0011 1010	
		m <sup>3</sup>	$10e-3$ $10e+4$	1x00 cccc 1000 xxxx 0000 00xx	1001 0nnn 1111 1101 0011 1010	
$\circ$	Meter count	7-0:3.1.0*VZ		Volume (meter), temperature converted $(Vtc)$ , forward, absolute, recent value		
		m <sup>3</sup>	$10e-6$ $10e+1$	1x00 cccc 1000 xxxx 0000 00xx	0001 0nnn	
		m <sup>3</sup>	$10e-3$ $10e+4$	1x00 cccc 1000 xxxx 0000 00xx	1001 0nnn 0111 1101	
$\circ$	Meter count	7-0:3.2.0*VZ		Volume (meter), base conditions $(Vb)$ , forward, absolute, recent value		
		m <sup>3</sup>	$10e-6$ $10e+1$	1x00 cccc 1000 xxxx 0000 00xx	1001 0nnn 0011 1110	
		m <sup>3</sup>	$10e-310e+4$	1x00 cccc 1000 xxxx 0000 00xx	1001 0nnn 1111 1101 0011 1110	
$\circ$	Flow rate	7-0:43.15.0*255	Flow rate at metering conditions, averaging period 1 (default period = 5 min), current interval $(V_m/t_l)$			
		m <sup>3</sup> /h	$10e-6$ $10e+1$	0000 cccc	1011 1nnn 0011 1010	

**Table O.8 — M-Bus-OBIS-Translation: gas meter**

## **Table O.8** *(continued)*





## **Table O.9 — M-Bus-OBIS-Translation: water meter (cold)**



## **Table O.10 — M-Bus-OBIS-Translation: water meter (hot, warm)**

### **O.2 Online addition of an entry for the M-Bus to OBIS conversion table**

When a meter uses an M-Bus data point, which is not declared in O.1 "M-Bus-OBIS Conversion table" in this European standard and which is required for billing, then it should assign the suggested concerning OBIScode for this data point as static data by this special data point. This OBIS-declaration should be sent as static data (refer to Table 15).

The OBIS-declaration uses the original DIF/VIF-combination of the declared M-Bus-data point added by the orthogonal VIFE "OBIS-declaration" (3Fh so far reserved). The value of this new data point consists of the assigned OBIS-code. The OBIS-code may be coded as BCD or binary value. In the low nibble of the original DIF (bold marked) is the content replaced by length and coding of OBIS-code. The binary value for the OBIScode is always unsigned. Use "binary" if recent value (OBIS-F)>99.

**EXAMPLE** max. flow rate of a water meter

A water meter supports a maximum flow rate value e.g. 0,123 m<sup>3</sup>/h. The M-Bus data point for max. flow rate is coded as e. g.:

- 1**A**h DIF; maximum value; 4 digits BCD
- 3Bh  $VIF$ ; Flow rate with unit 10<sup>-3</sup> m<sup>3</sup>/h
- 23h 01h Value 123

The relevant OBIS-declaration 8-0:2.5.0\*255 will be transmitted either binary or with BCD-numbers.

#### *BCD-coding:*

The relevant OBIS-Declaration will be transmitted as 12 digits BCD by:



NOTE The BCD Value "AA" in OBIS-field "F" signals an invalid value (refer to Annex A). This corresponds to a recent value of 255.

#### *Binary coding:*

Alternatively, the relevant OBIS-declaration will be transmitted, e.g. as 48-bit binary by:



# **Annex P**

## (informative)

# **Datagram examples for the M-Bus and the wM-Bus**

### **P.1 Gas meter**

# **Gas meter example**



#### **AES key according to FIPS 197 (LSB first):**

= Manu. spec. at least 8 bytes unique for each meter = 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F 11

#### **AES CBC initial vector according to FIPS 197 (LSB first):**

= M Field + A Field + 8 bytes Access No

= 93 15 78 56 34 12 33 03 2A 2A 2A 2A 2A 2A 2A 2A



### **Table P.1 — SND-NR - Gas meter (wM-Bus)**





SND_NR (wM-Bus)					
		wM-Bus frame	Gas meter example		
<b>Byte No</b>	<b>Field Name</b>	<b>Content</b>	<b>Bytes</b> [hex] plain	<b>Bytes</b> [hex] <b>AES</b> coded	
39	<b>Dummy</b>	Fill Byte due to AES	2Fh	52h	
40	<b>Dummy</b>	Fill Byte due to AES	2Fh	0Eh	
41	<b>Dummy</b>	Fill Byte due to AES	2Fh	<b>DFh</b>	
42	<b>Dummy</b>	Fill Byte due to AES	2Fh	F <sub>0</sub> h	
43	<b>Dummy</b>	Fill Byte due to AES	2Fh	EAh	
44	<b>Dummy</b>	Fill Byte due to AES	2Fh	6Dh	
45	<b>Dummy</b>	Fill Byte due to AES	2Fh	<b>EFh</b>	
46	<b>Dummy</b>	Fill Byte due to AES	2Fh	C <sub>9</sub> h	
47	CRC <sub>3</sub>		E <sub>1</sub> h	55h	山
48	CRC <sub>3</sub>		B <sub>3</sub> h	B <sub>2</sub> h	
49	<b>Dummy</b>	Fill Byte due to AES	2Fh	9 <sub>Dh</sub>	
50	<b>Dummy</b>	Fill Byte due to AES	2Fh	6Dh	
51	<b>Dummy</b>	Fill Byte due to AES	2Fh	69h	
52	<b>Dummy</b>	Fill Byte due to AES	2Fh	<b>EBh</b>	
53	<b>Dummy</b>	Fill Byte due to AES	2Fh	F <sub>3h</sub>	
54	CRC <sub>4</sub>		25h	<b>ECh</b>	
55	CRC <sub>4</sub>		EEh	8Ah	님

**Table P.1** *(continued)*



### **Table P.2 — RSP-UD - Gas meter (M-Bus)**

## **Table P.2** *(continued)*



### **P.2 Water meter**



#### **AES key according to FIPS 197 (LSB first):**

= Manu. spec. at least 8 bytes unique for each meter = 82 B0 55 11 91 F5 1D 66 EF CD AB 89 67 45 23 01

#### **AES CBC initial vector according to FIPS 197 (LSB first):**

 $=$  M Field + A Field + 8 bytes Access No = 24 23 44 22 75 92 29 07 1F 1F 1F 1F 1F 1F 1F 1F

### **Table P.3 — SND-NR - Water meter (wM-Bus)**



## **Table P.3** *(continued)*





## **Table P.3** *(continued)*



### **Table P.4 — RSP-UD - Water meter (M-Bus)**

RSP_UD (M-Bus)					
		<b>M-Bus frame</b>	Water meter example		
<b>Byte No</b>	<b>Field name</b>	<b>Content</b>	<b>Bytes [hex] plain</b>		
31	DR <sub>3</sub>	DIF (8 digit BCD, Storage No 1)	4Ch		
32	DR <sub>3</sub>	VIF (Volume liter)	13h		
33	DR <sub>3</sub>	<b>Value LSB</b>	19h		
34	DR <sub>3</sub>	Value $( = 1445419)$	54h		
35	DR <sub>3</sub>	Value	44h		
36	DR <sub>3</sub>	<b>Value MSB</b>	01h		
37	DR <sub>4</sub>	DIF (Data type G, Storage No 1)	42h		
38	DR <sub>4</sub>	VIF (Date)	6Ch		
39	DR <sub>4</sub>	<b>Value LSB</b>	<b>FFh</b>		
40	DR <sub>4</sub>	Value MSB (= 31.12.2007)	0Ch		
41	DR <sub>5</sub>	DIF (2 byte integer)	02h		
42	DR <sub>5</sub>	VIF (FD-Table)	<b>FDh</b>		
43	DR <sub>5</sub>	VIFE (error flag)	17 <sub>h</sub>		
44	DR <sub>5</sub>	<b>Value LSB</b>	00h		
45	DR <sub>5</sub>	Value MSB $( = 0)$	00h		
46	Checksum		99h		
47	<b>Stop</b>	Stop byte	<b>16h</b>	금	

**Table P.4** *(continued)*

### **P.3 Heat meter**



#### **AES key according to FIPS 197 (LSB first):**

= Manu. spec. at least 8 bytes unique for each meter = D3 51 D9 0E 58 C8 E8 C8 EF CD AB 89 67 45 23 01

#### **AES CBC initial vector according to FIPS 197 (LSB first):**

 $=$  M Field + A Field + 8 bytes Access No

= 24 23 78 56 34 12 2A 04 26 26 26 26 26 26 26 26



#### **Table P.5 — SND-NR - Heat meter (wM-Bus)**

## **Table P.5** *(continued)*



## **SND\_NR (wM-Bus) wM-Bus frame Heat meter example Bytes [hex] Byte No** Field name Content **Bytes** [hex] **plain AES coded** DR5 DIF (6 digit BCD) DEALL DR5 A0h DR5 VIF (Volume flow I/h) 3Bh 74h DR5 Value LSB 27h 27h E9h CRC 3 19h E1h  $\frac{1}{\Box}$  CRC 3 04h 29h DR5 Value (= 127) **120 CM 261** 01h 86h DR5 Value MSB 00h and 00h Abh DR6 DIF (6 digit BCD) DEALL DR6 VIF (Power 100 mW) 2Ah 2Ah 44h DR6 Value LSB 97h 8Dh DR6 Value (= 3297) 32h 32h DAh DR6 Value MSB 00h BCh **56** DR7 DIF (4 digit BCD) 0Ah <mark>ECh</mark> **AES-Encrypted Block 3** AES-Encrypted Block 3 DR7 VIF (Flow Temp. 100 m °C) 5Ah F6h DR7 Value LSB 43h 17h DR7 Value MSB (= 443) 04h 50h DR8 DIF (4 digit BCD) 0Ah 05h DR8 VIF (Return Temp. 100 m °C) 5Eh 59h DR8 Value LSB 51h 51h 22h DR8 Value MSB (= 251) 02h 92h 85h DR9 DIF (2 byte integer) **12DM** DR9 DDE (2 byte integer) CRC 4 7Dh 10Eh  $\overline{\mathsf{d}}$  CRC 4 **CRC 4** 68h CDh DR9 VIF (FD-Table) **FDh** FDh 93h DR9 VIFE (error flag) 17h 17h B9h DR9 Value LSB 00h B2h DR9 Value MSB ( = 0) 00h ABh Dummy Fill Byte due to AES 2Fh 2Fh 76h CRC 5 D7h 51h  $\overline{a}$ CRC 5 DBh A6h

### **Table P.5** *(continued)*



### **Table P.6 — RSP-UD - Heat meter (M-Bus)**

## **Table P.6** *(continued)*



## **P.4 Heat cost allocator**

#### **Example for heat cost allocator with RF-Adapter**



### **AES key according to FIPS 197 (LSB first):**

- = Manu. spec. at least 8 bytes unique for each meter
- = 00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F

#### **AES CBC initial vector according to FIPS 197 (LSB first):**

- = M Field + A Field + 8 bytes Access No
- = 93 44 88 77 66 55 55 08 00 00 00 00 00 00 00 00

### **Table P.7 — SND-NR - H.C.A. (wM-Bus)**



## **Table P.7** *(continued)*



## **Table P.7** *(continued)*





## **Table P.8 — RSP-UD - H.C.A. (M-Bus)**

## **Table P.8** *(continued)*



### **P.5 Installation procedure with a special installation message**

### **Example for COM controller**





#### **AES key according to FIPS 197 (LSB first):**

= Manu. spec. at least 8 bytes unique for each meter

= 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F 11

#### **AES CBC initial vector according to FIPS 197 (LSB first):**

 $=$  M Field + A Field + 8 bytes Access No

= 93 15 78 56 34 12 33 03 01 01 01 01 01 01 01 01



#### **Table P.9 — SND-IR (wM-Bus)**

## **Table P.9** *(continued)*





## **Table P.9** *(continued)*



## **Table P.9** *(continued)*



### **Table P.10 — CNF-IR (wM-Bus)**

### **P.6 Send a command with an acknowledge**

A SND-UD is applied to transport a command to a meter. When C-field 53h or 73h is applied, the meter will acknowledge a successful reception of the command. The bit "application error" in the status byte of the meter acknowledge indicates that an application error has happened during command execution.

### **Example for COM controller**



#### **Water meter with RF adapter example**



#### **AES key according to FIPS 197 (LSB first):**

= Manu. spec. at least 8 bytes unique for each meter

= 82 B0 55 11 91 F5 1D 66 EF CD AB 89 67 45 23 01

#### **AES CBC initial vector according to FIPS 197 (LSB first):**

= M Field + A Field + 8 bytes Access No

= 24 23 44 22 75 92 29 07 7D 7D 7D 7D 7D 7D 7D 7D



### **Table P.11 — SND-UD (wM-Bus)**

### **SND-UD; Correction of time (wM-Bus) wM-Bus frame COM-> water meter Bytes [hex] Byte No** Field name Content **Bytes** [hex] **plain AES coded** CI Field Special CI to add/subtract time offset 6Dh 6Dh **Ident.Nr.** Serial No LSB (BCD) 44h 44h 44h **Ident.Nr.** Serial No (BCD) **22h** 22h 22h Ident.Nr. Serial No (BCD) 8 16 175h 75h 75h Ident.Nr. Serial No MSB (BCD) of meter 92h 92h 92h **Application Layer** Application Layer Manufr Manufacturer code 24h 24h 24h Manufr Manufacturer code 23h 23h 23h Version Version (or Generation number) 29h 29h 29h **21** Device type  $\left|$  Device type (Medium = Water)  $\left|$  07h  $\right|$  07h Access No. Transmission counter 7Dh 7Dh 7Dh 7Dh Status State (no RSSI level available) 800h 00h 00h Configuration NNNNCCRHb (1 encr. block) 00h 10h Configuration BAS0MMMMb (bidir., RX on, AES) C0h | 05h AES-Verify Encryption verification 2Fh 3Ah AES-Verify Encryption verification 2Fh 2Fh 97h TC-Field Add time difference **01h 31h** 31h CRC 2 77h 14h  $\overline{a}$  CRC 2 61h 25h Time Value format J, LSB 32h **32h** FBh Time Value (add 1 minute, 50 seconds) 01h F4h Time Value MSB 00h 34h Reserved Reserved, set to 0 00h 68h Encrypted Block 1 AES Encrypted Block 1 Reserved Reserved, set to 0 00h 1Ch Reserved Reserved, set to 0 00h 41h Reserved Reserved, set to 0 00h 54h Reserved Reserved, set to 0 00h **78h** AES Reserved Reserved, set to 0 00h **FBh**  CMD-Verify Command verification 2Fh 2Fh EAh CMD-Verify Command verification 2Fh 2Fh 0Bh CMD-Verify Command verification 2Fh 2Fh C6h CMD-Verify Command verification 2Fh 2Fh 6Eh CRC 3 79h A0h  $\overline{a}$ CRC 3 F1h 27h

### **Table P.11** *(continued)*


### **Table P.12 — ACK long (wM-Bus)**

## **P.7 Request of the selected data**

A REQ\_UD2 is used either to request the standard meter consumption data or to read responses of a command or prove successful execution of a command. After a command, the RSP\_UD may consist of either the expected answer to that command (e.g. "get valve state") or the standard answer if the command "set new key" was applied, or an "application error" if the execution of the command was not successful (e.g. using the wrong encryption key for this meter). An application error will be indicated in the status byte of the meter's acknowledge datagram.

#### **Example for COM controller**



#### **Example for heat cost allocator**



#### **AES key according to FIPS 197 (LSB first):**

- = Manu. spec. at least 8 bytes unique for each meter
- = 00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F

#### **AES CBC initial vector according to FIPS 197 (LSB first):**

- $=$  M Field + A Field + 8 bytes Access No
- = 68 50 78 56 34 12 8F 08 02 02 02 02 02 02 02 02







## **Table P.14 — RSP-UD (wM-Bus data)**

## **Table P.14** *(continued)*



#### or alternative







#### **Table P.15** *(continued)*

NOTE This example shows an "application error", which is responded instead of expected data because the partner applied a wrong key in the encrypted command.

# **P.8 Reset of the link by a SND-NKE**

If the communication partner intends to finish communication, it sends a SND-NKE as last. The meter does not respond to this SND-NKE and stops the repetition of the last send datagram.

## **Example for COM controller**



#### **Table P.16 — SND-NKE (wM-Bus)**





## **Table P.16** *(continued)*

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